

Runge-Kutta Methods

$$u'(t) = f(u, t) \quad u \in \mathbb{R}^m$$

$$u(t_0) = \eta$$

$$Y_i = U^n + k \sum_{j=1}^s a_{ij} f(Y_j, t_n + c_j k) \quad 1 \leq i \leq s$$

$$U^{n+1} = U^n + k \sum_{j=1}^s b_j f(Y_j, t_n + c_j k)$$

Butcher
Tableau:

c	$A^{s \times s}$
	b^T

b: weights

c: abscissas

For example:

0	0	0
1	1	0
	$\frac{1}{2}$	$\frac{1}{2}$

$$Y_1 = U^n$$

$$Y_2 = U^n + k f(Y_1, t_n)$$

$$U^{n+1} = U^n + \frac{k}{2} (f(Y_1, t_n) + f(Y_2, t_n + k))$$

2nd-order $\tau = \mathcal{O}(k^2)$
2-stage

0	0			
$\frac{1}{2}$	$\frac{1}{2}$	0		
$\frac{1}{2}$	0	$\frac{1}{2}$	0	
1	0	0	1	0
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	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{6}$

RK4

4-stage

4th-order

$\frac{1}{2}-\gamma$	$\frac{1}{4}$	$\frac{1}{4}-\gamma$	
$\frac{1}{2}+\gamma$	$\frac{1}{4}+\gamma$	$\frac{1}{4}$	
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	$\frac{1}{2}$	$\frac{1}{2}$	

$$\gamma = \sqrt{3}/6$$

Gauss-Legendre
2-stage

4th order

Classes of Runge-Kutta methods

① Explicit: A is strictly lower-triangular

No need to solve anything

② Fully implicit: A is a full matrix

Need to solve a system of m equations

③ Diagonally implicit:
A is lower-triangular

Need to solve s systems of m equations

Let's apply a RK method to

$$u'(t) = \lambda u$$

$$Y_i = U^n + \lambda K \sum_j a_{ij} Y_j$$

$$U^{n+1} = U^n + \lambda K \sum_j b_j Y_j$$

Define:

$$Y = \begin{bmatrix} Y_1 \\ \vdots \\ Y_s \end{bmatrix} \quad \mathbb{1} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$z = K\lambda$$

$1 \leq i \leq s$

$$Y = U^n \mathbb{1} + z A Y$$

$$U^{n+1} = U^n + z b^T Y$$

$$(I - zA)Y = \mathbb{1} U^n$$

$$Y = (I - zA)^{-1} \mathbb{1} U^n$$

$$U^{n+1} = \underbrace{\left(1 + z b^T (I - zA)^{-1} \mathbb{1} \right)}_{R(z) \text{ (abs. stab. fcn.)}} U^n$$

$$U^{n+1} = R(z) U^n$$

$R(z)$ is a rational function

Neumann:

$$\frac{1}{1-x} = 1 + x + x^2 + \dots = \sum_{j=0}^{\infty} x^j$$

$$(I - zA)^{-1} = \sum_{j=0}^{\infty} z^j A^j$$

$$R(z) = I + b^T \sum_{j=0}^{\infty} z^{j+1} A^j \mathbb{1}$$

If A is strictly lower-triangular then $A^s = 0$.

So for explicit methods.

$$R(z) = I + b^T \sum_{j=0}^{s-1} z^{j+1} A^j \mathbb{1}$$

(polynomial of degree s)

For instance, for RK4

$$R(z) = I + z + \frac{1}{2}z^2 + \frac{1}{6}z^3 + \frac{1}{24}z^4$$

Exact solution of $u'(t) = \lambda u$
 $u(0) = \eta$
is

$$u(t) = e^{\lambda t} \eta$$

$$u(t_n) = e^{\lambda t_n} \eta$$

$$u(t_n + k) = e^{\lambda(t_n + k)} \eta$$

$$u(t_n + k) = e^{\lambda k} u(t_n) = e^z u(t_n)$$

$$\text{So } R(z) \approx e^z$$

i.e. we want (for explicit methods)

$$I + b^T \sum_{j=0}^{p-1} z^{j+1} A^j \mathbb{1} = \sum_{j=0}^p \frac{z^j}{j!}$$

To get accuracy of order K^p :

this means

$$b^T z^j A^{j-1} \mathbb{1} = \frac{z^j}{j!}$$

$$b^T A^{j-1} \mathbb{1} = \frac{1}{j!} \quad 1 \leq j \leq p$$

These conditions are necessary but not sufficient for accuracy of order p on a general ODE $u'(t) = f(u)$.

For instance, to achieve 3rd order we also require

$$\sum_i b_i \left(\sum_j a_{ij} \right)^2 = \frac{1}{3}.$$

How to choose K ?

We want both

- ① Small enough for stability
- ② Small enough to achieve desired accuracy

Bounding the global is very expensive. Instead we focus on bounding local errors.

The LTE depends on derivatives of $u(t)$, which may vary greatly.

So we want to adjust K adaptively, to enforce $\tau^n < \epsilon \leftarrow \text{tolerance}$

Embedded RK Pairs

$$Y_i = U^n + k \sum_{j=0}^s a_{ij} f(Y_j, t_n + c_j k)$$

$$U^{n+1} = U^n + k \sum_{j=0}^s b_j f(Y_j, t_n + c_j k)$$

$$\hat{U}^{n+1} = U^n + k \sum_{j=0}^s \hat{b}_j f(Y_j, t_n + c_j k)$$

b_j chosen to get order p

\hat{b}_j chosen to get order $p-1$

$$U^{n+1} = u(t_n + k) + \mathcal{O}(k^{p+1})$$

$$\hat{U}^{n+1} = u(t_n + k) + \mathcal{O}(k^p)$$

So $U^{n+1} - \hat{U}^{n+1} = \mathcal{O}(k^p)$
is an estimate of the
error in the second solution.

Step size adaption

- ① Take a step and estimate the local error

$$\delta = |U^{n+1} - \hat{U}^{n+1}|$$

- ② If $\delta > \epsilon$, go back and redo step with smaller k .

- ③ If $\delta < \epsilon$ continue.
(if δ is significantly smaller than ϵ , increase k)