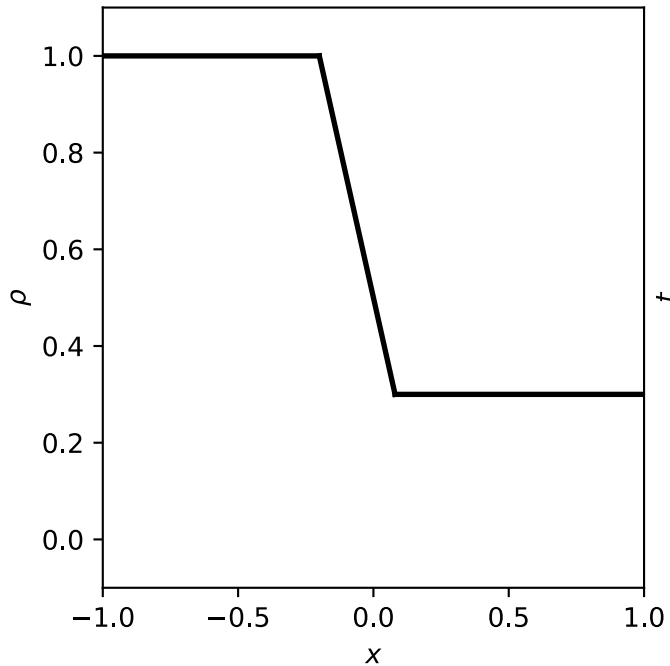


$t = 0.2$



Vehicle trajectories

