

# Numerical Methods for the initial value problem

We will march forward  
in time, computing  
 $U^1$ , then  $U^2$ , etc.

$$U'(t) = f(u)$$

$$U(t_0) = \eta$$

$$t \in [t_0, T]$$

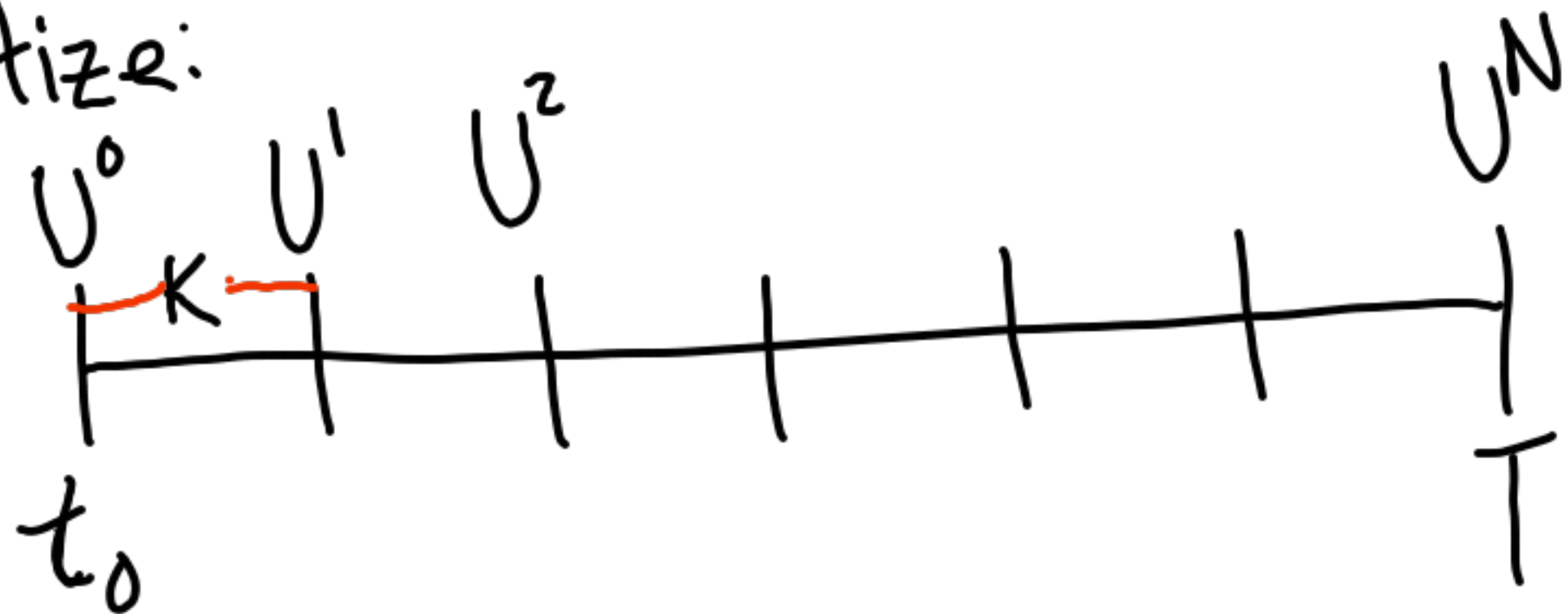
$$u(t) : \mathbb{R} \rightarrow \mathbb{R}^m$$

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^m$$

Computational cost:

$$N \times (\text{cost per step})$$
$$= (\text{cost per step}) \times \frac{T - t_0}{K}$$

Discretize:



$$N = \frac{T - t_0}{K}$$

## Some basic methods

Explicit Euler

$$U^{n+1} = U^n + k f(U^n)$$

or

$$\frac{U^{n+1} - U^n}{k} = f(U^n)$$

Conditionally  
stable.

Implicit Euler

$$U^{n+1} = U^n + k f(U^{n+1})$$

Need to solve  
algebraic eqns.  
at each step.

Unconditionally  
stable.

Trapezoidal method

$$U^{n+1} = U^n + \frac{K}{2} (f(U^n) + f(U^{n+1}))$$

Leapfrog Method

$$U^{n+1} = U^{n-1} + 2K f(U^n)$$

$$\frac{U^{n+1} - U^{n-1}}{2K} = f(U^n)$$

Local Truncation Error

Trapezoidal:

$$\frac{U^{n+1} - U^n}{K} = \frac{1}{2} (f(U^n) + f(U^{n+1}))$$

Substitute  $U^n \rightarrow u(t_n)$ :

$$\frac{u(t_{n+1}) - u(t_n)}{K} = \frac{1}{2} (f(u(t_n)) + f(u(t_{n+1})))$$

$$u(t_{n+1}) = u(t_n) + Ku'(t_n) + \frac{K^2}{2} u''(t_n) + \frac{K^3}{6} u'''(t_n) + O(K^4)$$

$$f(u(t_{n+1})) = u' + Ku'' + \frac{K^2}{2} u''' + \frac{K^3}{6} u^{(4)} + O(K^4)$$



$$\rightarrow \frac{\cancel{u} + \cancel{ku'} + \frac{k^2}{2}u'' + \frac{k^3}{6}u''' + \mathcal{O}(k^4) - \cancel{u}}{k} = \frac{1}{2} \left( \cancel{u} + \cancel{ku'} + \frac{k^2}{2}u'' + \frac{k^3}{6}u^{(4)} + \mathcal{O}(k^4) + \cancel{u'} \right) + \tau^n$$

$$\cancel{\frac{k}{2}u''} + \frac{k^2}{6}u''' + \mathcal{O}(k^3) = \cancel{\frac{k}{2}u''} + \frac{k^2}{4}u''' + \mathcal{O}(k^3) + \tau^n$$

$$\tau^n = -\frac{k^2}{12}u'''(t_n) + \mathcal{O}(k^3)$$

2nd-order accurate

One-step error

If we write  $U^{n+1} = U^n + \frac{k}{2}(f(U^n) + f(U^{n+1}))$

And substitute:  $u(t_{n+1}) = u(t_n) + \frac{k}{2}(f(u(t_n)) + f(u(t_{n+1}))) + k\tau^n$

We call  $\phi^n = k\tau^n$  the "one-step error"

# How to achieve higher-order accuracy

① Use more derivatives

multiderivative

② Use more evaluations of  $f$

multi-stage

③ Use more previous steps

multistep

# Multiderivative Methods

$$u(t_{n+1}) = u(t_n) + \kappa u'(t_n) + \frac{\kappa^2}{2} u''(t_n) + \frac{\kappa^3}{6} u'''(t_n) + \mathcal{O}(\kappa^4)$$

$$U^{n+1} = U^n + \kappa f(U^n) + \frac{\kappa^2}{2} f'(U^n) + \frac{\kappa^3}{6} (f''(f, f) + f'f'f)$$

$$\frac{d^2}{dt^2} u_i(t) = \frac{d}{dt} f_i(u(t)) = \sum_{j=1}^m \frac{\partial f_i}{\partial u_j(t)} u_j'(t)$$

$$= \sum_{j=1}^m \frac{\partial f_i}{\partial u_j} f_j = f'f$$

3rd-order  
accurate

$$= f''(f, f) + f'f'f$$

$$\frac{d^3 u}{dt^3} = \frac{d}{dt} \left( \sum_{j=1}^m \frac{\partial f_i}{\partial u_j} f_j \right)$$

$$= \sum_{j=1}^m \sum_{l=1}^m \frac{\partial^2 f_i}{\partial u_j \partial u_l} f_j$$

$$+ \sum_{j=1}^m \frac{\partial f_i}{\partial u_j} \sum_{l=1}^m \frac{\partial f_j}{\partial u_l} f_l$$



## ② Multi-stage (Runge-Kutta)

Example:  $U^* = U^n + \frac{k}{2} f(U^n)$   
(midpoint method)  $U^{n+1} = U^n + k f(U^*)$

$$\begin{array}{c|cc} & 0 & 0 \\ & \frac{1}{2} & 0 \\ \hline & 0 & 1 \end{array}$$

$$U^{n+1} = U^n + k f\left(U^n + \frac{k}{2} f(U^n)\right)$$

$$u(t_{n+1}) = u(t_n) + k f\left(u(t_n) + \frac{k}{2} f(u(t_n))\right) + k \tau^n$$

$$f\left(u + \frac{k}{2} f(u)\right) = f(u) + \frac{k}{2} f' f(u) + \frac{k^2}{8} f''(f, f) + \mathcal{O}(k^3)$$

~~$$u + k u' + \frac{k^2}{2} u'' + \frac{k^3}{6} u''' = u + k f + \frac{k^2}{2} f f' + \frac{k^3}{8} f'(f, f) + \mathcal{O}(k^4) + k \tau^n$$~~

$$\tau^n = \mathcal{O}(k^2)$$

$$Y_1 = U^n$$

$$Y_2 = U^n + \frac{1}{2} k f(Y_1)$$

$$U^{n+1} = U^n + k f(Y_2)$$

RK methods

$$Y_i = U^n + K \sum_{j=1}^s a_{ij} f(Y_j)$$

$$U^{n+1} = U^n + K \sum_{j=1}^s b_j f(Y_j)$$

	A
	$b^T$

4th-Order Runge-Kutta

	0	0	0	0
	$\frac{1}{2}$	0	0	0
	0	1	0	0
	0	0	1	0
	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{6}$

Pros/Cons

+ Self-starting

+ Easy to adapt K

- Multiple evaluations  
of  $f$  per step



### ③ Multistep

Example: Leapfrog

$$U^{n+1} = U^{n-1} + 2Kf(U^n)$$

Pros/Cons

- + Only evaluate  $f$  once per step
- Not self-starting
- Hard to adapt  $K$