

Equivalent source method for magnetic extrapolation

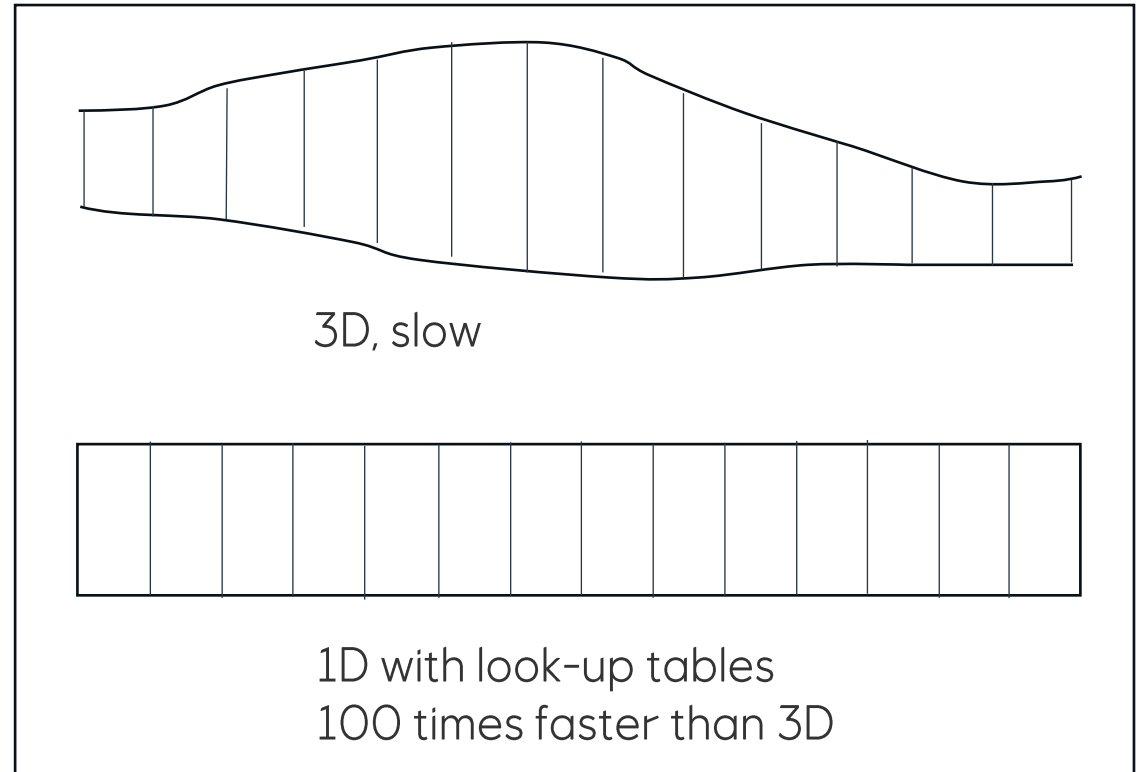
KetilH, 23. October 2025



Magnetic map inversion

What the code was made for:

- Deep-sea minerals (mid-ocean ridges)
- Geothermal exploration (Iceland)
- Basalt (MORB); $Q_K \sim 20$
- However, the code is also suitable for equivalent-source data extrapolation
- Implemented in Python
- The main numerical cost is computation of square-roots
- Can be improved by a compiled C/Fortran function with Python API (?)



References

Hokstad, K., Alasonati-Tašárová, Z., Sæther, B.M., and Tānavsū-Milkeviciene, K., 2020, Inversion of Magnetic Data for Subsurface Temperature: Proceedings of the World Geothermal Congress 2020+1.

Hokstad, K. and Kruber, C., 2023, Multigeophysical Inversion for Geothermal Exploration. GRC Transactions **47**, 2939.



Magnetic inversion scheme

Magnetic anomaly

$$\mathbf{B}_A(\mathbf{x}) = -\frac{\mu_0}{4\pi} \nabla \nabla \cdot \iiint \frac{\mathbf{M}(\mathbf{x}')}{|\mathbf{x}' - \mathbf{x}|} dV'$$

$$\mathbf{M} = \mathbf{M}_R + \mathbf{M}_I = \mathbf{M}_R + \chi \mathbf{H}$$

Assume \mathbf{M} is independent of z or average over z

$$\mathbf{M}(x, y) = \frac{1}{z_2 - z_1} \int_{z_1}^{z_2} \mathbf{M}(x, y, z) dz$$

$$\mathbf{M} = M \mathbf{e} \simeq M \mathbf{t}$$

$$\mathbf{t} = \frac{\mathbf{B}_0}{|\mathbf{B}_0|}$$

Analytic integration over z in the equation for \mathbf{B}_A

$$\int_{z_1}^{z_2} \frac{1}{r} dz' = \ln[(z' - z) + r] \Big|_{z_1}^{z_2} = F(z_2) - F(z_1)$$

$$F(z') = \ln[(z' - z) + r]$$

$$r = |\mathbf{x}' - \mathbf{x}|$$

Forward model

$$B_A(\mathbf{x}) = \frac{\mu_0}{4\pi} \sum_{i=1}^3 \sum_{j=1}^3 \iint t_i A_{ij}(\mathbf{x}, \mathbf{x}') M_j(\mathbf{x}', y') dx' dy'$$

$$B_A(x_i) = |\mathbf{B}_0 + \mathbf{B}_A| - |\mathbf{B}_0| \simeq \mathbf{t} \cdot \mathbf{B}_A(\mathbf{x})$$

$$A_{ij} = \frac{\partial^2 F(z_2)}{\partial x_i \partial x_j} - \frac{\partial^2 F(z_1)}{\partial x_i \partial x_j}$$

Vector-matrix form

$$\mathbf{d} = \mathbf{L} \mathbf{m} + \mathbf{n}$$

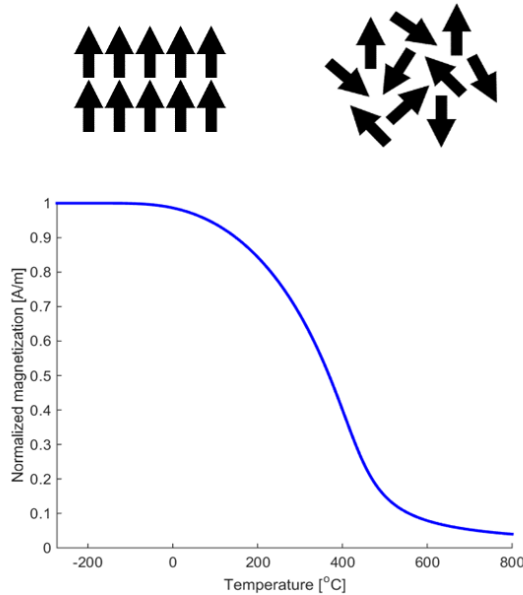
$$L_{ij} = \frac{\mu_0}{4\pi} \sum_{k=1}^3 \sum_{l=1}^3 t_k A_{kl}(x_i, y_i, z_i, x'_j, y'_j) t_l$$

Marquardt-Levenberg

$$\mathbf{m} = [\mathbf{L}^T \mathbf{\Sigma}_d^{-1} \mathbf{L} + \mathbf{\Sigma}_m^{-1}]^{-1} \mathbf{L}^T \mathbf{\Sigma}_d^{-1} \mathbf{d}$$

$$\mathbf{\Sigma}_m^{-1} = \lambda \text{diag}(\mathbf{L}^T \mathbf{L})$$

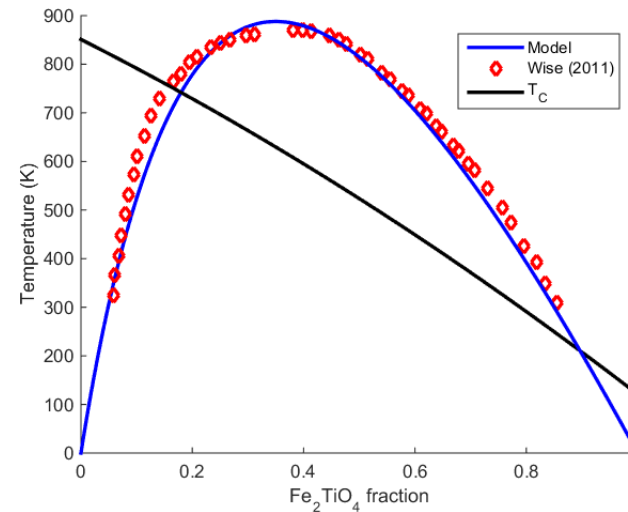
Part of multigeophysical inversion (MGI)



Ising (1925) model

Macroscopic magnetization

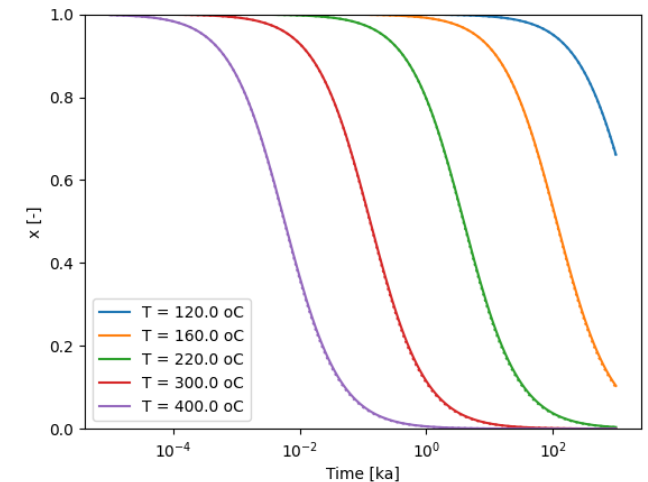
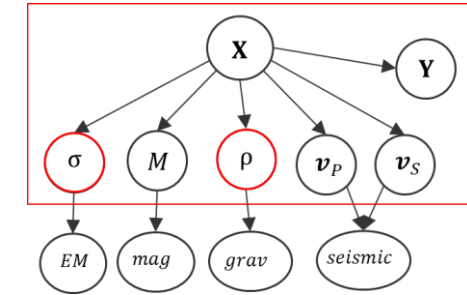
$$\frac{M}{M_0} = \tanh \left[\frac{T_C M}{T M_0} + \frac{CH}{T M_0} \right]$$



Spinodal exsolution

$$\frac{\partial^2 G}{\partial u^2} = -2W + k_B T \left[\frac{(1+h)}{u} + \frac{(1-h)}{v} \right] = 0$$

- Curie temperature from Lattard et al. (2006)
- Calibration using data from Wise et al. (2011)



Oxidation: Mixed 1st/2nd order Arrhenius

$$\frac{dx}{dt} = - \left(\frac{k_1 - k_2}{x_0} \right) x^2 - k_2 x$$

$$k_i = A e^{-\frac{E_i}{RT}}$$



Geothermal Iceland



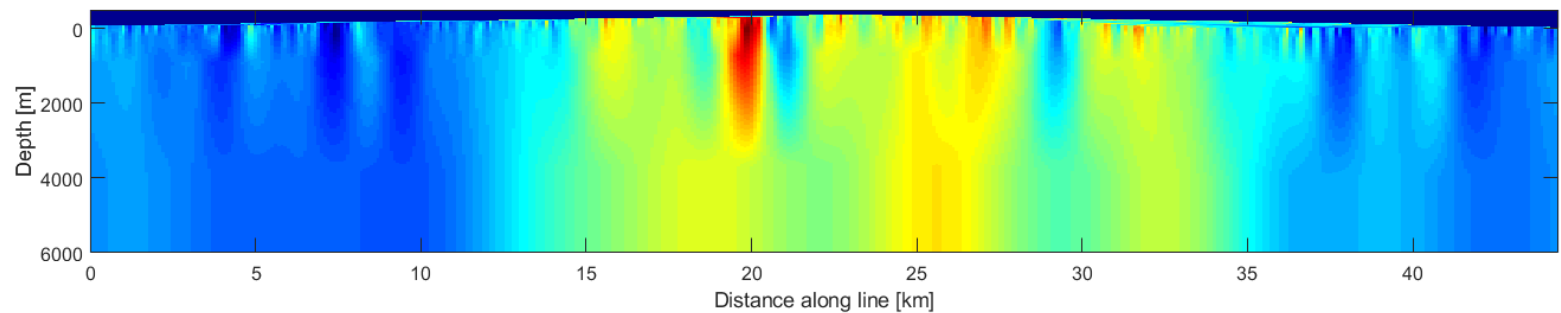
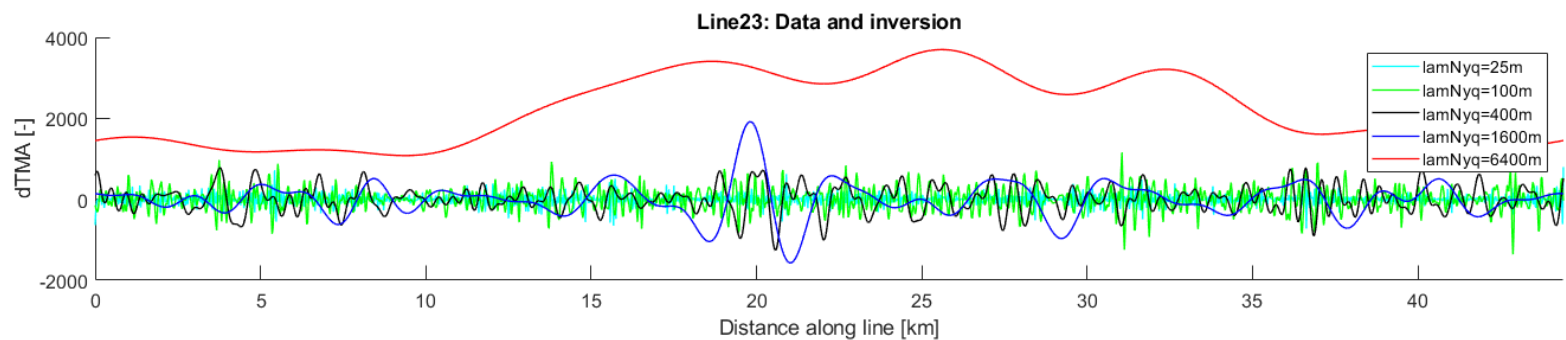
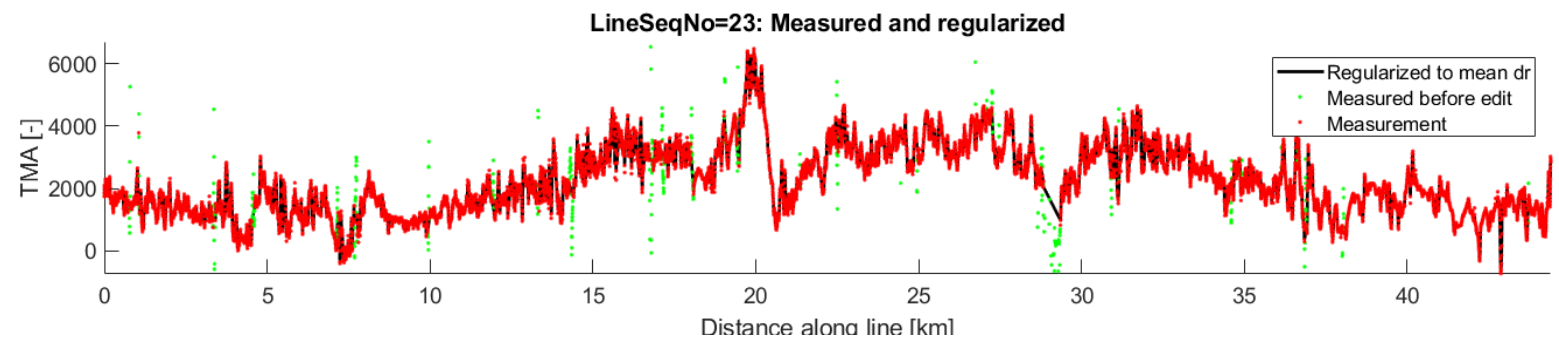
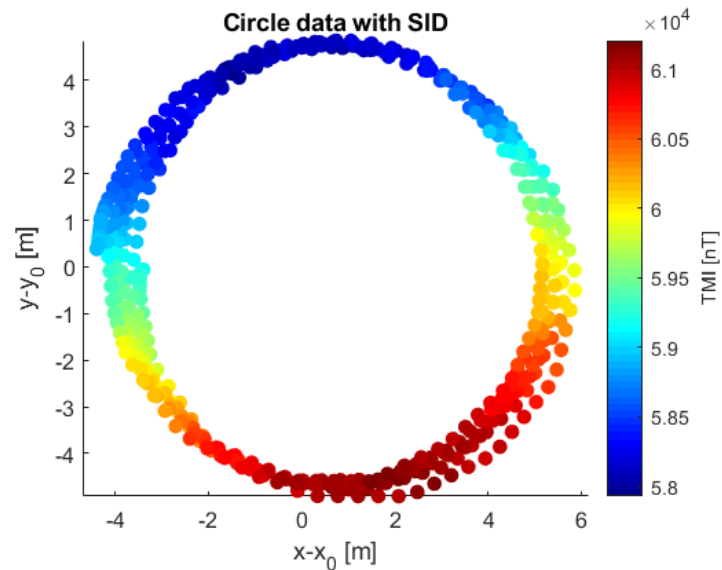
Reykjavik



Hellisheiði



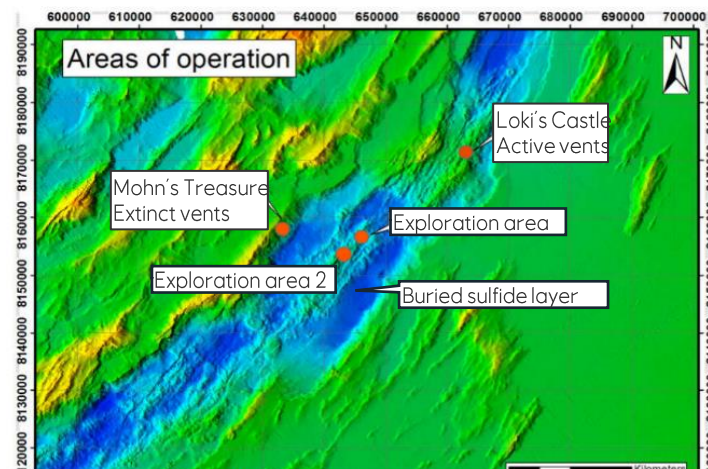
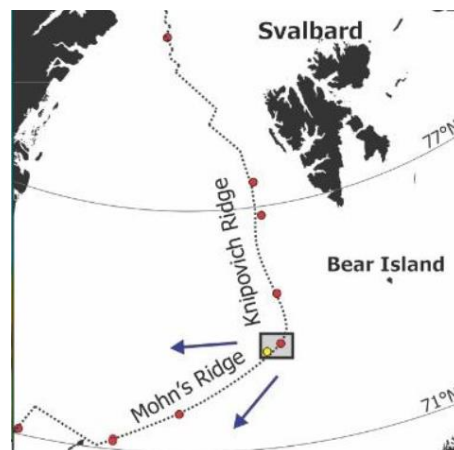
Selfoss



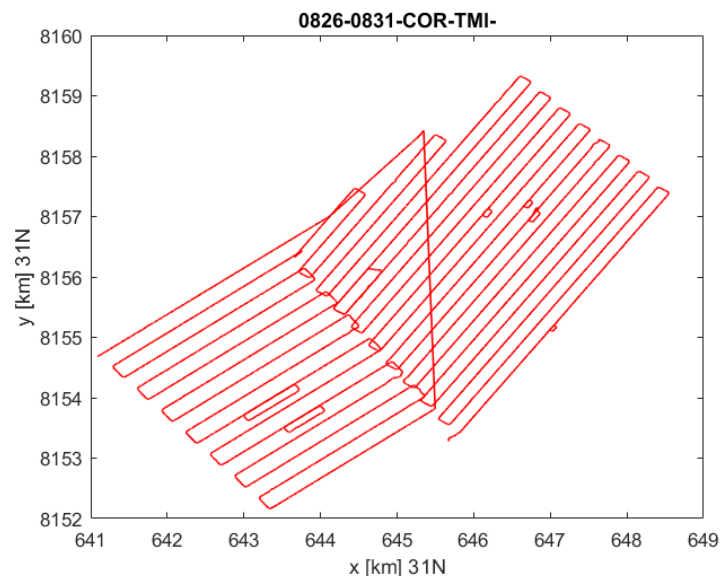
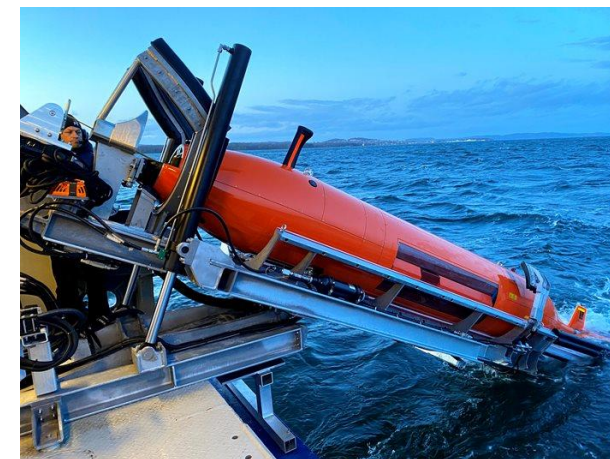
Deep-sea minerals Mohn's Ridge



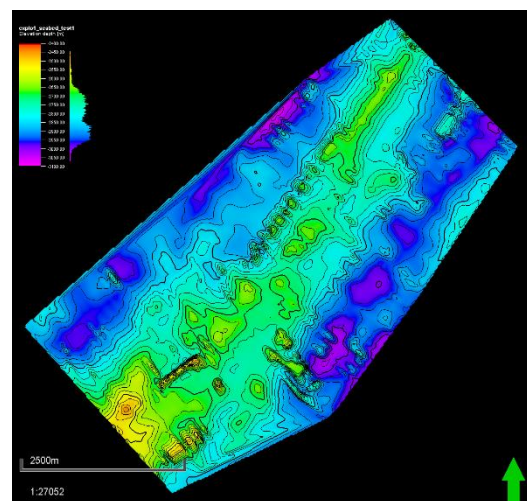
Data from NTNU
MarMine cruise to
Mohn's Ridge 2016
(Lim et al., 2019;
Lim PhD thesis,
2020)



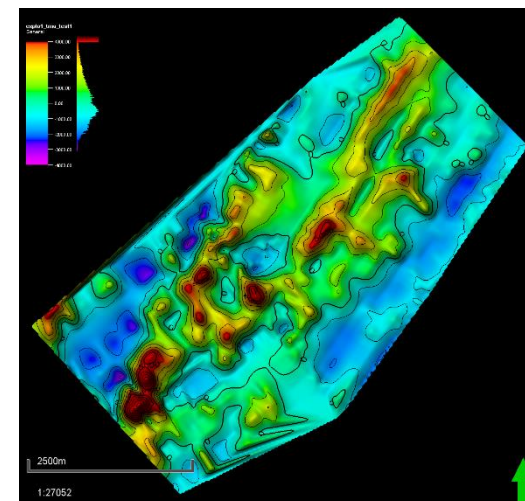
Figur 1 Figure 1. Area of operations.



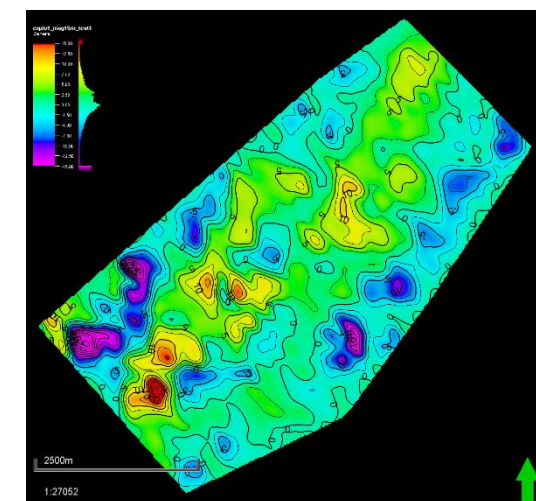
AUV track explo-area 1



Bathymetry



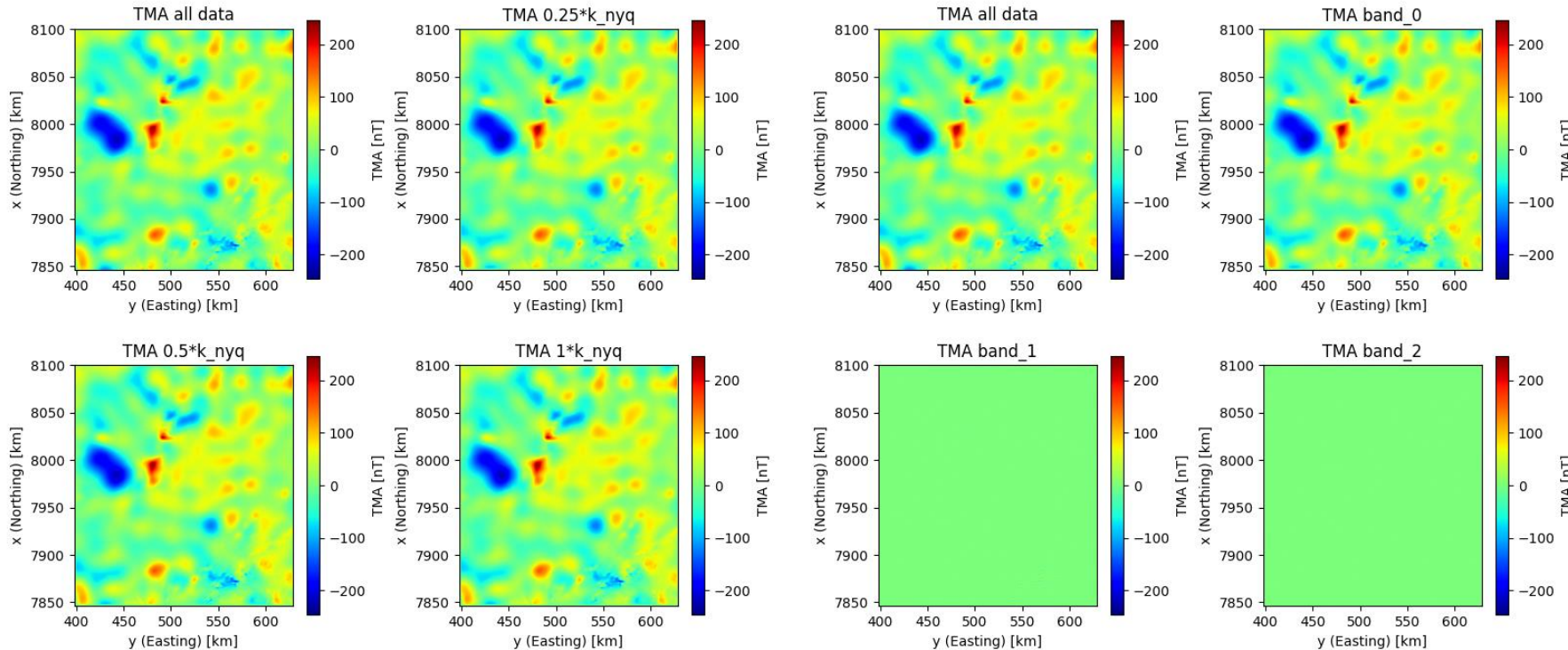
Total magnetic anomaly (TMA)



Magnetization from inversion



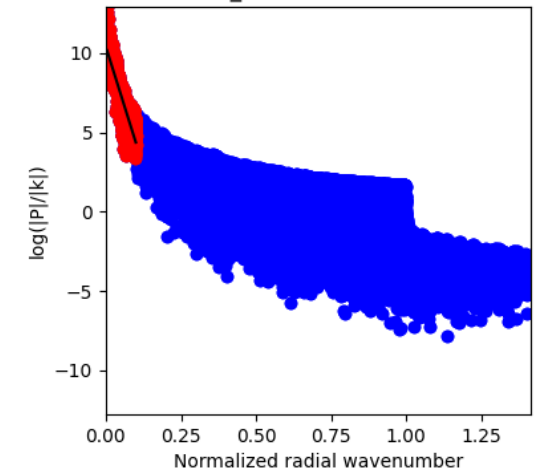
Equivalent-source test data analysis



Data input to analysis

DX=DY=500m

z_base = 18602m



Radial wavenumber filtering

$$k_r = \sqrt{k_x^2 + k_y^2}$$
$$k_{nyq} = \frac{\pi}{\Delta x}$$

Wavenumber band decomposition
in fractions of k_{nyq}

band_0 : 0 - $\frac{1}{4}$

band_1 : $\frac{1}{4}$ - $\frac{1}{2}$

band_2 : $\frac{1}{2}$ - 1

Approximate base of
magnetic layer from
power-band analysis
(Blakely, 1996)



Equivalent-source extrapolation

Data

DX=DY=1000m

Receiver altitude: 240m

Model:

DX=DY=4000m

Top magnetic layer: 10km

Base magnetic layer: 18km

Extrapolation depths:

z0 = 0m

z1 = 1200m

z2 = 2400m

z3 = 3600m

z4 = 4800m

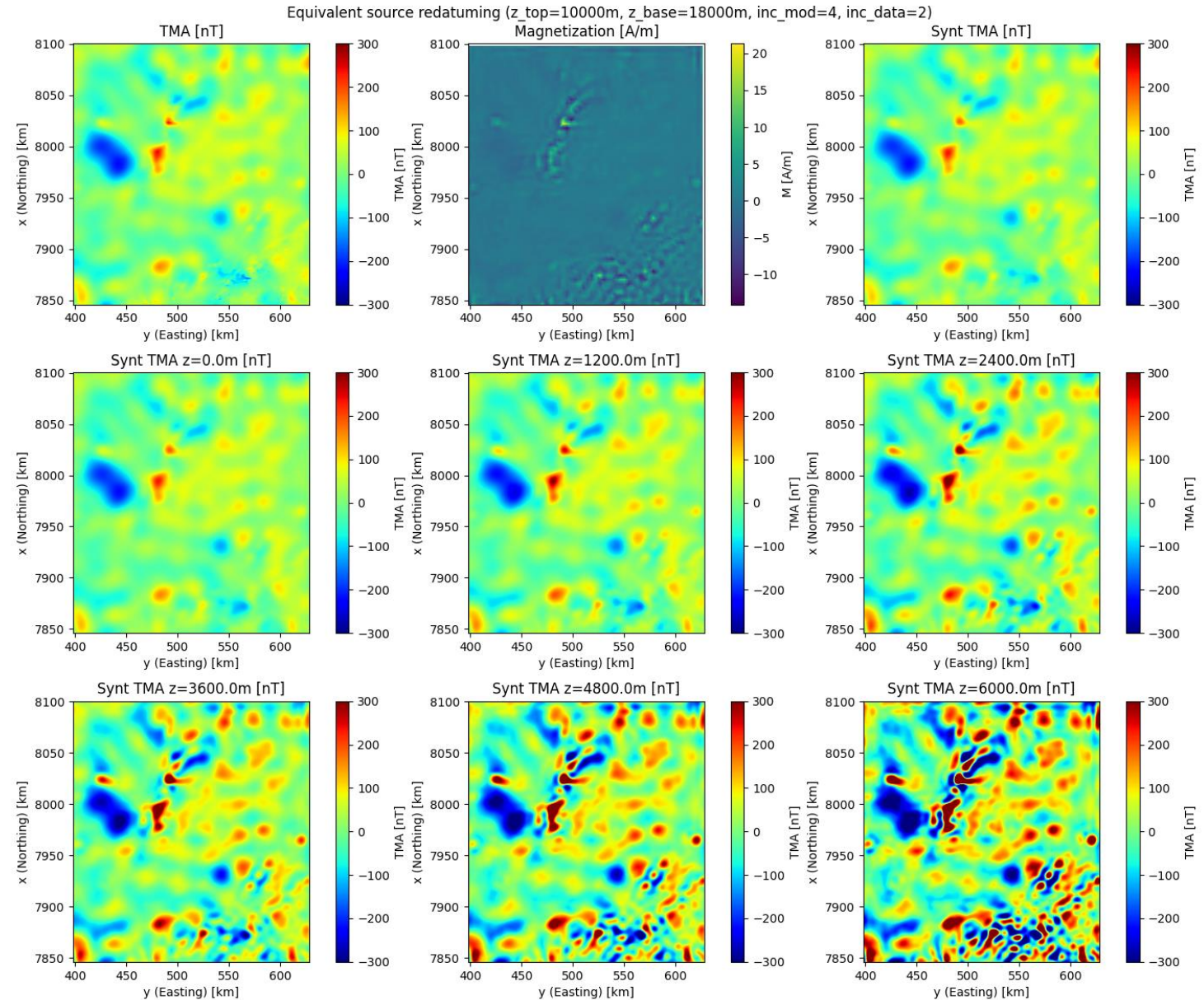
z5 = 6000m

Compute time

Inversion: 28 sec

Modeling: 108 sec

1D model is 100 times faster than 3D





Distance to top magnetic layer

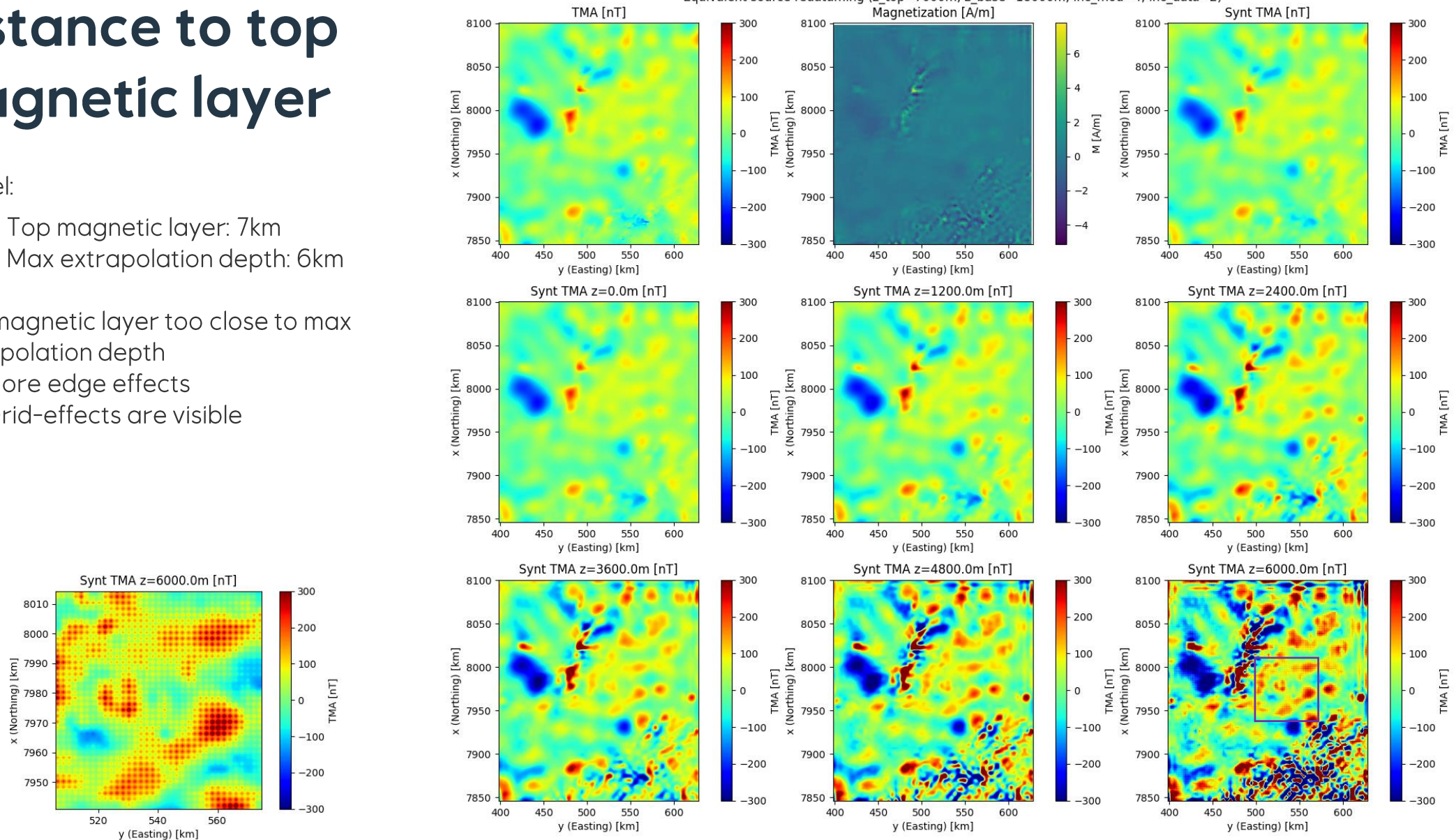
Model:

Top magnetic layer: 7km
Max extrapolation depth: 6km

Top magnetic layer too close to max extrapolation depth

- More edge effects
- Grid-effects are visible

Equivalent source redatuming ($z_{\text{top}}=7000\text{m}$, $z_{\text{base}}=18000\text{m}$, $\text{inc_mod}=4$, $\text{inc_data}=2$)





Removing edge effects - mirroring

Mirroring data on the edges:

- Extend data
- Extend model (important)

Comes at the cost of increased compute time

No mirroring

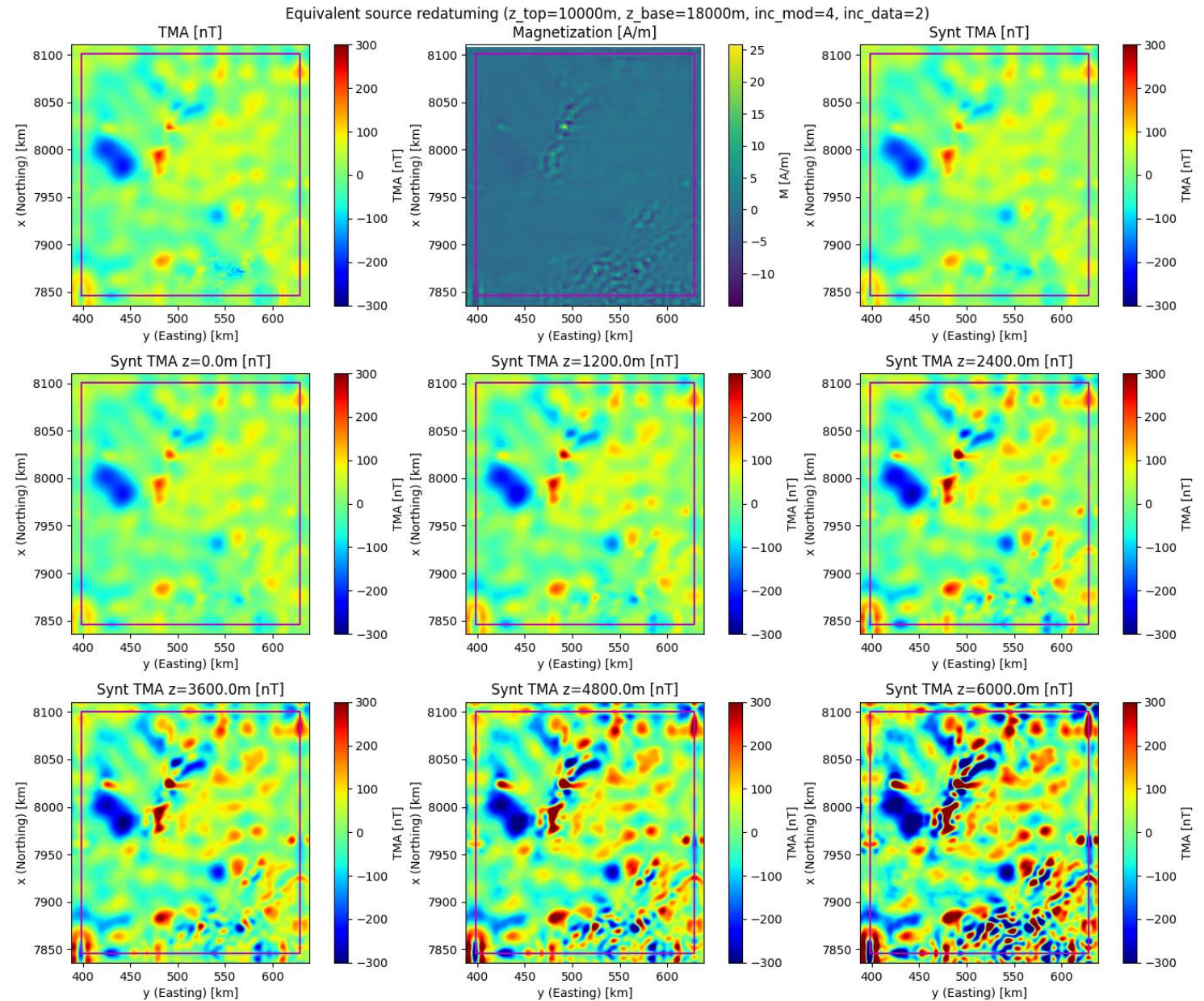
- Inversion: 28 sec
- Modeling: 108 sec

20 nodes mirroring

- Inversion: 44 sec
- Modeling: 186 sec

60 nodes mirroring

- Inversion: 103 sec
- Modeling: 1160 sec





Conclusions and recommendations

Conclusions

- Map inversion works well for equivalent source method
- Some challenges with edge effects
- Python code
- Fast option:
 - 1D model, with look up tables
 - Compute time: ~ 3 min
 - 100 times faster than 3D model
- Slow option
 - 3D model
 - Compute time: ~5 hours

Recommendations

- Select $\Delta x, \Delta y$ for data input to inversion by wavenumber spectral analysis
- Grid spacing for equivalent source model:

$$\Delta x_m = \Delta y_m = 4\Delta x = 4\Delta y$$

- Magnetic equivalent source layer:

$$z_{top} \geq z_n + dx_m$$

z_{base} from power spectral method (Blakely, 1996)

- Dealing with edge effects
 - Expand data area (if possible)
 - Data mirroring at the edges of the grid
- Monitor these numbers in the inversion:
 - Rank of the Marquardt-Levenberg matrix
 - Condition number (OK if $\sim 10^4$ or less)

Equivalent source method for magnetic extrapolation

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