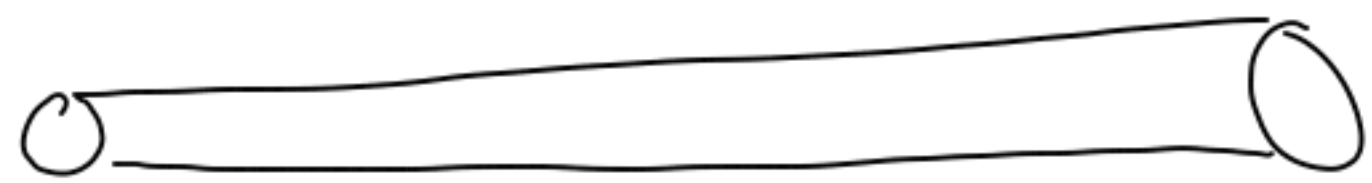


Homework

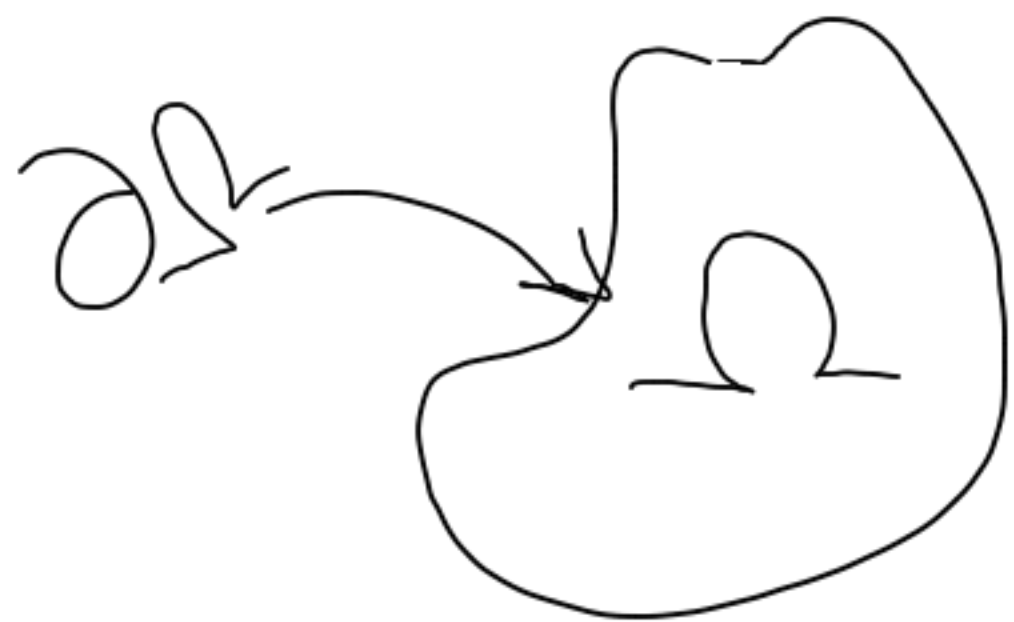
- Put all your solutions in one file
- Long blocks of code: separate file or in an appendix
- Make sure solutions are in order and labeled.

Past lectures:



Flow of heat in a rod
(1D)

Today: multiple dimensions



Fick's law of diffusion:

Heat flux is proportional
to the gradient ∇u

$$u_t = \nabla \cdot (K(x,y) \nabla u) + \psi(x,y)$$

$$u(x,y,t)$$

If $K(x,y) = K$:

$$u_t = K \nabla^2 u + \psi(x,y) \quad \text{Poisson's Eqn.}$$

Steady state:

$$\nabla^2 u = \frac{-\psi(x,y)}{K} = f(x,y)$$

If $f=0$: $\nabla^2 u=0$ Laplace's eqn.

$$\nabla^2 u = f(x, y)$$

$$u = g(x, y) \quad (x, y) \in \partial\Omega$$

BVP (elliptic PDE)

Applications:

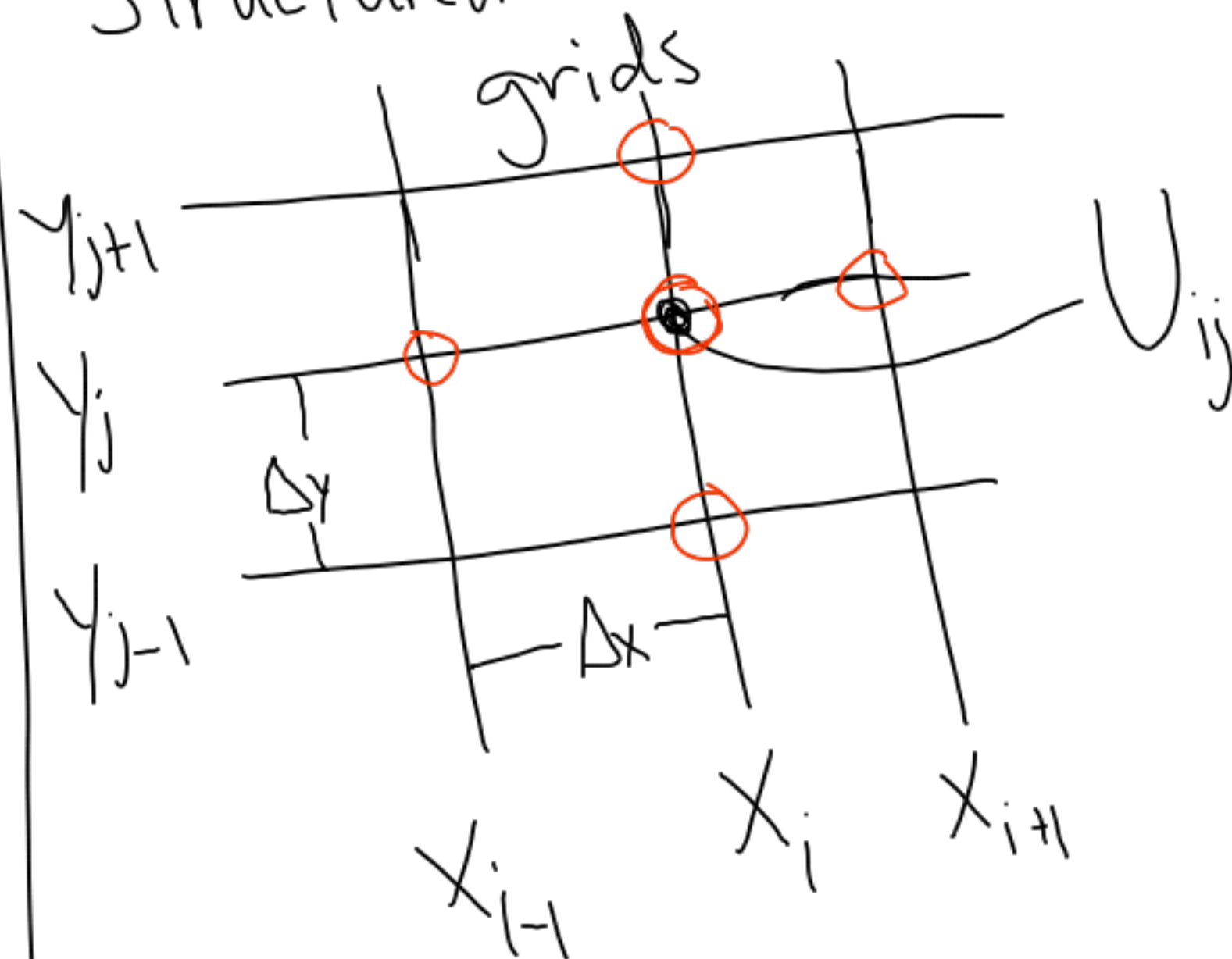
— Heat $u = \text{Temperature}$, $-f$: Heat source

— $u = \text{grav. potential}$, $f = \text{mass}$

— $u = \text{electrical potential}$, $f = \text{charge}$

Discretization in 2D

Structured vs. Unstructured

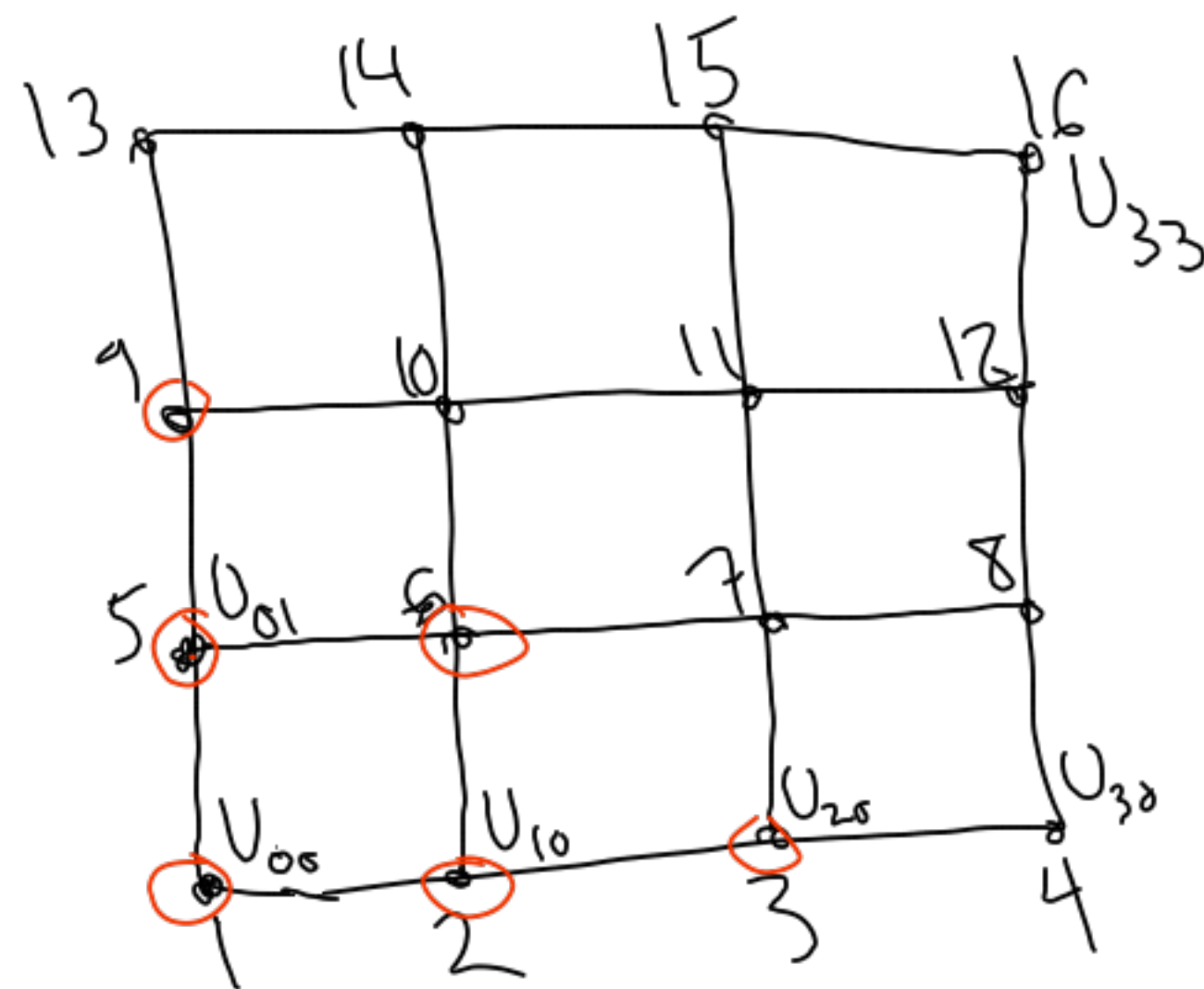


$$u_{xx} + u_{yy} = f(x, y)$$

$$u_{xx}(x_{ij}, y_j) \approx \frac{U_{i+1,j} - 2U_{ij} + U_{i-1,j}}{(\Delta x)^2}$$

$$u_{yy}(x_{ij}, y_j) \approx \frac{U_{i,j+1} - 2U_{ij} + U_{i,j-1}}{(\Delta y)^2}$$

$$\text{Let } \Delta x = \Delta y = h$$



$$U = [U_{00}, U_{10}, U_{20}, U_{30}, U_{01}, \dots, U_{33}]^T$$

$$\frac{1}{h^2} [U_{i+1,j} + U_{i-1,j} + U_{i,j+1} + U_{i,j-1} - 4U_{ij}] = f(x_{ij}, y_j) \leftarrow AU = F$$

$$\text{If } f=0: U_{ij} = \frac{1}{4} (U_{i+1,j} + U_{i-1,j} + U_{i,j+1} + U_{i,j-1})$$

What does A look like?

$$A = \frac{1}{h^2} \begin{bmatrix} & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ \text{row 6} & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 \\ & & & & & & & & & & & \\ & & & & & & & & & & & \end{bmatrix}$$

Sparse

If our grid is $m \times m$ then

A is $m^2 \times m^2$ but has only $5m^2$ non-zero entries

Toeplitz matrix:

A matrix where all entries on each diagonal are equal.

1D FD disc.

Circulant matrix:

Like Toeplitz, but diagonals "wrap around":

disc. with periodic BCS.

Block Toeplitz
matrix:

$$\begin{bmatrix} A & & & \\ C & A & & \\ & B & A & \\ & & B & A \end{bmatrix}$$

Each block diagonal
consists only of copies
of a given block

Multi-dimensional FD
discretizations.

$$\|A^{-1}\|_2 = \frac{1}{2\tau^2} + \mathcal{O}(h^2) \quad \text{as } h \rightarrow 0$$

So this method is stable
and convergent.

$$AU = F$$

$$AE = -\tau$$

$$\uparrow$$

$$\mathcal{O}(h^2)$$

$$E = U - \hat{U}$$

\uparrow
exact solution
vector

Stability requires that $\|A^{-1}\| < C$ as $h \rightarrow 0$