## Homework 1 Partial Solutions

#### Homework 1 problems:

### Section 1.1

8. Use elimination and back substitution to solve the given system:

$$x_1 + 2x_2 - 2x_3 = 1$$
$$2x_1 + 5x_2 + x_3 = 9$$

$$x_1 + 3x_2 + 4x_3 = 9$$

Elimination on the augmented system looks like:

$$\begin{bmatrix} 1 & 2 & -2 & | & 1 \\ 2 & 5 & 1 & | & 9 \\ 1 & 3 & 4 & | & 9 \end{bmatrix} \xrightarrow[\substack{r_2 - 2r_1 \to r_2 \\ r_3 - r_1 \to r_3} \begin{bmatrix} 1 & 2 & -2 & | & 1 \\ 0 & 1 & 5 & | & 7 \\ 0 & 1 & 6 & | & 8 \end{bmatrix} \xrightarrow[\substack{r_3 - r_2 \to r_3}]{} \begin{bmatrix} 1 & 2 & -2 & | & 1 \\ 0 & 1 & 5 & | & 7 \\ 0 & 0 & 1 & | & 1 \end{bmatrix}$$

This gives the triangular system

$$x_1 + 2x_2 - 2x_3 = 1$$
  
 $x_2 + 5x_3 = 7$   
 $x_3 = 1$ 

Back substitution gives:

$$x_2 = 7 - 5(1) = 2$$
  
 $x_1 = 1 + 2(1) - 2(2) = -1$ 

So we have the solution (-1, 2, 1). (Check this in the initial system!)

9.

(a) Suppose  $m_1 \neq m_2$ . Assume  $m_1 \neq 0$ . (If  $m_1 = 0$ , then  $m_2 \neq 0$  by our assumption so we could just swap the rolls below.) Multiply the first equation by  $-m_2/m_1$  add to the second

and replace the second. This yields the new system:

$$-m_1x_1 + x_2 = b_1$$
$$(1 - m_2/m_1)x_2 = b_2 - (m_2/m_1)b_1$$

Now you can use back substitution:

$$x_2 = \frac{b_2 - (m_2/m_1)b_1}{1 - m_2/m_1} = \frac{m_1b_2 - m_2b_1}{m_1 - m_2}$$
 (ok since  $m_1 \neq m_2$ )  
$$x_1 = -\frac{b_1 - x_2}{m_1} = \frac{2m_2b_1 - m_1(b_1 + b_2)}{m_1(m_1 - m_2)}$$

So we have a unique solution.

(b) If  $m_1 = m_2$ , then the system is just

$$-m_1 x_1 + x_2 = b_1$$
$$-m_1 x_1 + x_2 = b_2$$

This is equivalent to the single equation  $-m_1x_1+x_2=b_1$  if  $b_1=b_2$ , else you get  $0=b_2-b_1\neq 0$  which cannot happen.

(c) For (a) saying  $m_1 \neq m_2$  is equivalent to saying that the two lines have different slopes and hence have a unique point of intersection. For (b), if  $m_1 = m_2$ , the lines are parallel, they are the same line if  $b_1 = b_2$ , else they are distinct parallel lines and hence never intersect.

### Section 1.2

**5**.

(c)

$$x_1 + x_2 = 0$$
$$2x_1 + 3x_2 = 0$$
$$3x_1 - 2x_2 = 0$$

Gaussian Elimination looks like

$$\begin{bmatrix} 1 & 1 & 0 \\ 2 & 3 & 0 \\ 3 & -2 & 0 \end{bmatrix} \xrightarrow[\substack{r_2 - 2r_1 \to r_2 \\ r_3 - 3r_1 \to r_3}} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & -5 & 0 \end{bmatrix} \xrightarrow[\substack{r_3 + 5r_2 \to r_3}]{} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

This results in the triangular system

$$x_1 + x_2 = 0$$
$$x_2 = 0$$

Which is solved by back substitution to give:  $x_2 = 0$ , and  $x_1 = -x_2 = 0$ .

(d)

$$3x_1 + 2x_2 - x_3 = 4$$
$$x_1 - 2x_2 + 2x_3 = 1$$
$$11x_1 + 2x_2 + x_3 = 14$$

Gaussian Elimination looks like

$$\begin{bmatrix} 3 & 2 & -1 & | & 4 \\ 1 & -2 & 2 & | & 1 \\ 11 & 2 & 1 & | & 14 \end{bmatrix} \xrightarrow{r_1 \leftrightarrow r_2} \begin{bmatrix} 1 & -2 & 2 & | & 1 \\ 3 & 2 & -1 & | & 4 \\ 11 & 2 & 1 & | & 14 \end{bmatrix} \xrightarrow{r_2 - 3r_1 \to r_2} \begin{bmatrix} 1 & -2 & 2 & | & 1 \\ 0 & 8 & -7 & | & 1 \\ 0 & 24 & -21 & | & 3 \end{bmatrix} \xrightarrow{r_3 - 3r_2 \to r_3} \begin{bmatrix} 1 & -2 & 2 & | & 1 \\ 0 & 8 & -7 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

This is equivalent to the "triangular system"

$$x_1 - 2x_2 + 2x_3 = 1$$
$$8x_2 - 7x_3 = 1$$

So  $x_1$  and  $x_2$  are the two "pivot variables" an  $x_3$  is the "free variable." Let  $x_3 = t$  be any value, then we use back substitution to get:

$$x_2 = 1/8 + 7/8t$$
$$x_1 - 2(1/8 + 7/8t) + 2t = 1$$
$$x_1 = 5/4 - 1/4t$$

So

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5/4 - 1/4t \\ 1/8 + 7/8t \\ t \end{bmatrix} = \begin{bmatrix} 5/4 \\ 1/8 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1/4 \\ 7/8 \\ 1 \end{bmatrix}$$

(e)

$$2x_1 + 3x_2 + x_3 = 1$$
$$x_1 + x_2 + x_3 = 3$$
$$3x_1 + 4x_2 + 2x_3 = 4$$

Elimination on the augmented system looks like:

$$\begin{bmatrix} 2 & 3 & 1 & | & 1 \\ 1 & 1 & 1 & | & 3 \\ 3 & 4 & 2 & | & 4 \end{bmatrix} \xrightarrow[r_1 \leftrightarrow r_2]{} \begin{bmatrix} 1 & 1 & 1 & | & 3 \\ 2 & 3 & 1 & | & 1 \\ 3 & 4 & 2 & | & 4 \end{bmatrix} \xrightarrow[r_2 \to r_3 \to r_3]{} \begin{bmatrix} 1 & 1 & 1 & | & 3 \\ 0 & 1 & -1 & | & -5 \\ 0 & 1 & -1 & | & -5 \end{bmatrix} \xrightarrow[r_3 \to r_2 \to r_3]{} \begin{bmatrix} 1 & 1 & 1 & | & 3 \\ 0 & 1 & -1 & | & -5 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

The echelon form of the matrix coefficient matrix is now shown.

This system is consistent. if we let  $x_3 = t$ , then by back substitution get

$$x_3 = t$$
  
 $x_2 = -5 + t$   
 $x_1 = 3 - t - (-5 + t) = 8 - 2t$ 

so the solution set is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 8 \\ -5 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

**8.** For what values of a does the following have a unique solution?

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ -1 & 4 & 3 & 2 \\ 2 & -2 & a & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ -1 & 4 & 3 & 2 \\ 2 & -2 & a & 3 \end{bmatrix} \xrightarrow[r_{2}+r_{1}\to r_{2}]{r_{3}-2r_{1}\to r_{3}} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 6 & 4 & 3 \\ 0 & -6 & a-2 & 1 \end{bmatrix}$$

$$\xrightarrow[r_{3}+r_{2}\to r_{3}]{r_{3}-2r_{1}\to r_{3}} \begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 6 & 4 & -5 \\ 0 & 0 & a+2 & 4 \end{bmatrix}$$

All that is required to get a unique solution is that  $a + 2 \neq 0$  or  $a \neq -2$ .

#### **11.** Solve

$$x_1 + 2x_2 = 2$$
  $x_1 + 2x_2 = 1$   
 $3x_1 + 7x_2 = 8$   $3x_1 + 7x_2 = 7$ 

Set this up as:

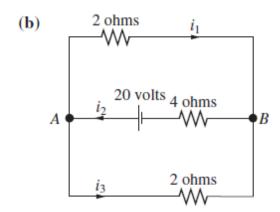
$$\begin{bmatrix} 1 & 2 & 2 & 1 \\ 3 & 7 & 8 & 7 \end{bmatrix} \xrightarrow[r_2-3r_3\rightarrow r_3]{} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 1 & 2 & 4 \end{bmatrix} \xrightarrow[r_1-2r_2\rightarrow r_1]{} \begin{bmatrix} 1 & 0 & -2 & -7 \\ 0 & 1 & 2 & 4 \end{bmatrix}$$

So the solutions are

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -7 \\ 4 \end{bmatrix}$$

respectively. As usual, you should check this.

(b)



From this we have

$$1_1 - i_2 + i_3 = 0$$
 (node B)  
 $-i_1 + i_2 - i_3 = 0$  (node A)  
 $2i_1 + 4i_2 = 20$  (top loop)  
 $4i_2 + 2i_3 = 20$  (bottom loop)

This gives

$$\begin{bmatrix} 1 & -1 & 1 & 0 \\ -1 & 1 & -1 & 0 \\ 2 & 4 & 0 & 20 \\ 0 & 4 & 2 & 20 \end{bmatrix} \xrightarrow[r_2+r_1\to r_2]{r_2+r_1\to r_2} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 6 & -2 & 20 \\ 0 & 4 & 2 & 20 \end{bmatrix}$$

$$\xrightarrow[r_2\leftrightarrow r_4]{1/2r_2\to r_2} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 2 & 1 & 10 \\ 0 & 3 & -1 & 10 \\ 0 & 3 & -1 & 10 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow[r_3-3/2r_2\to r_3]{1} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

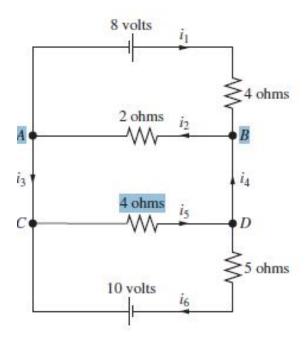
This gives the triangular system

$$i_1 - i_2 + i_3 = 0$$
  
 $2i_2 + i_3 = 10$   
 $-5/2i_3 = -5$ 

So

$$i_3 = 2 \Longrightarrow i_3 = 2$$
  
 $2i_2 + 2 = 10 \Longrightarrow i_2 = 4$   
 $i_1 - 4 + 2 = 0 \Longrightarrow i_1 = 2$ 

(c)



The equations here are

$$-i_1 + i_2 - i_3 = 0$$
 (Node A)  
 $i_1 - 1_2 + i_4 = 0$  (Node B)  
 $i_3 - i_5 + i_6 = 0$  (Node C)  
 $-i_4 + i_5 - i_6 = 0$  (Node D)  
 $4i_1 + 2i_2 = 8$  (Top Loop)  
 $4i_5 + 5i_6 = 10$  (Bottom Node)

The augmented matrix is

$$\begin{bmatrix} -1 & 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & -1 & 0 \\ 4 & 2 & 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 4 & 5 & 10 \end{bmatrix}$$

solving gives

$$\begin{bmatrix}
 1/2 \\
 3 \\
 5/2 \\
 5/2 \\
 5/2 \\
 0
 \end{bmatrix}$$

#### Section 1.3

- 6. This is just computational. Do this by hand, but this is also good to verify in MATLAB.
- 7. This is just computational. Do this by hand, but this is also good to verify in MATLAB.

13.

(a) Say the variables are  $x_1, x_2, x_3, x_4, x_5$  the variables  $x_2, x_4$  and  $x_5$  will be independent since the columns 2,4, and 5 do not contain pivot elements. The others can be solved in terms of those. Let s, t, u be arbitrary real numbers and set  $x_2 = s, x_4 = t$ , and  $x_5 = u$ , then

$$x_1 = -2 - 2s - 3t - u$$

$$x_2 = s$$

$$x_3 = 5 - 2t - 4u$$

$$x_4 = t$$

$$x_5 = u$$

We can write this nicely as

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 5 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -3 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + u \begin{bmatrix} -1 \\ 0 \\ -4 \\ 0 \\ 1 \end{bmatrix}$$
 (1)

(b)

We know

We also know that

$$\mathbf{x} = \begin{bmatrix} -2\\0\\5\\0\\0 \end{bmatrix}$$

is a solution, name ly the solution where s = t = u = 0

So 
$$A\mathbf{x} = -2\mathbf{a_1} + 5\mathbf{a_3} = -2\begin{bmatrix} 1\\1\\3\\4 \end{bmatrix} + 5\begin{bmatrix} 2\\-1\\1\\3 \end{bmatrix} = \begin{bmatrix} 8\\-7\\-1\\7 \end{bmatrix} = \mathbf{b}$$

**16.**  $A^T = -A$  implies  $a_{ii} = -a_{ii}$  so  $a_{ii} = 0$ .

# Section 1.4

**8.** Check that  $A^2 = I$ , so  $A^{2n+1} = A$  and  $A^{2n} = I$ .

**1.4** #**10** Assume  $A^T = A$  and  $B^T = B$ .

(a) Symmetric since:  $(A+B)^T = A^T + B^T = A + B$ 

**(b)** Symmetric since:  $(A^2)^T = A^T A^T = AA = A^2$ 

(c) Not necessarily transitive since:  $(AB)^T = B^T A^T = BA$ . Symmetry would only happen if AB = BA, i.e., A and B commute.

Example: Let  $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & -1 \\ -1 & -1 \end{bmatrix}$ , notice both A and B are symmetric.  $AB = \begin{bmatrix} 0 & -2 \\ 0 & -2 \end{bmatrix}$  is not symmetric so  $(AB)^T \neq AB$ .

(d) Symmetric since:  $(ABA)^T = A^T B^T A^T = ABA$ 

(e) Symmetric since:  $(AB + BA)^T = (AB)^T + (BA)^T = B^TA^T + A^TB^T = BA + AB =$ 

AB + BA

(f) Not symmetric since:  $(AB - BA)^T = (AB)^T - (BA)^T = B^T A^T - A^T B^T = BA - AB = -(AB - BA)$ . So AB - BA is symmetric iff AB - BA = 0, that is iff A and B commute.

The same example as in (c) works here.

22.

$$RR^{T} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} \cos^{2}(\theta) + \sin^{2}(\theta) & \cos(\theta)\sin(\theta) - \sin(\theta)\cos(\theta) \\ \sin(\theta)\cos(\theta) - \cos(\theta)\sin(\theta) & \sin^{2}(\theta) + \cos^{2}(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

**23.**  $H = I - 2uu^T$ , so

$$\begin{split} H^2 &= (I - 2\mathbf{u}\mathbf{u}^T)(I - 2\mathbf{u}\mathbf{u}^T) \\ &= I^2 - 2\mathbf{u}\mathbf{u}^TI - 2I\mathbf{u}\mathbf{u}^T + 4\mathbf{u}\mathbf{u}^T\mathbf{u}\mathbf{u}^T \\ &= I^2 - 4\mathbf{u}\mathbf{u}^T + 4\mathbf{u}\mathbf{u}^T\mathbf{u}\mathbf{u}^T \\ &= I^2 - 4\mathbf{u}\mathbf{u}^T + 4\mathbf{u}(1)\mathbf{u}^T \\ &= I^2 - 4\mathbf{u}\mathbf{u}^T + 4\mathbf{u}\mathbf{u}^T \\ &= I^2 \\ &= I \end{split}$$

**27.** Assume  $A^2 = I$  and let  $B = \frac{1}{2}(I+A)$  and  $C = \frac{1}{2}(I-A)$ . Note

$$B^2 = \frac{1}{4}(I^2 + IA + AI + A^2) = \frac{1}{4}(I + 2A + I) = \frac{1}{4}(2)(I + A) = B$$

Similarly,  $C^2 = C$ .

30.

$$(A + A^T)^T = A^T + (A^T)^T = A^T + A = A + A^T$$

So  $A + A^T$  is symmetric. Similarly,

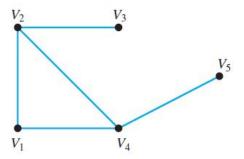
$$(A - A^T)^T = A^T - (A^T)^T = A^T - A = -(A - A^T)^T$$

So  $A - A^T$  is skew-symmetric.

Since  $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T)$  we see A can be written as symmetric + skew-symmetric.

**32.** This is false, for example let A = B = I and C = -I, then clearly A is row equivalent to B and C, but  $B + C = \mathbf{0}$  (the all 0 matrix). It is not true that A is row equivalent to  $\mathbf{0}$ , else  $I = \mathbf{0}$  (a version of I = 0).

33.



(a) Adjacency Matrix, A:

$$A = \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

(b)

$$A^{2} = \begin{bmatrix} 2 & 1 & 1 & 1 & 1 \\ 1 & 3 & 0 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 3 & 0 \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

There are 6 walks starting at  $V_1$  and that is the sum of column 1 or row 1 (the matrix is symmetric).  $V_1V_2V_1$ ,  $V_1V_4V_1$ ,  $V_1$ ,  $V_2V_3$ ,  $V_1V_2V_4$ ,  $V_1V_4V_2$ , and  $V_1V_4V_5$ .

(c)

$$A^{2} = \begin{bmatrix} 2 & 4 & 1 & 4 & 1 \\ 4 & 2 & 3 & 5 & 1 \\ 1 & 3 & 0 & 1 & 1 \\ 4 & 5 & 1 & 2 & 3 \\ 1 & 1 & 1 & 3 & 0 \end{bmatrix}$$

There are 5 walks of length 3 from  $V_2$  to  $V_4$  and 1 of length 2 so 6 altogether.