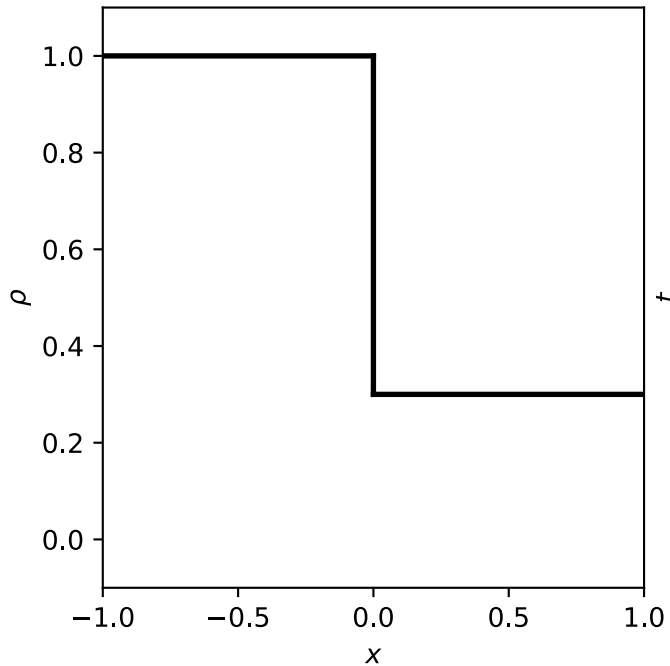


$t = 0.0$



Vehicle trajectories

