Name: Quiz 3 - MAT345

Problem 1 (15 points; 3 points each). Decide if each of the following are true or false and provide a justification or counterexample in each case. A justification could consist of a theorem from the text. All vector spaces are assumed to be finite-dimensional here.

(a) _____ There is a unique least squares solution to Ax = b.

FALSE: This was one of your DQs. You showed that the set of least square solutions to $A\mathbf{x} = \mathbf{b}$ is exactly $\hat{\mathbf{x}} + \mathrm{NS}(A)$, where $\hat{\mathbf{x}}$ is any fixed least squares solution, that is, $\hat{\mathbf{x}}$ satisfies, $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$.

In general, there is no reason for A^TA to be invertible, so $(A^TA)^{-1}$ need not even exist. If it does exist, then $\hat{x} = (A^TA)^{-1}A^T\boldsymbol{b}$ is unique.

What you do know is that there is a unique $\hat{\boldsymbol{b}}$ so that $\hat{\boldsymbol{b}}$ is the closest thing of the form $A\boldsymbol{x}$ to \boldsymbol{b} , in other words, $\|\hat{\boldsymbol{b}} - \boldsymbol{b}\|_2^2 = \min\{\|A\boldsymbol{x} - \boldsymbol{b}\|_2^2 \mid \boldsymbol{x} \in \mathbb{R}^n\}$ and a least-square solution is a solution to $A\boldsymbol{x} = \hat{\boldsymbol{b}}$.

(b) _____ There is a unique y so that ||y - b|| is minimal and Ax = y.

TRUE: This is is the conclusion of the main theorem about the existence of "least-square" solutions. This is covered in the notes and in the book.

(c) _____ If $\{\boldsymbol{u}_1,\ldots,\boldsymbol{u}_n\}$ is an orthonormal basis for V with respect to an inner product $\langle\cdot,\cdot\rangle:V\times V\to\mathbb{C}$ and $\boldsymbol{v}=\sum_{i=1}^n\alpha_i\boldsymbol{u}_i$, then $\|\boldsymbol{v}\|_2^2=\sum_{i=1}^n|\alpha_i|^2$.

This is true and is essentially the Pythagorean Theorem. This is a computation

$$\|\boldsymbol{v}\|_{2}^{2} = \langle \boldsymbol{v}, \boldsymbol{v} \rangle = \left\langle \sum_{i=1}^{n} \alpha_{i} \boldsymbol{u}_{i}, \sum_{i=1}^{n} \alpha_{i} \boldsymbol{u}_{i} \right\rangle$$

$$= \sum_{i=1}^{n} \alpha_{i} \left\langle \boldsymbol{u}_{i}, \sum_{i=1}^{n} \alpha_{i} \boldsymbol{u}_{i} \right\rangle$$

$$= \sum_{i=1}^{n} \alpha_{i} \left(\sum_{j=1}^{n} \bar{\alpha}_{j} \langle \boldsymbol{u}_{i}, \boldsymbol{u}_{j} \rangle \right)$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \bar{\alpha}_{j} \delta_{i,j}$$

$$= \sum_{i=1}^{n} \alpha_{i} \bar{\alpha}_{i} = \sum_{i=1}^{n} |\alpha_{i}|^{2}$$

Here

$$\delta_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

(d) _____ All norms $\|\cdot\|: \mathbb{R}^n \to [0,\infty)$ on \mathbb{R}^n come from an inner product.

This is false. The book provides several norms. For a norm $\|\cdot\cdot\cdot\|$ to be given by an inner product it must satisfy the parallelogram law $\|\boldsymbol{u}-\boldsymbol{v}\|^2 + \|\boldsymbol{u}+\boldsymbol{v}\|^2 = 2\|\boldsymbol{u}\|^2 + 2\|\boldsymbol{v}\|^2$.

Of all of the norms $\|\cdot\|_p$ for $1 \le p \le \infty$, the only one that satisfies the parallelogram law is p = 2, this is the only one given by an inner product.

For example, $||(a,b)||_{\infty} = \max\{|a|,|b|\}$ and clearly we can choose a,b,c, and d so that

$$\max\{|a-c|,|b-d|\} + \max\{|a+c|,|b+d|\} \neq 2\max\{|a|,|b|\} + 2\max\{|c|,|d|\}$$

Let (a, b) = (1, 3) and (c, d) = (2, 1), then

$$\max\{|1-2|,|3-1|\} + \max\{|1+2|,|3+1|\} = 2+4$$

$$\neq 2\max\{|1|,|3|\} + 2\max\{|2|,|1|\} = 6+4$$

(e) _____ If $C = \{u_1, \dots, u_n\}$ is an orthonormal basis for V with respect to an inner product $\langle \cdot, \cdot \rangle : V \times V \to \mathbb{C}$ and $\mathbf{v} \in V$, then for any $(c_1, \dots, c_n) = [\mathbf{v}]_C$, $c_i = \langle v, u_i \rangle$.

This is another computation. Say $(c_1, \ldots, c_n) = [v]_{\mathcal{C}}$, then $v = \sum_{i=1}^n c_i u_i$. Now just compute

$$\langle \boldsymbol{v}, \boldsymbol{u}_j \rangle = \left\langle \sum_{i=1}^n c_i \boldsymbol{u}_i, \boldsymbol{u}_j \right\rangle = \sum_{i=1}^n c_i \langle \boldsymbol{u}_i, \boldsymbol{u}_j \rangle = \sum_{i=1}^n c_i \delta_{i,j} = c_j$$

Problem 2 (25 points). You are given some data points $\{(x_i, y_i) \mid i = 1, ..., N\}$ and want to model the data by a function of the form $f(x) = a + bx + c\cos(x) + d\sin(x)$. This involves setting up a matrix A and finding a least-squares solution to $A\mathbf{x} = \mathbf{b}$.

a) (5 points) What is **b**? (In terms of the data.)

 \boldsymbol{b} is the vector of y_i 's

$$m{b} = egin{bmatrix} y_1 \ y_2 \ dots \ y_N \end{bmatrix}$$

b) (8 points) What is A? (Again, in terms of the data.)

Let X be the vector of x_i 's.

$$\boldsymbol{X} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

A is the matrix given my columns is

$$A = \begin{bmatrix} \mathbf{1} \ \mathbf{X} \cos(\mathbf{X}) \sin(\mathbf{X}) \end{bmatrix} = \begin{bmatrix} 1 & x_1 & \cos(x_1) & \sin(x_1) \\ 1 & x_2 & \cos(x_2) & \sin(x_2) \\ \vdots & \vdots & & \vdots \\ 1 & x_N & \cos(x_N) & \sin(x_N) \end{bmatrix}$$

c) (7 points) Suppose you have the least-squares solution $\hat{\mathbf{x}}$. What is f(x)? (In terms of $\hat{\mathbf{x}}$)
Let

$$\hat{m{x}} = egin{bmatrix} a \ b \ c \ d \end{bmatrix}$$

then $A\hat{x} = a\mathbf{1} + b\mathbf{X} + c\cos(\mathbf{X}) + d\sin(\mathbf{X}) = \hat{\mathbf{b}}$ is the vector closest to \mathbf{b} that is of the form $A\mathbf{x}$ for some \mathbf{x} . The model is

$$f(x) = a + bx + c\cos(x) + d\sin(x)$$

- So $f(\boldsymbol{X}) = \hat{\boldsymbol{b}}$.
- d) (5 points) What is the relationship between $\hat{\mathbf{b}} = A\hat{\mathbf{x}}$ and \mathbf{b} ?

This is described above, $\hat{\boldsymbol{b}}$ is the vector in \mathbb{R}^N closest to \boldsymbol{b} where $\hat{\boldsymbol{b}}$ is of the form $A\boldsymbol{x}$ for some $\boldsymbol{x} \in \mathbb{R}^4$.