

DnB ROS Event:

World Instructions:

Extract the `models.zip` to a folder you desire. Note this should be in the `GAZEBO_MODEL_PATH` variable for gazebo to detect the models. To do that, from the directory you extracted the `models.zip` file, run

```
export GAZEBO_MODEL_PATH=$(pwd):$GAZEBO_MODEL_PATH
```

Then run `gazebo sim` normally with the provided world.