Initial Value Problems

Examples:

Rigid Pendulum
$$\Theta'(t) = -\sin(\Theta(t))$$

$$\Theta(t_0) = \theta_0$$

$$A(t_0) = 0$$

>2nd-order ODE Can be re-written as a system of 1st-order ODEs (t)-0'(t)

> $\Omega'(t) = -\sin(\theta(t))$ $(4) = \Omega(4)$

Because we can always do this, we will focus ONLY on solving 1st-order ODEs.

$$S'(A) = -BSI$$

$$T'(A) = BSI - XI$$

$$R'(A) = XI$$

$$\frac{d_{t}(S+I+R)=0}{S+I+R=1}$$

$$\frac{d_{t}(S+I+R)=0}{S+I+R=1}$$

$$\frac{S(t)=S_{0}}{T(t)=I_{0}}$$

Linear INPS

Scalar:

$$u'(t) = \lambda u(t) \quad \lambda \in \mathbb{C}$$

$$u(t) = \gamma$$

$$u(t) = e^{\lambda (t - t_0)} \eta$$

Linear System: U(+):R>C

$$U'(t) = A U(t) \quad A \in \mathbb{C}^{m \times m}$$

$$U(t_0) = \gamma$$

$$U(t) = e^{A(t-t_0)} \gamma$$

$$U(t) = e^{A(t-t_0)} \gamma$$

$$e^{M} = I + M + \frac{M}{2!} + \frac{M}$$

Inhomogeneous System: u'(t) = Au(t) + g(t) $|u(t)| = e^{A(t-t_0)} \eta + \int_{1}^{t} e^{A(t-t_0)} g(t) dt$ Duhamel's Principle

Existence Uniqueness inear IVPS: A unique solution exists for all t. What about for ronlinear IVPs?

$$U'(t) = (U(t))^{2}$$

$$U(0) = 1 > 0$$

$$U(t) = \frac{1}{\eta^{-1} - t}$$

$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.
$$Solution exists$$

$$Only up to $t = \eta^{-1}$.$$$$$$$$$$$$$$$$

$$U'(t) = \sqrt{U(t)} \qquad \qquad \int (w) = \sqrt{U} \quad \text{is L.C.}$$
for $u \in [E, \infty)$ for any $E > 0$, but not $u(t) = \frac{1}{4}t^2$ or $u(t) = 0$ at $u = 0$.

$$U'(t) = \frac{1}{4}t^2 = \sqrt{u(t)}$$
Solution is not unique

Lipschitz Continuity Given a function f on domain D we say Lipschitz constant for for Dif 115(w)-fw1/~L/1u-v11 We say f is Lipschitz continuous if such an L<00 exists.

If f is differentiable

then we can take

L=sup | f'(u) |

ued

Examples

(D) Heaviside $f(u) = \begin{cases} 0 & u < 0 \\ 1 & u > 0 \end{cases}$ Not L.C.

Continuous
Not L.C.

If we take
$$D=[E,\infty)$$

then $f(X)=\frac{1}{x}$ is L.C.

We can always rewrite a non-autonomous one $u(t)=f(u,t)$
as an autonomous one
 $v'(t)=f(v)$
by Setting $v-[t]$ with $t'=1$

Given the IVY (1) = f(u) $T = [\eta - a, \eta + a]$ Suppose f'is L.C. $\eta - \alpha \leq u \leq \eta + \alpha$ Then a unique solution exists for t < to + sup I finst

Meaning of the Lipschitz Constant $\frac{1}{2}(t) = \eta + \int_{t}^{\tau} a(t)dt$ Fxamples: $(1)^{2}u(t) = g(t)$ $(1)^{2}u(t) = g(t)$ $(1)^{2}u(t) = g(t)$ $(2)^{2}u(t) = g(t)$ $(3)^{2}u(t) = g(t)$ $(4)^{2}u(t) = g(t)$

Trajectories
can either diverge
or converge at
a rate bounded by $u(t) = e^{\lambda t} \eta$ $= \left(\frac{\lambda}{\lambda} \right)$ (2) $u'(t) = \lambda u(t)$ M(0)=Mt=0 \ Solutions diverge to