## Lab Exercise 8: Image Stitching (Mosaicing)

- Objective: Stitch multiple images together to form a panorama.
- Task: Using feature detection and homography estimation, stitch two or more images into a single panoramic view.

```
import cv2 import
numpy as np
import sys
from google.colab.patches import cv2_imshow
class Image_Stitching():
                             def
 __init__(self) :
self.ratio=0.85
self.min_match=10
self.sift=cv2.SIFT_create()
self.smoothing_window_size=800
    def registration(self,img1,img2):
        img1 = cv2.cvtColor(img1, cv2.COLOR_BGR2GRAY)
img2 = cv2.cvtColor(img2, cv2.COLOR_BGR2GRAY)
kp1, des1 = self.sift.detectAndCompute(img1, None)
kp2, des2 = self.sift.detectAndCompute(img2, None)
matcher = cv2.BFMatcher()
                                  raw_matches =
matcher.knnMatch(des1, des2, k=2)
                                          good points =
                                   for m1, m2 in
           good_matches=[]
[]
raw matches:
            if m1.distance < self.ratio * m2.distance:</pre>
                good_points.append((m1.trainIdx, m1.queryIdx))
                                 img3 = cv2.drawMatchesKnn(img1, kp1, img2, kp2,
good_matches.append([m1])
good_matches, None, flags=2)
                                     cv2.imwrite('matching.jpg', img3)
len(good_points) > self.min_match:
            image1_kp = np.float32(
                [kp1[i].pt for (_, i) in good_points])
image2 kp = np.float32(
                [kp2[i].pt for (i, _) in good_points])
            H, status = cv2.findHomography(image2_kp, image1_kp, cv2.RANSAC,5.0)
return H
    def create_mask(self,img1,img2,version):
       height_img1 = img1.shape[0]
                                            width_img1 =
img1.shape[1]
                      width_img2 = img2.shape[1]
height_panorama = height_img1
                                      width_panorama = width_img1
+width_img2
                    offset = int(self.smoothing_window_size / 2)
barrier = img1.shape[1] - int(self.smoothing_window_size / 2)
mask = np.zeros((height_panorama, width_panorama))
version== 'left_image':
            mask[:, barrier - offset:barrier + offset ] = np.tile(np.linspace(1, 0, 2 * offset ).T, (height_panorama, 1))
mask[:, :barrier - offset] = 1
                                       else:
            mask[:, barrier - offset :barrier + offset ] = np.tile(np.linspace(0, 1, 2 * offset ).T, (height_panorama,
1))
                mask[:, barrier + offset:] = 1
        return cv2.merge([mask, mask, mask])
    def blending(self,img1,img2):
                                          H =
self.registration(img1,img2)
height img1 = img1.shape[0]
                                    width img1
= img1.shape[1]
                        width img2 =
img2.shape[1]
                     height panorama =
height_img1 width panorama = width img1 +width
             panorama1 =
np.zeroswidthbgptnpanonamawidthbmganowadah_3mg2
mask1 =
```

```
')
          panorama1[0:img1.shape[0],
0:img1.shape[1], :] = img1
                                  panorama1
*= mask1
                mask2 =
self.create_mask(img1,img2,version='right_imag
           panorama2 =
e')
cv2.warpPerspective(img2, H, (width_panorama,
height_panorama))*mask2
result=panorama1+panorama2
       rows, cols = np.where(result[:, :, 0] != 0)
min_row, max_row = min(rows), max(rows) + 1
                                                   min_col,
max_col = min(cols), max(cols) + 1
                                        final_result =
result[min_row:max_row, min_col:max_col, :]
                                                   return
final_result
def main(argv1,argv2):
    img1 = cv2.imread(argv1)
img2 = cv2.imread(argv2)
   # Check if images were loaded successfully
if img1 is None or img2 is None:
       print(f"Error: Could not load image files: {argv1}, {argv2}")
       # Print current working directory for debugging
import os
                  print(f"Current working directory:
{os.getcwd()}")
                       return # Exit the function if
images are not loaded
    final=Image_Stitching().blending(img1,img2)
cv2.imwrite('panorama.jpg', final) if __name__
== '__main__':
                 try:
       main(sys.argv[1],sys.argv[2])
                                         except
IndexError:
                   print ("Please input two
source images: ")
Error: Could not load image files: -f, /root/.local/share/jupyter/runtime/kernel-47a714ed-aeac-4422-bbf8-6a01f398645e.
     Current working directory: /content
# image 1
img1 = cv2.imread('q11.jpg')
```

self.create\_mask(img1,img2,version='left\_image

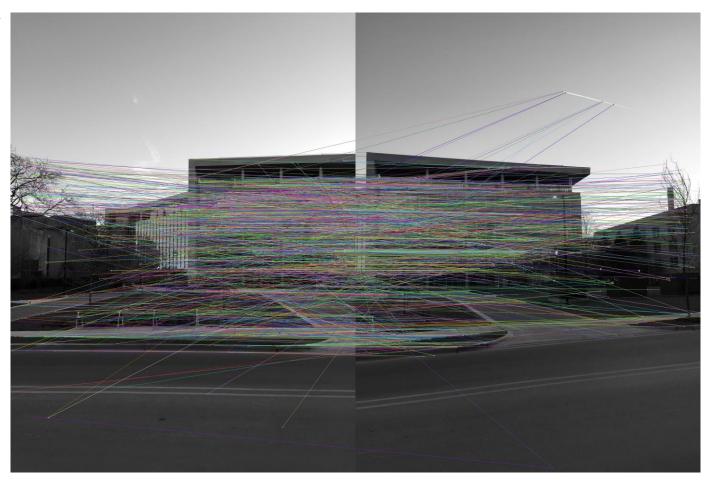
cv2\_imshow(img1)



# image 2 img2 =
cv2.imread('q22.jpg')
cv2\_imshow(img2)







## Paranoma

