

# Discrete-Time Signal processing

## Z-transform

- Introduction
- z-Transform
- Properties of the Region of Convergence for the z-transform
- The inverse z-Transform
- z-Transform Properties

## Introduction

- Fourier transform plays a key role in analyzing and representing discrete-time signals and systems, but does not converge for all signals.
- Continuous systems: Laplace transform is a generalization of the Fourier transform.
- Discrete systems : **z-transform, generalization of DTFT**, converges for a broader class of signals.

## Introduction

Motivation of z-transform:

- The Fourier transform does not converge for all sequences and it is useful to have a generalization of the Fourier transform.
- In analytical problems the z-Transform notation is more convenient than the Fourier transform notation.

## z-Transform

- ◆ z-Transform: two-sided, bilateral z-transform

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n} = \mathcal{Z}\{x[n]\}$$

$$x[n] \xleftrightarrow{Z} X(z)$$

- ◆ one-sided, unilateral z-transform

$$X(z) = \sum_{n=0}^{\infty} x[n] z^{-n}$$

- ◆ If  $z = e^{j\omega}$ , z-transform is Fourier transform.

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

## Relationship between z-transform and Fourier transform

- ◆ Express the complex variable  $z$  in polar form as

$$z = re^{j\omega}$$

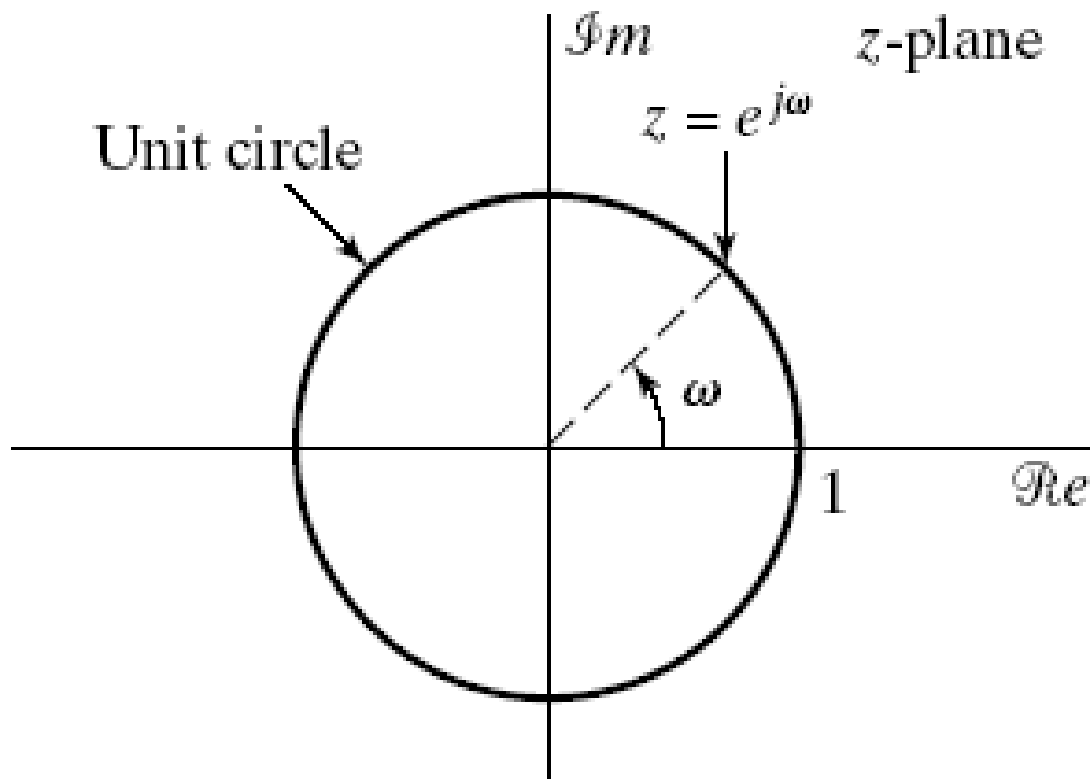
$$X(re^{j\omega}) = \sum_{n=-\infty}^{\infty} (x[n]r^{-n})e^{-j\omega n}$$

- ◆ The Fourier transform of the product of  $x[n]$  and the exponential sequence  $r^{-n}$

$$\text{If } r = 1, \quad X(Z) \longrightarrow X(e^{j\omega})$$

## Complex z plane

$$-\pi \leq \omega < \pi \quad \Leftrightarrow \quad \text{unit circle}$$



## Region of convergence (ROC)

For any given sequence, the set of values of  $z$  for which the  $z$ -transform converges is called the **Region Of Convergence (ROC)**.

$$z = re^{j\omega}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n} \quad \longrightarrow \quad X(re^{j\omega}) = \sum_{n=-\infty}^{\infty} (x[n]r^{-n})e^{-j\omega n}$$

Absolute Summability

$$\left| X(re^{j\omega}) \right| \leq \sum_{n=-\infty}^{\infty} |x[n]r^{-n}| < \infty$$

$$\left| X(z) \right| \leq \sum_{n=0}^{\infty} |x[n]| |z|^{-n} < \infty$$

The ROC consists of all values of  $z$  such that the inequality in the above holds



## Region of convergence (ROC)

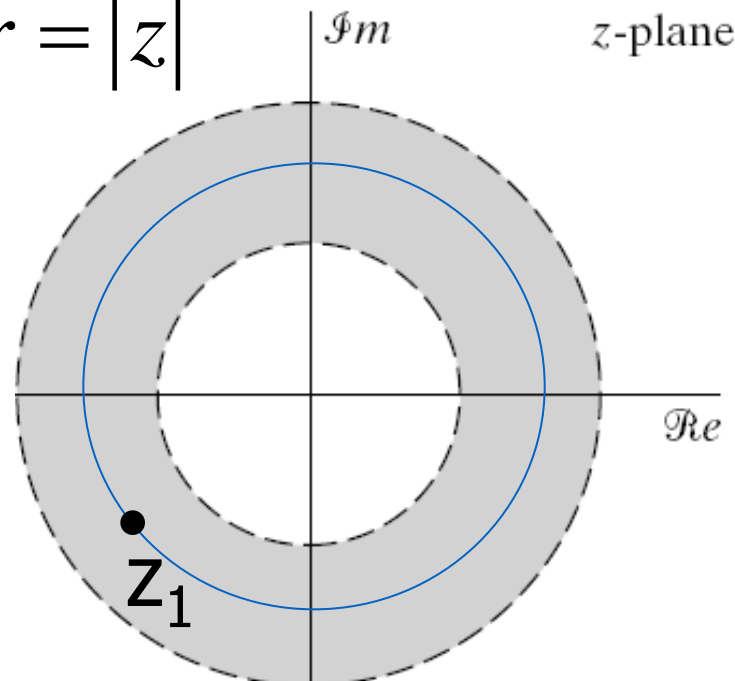
$$|X(z)| \leq \sum_{n=0}^{\infty} |x[n]| |z|^{-n} < \infty$$

- ◆ Convergence of the z-transform for a given sequence depends only on

$$r = |z|$$

if some value of  $z$ , say,  $z = z_1$ , is in the ROC,

then all values of  $z$  on the circle defined by  $|z| = |z_1|$  will also be in the ROC.



if ROC includes unit circle, then Fourier transform and all its derivatives with respect to  $\omega$  must be continuous functions of  $\omega$ .

- ◆ The z-transform is most useful when the infinite sum can be expressed in closed form, usually a ratio of polynomials in  $z$  (or  $z^{-1}$ ).

$$X(z) = \frac{P(z)}{Q(z)}$$

- ◆ Zero: The value of  $z$  for which  $X(z) = 0$
- ◆ Pole: The value of  $z$  for which  $X(z) = \infty$

**Example:****Ex.1 Right-sided exponential sequence**

- ◆ Determine the z-transform, including the ROC in z-plane and a sketch of the pole-zero-plot, for sequence:

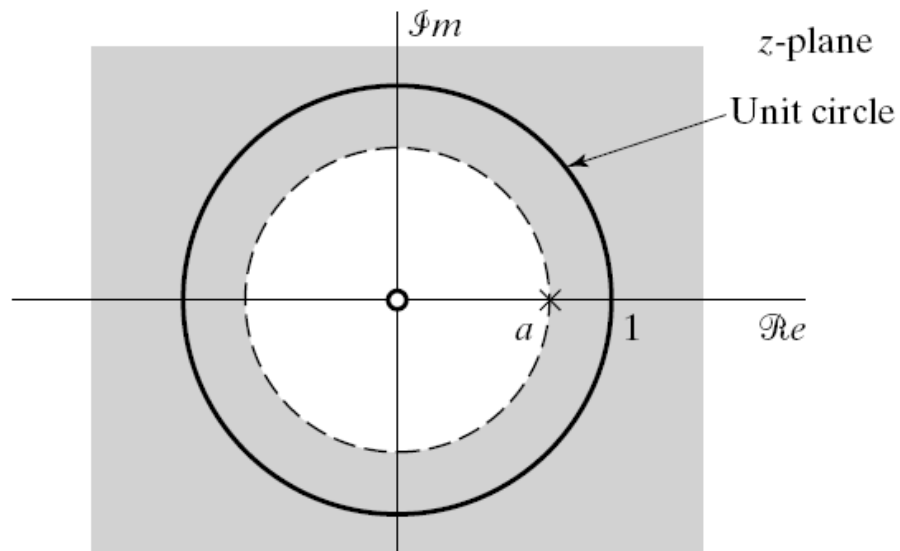
$$x[n] = a^n u[n]$$

**Solution:**

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

**ROC:**  $|az^{-1}| < 1$  or  $|z| > |a|$

*zero :  $z = 0$       pole :  $z = a$*



○ : zeros

× : poles

Gray region: ROC

$$x[n] = a^n u[n]$$

$$X(z) = \frac{z}{z - a}$$

$$\text{for } |z| > |a|$$

## Ex.2 Left-sided exponential sequence

- ◆ Determine the z-transform, including the ROC, pole-zero-plot, for sequence:

$$x[n] = -a^n u[-n-1]$$

Solution:

$$X(z) = -\sum_{n=-\infty}^{\infty} a^n u[-n-1] z^{-n} = -\sum_{n=-\infty}^{-1} a^n z^{-n}$$

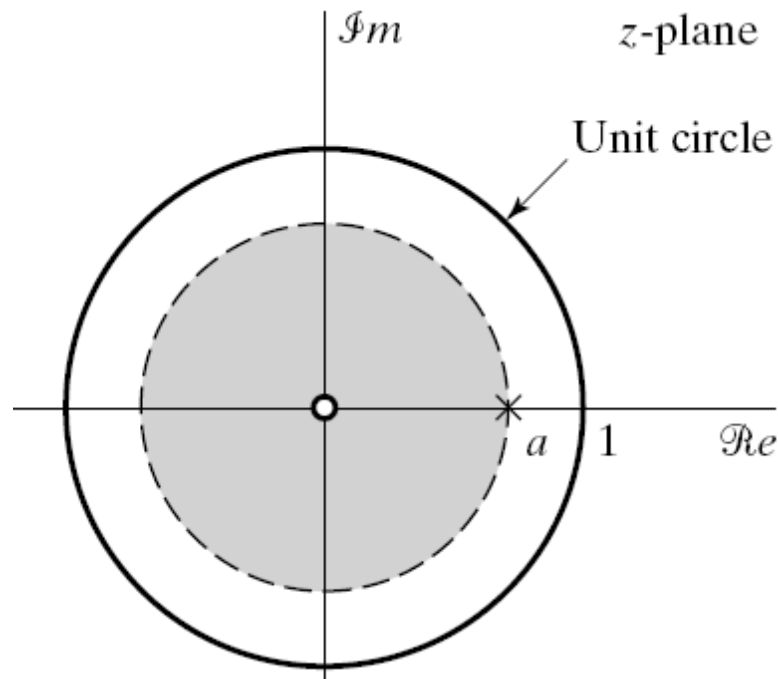
$$= -\sum_{n=1}^{\infty} a^{-n} z^n = -\sum_{n=1}^{\infty} (a^{-1} z)^n = -\frac{a^{-1} z}{1 - a^{-1} z} = \frac{z}{z - a}$$

ROC:  $|z| < |a|$ ,    *zero* :  $z = 0$     *pole* :  $z = a$

$$x[n] = -a^n u[-n-1]$$

$$X(z) = \frac{z}{z-a}$$

$$\text{for } |z| < |a|$$



### Ex. 3 Sum of two exponential sequences

◆ Determine the z-transform, including the ROC, pole-zero-plot, for sequence:

**Solution:**

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + \left(-\frac{1}{3}\right)^n u[n]$$

$$X(z) = \sum_{n=-\infty}^{\infty} \left\{ \left(\frac{1}{2}\right)^n u[n] + \left(-\frac{1}{3}\right)^n u[n] \right\} z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} \left(\frac{1}{2}\right)^n u[n] z^{-n} + \sum_{n=-\infty}^{\infty} \left(-\frac{1}{3}\right)^n u[n] z^{-n}$$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{2} z^{-1}\right)^n + \sum_{n=0}^{\infty} \left(-\frac{1}{3} z^{-1}\right)^n$$

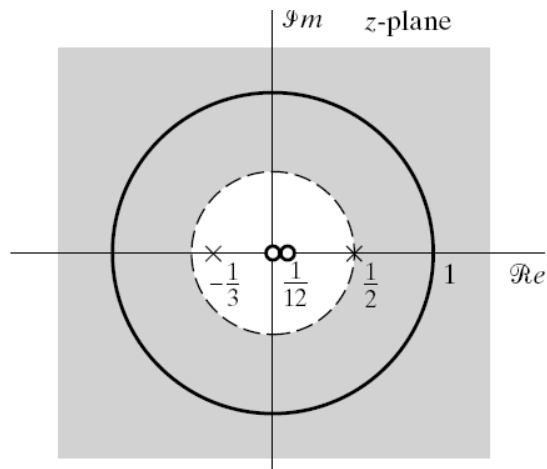
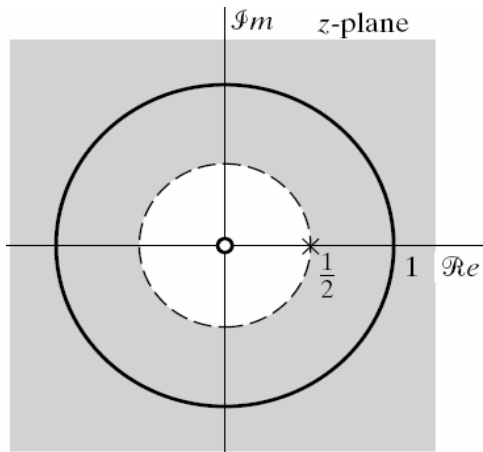
### Example 3

#### Sum of two exponential sequences

$$\begin{aligned}
 X(z) &= \sum_{n=0}^{\infty} \left( \frac{1}{2} z^{-1} \right)^n + \sum_{n=-\infty}^{\infty} \left( -\frac{1}{3} z^{-1} \right)^n \\
 &= \frac{1}{1 - \frac{1}{2} z^{-1}} + \frac{1}{1 + \frac{1}{3} z^{-1}} = \frac{2z \left( z - \frac{1}{12} \right)}{\left( 1 - \frac{1}{2} z^{-1} \right) \left( 1 + \frac{1}{3} z^{-1} \right)}
 \end{aligned}$$

ROC:  $|z| > \frac{1}{2}$  and  $|z| > \frac{1}{3} \Rightarrow ROC : |z| > \frac{1}{2}$





$$\frac{1}{1 - \frac{1}{2} z^{-1}}$$

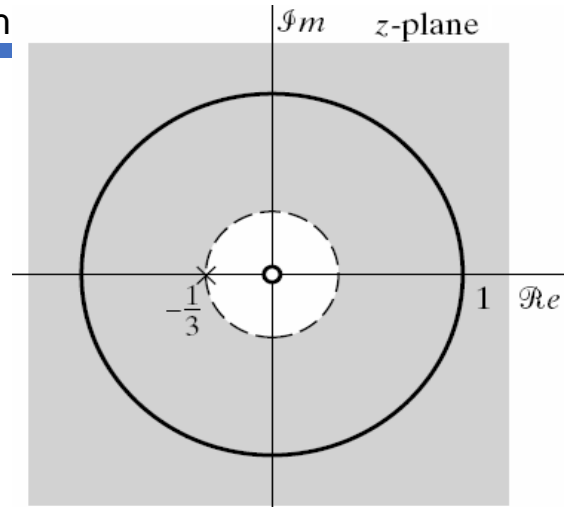
+

$$\frac{1}{1 + \frac{1}{3} z}$$



$$\frac{2z \left( z - \frac{1}{12} \right)}{\left( 1 - \frac{1}{2} z^{-1} \right) \left( 1 + \frac{1}{3} z^{-1} \right)}$$

$$x[n] = \left( \frac{1}{2} \right)^n u[n] + \left( -\frac{1}{3} \right)^n u[n]$$



### Example 4: Sum of two exponential

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + \left(-\frac{1}{3}\right)^n u[n]$$

$$x[n] = a^n u[n]$$

Solution:

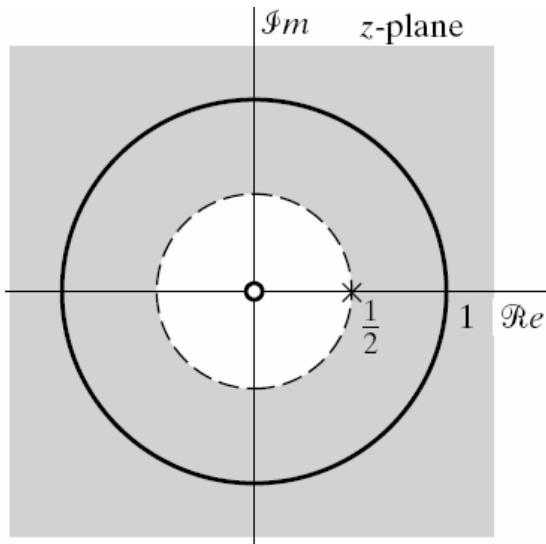
$$\left(\frac{1}{2}\right)^n u[n] \xleftrightarrow{z} \frac{1}{1 - \frac{1}{2} z^{-1}}, \quad |z| > \frac{1}{2}$$

$$X(z) = \frac{z}{z - a}$$

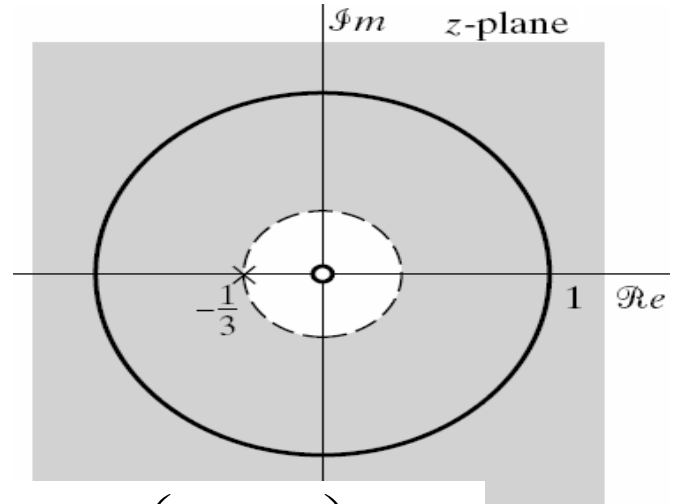
for  $|z| > |a|$

$$\left(-\frac{1}{3}\right)^n u[n] \xleftrightarrow{z} \frac{1}{1 + \frac{1}{3} z^{-1}}, \quad |z| > \frac{1}{3}$$

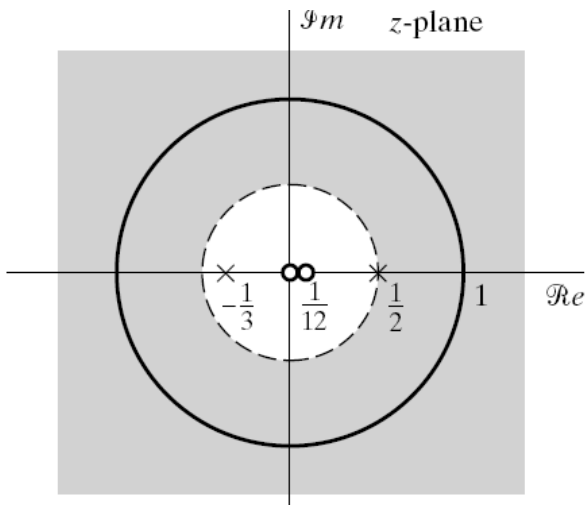
$$\left(\frac{1}{2}\right)^n u[n] + \left(-\frac{1}{3}\right)^n u[n] \xleftrightarrow{z} \frac{1}{1 - \frac{1}{2} z^{-1}} + \frac{1}{1 + \frac{1}{3} z^{-1}}, \quad |z| > \frac{1}{2} \quad \text{ROC:}$$



$$\frac{1}{1 - \frac{1}{2} z^{-1}} + \frac{1}{1 + \frac{1}{3} z^{-1}}$$



$$\frac{2z \left( z - \frac{1}{12} \right)}{\left( 1 - \frac{1}{2} z^{-1} \right) \left( 1 + \frac{1}{3} z^{-1} \right)}$$



$$x[n] = \left( \frac{1}{2} \right)^n u[n] + \left( -\frac{1}{3} \right)^n u[n]$$

Example 5:

Two-sided exponential sequence

$$x[n] = \left(-\frac{1}{3}\right)^n u[n] - \left(\frac{1}{2}\right)^n u[-n-1]$$

Solution:

$$\left(-\frac{1}{3}\right)^n u[n] \xleftrightarrow{z} \frac{1}{1 + \frac{1}{3}z^{-1}}, \quad |z| > \frac{1}{3}$$

$$-\left(\frac{1}{2}\right)^n u[-n-1] \xleftrightarrow{z} \frac{1}{1 - \frac{1}{2}z^{-1}}, \quad |z| < \frac{1}{2}$$

$$X(z) = \frac{1}{1 + \frac{1}{3}z^{-1}} + \frac{1}{1 - \frac{1}{2}z^{-1}} = \frac{2z\left(z - \frac{1}{12}\right)}{\left(1 + \frac{1}{3}z^{-1}\right)\left(1 - \frac{1}{2}z^{-1}\right)}$$

$$ROC: \frac{1}{3} < |z| < \frac{1}{2}$$

$$x[n] = -a^n u[-n-1]$$

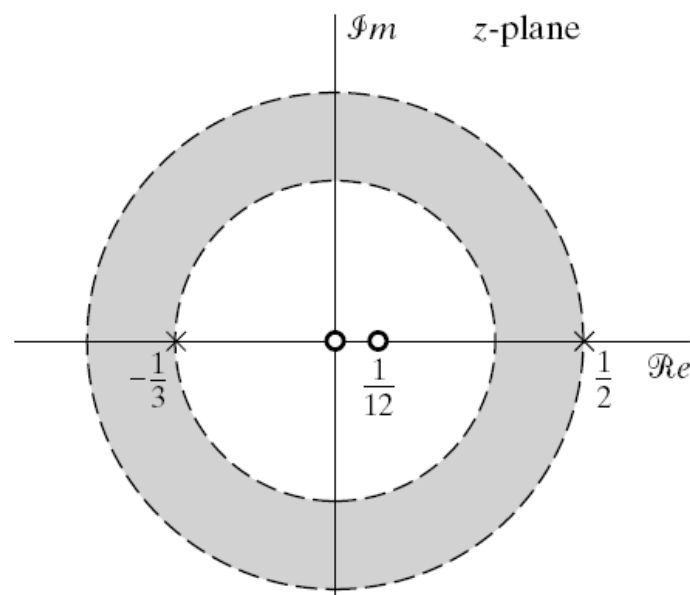
$$X(z) = \frac{z}{z-a}$$

$$\text{for } |z| < |a|$$

$$X(z) = \frac{1}{1 + \frac{1}{3}z^{-1}} + \frac{1}{1 - \frac{1}{2}z^{-1}} = \frac{2z\left(z - \frac{1}{12}\right)}{\left(1 + \frac{1}{3}z^{-1}\right)\left(1 - \frac{1}{2}z^{-1}\right)} \quad ROC: \frac{1}{3} < |z| < \frac{1}{2}$$

$$x[n] = \left(-\frac{1}{3}\right)^n u[n] - \left(\frac{1}{2}\right)^n u[-n-1]$$

ROC, pole-zero-plot



## Finite-length sequence

$$X(z) = \sum_{n=N_1}^{N_2} x[n] z^{-n}$$

**Example :**

$$x[n] = \delta[n] + \delta[n-5]$$

$$X(z) = 1 + z^{-5} \quad ROC : |z| > 0$$

## Example 6: Finite-length sequence

- ◆ Determine the z-transform, including the ROC, pole-zero-plot, for sequence:

$$x[n] = \begin{cases} a^n, & 0 \leq n \leq N-1 \\ 0, & \text{otherwise} \end{cases}$$

**Solution:**

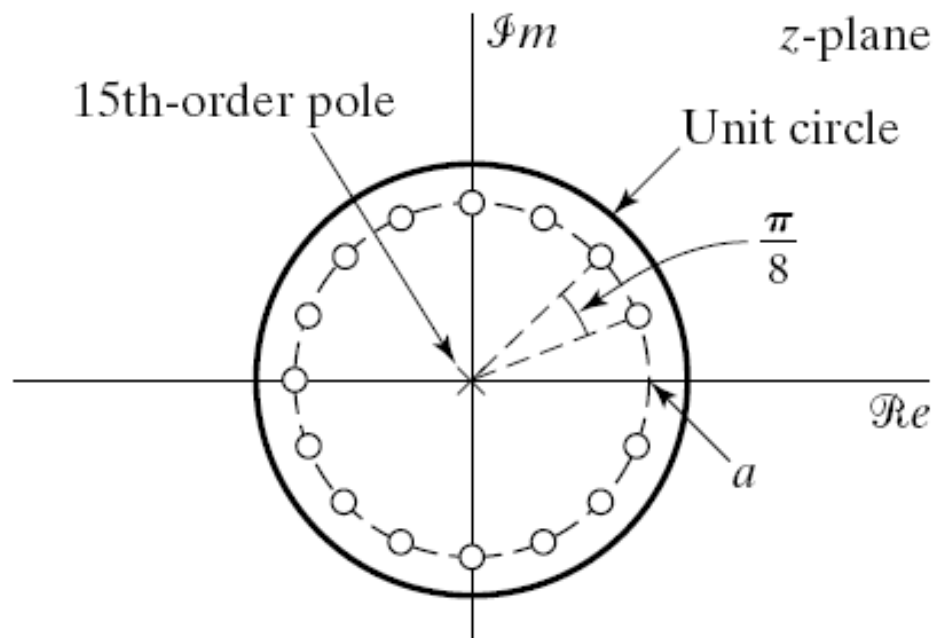
$$\begin{aligned} X(z) &= \sum_{n=0}^{N-1} a^n z^{-n} = \sum_{n=0}^{N-1} (az^{-1})^n \\ &= \frac{1 - (az^{-1})^N}{1 - az^{-1}} = \frac{1}{z^{N-1}} \frac{z^N - a^N}{z - a} \quad \text{ROC: } |z| > 0 \end{aligned}$$

**$N=16$ ,  $a$  is real**

$$X(z) = \frac{1}{z^{N-1}} \frac{z^N - a^N}{z - a}$$

$$ROC : |z| > 0$$

pole-zero-plot





## **z-transform pairs**

$$\delta[n] \leftrightarrow 1, \quad ROC : all \ z$$

$$u[n] \leftrightarrow \frac{1}{1-z^{-1}}, \quad ROC : |z| > 1$$

$$-u[-n-1] \leftrightarrow \frac{1}{1-z^{-1}}, \quad ROC : |z| < 1$$

$$\delta[n-m] \leftrightarrow z^{-m},$$

$$ROC : all \ z \text{ except } 0 \text{ (if } m > 0) \text{ or } \infty \text{ (if } m < 0)$$

**z-transform pairs**

$$a^n u[n] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad ROC : |z| > |a|$$

$$-a^n u[-n-1] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad ROC : |z| < |a|$$

$$na^n u[n] \leftrightarrow \frac{az^{-1}}{(1 - az^{-1})^2}, \quad ROC : |z| > |a|$$

$$-na^n u[-n-1] \leftrightarrow \frac{az^{-1}}{(1 - az^{-1})^2}, \quad ROC : |z| < |a|$$

## z-transform pairs

$$[\cos w_0 n]u[n] \leftrightarrow \frac{1 - [\cos w_0]z^{-1}}{1 - 2[\cos w_0]z^{-1} + z^{-2}}, \quad ROC : |z| > 1$$

$$[\cos w_0 n]u[n] = \frac{1}{2} \left( e^{jw_0 n} + e^{-jw_0 n} \right) u[n]$$

$$\frac{1}{2} \left( \frac{1}{1 - e^{jw_0} z^{-1}} + \frac{1}{1 - e^{-jw_0} z^{-1}} \right)$$

$$[\sin w_0 n]u[n] \leftrightarrow \frac{[\sin w_0]z^{-1}}{1 - 2[\cos w_0]z^{-1} + z^{-2}}, \quad ROC : |z| > 1$$

## z-transform pairs

$$\left[ r^n \cos w_0 n \right] u[n] \leftrightarrow \frac{1 - [r \cos w_0] z^{-1}}{1 - [2r \cos w_0] z^{-1} + r^2 z^{-2}}, \quad ROC : |z| > r$$

$$\left[ r^n \cos w_0 n \right] u[n] = \frac{1}{2} \left( r^n e^{jw_0 n} + r^n e^{-jw_0 n} \right) u[n]$$

$$\frac{1}{2} \left( \frac{1}{1 - r e^{jw_0} z^{-1}} + \frac{1}{1 - r e^{-jw_0} z^{-1}} \right)$$

$$\left[ r^n \sin w_0 n \right] u[n] \leftrightarrow \frac{[r \sin w_0] z^{-1}}{1 - [2r \cos w_0] z^{-1} + r^2 z^{-2}}, \quad ROC : |z| > r$$

z-transform pairs

$$\begin{cases} a^n, & 0 \leq n \leq N-1 \\ 0, & \text{otherwise} \end{cases} \leftrightarrow \frac{1 - a^N z^{-N}}{1 - az^{-1}},$$

$$ROC : |z| > 0$$

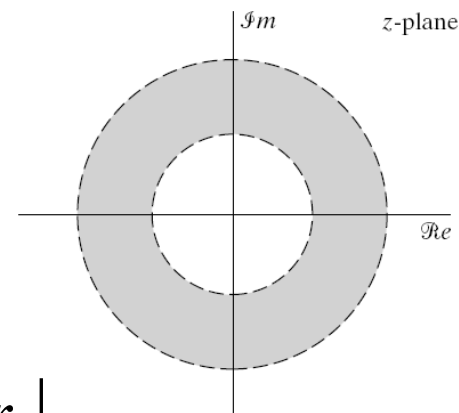
## 3.2 Properties of the ROC for the z-transform

- ◆ **Property 1:** The ROC is a ring or disk in the z-plane centered at the origin.

$$0 \leq r_R < |z| < r_L \leq \infty$$

- ◆ For a given  $x[n]$ , ROC is dependent only on  $|z|$

$$\begin{aligned}
 & r_R^n u[n] - r_L^n u[-n-1] \\
 & \quad \quad \quad \frac{1}{1 - r_R z^{-1}} + \frac{1}{1 - r_L z^{-1}}, \quad \text{ROC: } |r_R| < |z| < |r_L|
 \end{aligned}$$



## 3.2 Properties of the ROC for the z-transform

- ◆ **Property 2:** The Fourier transform of  $x[n]$  converges absolutely if the ROC of the z-transform of  $x[n]$  includes the unit circle.
- ◆ The z-transform reduces to the Fourier transform when  $|z|=1$  ie.  $z = e^{j\omega}$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n} \longrightarrow X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$$

## 3.2 Properties of the ROC for the z-transform

**Property 3:** The ROC cannot contain any poles.

◆  $X(z)$  is infinite at a pole and therefore does not converge.

$$X(z) = \sum_{n=0}^{\infty} x[n] z^{-n} = \frac{P(z)}{Q(z)}$$



### 3.2 Properties of the ROC for the z-transform

- ◆ **Property 4:** If  $x[n]$  is a **finite-duration sequence**, i.e., a sequence that is zero except in a finite interval :  $N_1 \leq n \leq N_2$
- ◆ then the ROC is the entire z-plane, except possible  $z = 0$  or  $z = \infty$

$$X(z) = \sum_{n=N_1}^{N_2} a^n z^{-n}$$

## 3.2 Properties of the ROC for the z-transform

◆ **Property 5:** If  $x[n]$  is a **right-sided sequence**, i.e., a sequence that is zero for  $n \leq N_1 < \infty$  the ROC extends outward from the **outermost** finite pole in  $X(z)$  to (may including)

$z = \infty$

**Proof:**  $x[n] = \sum_{k=1}^N A_k (d_k)^n, n \geq N_1, \quad \sum_{n=-\infty}^{\infty} |x[n]| r^{-n} < \infty$

$$\sum_{n=N_1}^{\infty} \left| \sum_{k=1}^N A_k (d_k)^n \right| r^{-n} \leq \sum_{k=1}^N |A_k| \left( \sum_{n=N_1}^{\infty} |d_k / r|^n \right) < \infty$$

if  $r > |d_N| > |d_{N-1}| > \dots > |d_1|, \quad i.e. \quad r > |d_N|$

## 3.2 Properties of the ROC for the z-transform

- ◆ **Property 6:** If  $x[n]$  is a **left-sided sequence**, i.e., a sequence that is zero for  $n \geq N_2 > -\infty$ , the **ROC** extends inward from the **innermost** nonzero pole in  $X(z)$  to  $z=0$ .

**Proof:**  $x[n] = \sum_{k=1}^N A_k (d_k)^n, n < N_2, \quad \sum_{n=-\infty}^{\infty} |x[n]| r^{-n} < \infty$

$$\sum_{n=-\infty}^{n=N_2} \left| \sum_{k=1}^N A_k (d_k)^n \right| r^{-n} \leq \sum_{k=1}^N |A_k| \left( \sum_{n=-\infty}^{n=N_2} |d_k/r|^n \right) < \infty$$

$$r < |d_k|, \quad r < |d_1|, \quad \dots, \quad r < |d_N|, \quad r < |d_1|$$

## 3.2 Properties of the ROC for the z-transform

- ◆ **Property 5:** If  $x[n]$  is a **right-sided sequence**, i.e., a sequence that is zero for  $n \leq N_1 < \infty$ , the ROC extends outward from the **outermost** finite pole in  $x(z)$  to (possibly including)  $z = \infty$

**Proof:**

$$\begin{aligned}
 x[n] &= \sum_{k=1}^N A_k (d_k)^n & n \geq N_1 \\
 &= \sum_{k=1}^N A_k (d_k)^n u[n], & \text{if } N_1 = 0, \text{ ie. } n \geq 0
 \end{aligned}$$

## Property 5: **right-sided sequence**

$$x[n] = \sum_{k=1}^N A_k (d_k)^n = \sum_{k=1}^N A_k (d_k)^n u[n], \quad n \geq 0$$

for  $A_k (d_k)^n u[n]$  the z-transform:

$$\sum_{n=0}^{\infty} A_k (d_k)^n z^{-n} = \frac{A_k}{1 - d_k z^{-1}}, \quad |z| = r > |d_k|$$

For other terms:

$$r > |d_1|, \dots, r > |d_N|$$

$$\text{if } |d_N| > |d_{N-1}| > \dots > |d_1|$$



ROC

$$r > |d_N|$$

## 3.2 Properties of the ROC for the z-transform

- ◆ **Property 6:** If  $x[n]$  is a **left-sided sequence**, i.e., a sequence that is zero for  $n \geq N_2 > -\infty$ , the ROC extends inward from the **innermost** nonzero pole in  $X(z)$  to  $z = 0$

**Proof:** 
$$x[n] = \sum_{k=1}^N A_k (d_k)^n \quad n < N_2$$

$$= \sum_{k=1}^N A_k (d_k)^n u[-n-1], \quad \text{if } N_2 = 0, \text{ ie. } n < 0$$

## Property 6: left-sided sequence

$$x[n] = \sum_{k=1}^N A_k (d_k)^n = \sum_{k=1}^N A_k (d_k)^n u[-n-1] \quad n < 0$$

for  $A'_k \left[ -(d_k)^n u[-n-1] \right]$  the z-transform:

$$\sum_{n=-\infty}^{-1} -A'_k (d_k)^n z^{-n} = \frac{A'_k}{1 - d_k z^{-1}}, \quad |z| = r < |d_k|$$

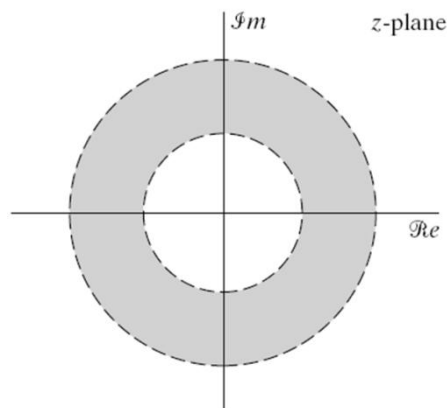
For other terms:

$$r < |d_1|, \dots, r < |d_N| \quad \longrightarrow \quad r < |d_1| \quad \text{ROC}$$

## 3.2 Properties of the ROC for the z-transform

◆ **Property 7:** A **two-sided sequence** is an infinite-duration sequence that is neither right-sided nor left-sided.

If  $x[n]$  is a two-sided sequence, the **ROC** will consist of a **ring** in the z-plane, **bounded** on the **interior** and **exterior** by a **pole** and not containing any poles.





## 3.2 Properties of the ROC for the z-transform

Property 8: ROC must be a connected region.

◆ for **finite-duration sequence**

$$\text{ROC: } 0 < |z| < \infty \quad \text{possible} \quad \begin{matrix} z = 0 \\ z = \infty \end{matrix}$$

◆ for **right-sided sequence**

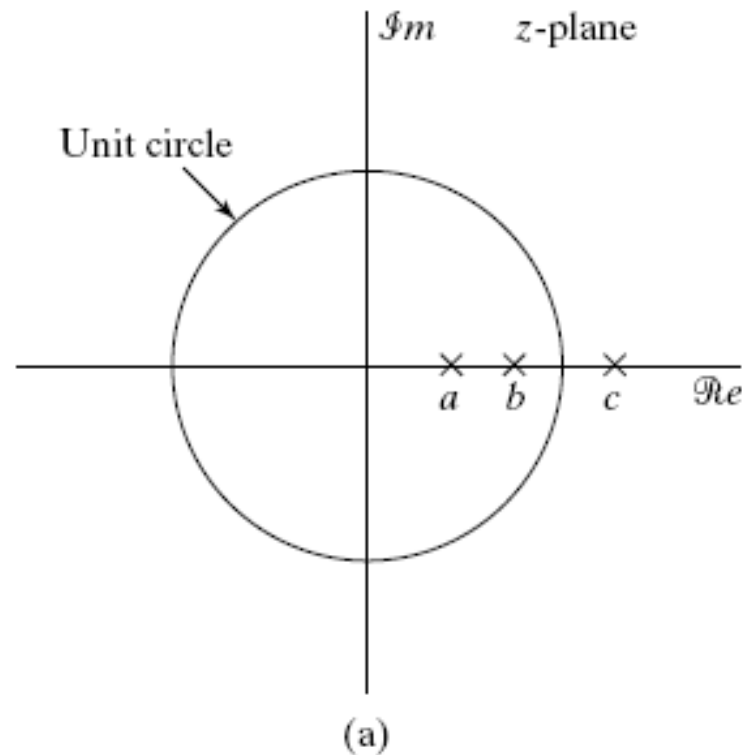
$$\text{ROC: } r_R < |z| < \infty \quad \text{possible} \quad z = \infty$$

◆ for **left-sided sequence**

$$\text{ROC: } 0 < |z| < r_L \quad \text{possible} \quad z = 0$$

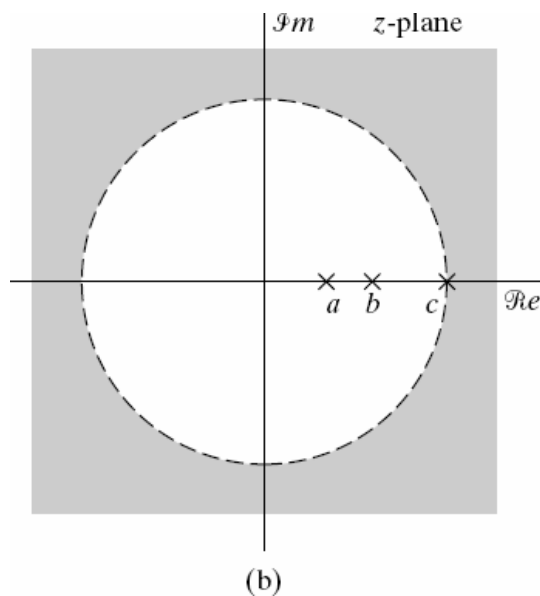
◆ for **two-sided sequence**  $r_R < |z| < r_L$

**Example:** Different possibilities of the ROC define different sequences

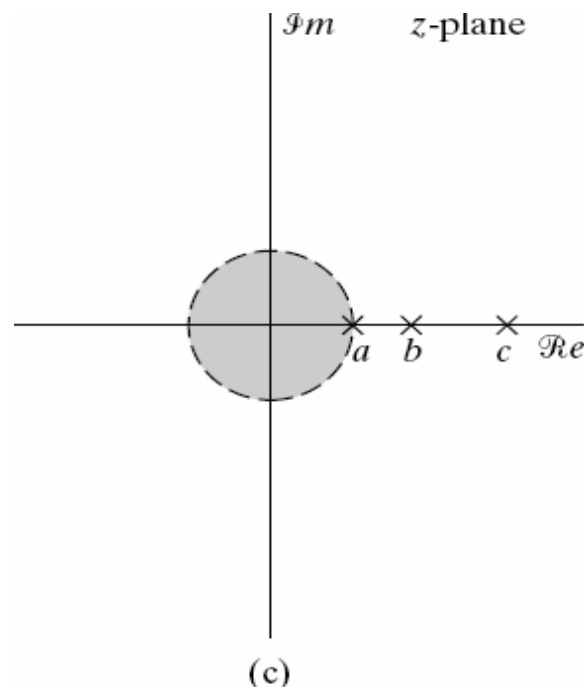


A system with three poles

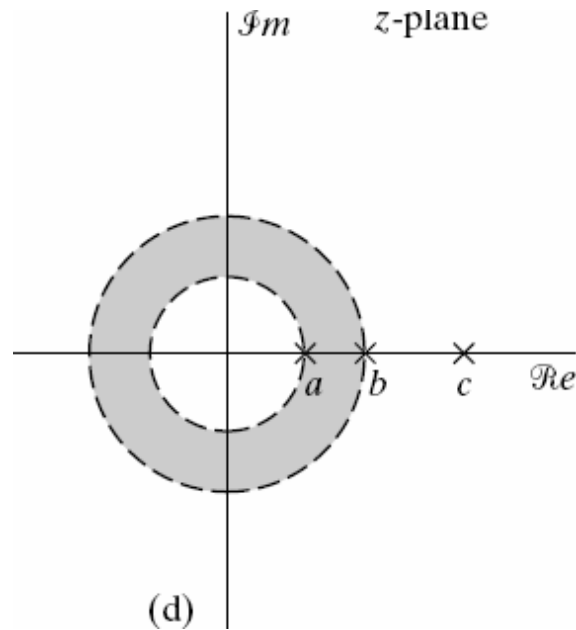
## Different possibilities of the ROC.



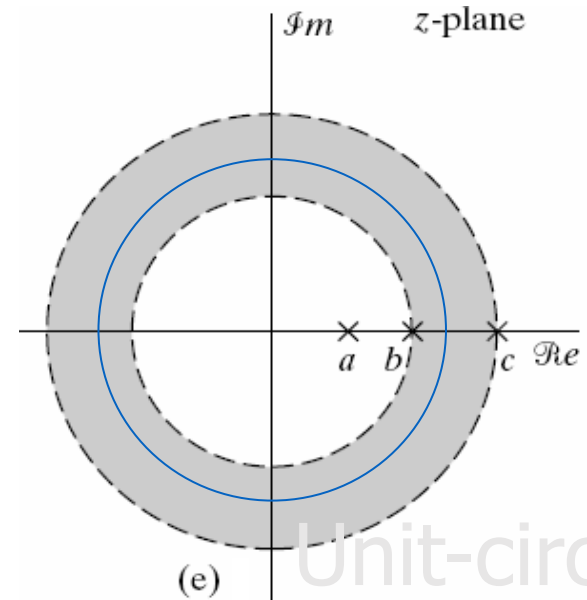
(b) ROC to a  
right-sided sequence



(c) ROC to a  
left-handed sequence



(d) ROC to a  
two-sided sequence.



(e) ROC to another  
two-sided sequence

Unit-circle  
included

## LTI system Stability, Causality, and ROC

A z-transform does not **uniquely determine** a sequence without **specifying the ROC**

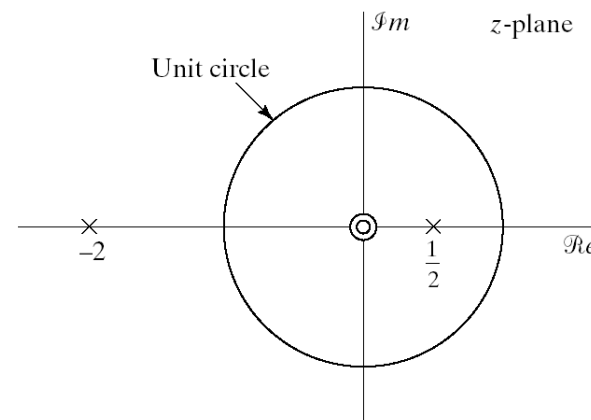
- ◆ It's convenient to specify the ROC implicitly through **time-domain property** of a sequence
- ◆ Consider a **LTI system** with **impulse response  $h[n]$** . The z-transform of  $h[n]$  is called the **system function  $H(z)$**  of the LTI system.
- ◆ **stable system**( $h[n]$  is **absolutely summable** and therefore has a Fourier transform):  
**ROC** include **unit-circle**.
- ◆ **causal system** ( $h[n]=0, \text{for } n<0$ ) : right sided

## Ex. 3.7 Stability, Causality, and the ROC

Consider a LTI system with impulse response  $h[n]$ . The z-transform of  $h[n]$  i.e. the system function  $H(z)$  has the pole-zero plot shown in Figure. Determine the ROC, if the system is:

◆ (1) stable system: (ROC include unit-circle)

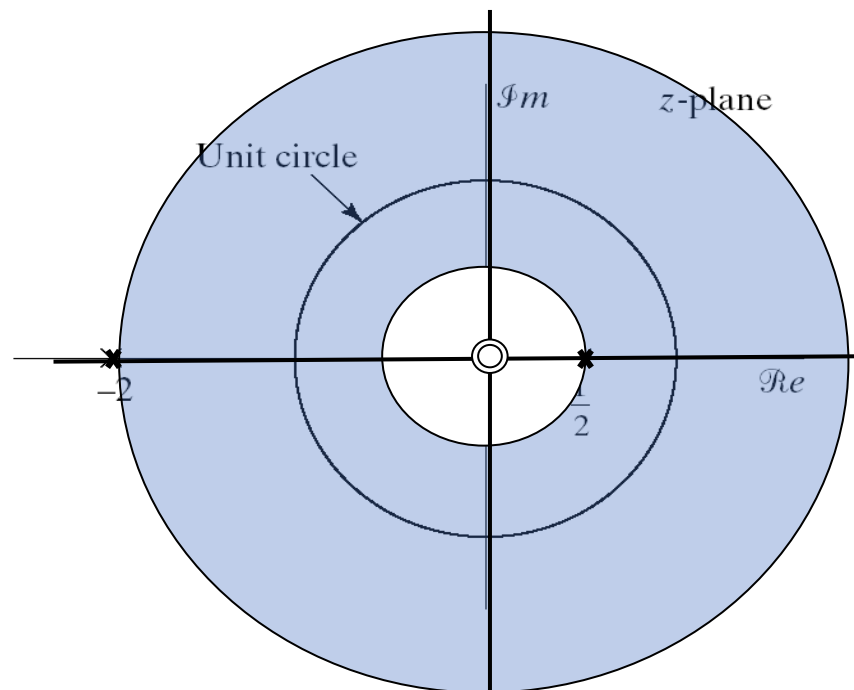
◆ (2) causal system: (right sided sequence)



## Ex. 3.7 Stability, Causality, and the ROC

Solution: (1) **stable system** (ROC include unit-circle),

ROC:  $\frac{1}{2} < |z| < 2$  , the impulse response is **two-sided**, system is **non-causal**. **stable**.

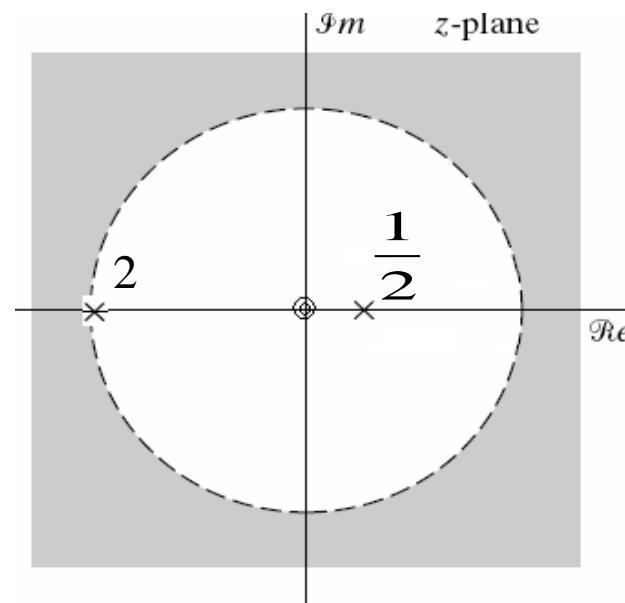


## Ex. 3.7 Stability, Causality, and the ROC

◆ (2) causal system: (right sided sequence)

ROC:  $|z| > 2$ , the impulse response is right-sided. system is causal but unstable.

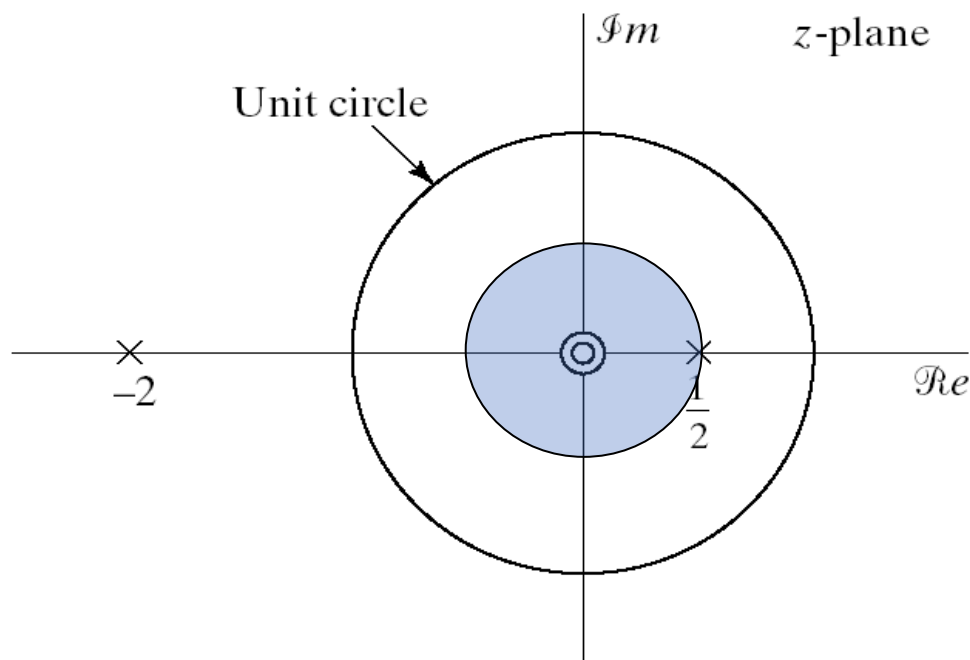
◆ A system is causal and stable if all the poles are inside the unit circle.





## Ex. 3.7 Stability, Causality, and the ROC

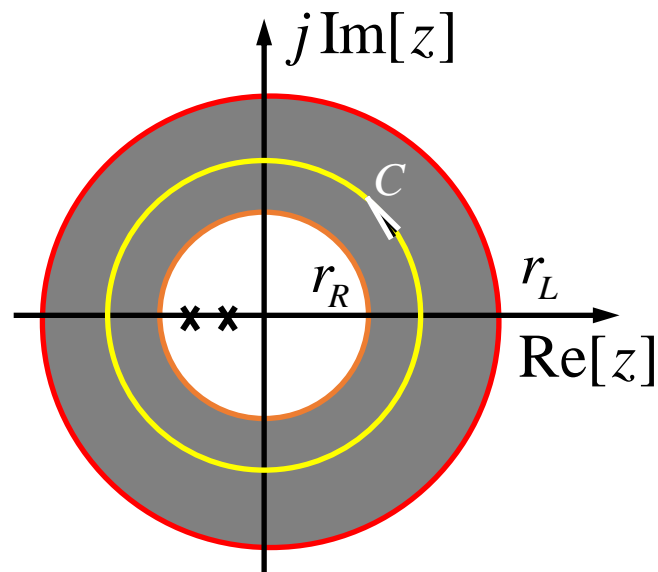
ROC:  $|z| < \frac{1}{2}$ , the impulse response is **left-sided**, system is **non-causal**, **unstable** since the ROC does not include unit circle.



### 3.3 The Inverse Z-Transform

Formal inverse z-transform is based on a Cauchy integral theorem.

$$x_n = \frac{1}{2\pi j} \oint_c X(z) z^{n-1} dz \quad c \in ROC$$



### 3.3 The Inverse Z-Transform

- ◆ Less formal ways are sufficient and preferable in finding the **inverse z-transform**. :
  - ◆ Inspection method
  - ◆ Partial fraction expansion
  - ◆ Power series expansion

## 3.3 The inverse z-Transform

### 3.3.1 Inspection Method

$$a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| > |a|$$

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}}, \quad |z| > \frac{1}{2}$$

$$x[n] = \left(\frac{1}{2}\right)^n u[n]$$

## 3.3 The inverse z-Transform

### 3.3.1 Inspection Method

$$-a^n u[-n-1] \stackrel{z}{\longleftrightarrow} \frac{1}{1-az^{-1}}, \quad |z| < |a|$$

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}}, \quad |z| < \frac{1}{2}$$

$$x[n] = -\left(\frac{1}{2}\right)^n u[-n-1]$$

## 3.3 The inverse z-Transform

### 3.3.2 Partial Fraction Expansion

$$X(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}} = \frac{z^N \sum_{k=0}^M b_k z^{M-k}}{z^M \sum_{k=0}^N a_k z^{N-k}} = \frac{b_0 \prod_{k=0}^M (1 - c_k z^{-1})}{a_0 \prod_{k=0}^N (1 - d_k z^{-1})}$$

$$= \sum_{k=1}^N \frac{A_k}{1 - d_k z^{-1}} \quad \text{if } M < N$$

$$\text{where } A_k = \left( (1 - d_k z^{-1}) X(z) \right) \Big|_{z=d_k}$$

### Example 3.8: Second-Order z-Transform

$$X(z) = \frac{1}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{2}z^{-1}\right)}, \quad |z| > \frac{1}{2}$$

$$X(z) = \frac{A_1}{\left(1 - \frac{1}{4}z^{-1}\right)} + \frac{A_2}{\left(1 - \frac{1}{2}z^{-1}\right)}$$

$$A_1 = \left(1 - \frac{1}{4}z^{-1}\right)X(z)\bigg|_{z=\frac{1}{4}} = -1 \quad A_2 = \left(1 - \frac{1}{2}z^{-1}\right)X(z)\bigg|_{z=\frac{1}{2}} = 2$$

### Example 3.8 : Second-Order z-Transform

$$X(z) = \frac{-1}{\left(1 - \frac{1}{4}z^{-1}\right)} + \frac{2}{\left(1 - \frac{1}{2}z^{-1}\right)}, \quad |z| > \frac{1}{2}$$

$$x[n] = 2\left(\frac{1}{2}\right)^n u[n] - \left(\frac{1}{4}\right)^n u[n]$$



## Inverse Z-Transform by Partial Fraction Expansion

$$X(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}} \quad \text{if } M \geq N$$

$$X(z) = \sum_{r=0}^{M-N} B_r z^{-r} + \sum_{k=1}^N \frac{A_k}{1 - d_k z^{-1}}$$

Br is obtained by long division

## Inverse Z-Transform by Partial Fraction Expansion

◆ if  $M > N$ , and  $X(z)$  has a pole of order  $s$  at  $d = d_i$

$$X(z) = \sum_{r=0}^{M-N} B_r z^{-r} + \sum_{k=1, k \neq i}^N \frac{A_k}{1 - d_k z^{-1}} + \sum_{m=1}^s \frac{C_m}{(1 - d_i z^{-1})^m}$$

$B_r$  is obtained by long division

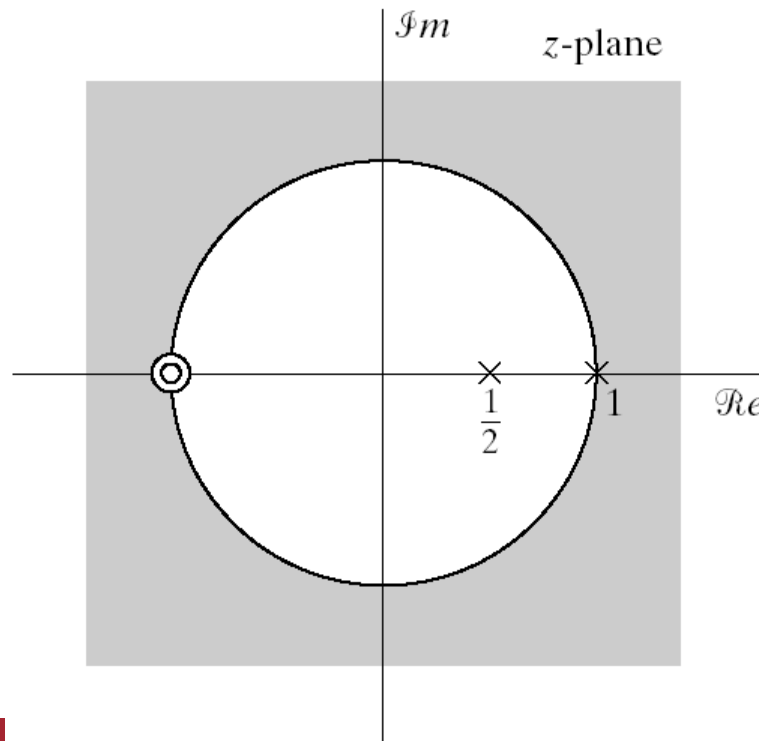
$$A_k = (1 - d_k z^{-1}) X(z) \Big|_{z=d_k}$$

$$C_m = \frac{1}{(s-m)! (-d_i)^{s-m}} \left\{ \frac{d^{s-m}}{d w^{s-m}} \left[ (1 - d_i w)^s X(w^{-1}) \right] \right\}_{w=d_i^{-1}}$$

Example 3.9:

Inverse by Partial Fractions

$$X(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} = \frac{(1 + z^{-1})^2}{\left(1 - \frac{1}{2}z^{-1}\right)(1 - z^{-1})}, \quad |z| > 1$$



$$X(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} = B_0 + \frac{A_1}{1 - \frac{1}{2}z^{-1}} + \frac{A_2}{1 - z^{-1}}$$

$$\left( \frac{1}{2}z^{-2} - \frac{3}{2}z^{-1} + 1 \right) \frac{2}{z^{-2} - 3z^{-1} + 2} = \frac{2}{5z^{-1} - 1}$$

$$X(z) = 2 + \frac{-1 + 5z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)(1 - z^{-1})}$$

$$X(z) = 2 + \frac{-1 + 5z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)(1 - z^{-1})} = 2 + \frac{A_1}{1 - \frac{1}{2}z^{-1}} + \frac{A_2}{1 - z^{-1}}$$

$$A_1 = \left[ \frac{-1 + 5z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)(1 - z^{-1})} \times \left(1 - \frac{1}{2}z^{-1}\right) \right]_{z=\frac{1}{2}} = -9$$

$$A_2 = \left[ \frac{-1 + 5z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)(1 - z^{-1})} \times (1 - z^{-1}) \right]_{z=1} = 8$$

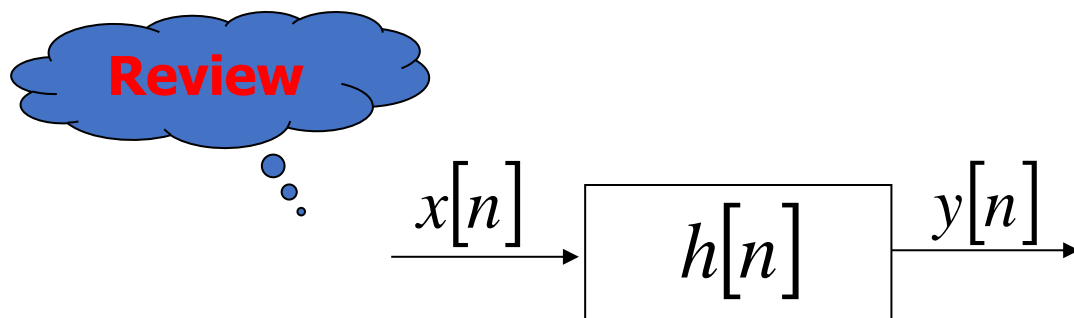
$$X(z) = 2 - \frac{9}{\left(1 - \frac{1}{2}z^{-1}\right)} + \frac{8}{(1 - z^{-1})}, \quad |z| > 1$$

$$2 \xleftrightarrow{z} 2\delta[n] \qquad \frac{1}{\left(1 - \frac{1}{2}z^{-1}\right)} \xleftrightarrow{z} \left(\frac{1}{2}\right)^n u[n]$$

$$\frac{1}{(1 - z^{-1})} \xleftrightarrow{z} u[n]$$

$$x[n] = 2\delta[n] - 9\left(\frac{1}{2}\right)^n u[n] + 8u[n]$$

## LTI system Stability, Causality, and ROC



- ◆ For a LTI system with impulse response  $h[n]$ , if it is causal, what do we know about  $h[n]$ ? Is  $h[n]$  one-sided or two-sided sequence? Left-sided or right-sided?
- ◆ Then what do we know about the ROC of the system function  $H(z)$ ?
- ◆ If the poles of  $H(z)$  are all in the unit circle, is the system stable?

## LTI system Stability, Causality, and ROC

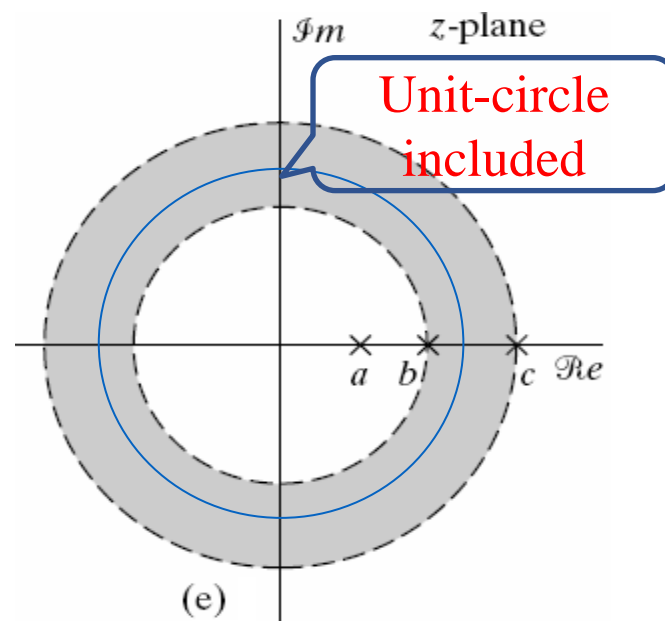
- ◆ For  $H(z)$  with the poles as shown in figure ,



$$H(z) = \frac{1}{(1 - az^{-1})(1 - bz^{-1})(1 - cz^{-1})}$$

can we **uniquely** determine  $h[n]$  ?

- ◆ If ROC of  $H(z)$  is as shown in figure, can we **uniquely** determine  $h[n]$  ?



- ◆ is the system stable ?



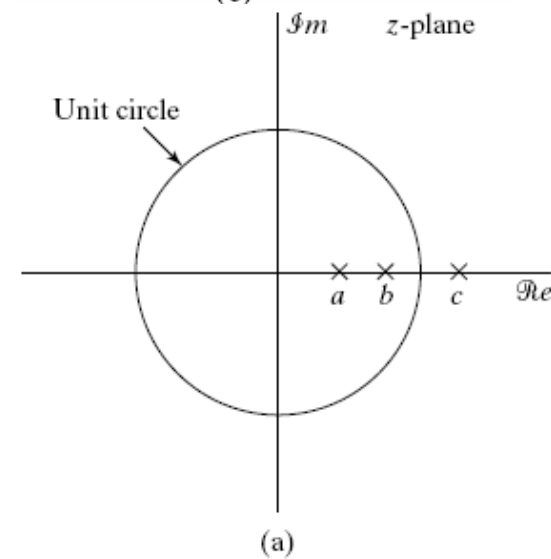
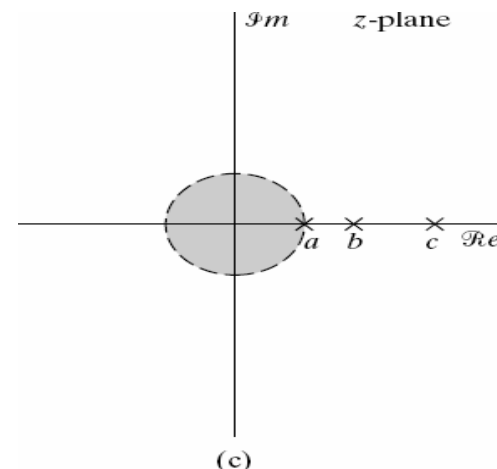
## LTI system Stability, Causality, and ROC

- ◆ For  $H(z)$  with the poles as shown in figure ,

**Review**

$$H(z) = \frac{1}{(1 - az^{-1})(1 - bz^{-1})(1 - cz^{-1})}$$

- ◆ If the system is causal ( $h[n]=0$ , for  $n < 0$ , right-sided ), **What's the ROC like?**
- ◆ If ROC is as shown in figure, is  $h[n]$  one-sided or two-sided? Is the system causal or stable?



### 3.3 The Inverse Z-Transform

#### Review

- ◆ Inspection method
- ◆ Partial fraction expansion
- ◆ Power series expansion

$$\delta[n] \leftrightarrow 1, \quad ROC : all \ z$$

$$a^n u[n] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad ROC : |z| > |a|$$

$$-a^n u[-n-1] \leftrightarrow \frac{1}{1 - az^{-1}}, \quad ROC : |z| < |a|$$

**Review**

Partial Fraction Expansion

◆ if  $M > N$ , and  $X(z)$  has a pole of order  $s$  at  $d = d_i$

$$X(z) = \sum_{r=0}^{M-N} B_r z^{-r} + \sum_{k=1, k \neq i}^N \frac{A_k}{1 - d_k z^{-1}} + \sum_{m=1}^s \frac{C_m}{(1 - d_i z^{-1})^m}$$

$B_r$  is obtained by long division

$$A_k = (1 - d_k z^{-1}) X(z) \Big|_{z=d_k}$$

$$C_m = \frac{1}{(s-m)! (-d_i)^{s-m}} \left\{ \frac{d^{s-m}}{d w^{s-m}} \left[ (1 - d_i w)^s X(w^{-1}) \right] \right\}_{w=d_i^{-1}}$$

## 3.3 The inverse z-Transform

### 3.3.3 Power Series Expansion

$$X(z) = \sum_{n=-\infty}^{n=\infty} x[n] z^{-n}$$
$$= \cdots + x[-2] z^2 + x[-1] z^1 + x[0] + x[1] z^{-1} + x[2] z^{-2} + \cdots$$

### Example 3.10: Finite-Length Sequence

$$X(z) = z^2 \left( 1 - \frac{1}{2} z^{-1} \right) (1 + z^{-1}) (1 - z^{-1}) = z^2 - \frac{1}{2} z - 1 + \frac{1}{2} z^{-1}$$

$$x[n] = \begin{cases} 1, & n = -2 \\ -\frac{1}{2}, & n = -1 \\ -1, & n = 0 \\ \frac{1}{2}, & n = 1 \\ 0, & \text{otherwise} \end{cases}$$

$$x[n] = \delta[n+2] - \frac{1}{2} \delta[n+1] - \delta[n] + \frac{1}{2} \delta[n-1]$$

Ex. 3.11: Inverse Transform by power series expansion

$$X(z) = \log(1 + az^{-1}), \quad |z| > |a|$$

$$\log(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 - \frac{1}{4}x^4 + \dots = \sum_{n=1}^{\infty} \frac{(-1)^{n+1} x^n}{n} \quad |x| < 1$$

$$X(z) = \sum_{n=1}^{\infty} \frac{(-1)^{n+1} a^n z^{-n}}{n}, \quad |az^{-1}| < 1$$

$$x(n) = \begin{cases} (-1)^{n+1} \frac{a^n}{n}, & n \geq 1 \\ 0, & n < 1 \end{cases} = (-1)^{n+1} \frac{a^n}{n} u[n-1]$$

### Example 3.12: Power Series Expansion by Long Division

$$X(z) = \frac{1}{1 - az^{-1}}, \quad |z| > |a| \quad \stackrel{z}{\longleftrightarrow} a^n u[n]$$

$$\begin{array}{r}
 1 + az^{-1} + a^2 z^{-2} \\
 1 - az^{-1} \overline{) 1} \\
 \underline{1 - az^{-1}} \\
 az^{-1} \\
 \underline{az^{-1} - a^2 z^{-2}} \\
 a^2 z^{-2} \dots
 \end{array}$$

$$\frac{1}{1 - az^{-1}} = 1 + az^{-1} + a^2 z^{-2} + \dots$$

$$x[n] = a^n u[n]$$

### Example 3.13: Power Series Expansion for a Left-sided Sequence

$$X(z) = \frac{1}{1 - az^{-1}}, \quad |z| < |a| \quad \xleftrightarrow{z} -a^n u[-n-1]$$

$$\begin{array}{r} -a^{-1}z - a^{-2}z^2 \\ -az^{-1} + 1 \overline{) 1} \\ \underline{1 - a^{-1}z} \phantom{00} \\ a^{-1}z \phantom{00} \\ \underline{a^{-1}z - a^{-2}z^2} \phantom{00} \\ a^{-2}z^2 \dots \end{array}$$

$$\frac{1}{1 - az^{-1}} = -a^{-1}z - a^{-2}z^2 + \dots$$

$$x[n] = -a^n u[-n-1]$$



### 3.4 z-Transform Properties

$$x[n] \xleftrightarrow{Z} X(z), \quad ROC = R_x$$

#### 3.4.1 Linearity

$$x_1[n] \xleftrightarrow{Z} X_1(z), \quad ROC = R_{x_1}$$

$$x_2[n] \xleftrightarrow{Z} X_2(z), \quad ROC = R_{x_2}$$

$$ax_1[n] + bx_2[n] \xleftrightarrow{Z} aX_1(z) + bX_2(z)$$

$$ROC \text{ contains (may more than) } R_{x_1} \cap R_{x_2}$$

## Example of Linearity

$$x[n] = a^n u[n] - a^n u[n - N]$$

$$a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad ROC : |z| > a$$

$$a^n u[n - N] \xleftrightarrow{z} \frac{a^N z^{-N}}{1 - az^{-1}}, \quad ROC : |z| > a$$

$$\frac{1}{1 - az^{-1}} - \frac{a^N z^{-N}}{1 - az^{-1}} \xleftrightarrow{z} a^n u[n] - a^n u[n - N]$$

$$= \left( 1 + az^{-1} + a^2 z^{-2} + \dots + a^{N-1} z^{-(N-1)} \right) \quad |z| > 0$$

$$= \frac{(1 - az^{-1})(1 + az^{-1} + a^2 z^{-2} + \dots + a^{N-1} z^{-(N-1)})}{1 - az^{-1}}$$

### 3.4.2 Time Shifting

$$x[n - n_0] \xleftrightarrow{Z} z^{-n_0} X(z)$$

- ◆  $n_0$  is an integer
  - ◆  $n_0$  is positive,  $x[n]$  is shifted right
  - ◆  $n_0$  is negative,  $x[n]$  is shifted left

$$ROC = R_x \left( \begin{array}{l} \textit{except for the possible addition} \\ \textit{or deletion of } z = 0 \text{ or } z = \infty \end{array} \right)$$

## Time Shifting: Proof

$$\text{if } y[n] = x[n - n_0]$$

$$Y(z) = \sum_{n=-\infty}^{\infty} x[n - n_0] z^{-n} \quad \text{Let } m = n - n_0$$

$$Y(z) = \sum_{m=-\infty}^{\infty} x[m] z^{-(m+n_0)}$$

$$= z^{-n_0} \sum_{m=-\infty}^{\infty} x[m] z^{-m} = z^{-n_0} X(z)$$

### Example 3.14: Shifted Exponential Sequence

$$X(z) = \frac{1}{z - \frac{1}{4}}, \quad |z| > \frac{1}{4} \quad \longleftrightarrow^z \quad \left(\frac{1}{4}\right)^n u[n]$$

$$X(z) = \frac{z^{-1}}{1 - \frac{1}{4}z^{-1}} = -4 + \frac{4}{1 - \frac{1}{4}z^{-1}}$$

$$x[n] = -4\delta[n] + 4\left(\frac{1}{4}\right)^n u[n]$$

$$X(z) = z^{-1} \left( \frac{1}{1 - \frac{1}{4}z^{-1}} \right)$$

$$x[n] = \left(\frac{1}{4}\right)^{n-1} u[n-1]$$

### 3.4.3 Multiplication by an Exponential sequence

$$z_0^n x[n] \xleftrightarrow{Z} X(z / z_0), \quad ROC = |z_0| R_x$$

if  $R_x$  is  $r_R < |z| < r_L$ ,  $|z_0| R_x$  is  $|z_0| r_R < |z| < |z_0| r_L$

$$\text{if } z_0 = e^{j\omega_0} \quad z = e^{j\omega}$$

$$e^{j\omega_0 n} x[n] \xleftrightarrow{F} X(e^{j(\omega - \omega_0)}): AM$$

### Example 3.15: Exponential Multiplication

$$u[n] \xleftrightarrow{z} \frac{1}{1 - z^{-1}}, \quad |z| > 1$$

$$\begin{aligned} x[n] &= r^n \cos(w_0 n) u[n] \\ &= \frac{1}{2} (re^{jw_0})^n u[n] + \frac{1}{2} (re^{-jw_0})^n u[n] \end{aligned}$$

$$\frac{1}{2} (re^{jw_0})^n u[n] \xleftrightarrow{z} \frac{\frac{1}{2}}{1 - re^{jw_0} z^{-1}}, \quad |z| > r$$

$$x[n] = \frac{1}{2} \left( re^{jw_0} \right)^n u[n] + \frac{1}{2} \left( re^{-jw_0} \right)^n u[n]$$

$$\frac{1}{2} \left( re^{-jw_0} \right)^n u[n] \xleftrightarrow{z} \frac{\frac{1}{2}}{1 - re^{-jw_0} z^{-1}}, \quad |z| > r$$

$$\begin{aligned} X(z) &= \frac{\frac{1}{2}}{1 - re^{jw_0} z^{-1}} + \frac{\frac{1}{2}}{1 - re^{-jw_0} z^{-1}} \\ &= \frac{(1 - r \cos w_0 z^{-1})}{1 - 2r \cos w_0 z^{-1} + r^2 z^{-2}}, \quad |z| > r \end{aligned}$$



### 3.4.4 Differentiation of $X(z)$

$$nx[n] \xleftrightarrow{z} -z \frac{dX(z)}{dz}, \quad \textcolor{red}{ROC = R_x}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$-z \frac{dX(z)}{dz} = -z \sum_{n=-\infty}^{\infty} (-n) x[n] z^{-n-1}$$

$$= \sum_{n=-\infty}^{\infty} nx[n] z^{-n} = Z \{ nx[n] \}$$

### Example 3.16: Inverse of Non-Rational z-Transform

$$X(z) = \log(1 + az^{-1}), \quad |z| > |a|$$

$$\frac{dX(z)}{dz} = \frac{-az^{-2}}{1 + az^{-1}}$$

$$nx[n] \xleftrightarrow{z} -z \frac{dX(z)}{dz} = \frac{az^{-1}}{1 - (-a)z^{-1}}, \quad |z| > |a|$$

$$nx[n] = a(-a)^{n-1} u[n-1]$$

Look

$$(-1)^{n-1} \frac{a^n}{n} u[n-1] \xleftrightarrow{z} \log(1 + az^{-1}), \quad |z| > |a|$$

### Example 3.17: Second-Order Pole

$$x[n] = na^n u[n] = n(a^n u[n])$$

$$a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| > |a|$$

$$X(z) = -z \frac{d}{dz} \left( \frac{1}{1 - az^{-1}} \right), \quad |z| > |a|$$

$$= \frac{az^{-1}}{(1 - az^{-1})^2}, \quad |z| > |a|$$

$$na^n u[n] \xleftrightarrow{z} \frac{az^{-1}}{(1 - az^{-1})^2}, \quad |z| > |a|$$

### 3.4.5 Conjugation of a complex Sequence

$$x^*[n] \xleftrightarrow{Z} X^*(z^*), \quad ROC = R_x$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

$$\begin{aligned} \sum_{n=-\infty}^{\infty} x^*[n]z^{-n} &= \left( \left( \sum_{n=-\infty}^{\infty} x^*[n]z^{-n} \right)^* \right)^* \\ &= \left( \sum_{n=-\infty}^{\infty} x[n](z^*)^{-n} \right)^* = X^*(z^*) \\ &\quad X(z^*) \end{aligned}$$

### 3.4. 6 Time Reversal

$$x^*[-n] \xleftrightarrow{z} X^*\left(\frac{1}{z^*}\right), \quad ROC = 1/R_x$$

$$R_x : r_R < |z| < r_L \Rightarrow \frac{1}{R_x} : 1/r_L < |z| < 1/r_R$$

*if  $x[n]$  is real or we do not conjugate  $x[-n]$*

$$x[-n] \xleftrightarrow{z} X\left(\frac{1}{z}\right), \quad ROC = 1/R_x$$

### Example 3.18: Time-Reverse Exponential Sequence

$$x[n] = a^{-n}u[-n] \quad a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| > |a|$$

$$x[-n] \xleftrightarrow{z} X\left(\frac{1}{z}\right), \quad ROC = 1/R_x$$

$$X(z) = \frac{1}{1 - az} = \frac{-a^{-1}z^{-1}}{1 - a^{-1}z^{-1}}, \quad |z| < |a^{-1}|$$

### 3.4.7 Convolution of Sequences

$$x_1[n] * x_2[n] \xleftrightarrow{Z} X_1(z)X_2(z), \quad \text{ROC contains } R_{x_1} \cap R_{x_2}$$

$$y[n] = x_1[n] * x_2[n] = \sum_{k=-\infty}^{\infty} x_1[k]x_2[n-k]$$

$$Y(z) = \sum_{n=-\infty}^{\infty} y[n]z^{-n} = \sum_{n=-\infty}^{\infty} \left\{ \sum_{k=-\infty}^{\infty} x_1[k]x_2[n-k] \right\} z^{-n}$$

$$= \sum_{k=-\infty}^{\infty} x_1[k] \sum_{n=-\infty}^{\infty} x_2[n-k]z^{-n} = \sum_{k=-\infty}^{\infty} x_1[k] \left\{ \sum_{m=-\infty}^{\infty} x_2[m]z^{-m} \right\} z^{-k}$$

$$= X_2(z) \sum_{k=-\infty}^{\infty} x_1[k]z^{-k} = X_1(z)X_2(z)$$

### Ex. 3.19: Evaluating a Convolution Using the z-transform

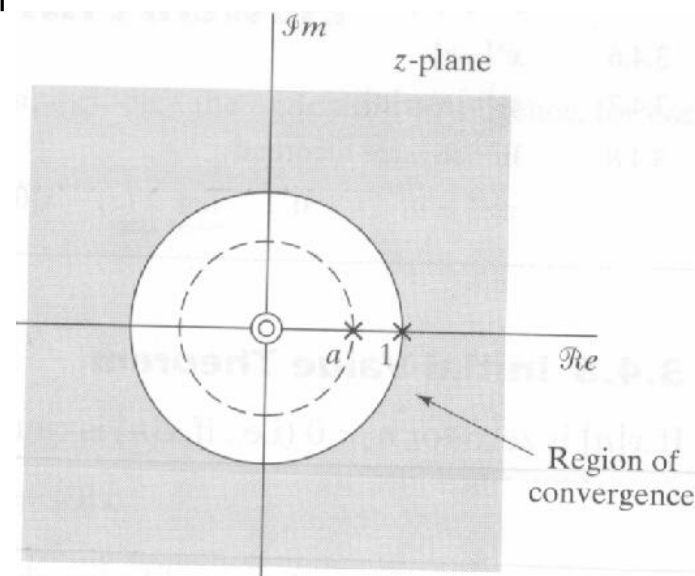
**Solution:**  $y[n] = x_1[n] * x_2[n]$

$$x_1[n] = a^n u[n] \quad \xleftrightarrow{z} X_1(z) = \frac{1}{1 - az^{-1}}, |z| > |a|$$

$$x_2[n] = u[n] \quad \xleftrightarrow{z} X_2(z) = \frac{1}{1 - z^{-1}}, |z| > 1$$

$$Y(z) = \frac{1}{(1 - az^{-1})(1 - z^{-1})} \quad \text{if } |a| < 1$$

$$|z| > 1$$





### Example 3.19: Evaluating a Convolution Using the z-transform

$$Y(z) = \frac{1}{(1 - az^{-1})(1 - z^{-1})}, \quad |z| > 1$$

$$= \frac{1}{1-a} \left( \frac{1}{(1 - z^{-1})} - \frac{a}{(1 - az^{-1})} \right), \quad |z| > 1$$

$$y[n] = \frac{1}{1-a} (u[n] - a^{n+1}u[n])$$

### 3.4.8 Initial Value Theorem

*if  $x[n] = 0$  for  $n < 0$*

$$x[0] = \lim_{z \rightarrow \infty} X(z)$$

$$X(z) = \sum_{n=0}^{\infty} x[n] z^{-n} = x[0] + \sum_{n=1}^{\infty} \frac{x[n]}{z^n}$$

$$\lim_{z \rightarrow \infty} X(z) = x[0] + \lim_{z \rightarrow \infty} \sum_{n=1}^{\infty} \frac{x[n]}{z^n} = x[0]$$

## Region of convergence (ROC)

$$\cos(w_0 n) = \frac{1}{2} (e^{jw_0 n} + e^{-jw_0 n}) \quad -\infty < n < \infty,$$



$$\sum_{k=-\infty}^{\infty} [\pi \delta(w - w_0 + 2\pi k) + \pi \delta(w + w_0 + 2\pi k)]$$

$$h_{lp}[n] = \frac{\sin w_c n}{\pi n} \quad -\infty < n < \infty \quad H_{lp}(e^{jw}) = \begin{cases} 1, & |w| < w_c \\ 0, & w_c < |w| \leq \pi \end{cases}$$

$$\sum_{n=-\infty}^{\infty} \frac{\sin w_c n}{\pi n} e^{-jwn} \quad \blacklozenge \text{ does not converge uniformly to the discontinuous function } H_{lp}(e^{jw}).$$

## Example

- ◆ There's no Z-Transform for  $x[n] = 1, -\infty < n < \infty$

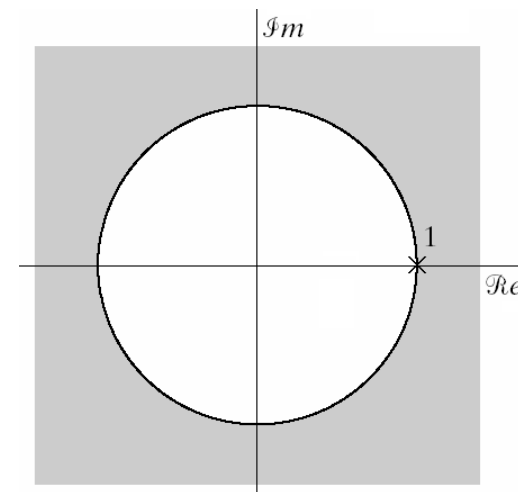
For  $x[n] = u[n]$

$$X(e^{jw}) = \sum_{n=0}^{\infty} e^{-jwn} = \frac{1}{1 - e^{-jw}} + \sum_{k=-\infty}^{\infty} \pi \delta(w + 2\pi k)$$

*does not absolutely converge*

$$X(z) = X(re^{jw}) = \sum_{n=0}^{\infty} r^{-n} e^{-jwn} = \frac{1}{1 - r^{-1} e^{-jw}}$$

*absolutely converge if  $|r| > 1 \Rightarrow ROC : |z| > 1$*



Thank You! Keep Learning