$(H)u\zeta = (H)U$ Exact solution: u(t)= ext Backward Euler $\int_{u+1} = \int_{u} + K f(f_{u+1})$ $\int_{U+1} = \underbrace{\frac{1-ky}{1}}_{U}$ R(KX)

Solute Stability (Ch. 7 of | Ent = 1 - KXEn + KZn 5= SZEC: [RE](5)

Trapezoidal Method

$$U^{m'} = U^n + \frac{1}{2} (f(U^n) + f(U^{m+1}))$$
 $U^{m+1} = U^n + \frac{1}{2} (U^n + U^{n+1})$
 $(1 - \frac{1}{2}) U^{m+1} = (1 + \frac{1}{2}) U^n$
 $V^{m+1} = \frac{1 + \frac{1}{2}}{1 - \frac{1}{2}} U^n$

$$(1+\frac{x^{2}}{2}+y^{2} \leq (1-\frac{x^{2}}{2}+y^{2})$$

$$x \leq -x \qquad \text{We say a method}$$

$$2x \leq 0 \qquad \text{is } A-\text{stable if}$$

$$x \leq 0 \qquad C = \{x+iy: x \leq 0\} \subseteq S$$

$$\text{Both Backward Euler}$$

$$\text{and the implicit trapezoidal}$$

$$\text{method are } A-\text{stable}.$$

Consider the linear system (H) _ Lu(t) Where L=RAR Eigenvalue Le composition (x(4)= R 1 x (4) $R'u(t) = \Lambda R'u(t) \quad w(t) = R'u(t)$ (t)W/1=(H)W

If we apply a numerical method to this problem, we will have absolute stability iff

0(1) 6

$$\sum_{j=0}^{\infty} \alpha_j U^{nj} = K \sum_{j=0}^{\infty} \beta_j f(U^{n+j})$$

$$\sum_{j=0}^{\infty} (x_j - Z \beta_j) V^{*,j} = 0$$

Ansatz:
$$U^n = S^n$$
:

$$T(S;z) = \sum_{j=0}^{\infty} (x_j - z_j S_j) S_j = 0$$

We have absolute stability for a given ZEC if the roots
$$\{S_1,...,S_r\}$$
 of $\{S_j\}$ satisfy: $|S_j| \le 1$ and $|S_j| \le 1$ if S_j is a multiple root.

Boundary locus method
$$S=e^{i\theta}$$

$$\frac{\sum_{j=0}^{\infty}(x_{j}-z\beta_{j})e^{i\theta_{j}}=0}{\sum_{j=0}^{\infty}(x_{j}e^{i\theta_{j}}=z\zeta_{j}\beta_{j}e^{i\theta_{j}}}$$

$$z(x_{j}e^{i\theta_{j}}=z\zeta_{j}\beta_{j}e^{i\theta_{j}})$$

$$z(x_{j}e^{i\theta_{j}}=z\zeta_{j}\beta_{j}e^{i\theta_{j}})$$

$$Z = \sum_{i \in \mathcal{S}, e^{i\theta j}} Z = \sum_{i \in \mathcal{S}, e^$$

Leapt roa

$$U^{n+2} = U^n + 2kf(U^{n+1})$$

 $U^{n+2} = U^n + 2zU^{n+1}$
 $S^2 - 2zS - 1 = 0$
 $S_{\pm} = z \pm \sqrt{z^2 + 1}$
 $S_{\pm} = z \pm \sqrt{z^2 + 1}$

$$e^{i\theta} - 1 = 2ze^{i\theta}$$

$$e^{i\theta} - e^{i\theta} = 2z$$

$$z = e^{i\theta} - e^{-i\theta}$$

$$z = (\sin\theta)$$

$$\Theta'(t) = -\alpha\Theta(t)$$

$$U_1'(t) = U_2(t)$$

$$u_2(t) = -au_1(t)$$

$$U'(t) = \begin{bmatrix} 0 & 1 \\ -a & 0 \end{bmatrix} u(t)$$

$$\chi + \alpha = 0$$
 $\chi = \pm i \sqrt{\alpha}$

Which methods could we use for this problem?

-Leapfrog
$$K\lambda \in [-i,i]$$
 $tiKVa \in [-i,i]$
 $0 \leq KVa \leq [-i,i]$
 $0 \leq KVa \leq [-i,i]$

- Backward Euler: Abs. Stable & K Pendulum will be damped

- Trapezoidal: Abs. Stable & K

Runge-Kutta Methods

$$Y_{i} = U^{n} + K \sum_{j=1}^{n} a_{i,j} f(Y_{i,j}, t_{n} + c_{j}K)$$

$$U^{n+1} = U^n + K \leq b_j f(Y_j, t_n + c_j k)$$

Butcher Tableall

$$\begin{array}{ll}
(z) & t_{1} + c_{1}k \\
(z) & t_{2} + c_{3}k \\
(z) & t_{3} + c_{4}k \\
(z) & t_{4} + c_{5}k \\
(z) & t_{5} +$$

Lt H 15 Strictly lower triangular: Ar = Orxn

So R(Z) is a polynomial of degree at most r. (Explicit methods)

For implicit methods $R(z) = \frac{P(z)}{Q(z)}$

Where P, a are polynomials of degree at most r.