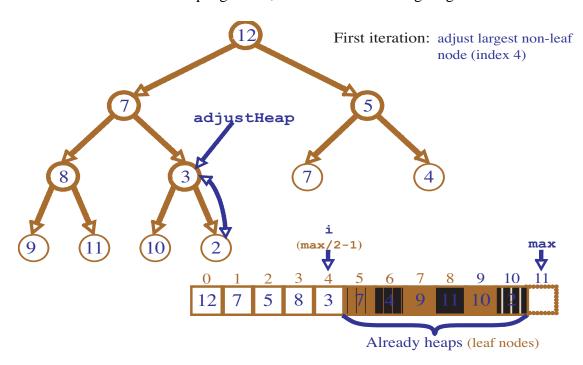
## Worksheet 34: BuildHeap and Heap Sort

**In preparation**: If you have not done so already, you should complete Worksheet 33 to learn more about the heap data structure.

In some applications it is useful to initialize a Heap with an existing vector of values. The values are not assumed to be organized into a heap, and so a routine named buildHeap is invoked for this purpose.

```
void buildHeap (struct dyArray *heap) {
  int max = dyArraySize(heap); int i;
  for ( i = max/2-1; i >= 0; i--)
    _adjustHeap(heap, max, i);
}
```

To understand the buildHeap algorithm, consider the following diagram:



All values indexed after max/2 are leaves, and are therefore already a heap. The first value that could potentially not be a heap is found at max/2. Walking backwards from this value until the root is reached eventually makes all nodes into a heap.

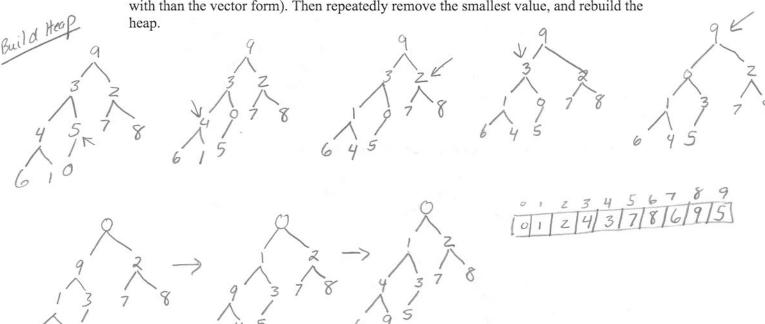
The heap data structure provides an elegant technique for sorting a vector. First form the vector into a heap. To sort the vector, the top of the heap (the smallest element) is swapped with the last element, and the size of the heap is reduced by 1 and readjusted. Repeat until all elements have been processed.

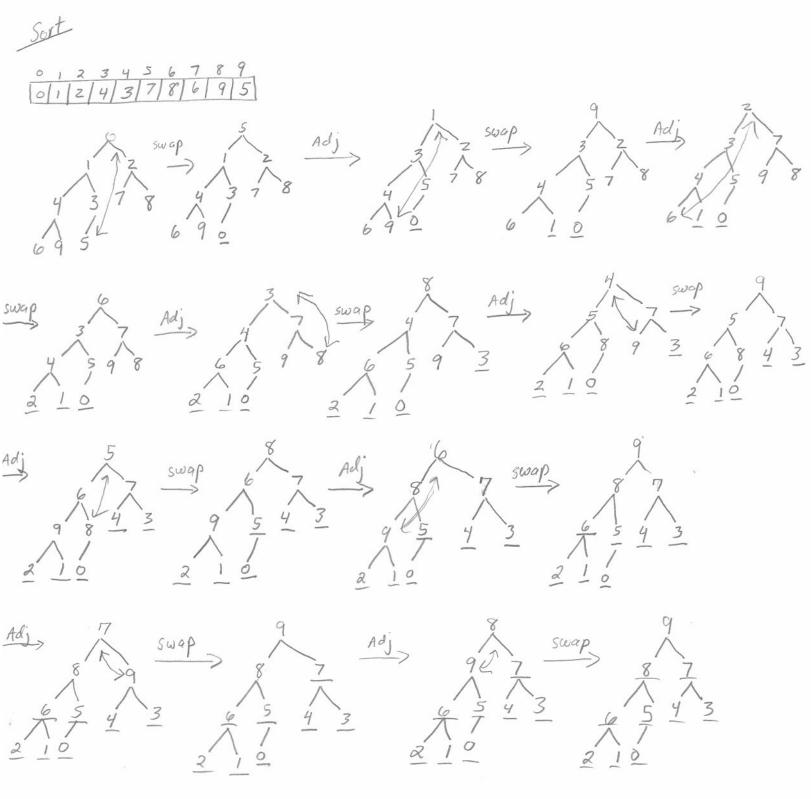
```
void heapsort (struct dyArray * v) { int i;
buildHeap(v);
for (i = dyArraySize(v) - 1; i > 0; i--) {
    dyArraySwap(v, 0, i);
    _adjustHeap (v, i, 0);
}
}
```

Simulate execution of the Heap sort algorithm on the following values:

## 9324578610

First make the values into a heap (the graphical representation is probably easier to work with than the vector form). Then repeatedly remove the smallest value, and rebuild the





0 1 2 3 4 5 6 7 8 9