Real-Time End-to-End Scheduling

做下一件事要等其他事一起完成

Embedded System Software Design

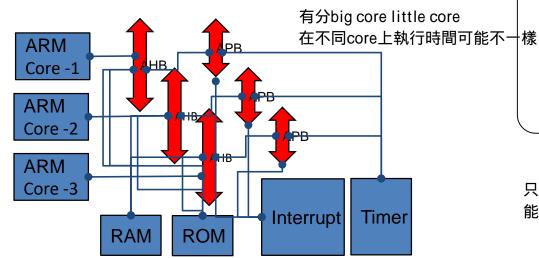
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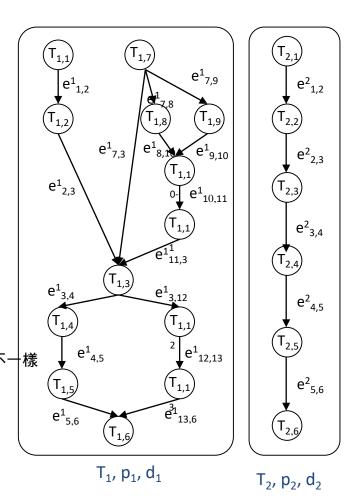
End-to-End Scheduling

- Task model
 - Each task needs to execute on a set of processors in a certain order
 - Each task may require a different order
- Problems in End-to-End scheduling
 - Priority assignment 優先分配
 - Assign fixed priorities to tasks so that the system is schedulable
 - Synchronization of tasks
 - Control the releases of subtask instances (non-first subtasks)
 - Schedulability analysis 可調度性分析
 - For a given priority assignment and a given synchronization protocol, whether every instance of each task meets its deadline

System Model

- Platform: A set of processors
- Task graph, $G = \{T_1, T_2, ..., T_n\}$
 - Sink node
 - − Deadline: *di*
 - Precedence edge: $e^{i_{j,k}}$
 - Predecessors and Sucessors
 - Period or Minimum separation time: p_i
- Characteristics of *T_{i,j}*:
 - Execution time (on processor m): $c^{m_{i,j}}$





只要找到最長的路徑 能排就能排

Priority Assignment

- To find feasible priority assignments off-line if all tasks executed are known in prior

 同一條路優先權怎麼設
 不一定 這有很多作法
- NP-hard problem 沒有定論 哪一個表現特別好
- Algorithms
 - Branch and bound
 - Search algorithm
 - Simulated annealing
 - Generic algorithm
 - Heuristic
 - Deadline assignment

Deadline Assignment

Ultimate deadline

$$-UD_{i,k}=D_i$$
 期限

Effective deadline

$$-ED_{i.k}=D_i-\sum_{l=k+1}^{n(i)}e_{i.l}$$
期限 - 同T比他低的執行時間

Proportional deadline

$$-PD_{i,k}=D_ie_{i,k}/e_i$$
 期限 * 執行時間 / 總執行時間

Normalized Proportional deadline

$$-\ NPD_{i,k} = D_i rac{e_{i,k}U(V_{i,k})}{\sum_{l=1}^{n(i)}e_{i,l}U(V_{i,l})}$$
 (執行時間 * U) / (總執行時間 * U) \simeq 整個T的執行時間 * U) 整個T的執行時間 * U)

– $U(V_{i,l})$ is the total utilization of the all the subtasks that execute on the processor $V_{i,l}$

Example

$T_{i,k}$	$V_{i,k}$	p_i	$e_{i,k}$	$UD_{i,k}$	$ED_{i,k}$	$PD_{i,k}$	$NPD_{i,k}$
$T_{1,1}$	P_1	15	1	15	11	3	2.0
$T_{1,3}$	P_1	15	2	15	15	6	4.1
$T_{2,1}$	P_1	20	4	20	20	20	20
$T_{3,1}$	P_2	2	1	2	2	2	2
$T_{1,2}$	P_2	15	2	15	13	6	8.9
$T_{4,1}$	P_2	20	5	20	20	20	20

UD = D
UD11=15
UD13=15
UD21=20

ED11=15-(2+2)=1
ED12=15-(2)=13
ED13=15
ED21=20
ED31=2
ED41=20

U=E/D Up1=1/15+2/15+4/20=0.4 Up2=1/2+2/15+5/20=0.88

NPD11=15*(1*0.4)/(1*0.4+2*0.88+2*0.4)=2 NPD13=15*(2*0.4)/(1*0.4+2*0.88+2*0.4)=4.1 NPD21=20*(4*0.4)/(4*0.4)=20 NPD31=2*(1*0.88)/(1*0.88)=2 NPD12=15*(2*0.88)/(1*0.4+2*0.88+2*0.4)=8.9 NPD41=20*(5*0.88)/(5*0.88)=20

The Synchronization Problem

同步問題

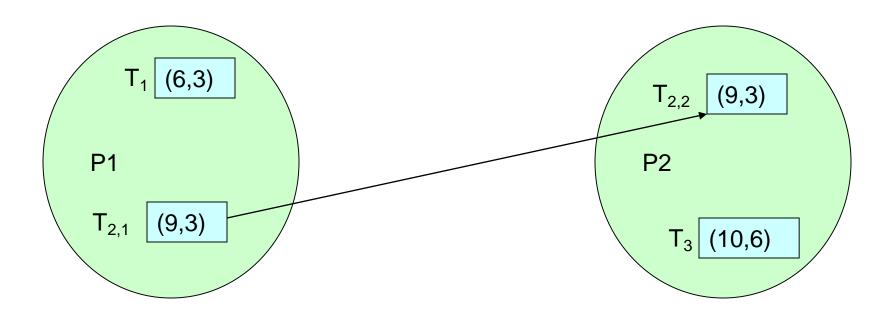
- Given that
 - Priorities are assigned to subtasks in a task chain using some fixed priority assignment algorithm
- How do we coordinate the release of subtasks in a task chain so that
 - Precedence constraints among subtasks are satisfied
 - Subtask deadlines are met
 - End-to-end deadlines are met

Synchronization Protocols

同步協議

- Direct Synchronization (DS) Protocol 做完呼叫繼續做
 - Simple and straightforward
- Phase Modification (PM) Protocol 相位修改
 - Used by flow-shop tasks
 - Extension called Modified Phase Modification (MPM) Protocol
- Release Guard Protocol 釋放
 - Reclaim the idle time 回收idle 時

Example



 $T_{i,j} - j^{th}$ subtask of task T_i

Task T3 releases at 6

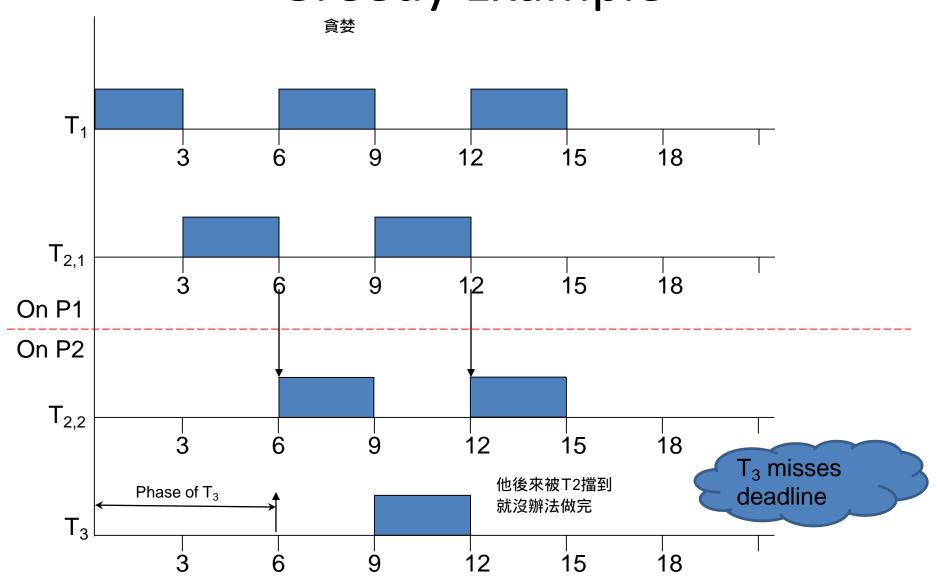
(period, execution time)

Period = relative deadline of parent task

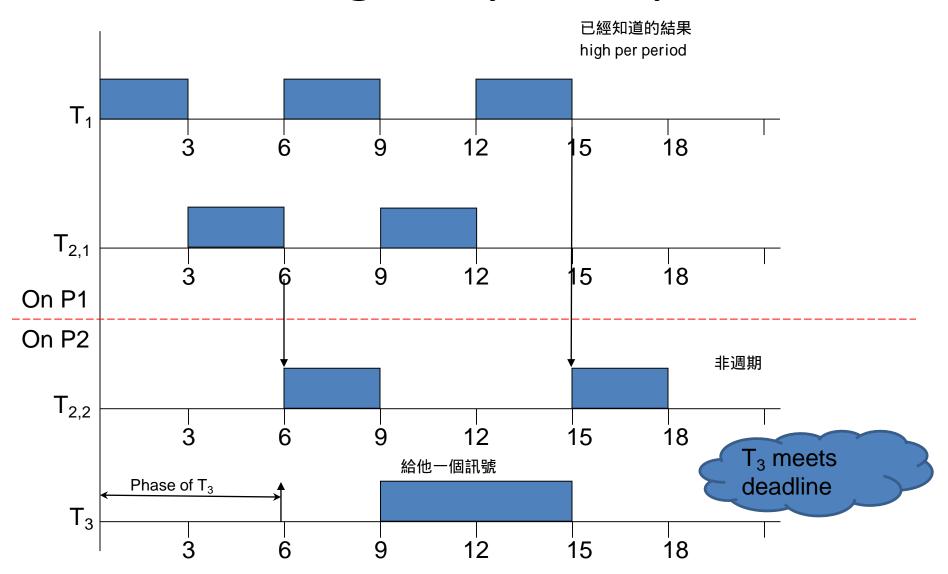
Direct Synchronization Protocol

- Greedy strategy
- On completion of subtask
 - A synchronization signal sent to the next processor
 - Successor subtask competes with other tasks/subtasks on the next processor

Greedy Example



Non-greedy Example



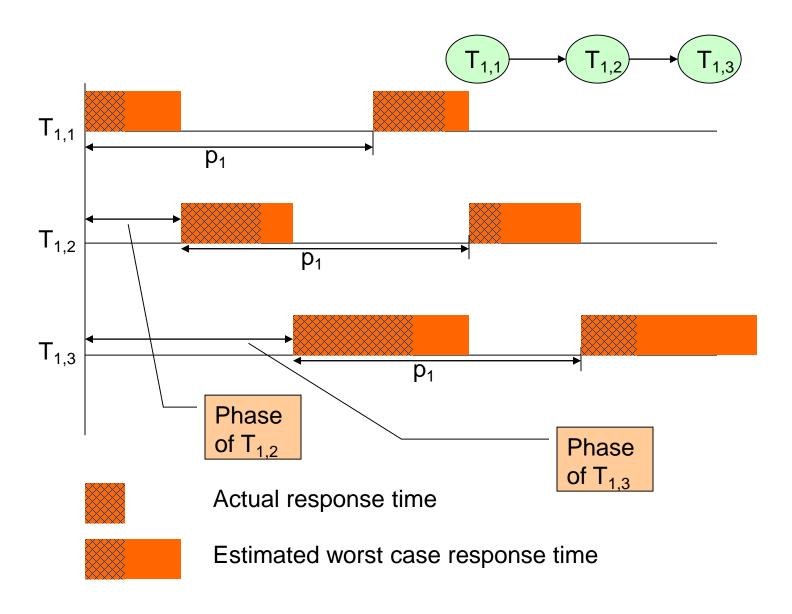
Phase Modification Protocol

- Release subtasks periodically 定期釋放子任務
 - According to the periods of their parent tasks
 根據其上級任務的期限
- Each subtask given its own phase 每個子任務都有自己的階段
- Phase determined by subtask precedence constraints

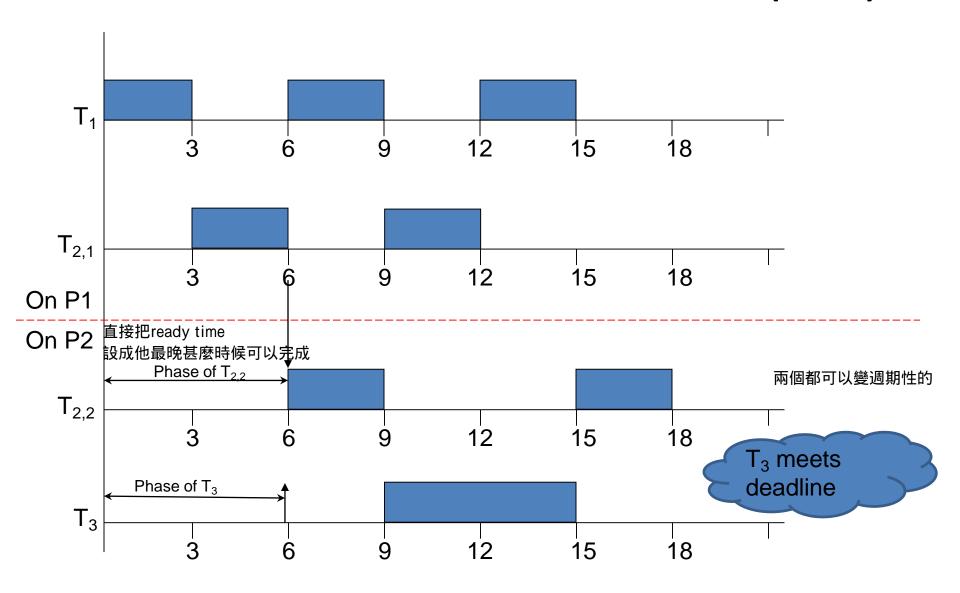
 <sup>階段由子任務優先級確定 約束條件</sub>

 </sup>

Phase Modification Protocol (1/2)



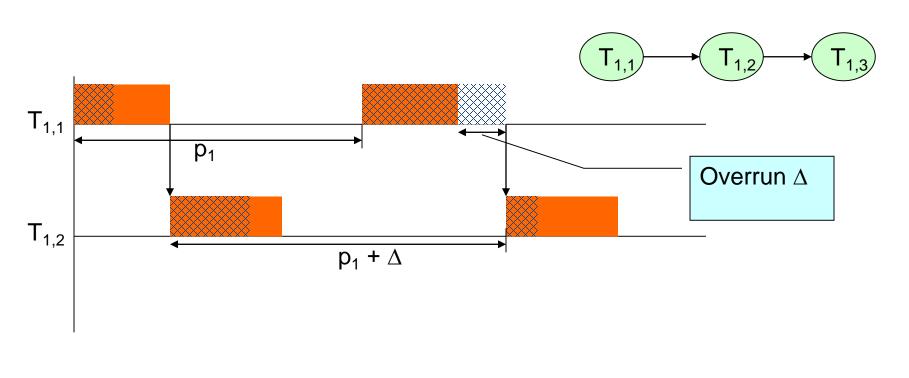
Phase Modification Protocol (2/2)



Phase Modification Protocol - Analysis

- Periodic timer interrupt to release subtasks
- Centralized clock or strict clock synchronization
- Task overruns could cause precedence constraint violations

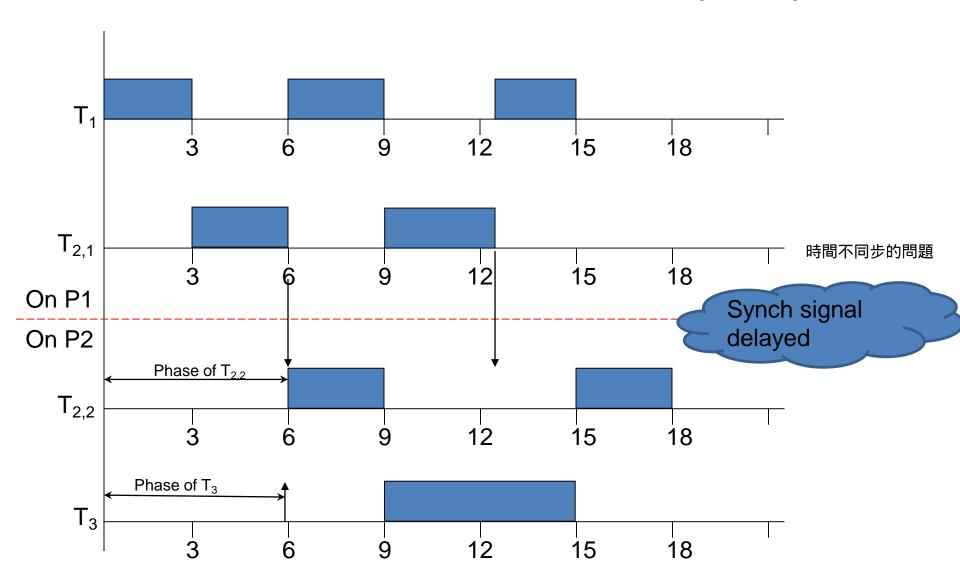
Modified PM Protocol (1/2)



Actual response time

Estimated worst case response time

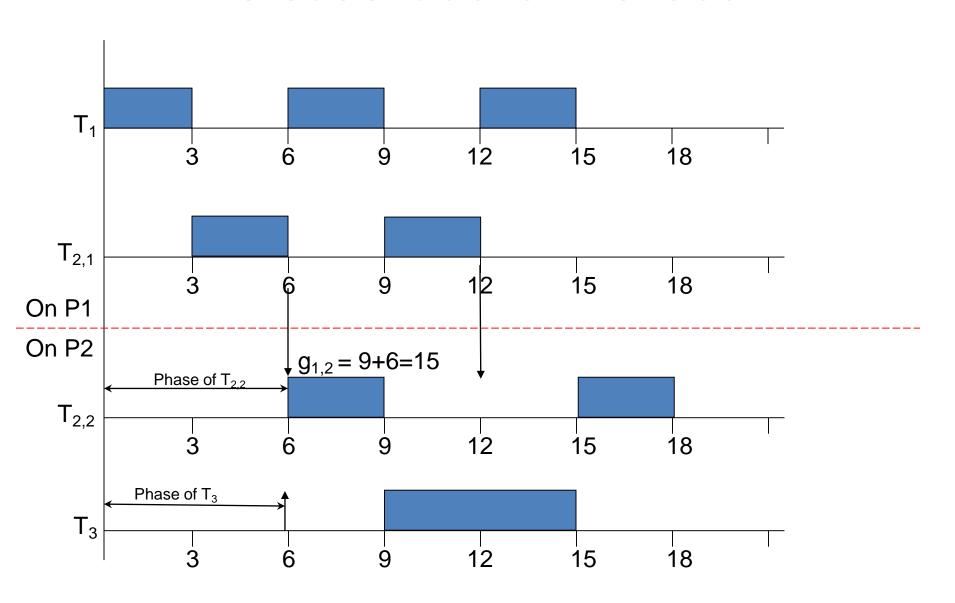
Modified PM Protocol (2/2)



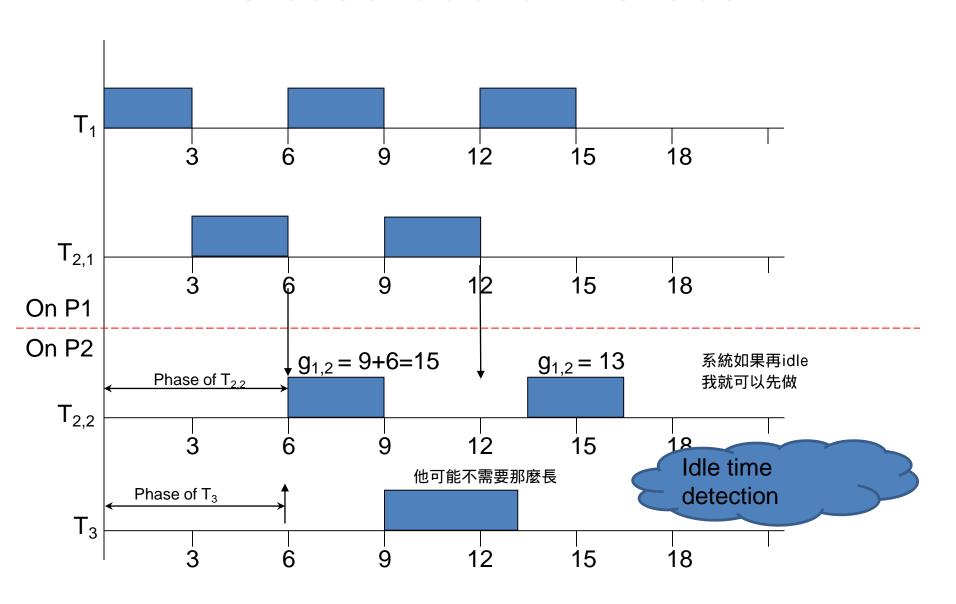
Release Guard Protocol

- A guard variable release guard associated with each subtask
- Release guard used to control release of each subtask
 - Contains next release time of subtask
- Synchronization signals as MPM
- Release guard updated
 - On getting synchronization signal
 - During idle time

Release Guard Protocol



Release Guard Protocol



Release Guard Protocol - Analysis

- Shares the same advantages as MPM
- Upper bound on EER still the same as MPM
 - Since upper bound on release time enforced by release guard
- Lower bound on EER less than that of MPM
 - If there are idle times
 - Results in lower average EER (end-to-end response time)

Schedulability Analysis

可排程分析

An upper bound W_i to the end-to-end response time of any periodic task T_i in a fixed-priority system synchronized according to the MPM protocol or the RG protocol is given by

$$W_i = \sum_{k=1}^{n(i)} W_{i,k}$$

比我低block我的影響

and

自己執行時間

優先比我>=對我的影響

$$W_{i,k} = \frac{e_{i,k} + b_{i,k} + \sum_{\phi_{j,l} \leq \phi_{i,k}} \text{ and } \tau_{j,l} \in V_{i,k}}{1 - \sum_{\phi_{j,l} < \phi_{i,k}} \text{ and } \tau_{j,l} \in V_{i,k}} \frac{e_{j,l}}{u_{j,l}} \quad \text{ 1-優先比我高的人的U}}$$
 通通不用比我高的資源

where n(i) is the number of subtasks in T_i , $\phi_{i,k}$ is the priority of $\tau_{i,k}$, and the upper bound $W_{i,k}$ to the response time of every subtask $T_{i,k}$ is obtained by considering only subtasks on the same processor $V_{i,k}$, and by treating every such subtask $T_{j,l}$ as periodic task whose period is equal to the period p_j of the parent task T_j .

General Scheduling Test (GST)

- Response time analysis
 - The response time of the job of Ti at critical instant can be calculated by the following recursive function

$$r_0 = \sum_{\forall i} c_i$$
 $r_n = \sum_{\forall i} c_i \left[\frac{r_{n-1}}{p_i} \right]$

- Observation: the sequence of r_x , x>=0 may or may not converge

General Scheduling Test (GST)

- Example: T1=(2,5), T2=(2,7), T3=(3,8)
 - T1:
 - $R_0 = 2 \le 5$ ok
 - T2:
 - $R_0 = 2 + 2 = 4 \le 7$
 - $R_1 = 2 *_{\Gamma} 4/5_{\Gamma} + 2 *_{\Gamma} 4/7_{\Gamma} = 4 \le 7 \text{ ok}$
 - T3:
 - $R_0 = 2 + 2 + 3 = 7 \le 8$
 - $R_1 = 2 * {7/5} + 2 * {7/7} + 3 * {7/8} = 9 > 8$ failed
 - Note: each task succeeds → the task set succeeds

W12=(1+0+2)/(1-0)=3 W13=(2+1+1)/(1-0)=4 W21=(4+0+(1+2))/(1-1/15-2/15)=8.75

Example

W31=(1+0+0)/(1-0)=1 W12=(2+1+1)/(1-1/2)=8 W41=(5+0+(1+2))/(1-1/2-2/15)=21.8 W12 R0=1+2=3 W12 R1=1*ceil(3/2)+2*ceil(3/15) = 4

W12b R0=1+2+1=4 W12b R1=1*ceiI(4/2)+3*ceiI(4/15) = 5 W12b R2=1*ceiI(5/2) + 3*ceiI(5/15) = 6

$T_{i,k}$	$V_{i,k}$	p_i	$e_{i,k}$	$UD_{i,k}$	$b_{i,k}$	$W_{i,k}$	$W_{i,k}(GST)$
$T_{1,1}$	P_1	15	1	15	0	3	3
$T_{1,3}$	P_1	15	2	15	1	4	3(4)
$T_{2,1}$	P_1	20	4	20	0	8.75	7
$T_{3,1}$	P_2	2	1	2	0	1	1
$T_{1,2}$	P_2	15	2	15	1	8	4(6)
$T_{4,1}$	P_2	20	5	20	0	21.8	14

W41 R0=1+2+5=8

W41 R1=1*ceil(8/2)+2*ceil(8/15)+5*ceil(8/20) = 11

W41 R2=1*ceil(11/2)+2*ceil(11/15)+5*ceil(11/20)=13

W41 R3=1*ceil(13/2)+2*ceil(13/15)+5*ceil(13/20)=14

W41 R4=1*ceil(14/2)+2*ceil(14/15)+5*ceil(14/20)=14.3

Comparison of Protocols

	DS	PM	MPM	RG
Implementation complexity	Synch interrupts	Timer interrupts clock synchronization	Synch & timer interrupts	Synch & timer interrupts
Run-time overhead				
Average EER				
Estimated worst case EER				
Inherently missed deadlines	Yes		No	

Reference

- Real-time Systems, Jane Liu
- Bettati,R.,``End-to-end scheduling to meet deadlines in distributed systems," Ph.D. thesis, University of Illinois at Urbana-Champaign
- Sun, J., `` Fixed-Priority Scheduling of Periodic Tasks With End-to-End Deadlines," Ph.D. thesis, University of Illinois at Urbana-Champaign