Homework 7 Partial Solutions

Section 6.4

14. Write $A = B^H B$ where

$$A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & i \\ 0 & -i & 1 \end{bmatrix}$$

clearly A is Hermitian, so we know A is orthogonally diagonalized.

 $A-tI=\begin{bmatrix} 4-t & 0 & 0 \\ 0 & 1-t & i \\ 0 & -i & 1-t \end{bmatrix}$ so $\det(A-tI)=(4-t)((1-t)^2+i^2)=(4-t)(t^2-2t+1-1)=-(t-4)(t-2)t$ so the eigenvalues are 4>2>0. Note all eigenspaces are dimension 1 so we need only find a single eigenvector in each eigenspace to get a basis.

$$NS(A - 4I) = NS\begin{bmatrix} 0 & 0 & 0 \\ 0 & -3 & i \\ 0 & -i & -3 \end{bmatrix} = span\{(1, 0, 0)\}$$

$$NS(A - 2I) = NS\begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & i \\ 0 & -i & -1 \end{bmatrix} = span\{(0, i, 1)\}$$

$$NS(A - 0I) = NS\begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & i \\ 0 & -i & 1 \end{bmatrix} = span\{(0, 1, i)\}$$

Our orthonormal basis will be

$$oldsymbol{u}_1 = egin{bmatrix} 1 \ 0 \ 0 \end{bmatrix} \qquad oldsymbol{u}_2 = egin{bmatrix} 0 \ i/\sqrt{2} \ 1/\sqrt{2} \end{bmatrix} \qquad oldsymbol{u}_3 = egin{bmatrix} 0 \ 1/\sqrt{2} \ i/\sqrt{2} \end{bmatrix}$$

So

$$A = UDU^{H} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & i/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} & i/\sqrt{2} \end{bmatrix} \begin{bmatrix} 4 & \\ & 2 \\ & & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -i/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} & -i/\sqrt{2} \end{bmatrix}$$

Let

$$B = D^{1/2}U^H = \begin{bmatrix} 2 & & \\ & \sqrt{2} & \\ & & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -i/\sqrt{2} & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} & -i/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -i & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

then

$$A = B^H B$$

as desired.

15. Let U be unitary.

(a) $U^H U = U U^H = I$ so U is normal.

(b) Clearly
$$\langle U\boldsymbol{x}, U\boldsymbol{y} \rangle = (U\boldsymbol{y})^H(U\boldsymbol{x}) = \boldsymbol{y}^H U^H U\boldsymbol{x} = \boldsymbol{y}^H \boldsymbol{x} = \langle \boldsymbol{x}, \boldsymbol{y} \rangle$$
. So $\|\boldsymbol{x}\|_2^2 = \langle \boldsymbol{x}, \boldsymbol{x} \rangle = \langle U\boldsymbol{x}, U\boldsymbol{x} \rangle = \|U\boldsymbol{x}\|_2^2$. So $\|\boldsymbol{x}\|_2 = \|U\boldsymbol{x}\|_2$.

(c) If λ is an eigenvalue, then from (b)

$$1 = \frac{\langle U\boldsymbol{x}, U\boldsymbol{x} \rangle}{\langle \boldsymbol{x}, \boldsymbol{x} \rangle} = \frac{\lambda \bar{\lambda} \langle \boldsymbol{x}, \boldsymbol{x} \rangle}{\langle \boldsymbol{x}, \boldsymbol{x} \rangle} = |\lambda|^2$$

So $|\lambda| = 1$.

26. If you are at site i, the probability of jumping to site j is a_{ij} and is determined as follows. There is an 85% chance that the user will choose on of the m_i links on the page and there is a 15% chance the user will just choose a random link from the i possible links. (This is just a heuristic.)

$$a_{ij} = \begin{cases} (.85)\frac{1}{m_i} + (.15)\frac{1}{n} & \text{if there is a link from } i \text{ to } j + (.15)\frac{1}{n} \\ (.15)\frac{1}{n} & \text{otherwise} \end{cases}$$

So for this problem the matrix is:

$$A = \begin{bmatrix} .15/4 & .85/2 + .15/4 & .15/4 & 1/4 \\ .85/3 + .15/4 & .15/4 & .15/4 & 1/4 \\ .85/3 + .15/4 & .85/2 + .15/4 & .15/4 & 1/4 \\ .85/3 + .15/4 & .15/4 & .85 + .15/4 & 1/4 \end{bmatrix} = \begin{bmatrix} 0.037500 & 0.4625 & 0.0375 & 0.25 \\ 0.320833 & 0.0375 & 0.0375 & 0.25 \\ 0.320833 & 0.4625 & 0.0375 & 0.25 \\ 0.320833 & 0.0375 & 0.25 \\ 0.320833 & 0.0375 & 0.8875 & 0.25 \end{bmatrix}$$

This is a Markov matrix and we are interested in the steady state eigenvector, that is \boldsymbol{x} so that $A\boldsymbol{x} = \boldsymbol{x}$ and $x_i \geq 0$ and $\sum x_i = 1$. This vector is $\boldsymbol{x} = (0.19322, 0.17401, 0.24797, 0.38479)$. To get this with MATLAB:

$$\begin{array}{|c|c|} \hline [V,D] &= eig(A); \\ x &= V(:,1)/sum(V(:,1)) \end{array}$$

27. $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ so $\det(A - tI) = \det\begin{bmatrix} -t & 1 \\ 1 & -t \end{bmatrix} = t^2 - 1 = (t - 1)(t + 1)$. The eigenvalues are 1 > -1.

$$NS(A - 1 \cdot I) = NS\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} = span\{(1, 1)\}.$$

$$NS(A + 1 \cdot I) = NS\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = span\{(-1, 1)\}.$$

Let

$$oldsymbol{u}_1 = rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix} \qquad oldsymbol{u}_2 = rac{1}{\sqrt{2}} egin{bmatrix} -1 \ 1 \end{bmatrix}$$

and

$$A = egin{bmatrix} oldsymbol{u}_1 & oldsymbol{u}_2 \end{bmatrix} egin{bmatrix} oldsymbol{u}_1^H \ oldsymbol{u}_2 \end{bmatrix} egin{bmatrix} oldsymbol{u}_1^H \ oldsymbol{u}_2 \end{bmatrix} = \lambda_1 oldsymbol{u}_1 oldsymbol{u}_1^H + \lambda_2 oldsymbol{u}_2 oldsymbol{u}_2^H \end{pmatrix}$$

28. Let u_1, \ldots, u_n be an orthonormal basis of eigenvectors for Hermitian A with eigenvalues $\lambda_1, \ldots, \lambda_n$ S. Let $x = \sum_{i=1}^n c_i u_i$.

(a)
$$Ax = \sum_{i=1}^{n} \lambda_i c_i u_i$$
, so $x^H Ax = \left(\sum_{j=1}^{n} \bar{c}_j u_j^H\right) \left(\sum_{i=1}^{n} c_i u_i\right) = \sum_{j=1}^{n} \sum_{i=1}^{n} \bar{c}_j c_i u_j^H u_i = \sum_{i=1}^{n} |c_i|^2 \lambda_i$.

Similarly, $\mathbf{x}^H \mathbf{x} = \sum_{i=1}^n |c_i|^2$ so

$$\rho(\boldsymbol{x}) = \frac{\boldsymbol{x}^H A \boldsymbol{x}}{\boldsymbol{x}^H \boldsymbol{x}} = \frac{\sum_{i=1}^n |c_i|^2 \lambda_i}{\sum_{i=1}^n |c_i|^2}$$

(b) If $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n$, then clearly

$$\lambda_1 = \frac{\sum_{i=1}^n |c_i|^2 \lambda_1}{\sum_{i=1}^n |c_i|^2} \ge \rho(\boldsymbol{x}) = \frac{\sum_{i=1}^n |c_i|^2 \lambda_i}{\sum_{i=1}^n |c_i|^2} \ge \frac{\sum_{i=1}^n |c_i|^2 \lambda_n}{\sum_{i=1}^n |c_i|^2} = \lambda_n$$

Section 6.5

4. We are given an SVD of A as

$$A = \begin{bmatrix} 3/5 & -4/5 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 30 & & \\ & 15 & \\ & & 3 \end{bmatrix} \begin{bmatrix} 3/5 & 4/5 & 0 \\ -4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

A rank 2 matrix of minimal $\|\cdot\|_F$ distance is

$$A_{2} = \begin{bmatrix} 3/5 & -4/5 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 30 \\ 15 \\ 0 \end{bmatrix} \begin{bmatrix} 3/5 & 4/5 & 0 \\ -4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 3/5 & -4/5 \\ 4/5 & 3/5 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 30 \\ 15 \end{bmatrix} \begin{bmatrix} 3/5 & 4/5 & 0 \\ -4/5 & 3/5 & 0 \end{bmatrix}$$

A rank 1 matrix of minimal $\|\cdot\|_F$ distance is

$$A_{1} = \begin{bmatrix} 3/5 & -4/5 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 30 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 3/5 & 4/5 & 0 \\ -4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 3/5 \\ 4/5 \\ 0 \end{bmatrix} \begin{bmatrix} 30 \end{bmatrix} \begin{bmatrix} 3/5 & 4/5 & 0 \end{bmatrix}$$
$$= \sigma_{1} \boldsymbol{u}_{1} \boldsymbol{u}_{1}^{T}$$

7. $A = U\Sigma V^T$, if rank(A) = r, then

$$A = \begin{bmatrix} oldsymbol{u}_1 & \cdots & oldsymbol{u}_r \end{bmatrix} egin{bmatrix} \sigma_1 & & & \ & \ddots & \ & & \sigma_r \end{bmatrix} egin{bmatrix} oldsymbol{v}_1^T \ dots \ oldsymbol{v}_r^T \end{bmatrix} = B egin{bmatrix} oldsymbol{v}_1^T \ dots \ oldsymbol{v}_r^T \end{bmatrix}$$

for some B so all rows of A are liner combinations of the vectors $\{v_1, \ldots, v_r\}$ and so $\operatorname{rng}(A^T) = \operatorname{RS}(A) = \operatorname{span}\{v_1, \ldots, v_r\}$. Trivially, $\{v_1, \ldots, v_r\}$ is independent so it is a basis for $\operatorname{rng}(A^T)$.

9. If A is $n \times n$ and $A = U \Sigma V^T$, then $\det(A) = \det(U) \det(\Sigma) \det(V^T) = \det(\Sigma) = \prod_{i=1}^n \sigma_i$. Since U and V are unitary $\det(U), \det(V) \in \{1, -1\}$ and so

$$\det(A) = \pm \prod_{i=1}^{n} \sigma_i = \prod_{i=1}^{n} \lambda_i$$

Since all $\sigma_i \geq 0$, it follows that

$$\prod_{i=1}^{n} \sigma_i = \left| \prod_{i=1}^{n} \lambda_i \right|$$

11. Let σ be a singular value for A and v be a corresponding right singular vector. $Av = \sigma u$ where u is the associated left singular vector. Then

$$\frac{\langle A\boldsymbol{v}, A\boldsymbol{v}\rangle}{\langle \boldsymbol{v}, \boldsymbol{v}\rangle} = \frac{\langle \sigma\boldsymbol{u}, \sigma\boldsymbol{u}\rangle}{\langle \boldsymbol{v}, \boldsymbol{v}\rangle} = \frac{\sigma^2 \|\boldsymbol{u}\|_2^2}{\|\boldsymbol{v}\|_2^2} = \sigma^2$$

12. This defines what is called the psuedo-inverse of a matrix A. This is very important, say in least squares. Recall, that in least squares we have a matrix A and we want to "solve" Ax = b, but this might not have an exact solution, so instead we search for b that is as close as possible to CS(A).

In general, given a subspace $S \subset V$ (in an inner product space), if we want the $\hat{\boldsymbol{b}} \in S$ closest to some $\boldsymbol{b} \in V$, then what we are looking for is the *orthogonal projection of* \boldsymbol{b} on S. This means that we want $\boldsymbol{b} - \hat{\boldsymbol{b}} \perp S$ and $\hat{\boldsymbol{b}} \in S$. To see why this yields $\hat{\boldsymbol{b}}$ is the closest point in S to \boldsymbol{b} take any other $\boldsymbol{v} \in S$, then we have

$$||m{b} - m{v}||^2 = ||m{b} - \hat{m{b}} + \hat{m{b}} - m{v}||^2 = ||m{b} - \hat{m{b}}||^2 + ||\hat{m{b}} - m{v}||^2 \ge ||m{b} - \hat{m{b}}||^2$$

This is by Pythagorean theorem (this is a good exercise!) using the fact that $b - \hat{b} \perp v - \hat{b}$, since $v - \hat{b} \in S$ and $b - \hat{b} \perp S$.

If we want to find the least square solution to Ax = b, then we want to find a point $\hat{b} \in CS(A)$ so that $b - \hat{b} \perp CS(A)$. Just take S from above to be CS(A). This means we want two things $\hat{b} = A\hat{x}$ for some \hat{x} and $A^T(b - \hat{b}) = 0$. Putting these together, this means we want

$$A^T \boldsymbol{b} = A^T A \hat{\boldsymbol{x}} \tag{1}$$

Let $A^\dagger = V \Sigma^\dagger U^T$ where $A = U \Sigma V^T$ is the svd decomposition of A and

$$\Sigma^{\dagger} = \begin{bmatrix} 1/\sigma_1 & 0 & 0 & \dots \\ 0 & 1/\sigma_2 & 0 & \dots \\ 0 & 0 & 1/\sigma_3 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

is $n \times m$, if A is $m \times n$. Notice

$$\Sigma \Sigma^{\dagger} = \begin{bmatrix} I_k & O \\ O & O \end{bmatrix}$$

is $m \times m$ and

$$\Sigma^T \Sigma \Sigma^{\dagger} = \Sigma^T \tag{2}$$

Now what makes A^{\dagger} the psuedo-inverse is exactly that $A^{\dagger} \boldsymbol{b}$ is a least squares solution to $A\boldsymbol{x} = \boldsymbol{b}$. To show this we need to show $\hat{\boldsymbol{x}} = A^{\dagger} \boldsymbol{b}$ satisfies equation (1), that is:

$$A^T \boldsymbol{b} = A^T A \hat{\boldsymbol{x}} = A^T A A^{\dagger} \boldsymbol{b}$$

For this, just compute and use equation (2).

$$A^TAA^\dagger = V\Sigma^TU^TU\Sigma V^TV\Sigma^\dagger U^T = V\Sigma^TI\Sigma I\Sigma^\dagger U^T = V\Sigma^T(\Sigma\Sigma^\dagger)U^T = V\Sigma^TU^T = A^TI\Sigma I\Sigma^\dagger U^T = A^TI\Sigma U^T = A^$$

There are two ways to compute the psuedo-inverse in MATLAB and three ways to compute a least-squares solution to Ax = b.

```
[U,S,V] = svd(A);
% Compute the psuedo-inverse using the definition
Adag1 = V*diag(diag(S(1:rank(A),1:rank(A))).^-1)*U';
% Compute the psuedo -nverse using the builtin function
Adag2 = pinv(A);
% Note Adag1 = Adag2

% Compute the least squares solution to Ax = b using "\"
shat1 = A\b;
% Compute the least squares solution using the psuedo-inverse
xhat2 = Adag*b;
% or
xhat3 = Ainv*b;
% xhat1 = xhat2 = xhat3
```

There are other solutions to the least squares problem, namely, any element of $\hat{x} + \ker(A)$ is a solution.

Section 7.6

5. Let

$$A = \begin{bmatrix} 5 & 2 & 2 \\ -2 & 1 & -1 \\ -3 & -4 & 2 \end{bmatrix}$$

a. Verify that (4, (2, -2, 1)) is an "eigenpair".

This is trivial, just verify that

$$\begin{bmatrix} 5 & 2 & 2 \\ -2 & 1 & -2 \\ -3 & -4 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} = 4 \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$$

b. Find a Householder transformation H so that

$$HAH = HAH^{-1} = \begin{bmatrix} 4 & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix}$$
 (3)

The point is that if A and B are similar, then A and B have the same eigenvalues, since they have the same characteristic equation. (Quick proof: $\chi_A(\lambda) \det(A - \lambda I) = \det(SBS^{-1} - \lambda SIS^{-1}) = \det(S(B - \lambda I)S^{-1}) = \det(S) \det(S - \lambda I) \det(S)^{-1} = \det(S - \lambda I) = \chi_B(\lambda)$.)

Since

$$HAH^{-1} = \begin{bmatrix} 4 & B \\ \mathbf{0} & C \end{bmatrix}$$

we have $\det(HAH^{-1}) = (\lambda - 4)\det(C - \lambda I)$ so we have reduced out problem to finding the eigenvalues of a smaller matrix C.

Recall a Householder transformation is of the form $H_x = I - 2uu^T$ and is defined for a specific vector x so that $Hx = ||x||e_1$. Some things to remember:

- H is symmetric. (Proof: $H^T = (I^T 2(\boldsymbol{u}^T)^T \boldsymbol{u}^T) = (I \boldsymbol{u} \boldsymbol{u}^T)$.)
- H is orthogonal. (Proof: $H^TH = HH = H^2 = (I 2\boldsymbol{u}\boldsymbol{u}^T)(I 2\boldsymbol{u}\boldsymbol{u}^T) = (I^2 2I\boldsymbol{u}\boldsymbol{u}^T 2\boldsymbol{u}\boldsymbol{u}^TI + 4(\boldsymbol{u}\boldsymbol{u}^T)(\boldsymbol{u}\boldsymbol{u}^T)) = I 4\boldsymbol{u}\boldsymbol{u}^T + 4\boldsymbol{u}(\boldsymbol{u}^T\boldsymbol{u})\boldsymbol{u}^T = I 4\boldsymbol{u}\boldsymbol{u}^T + 4\boldsymbol{u}I\boldsymbol{u}^T = I.$)
- So $H = H^{-1}$, that is, H is **idempotent**.
- Hx = v iff Hv = x. (Proof: Hx = v implies HHx = x = Hv. Similarly in the other direction.)

For this problem, let $\mathbf{x} = 4/3(-2, 2, -1)$ so that $||\mathbf{x}|| = 4$ and \mathbf{x} is an eigenvector for 4 for A. This way $H = H_{\mathbf{x}}$ satisfies $H\mathbf{x} = 4\mathbf{e}_1$ and thus

$$HAHe_1 = HA(1/4x) = 1/4HAx = 1/4H(4x) = (1/4)(4)Hx = 4e_1$$

so e_1 is an eigenvector for 4 in HAH. Thus equation (3) holds.

All that is left is to provide u to define H, this is done as follows:

$$\mathbf{u} = \frac{1}{\sqrt{2\beta}}(x_1 - \alpha, x_2, x_3),$$

where $\beta = \alpha(\alpha - x_1)$ and

$$\alpha = \begin{cases} -||x|| & \text{if } x_1 > 0\\ ||x|| & \text{if } x_1 \le 0 \end{cases}$$

Note that $\beta > 0$. (α is chosen this way to optimize numeric stability of the calculation.) It is a simple exercise to show ||u|| = 1.

Let $\mathbf{v} = (x_1 - \alpha, x_2, x_3)$, then

$$2uu^T = \frac{1}{\beta}vv^T$$
 so $H = I - 2uu^T = I - \frac{1}{\beta}vv^T$

and

$$Hx = x - \frac{1}{\beta}v(v^Tx) = x - \frac{1}{\beta}v(x_1^2 - \alpha x_1 + x_2 + x_3^2) = x - \frac{1}{\beta}v(\alpha^2 - \alpha x_1) = x - v = \alpha e_1$$

as desired.

So $\boldsymbol{x}=4/3(-2,2,-1)$ and thus $\alpha=4$ and $\beta=4(4+8/3)=80/3$ and $\boldsymbol{v}=(-8/3-4,8/3,-4/3)=4/3(-5,2,-1)$ and

$$H = I - \frac{1}{\beta} \boldsymbol{v} \boldsymbol{v}^T = I - \begin{bmatrix} 5/3 & -2/3 & 1/3 \\ -2/3 & 4/15 & -2/15 \\ 1/3 & -2/15 & 1/15 \end{bmatrix} = \begin{bmatrix} -2/3 & 2/3 & -1/3 \\ 2/3 & 11/15 & 2/15 \\ -1/3 & 2/15 & 14/15 \end{bmatrix}$$

c. Compute HAH and find the remaining two eigenvalues.

$$HAH = \begin{bmatrix} 4 & -12/5 & -9/5 \\ 0 & 53/25 & -4/25 \\ 0 & -154/25 & 47/25 \end{bmatrix}$$

So

$$C = \frac{1}{25} \begin{bmatrix} 53 & -4 \\ -154 & 47 \end{bmatrix}$$

and

$$\det(C-\lambda I)=(\lambda-3)(\lambda-1)$$

so the remaining two eigenvalues of A are 3 and 1.