

# Poisson's Equation (2D)

$$\nabla^2 u(x,y) = f(x,y) \quad x \in \Omega$$

$$u(x,y) = g(x,y) \quad x \in \partial\Omega$$

Applications:

u  
Temperature  
Electrical potential  
Pressure potential  
Gravitational potential

f  
Heat source  
Charge distribution  
Source/sink of fluid  
Mass distribution

More generally we could have

$$\nabla \cdot (K(x,y) \nabla u) = f(x,y)$$

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Heat diffusion in a square plate

$$\nabla^2 u = f(x,y) \quad \begin{matrix} 0 < x < 1 \\ 0 < y < 1 \end{matrix}$$

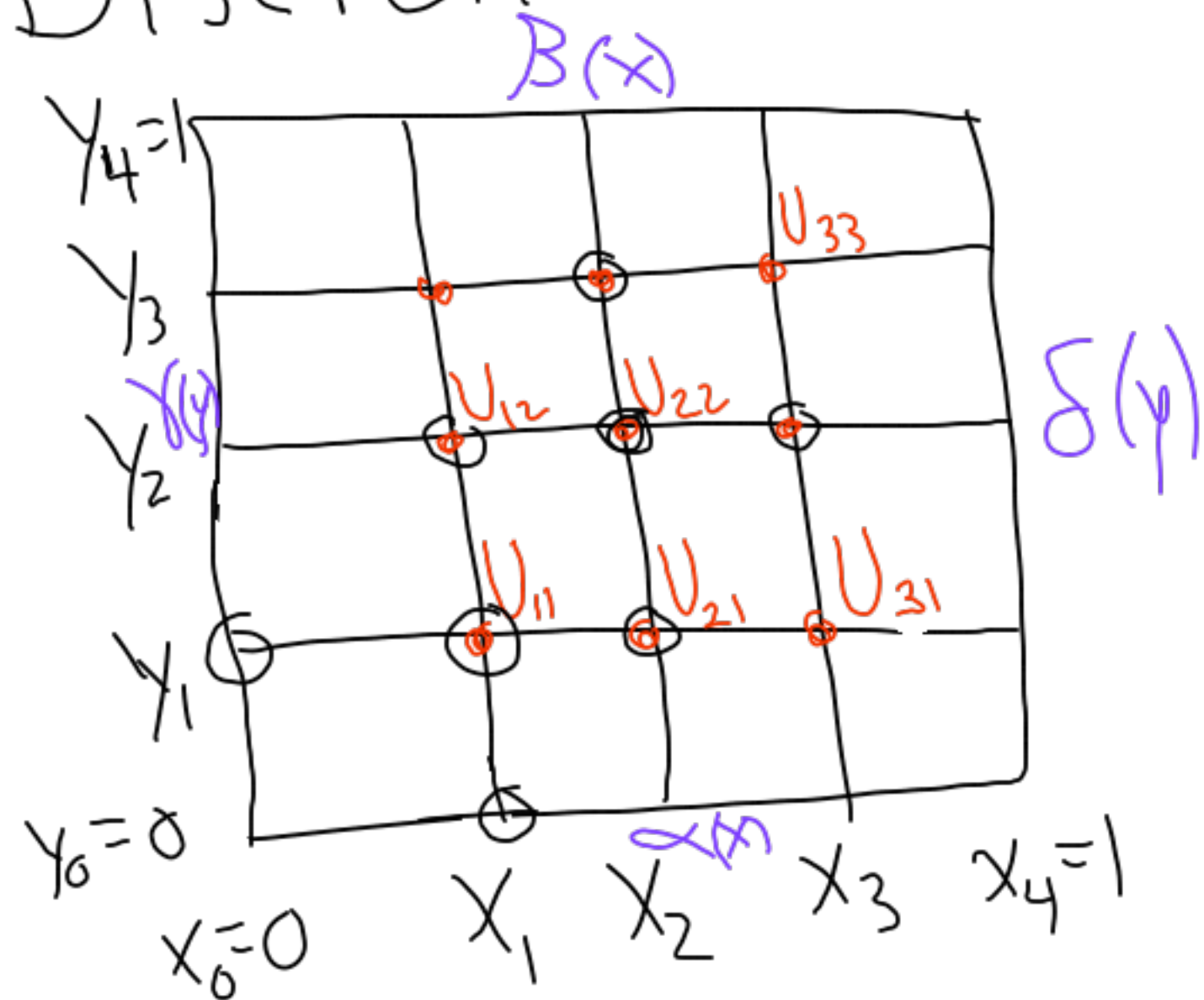
$$u(x,0) = \alpha(x)$$

$$u(x,1) = \beta(x)$$

$$u(0,y) = \gamma(y)$$

$$u(1,y) = \delta(y)$$

Discretize:



$$U_{ij} \approx U(x_i, y_j) \quad (1 \leq i, j \leq m)$$

$$U_{xx}(x_i, y_j) \approx \frac{U_{i+1,j} - 2U_{i,j} + U_{i-1,j}}{(\Delta x)^2}$$

$$U_{yy}(x_i, y_j) = \frac{U_{i,j+1} - 2U_{i,j} + U_{i,j-1}}{(\Delta y)^2}$$

Assume  $\Delta x = \Delta y = h$   $AU = F$

$$\frac{1}{h^2} [U_{i+1,j} + U_{i,j+1} + U_{i-1,j} + U_{i,j-1} - 4U_{i,j}] = f(x_i, y_j)$$

Row-wise ordering:

5-point stencil

$$U = \begin{bmatrix} U_{11} \\ U_{21} \\ U_{31} \\ U_{12} \\ U_{22} \\ U_{32} \\ U_{13} \\ U_{23} \\ U_{33} \end{bmatrix}$$

$$A = \frac{1}{h^2}$$

$$\begin{bmatrix} -4 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & -4 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -4 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & -4 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & -4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & -4 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & -4 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & -4 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4 \end{bmatrix}$$

A is sparse

$$A \in \mathbb{R}^{m^2 \times m^2}$$

$$U \in \mathbb{R}^{m^2}$$

Only  $\sim 5m^2$  entries of A are non-zero

$$F = \begin{bmatrix} f(x_1, y_1) \\ f(x_2, y_1) \\ \vdots \\ f(x_m, y_m) \end{bmatrix}$$

## Consistency

$$\text{Substute: } U_{ij} \leftarrow u(x_i, y_j)$$

$$\frac{1}{h^2} \left[ u(x_{i+1}, y_j) + u(x_{i-1}, y_j) + u(x_i, y_{j+1}) + u(x_i, y_{j-1}) - 4u(x_i, y_j) \right] = f(x_i, y_j)$$

$$\tau_{ij} = \frac{h^2}{12} \left( u_{xxxx}(x_i, y_j) + u_{yyyy}(x_i, y_j) \right) + \mathcal{O}(h^4)$$

$\uparrow$   
local trunc.  
error

$$\hat{U} = \begin{bmatrix} u(x_1, y_1) \\ u(x_2, y_1) \\ \vdots \\ u(x_m, y_m) \end{bmatrix}$$

$$AU = F$$

$$A\hat{U} = F + \tau$$

$$A(\underbrace{U - \hat{U}}_E) = -\tau$$

$$AE = -\tau \Rightarrow E = -A^{-1}\tau$$
$$\|E\| \leq \|A^{-1}\| \cdot \|\tau\|$$



We know  $\|E\| = O(h^2)$  Stability

We will show that  $\|A^{-1}\| < C$   
so that

$$\lim_{h \rightarrow 0} \|E\| = 0 \quad (\text{convergence})$$

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Take  $\|\cdot\| = \|\cdot\|_2$ . What is  $\|A^{-1}\|_2$ ?

Let's find the eigenvalues of  $A$ .

$$AV = \lambda V$$

$$(AV)_{ij} = \frac{V_{i+1,j} - 2V_{i,j} + V_{i-1,j}}{(\Delta x)^2} + \frac{V_{i,j+1} - 2V_{i,j} + V_{i,j-1}}{(\Delta y)^2} = \lambda V_{ij}$$

Assume  $V_{ij} = R_i S_j$  (separable)

$$\text{Then } \frac{S_j}{(\Delta x)^2} (R_{i+1} - 2R_i + R_{i-1}) + \frac{R_i}{(\Delta y)^2} (S_{j+1} - 2S_j + S_{j-1}) = \lambda R_i S_j$$

Divide by  $R_i S_j$ :

$$\underbrace{\frac{1}{R_i (\Delta x)^2} (R_{i+1} - 2R_i + R_{i-1})}_{\text{only depends on } i = C_1} + \underbrace{\frac{1}{S_j (\Delta y)^2} (S_{j+1} - 2S_j + S_{j-1})}_{\text{only depends on } j = C_2} = \lambda$$

$$\lambda = C_1 + C_2$$

$$R_{i+1} - (2 + C(\Delta x)^2)R_i + R_{i-1} = 0$$

of  
system linear  
difference equations

$$R_0 = 0 \quad R_{m+1} = 0$$

$$R_i = \rho^i \quad (\text{Ansatz})$$

$$\rho^{i+1} - (2 + C(\Delta x)^2)\rho^i + \rho^{i-1} = 0$$

Divide by  $\rho^{i-1}$

$$\rho^2 - 2\alpha \rho + 1 = 0$$

$\alpha = \frac{1}{2}(2 + C(\Delta x)^2)$

$$\rho_{\pm} = \alpha \pm \sqrt{\alpha^2 - 1}$$

General Solution:  $R_i = R_+ \rho_+^i + R_- \rho_-^i$

$$R_0 = 0: R_+ + R_- = 0$$

$$R_- = -R_+$$

$$R_i = R_+ (\rho_+^i - \rho_-^i)$$

$$i = m+1:$$

$$(\rho_+^{m+1} - \rho_-^{m+1}) = 0$$

$$\rho_+^{m+1} = \rho_-^{m+1}$$

$$\rho_+ \rho_- = (\alpha + \sqrt{\alpha^2 - 1})(\alpha - \sqrt{\alpha^2 - 1})$$

$$= \alpha^2 - (\alpha^2 - 1) = 1$$

$$\rho_+^{2m+2} = \rho_+^{m+1} \rho_+^{m+1} = 1$$

So  $\rho_+$  is a  $(2m+2)$ -root of unity:

$$\rho_+ = e^{i2\pi \frac{p}{2m+2}}$$

$$p=1,2,\dots,m$$

$$\rho_+ = e^{i\pi \frac{p}{m+1}} = e^{i\pi p \Delta x}$$

$$\rho_- = e^{-i\pi p \Delta x}$$

$$\alpha = \frac{1}{2}(\rho_+ + \rho_-) = \cos(\pi p \Delta x)$$

$$C_1 = \frac{2(\alpha-1)}{(\Delta x)^2} = \frac{2}{(\Delta x)^2} (\cos(p\pi \Delta x) - 1)$$

$$p=1,2,\dots,m_x$$

Similarly

$$C_2 = \frac{2}{(\Delta y)^2} (\cos(q\pi \Delta y) - 1)$$

$$q=1,2,\dots,m_y$$

$$\lambda_{p,q} = 2 \left[ \frac{\cos(p\pi \Delta x) - 1}{(\Delta x)^2} + \frac{\cos(q\pi \Delta y) - 1}{(\Delta y)^2} \right]$$

We care about the smallest (in magnitude)

Take  $p=q=1$

$$\cos(x) = 1 - \frac{x^2}{2} + O(x^4)$$

$$\lambda_{1,1} = 2 \left[ \frac{1 - \frac{(\pi \Delta x)^2}{2} - 1}{(\Delta x)^2} + \frac{1 - \frac{(\pi \Delta y)^2}{2} - 1}{(\Delta y)^2} \right] + O(\Delta x^2) + O(\Delta y^2)$$

$$\lambda_{1,1} = 2 \left[ -\frac{\pi^2}{2} - \frac{\pi^2}{2} \right] + O(\Delta x^2, \Delta y^2)$$

$$\lim_{\Delta x, \Delta y \rightarrow 0} \lambda_{1,1} = -2\pi^2$$

$$\text{So } \|A^{-1}\| \approx \frac{1}{2\pi^2} \text{ as } \Delta x, \Delta y \rightarrow 0.$$