

Reminders:

- Homework 4 due today
- Proposal revisions due Thursday (if requested)

$$\begin{array}{c|c} C & A \\ \hline & b^T \end{array}$$

Method with
 m stages:

$$\frac{m(m-1)}{2} + m$$

$$= \frac{m(m+1)}{2}$$

coefficients

9th order: 486 eqns.
10th order: 1205 eqns.

1970: 10th order, 17 stages
2019: 10th order, 16 stages*

Initial-Boundary Value Problems: The Heat Equation

$$u_t = k u_{xx} + f(x, t)$$

Initial data: $u(x, 0) = \eta(x)$

Boundary data:

$$u(0, t) = \alpha(t)$$
$$u(1, t) = \beta(t)$$

$$\frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2} + f(x, t) \quad \begin{matrix} 0 \leq x \leq 1 \\ 0 \leq t \leq T \end{matrix}$$

$u(x, t)$: distribution of heat

k : Heat conductance

f : source/sink of heat

Simple case: $k=1$ $f=0$

$$\alpha(t)=0 \quad \beta(t)=0$$

$$u_t = u_{xx}$$

Exact solution

Fourier series of I.C.:

$$u(x,0) = \sum_{p=0}^{\infty} \hat{u}_p(0) \sin(p\pi x)$$

Ansatz:

$$u(x,t) = \sum_{p=0}^{\infty} \hat{u}_p(t) \sin(p\pi x)$$

Substitute into PDE:

$$\sum_{p=0}^{\infty} \hat{u}'_p(t) \sin(p\pi x) = \sum_{p=0}^{\infty} \hat{u}_p(t) (-p^2 \pi^2) \sin(p\pi x)$$

Decouple: $\hat{u}'_p(t) = -p^2 \pi^2 \hat{u}_p(t)$

Solution:

$$\hat{u}_p(t) = e^{-p^2 \pi^2 t} \hat{u}_p(0)$$

$$\Rightarrow u(x,t) = \sum_{p=0}^{\infty} \hat{u}_p(0) e^{-p^2 \pi^2 t} \sin(p\pi x)$$

Discretization

We will use the method of lines:

- ① Discretize in space \rightarrow IV ODE
- ② Apply a RKM or LMM in time.

① $x_j = jh \quad j=0, 1, \dots, m+1$
 $h = \frac{1}{m+1}$

$$U_j(t) \approx u(x_j, t)$$

$$u_{xx}(x_j, t) = \frac{U_{j+1} - 2U_j + U_{j-1}}{h^2}$$

We get an ODE system

$$\begin{bmatrix} U_1 \\ \vdots \\ U_m \end{bmatrix} = \frac{1}{h^2} \begin{bmatrix} -2 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & -2 \end{bmatrix} \begin{bmatrix} U_1 \\ \vdots \\ U_m \end{bmatrix}$$

$\underbrace{\hspace{10em}}_A$

$$U'(t) = AU \Rightarrow U(t) = e^{tA}U(0)$$

Semi-discrete system

$$A = R \Lambda R^{-1} \quad p=1, 2, \dots, m$$

$$\text{Here: } \lambda_p = \frac{2}{h^2} (\cos(p\pi h) - 1)$$

$$r_{jp} = \sin(p\pi x_j) = \sin(p\pi jh)$$

$$U'(t) = R \Lambda R^{-1} U(t)$$

$$R^{-1} U'(t) = \Lambda R^{-1} U(t)$$

$$\hat{U}'(t) = \Lambda \hat{U}(t)$$

$$\hat{U}(t) = e^{t\Lambda} \hat{U}(0)$$

$$\hat{U}(t) = R^{-1} U(t)$$

$$\cos(p\pi h) \approx 1 - \frac{1}{2} p^2 \pi^2 h^2$$

$$\text{So } \lambda_p = -p^2 \pi^2 + O(h^2)$$

for small ph .

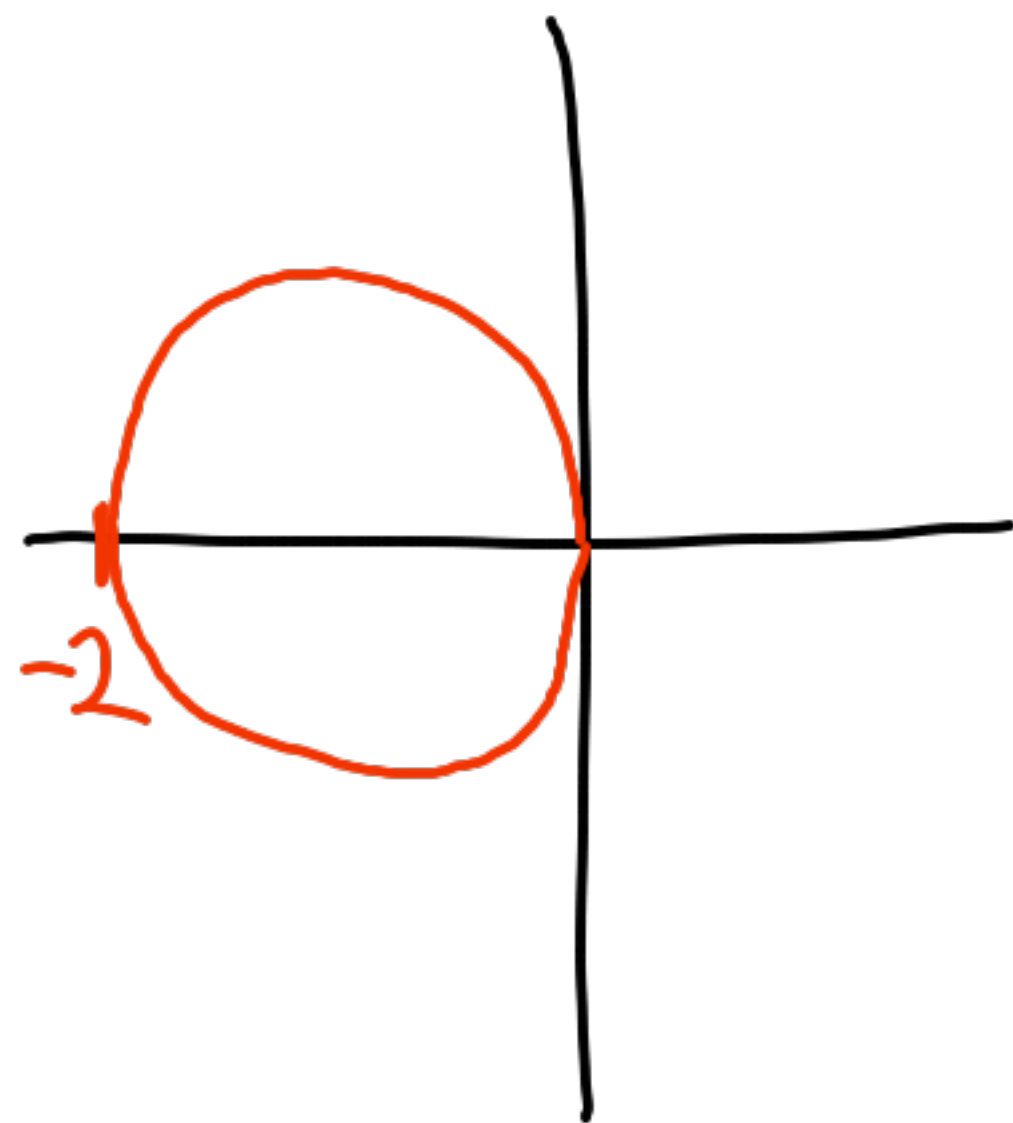
Very accurate for small ph .

How large is the largest eigenvalue?

$$-\frac{4}{h^2}$$

We need $-\frac{4}{h^2} K \in S$ (the region of absolute stability)

For instance, with
Explicit Euler:



$$-\frac{4K}{h^2} \geq -2$$

$$K \leq \frac{h^2}{2}$$

Requires a very small
step size.

We should use an A-stable
or A(∞)-stable method.
Then there is no stability
restriction on K.

One nice method is
TR-BDF2 (DIRK)

0	0	0	0
$\frac{1}{2}$	$\frac{1}{4}$	$\frac{1}{4}$	0
1	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{3}$
<hr/>			
	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{3}$

Need to solve
a tridiagonal system
of size m for
each stage.

This method is:

A-stable

L-stable

2nd-order accurate

Local truncation error (Explicit Euler)

$$U_j^{n+1} = U_j^n + \frac{K}{h^2} (U_{j+1}^n - 2U_j^n + U_{j-1}^n)$$

To find LTE:

$$U(x_j, t_{n+1}) = U(x_j, t_n) + \frac{K}{h^2} (U(x_{j+1}, t_n) - 2U(x_j, t_n) + U(x_{j-1}, t_n)) + K \tau_j^n$$

$$\Rightarrow \tau_j^n = \frac{K}{2} U_{tt} - \frac{h^2}{12} U_{xxxx} + O(K^2) + O(h^4)$$

1st-order in t

2nd-order in x

In general if
we use a time
stepping of order p
we get

$$\tau_j^n = O(K^p) + O(h^2)$$