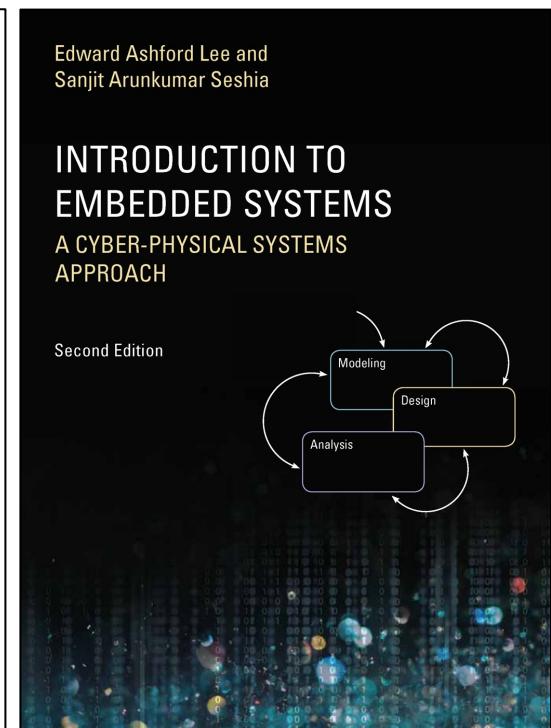
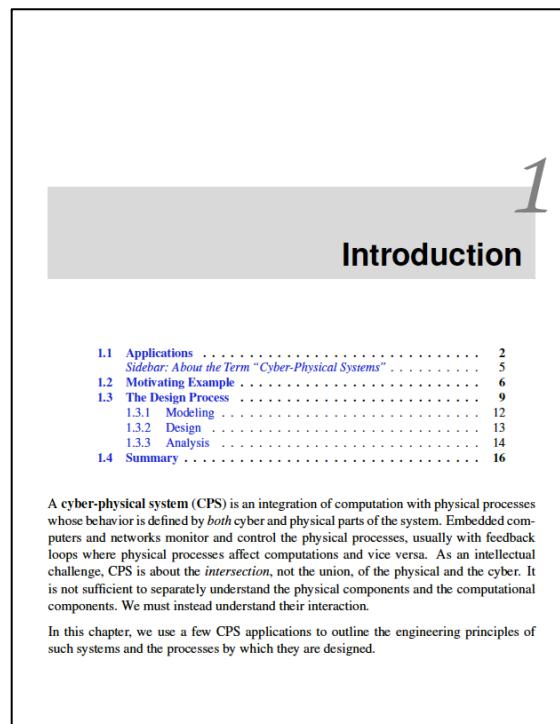


Lecture 2 : Cyber-Physical Systems (CPS)

Slides were originally developed by Profs. Edward Lee and Sanjit Seshia, and subsequently updated by Profs. Gavin Buskes and Iman Shames.

Outline

- Cyber-physical systems
- Motivating examples

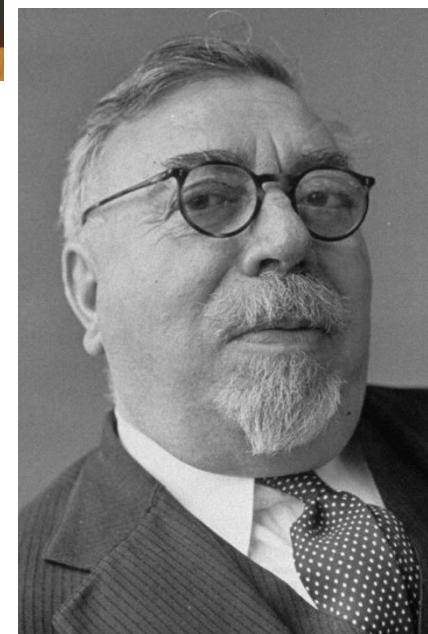


Origins of CPS

- Proposed by Helen Gill in 2006 at the National Science Foundation.
- It is rooted in “Cybernetics” proposed by Norbert Wiener from *kybernetes* in Greek meaning “governor”.
- The original work involved designing an automated Anti-air system in WWII using an analogue computer.



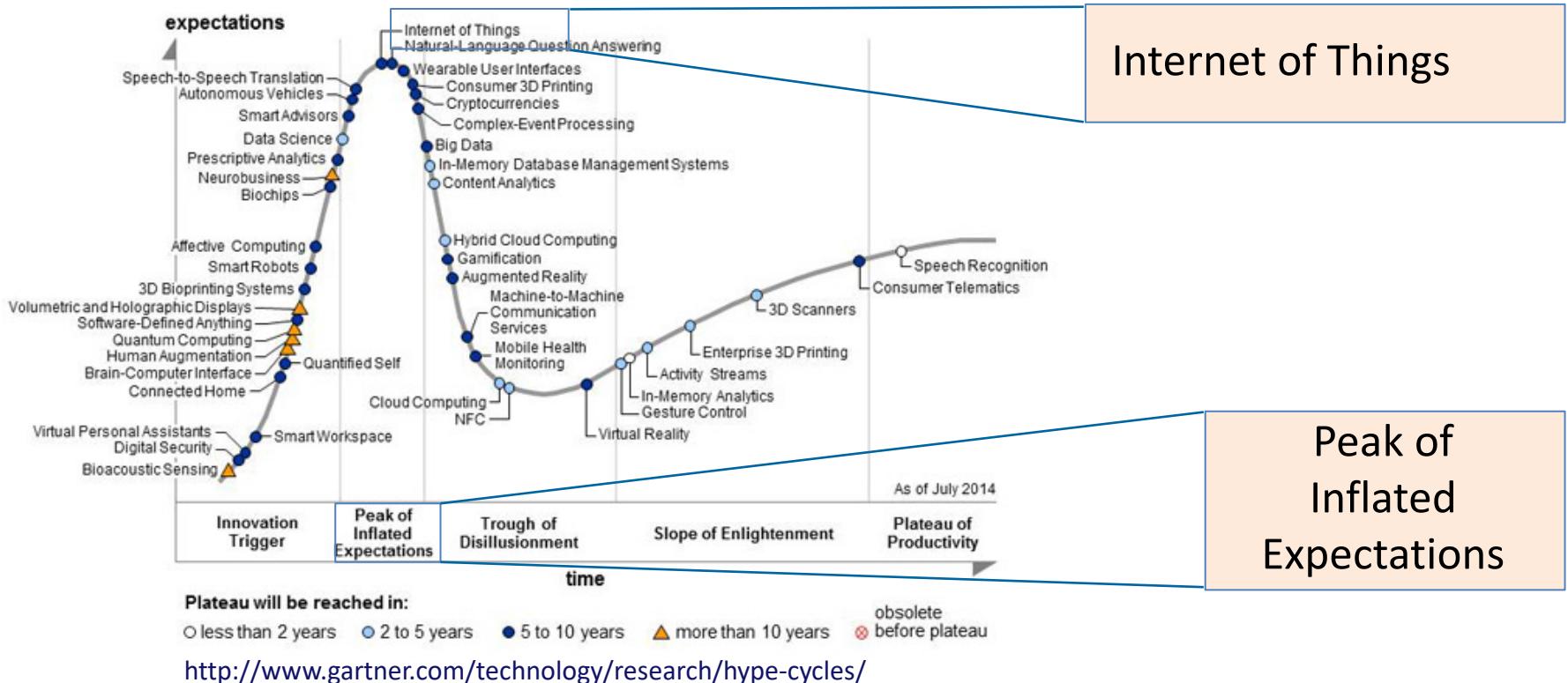
Helen Gill



Norbert Wiener

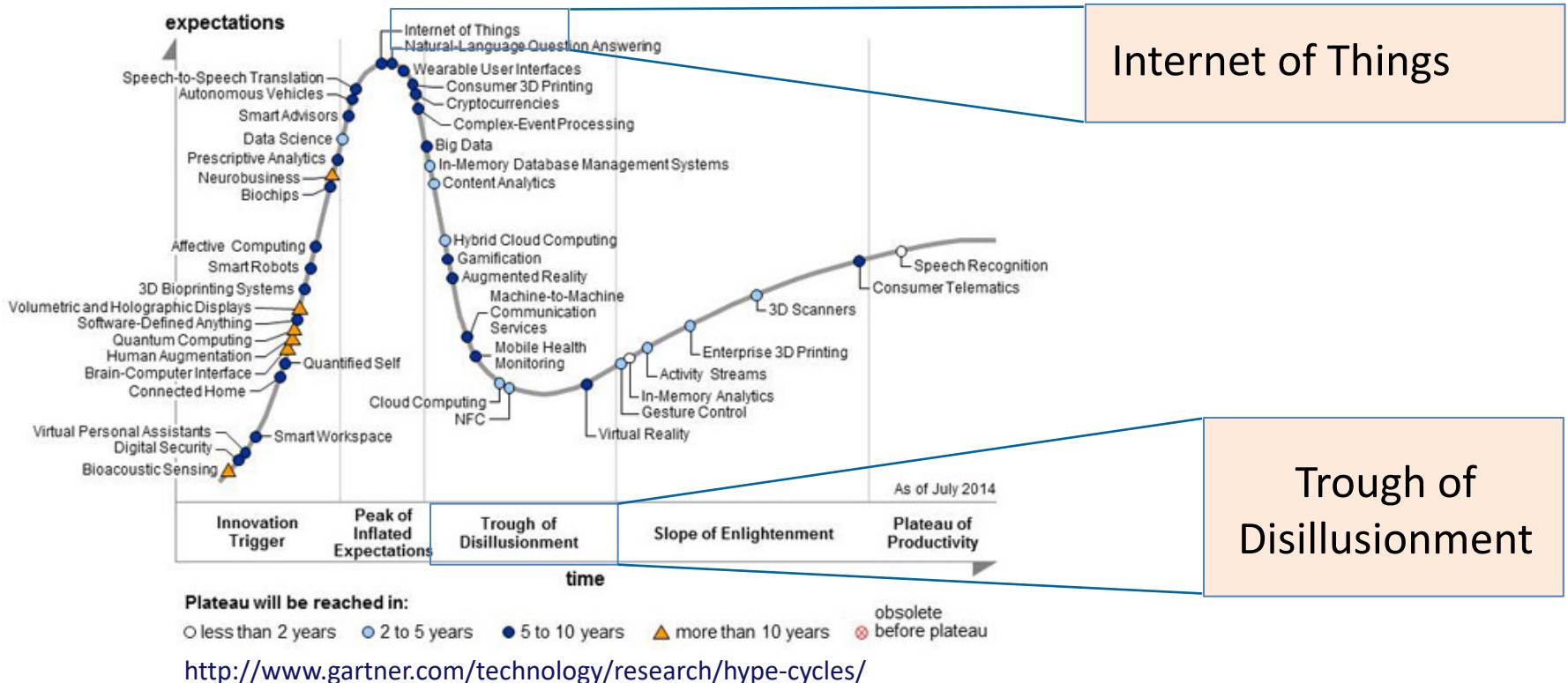
The Hype Around The Internet of Things

Using Internet technology to connect physical devices (“things”).



The Hype Around The Internet of Things

Using Internet technology to connect physical devices (“things”).



IoT is the use of Internet technology for Cyber-Physical Systems

Industrial automation from 2008: Bosch-Rexroth printing press.

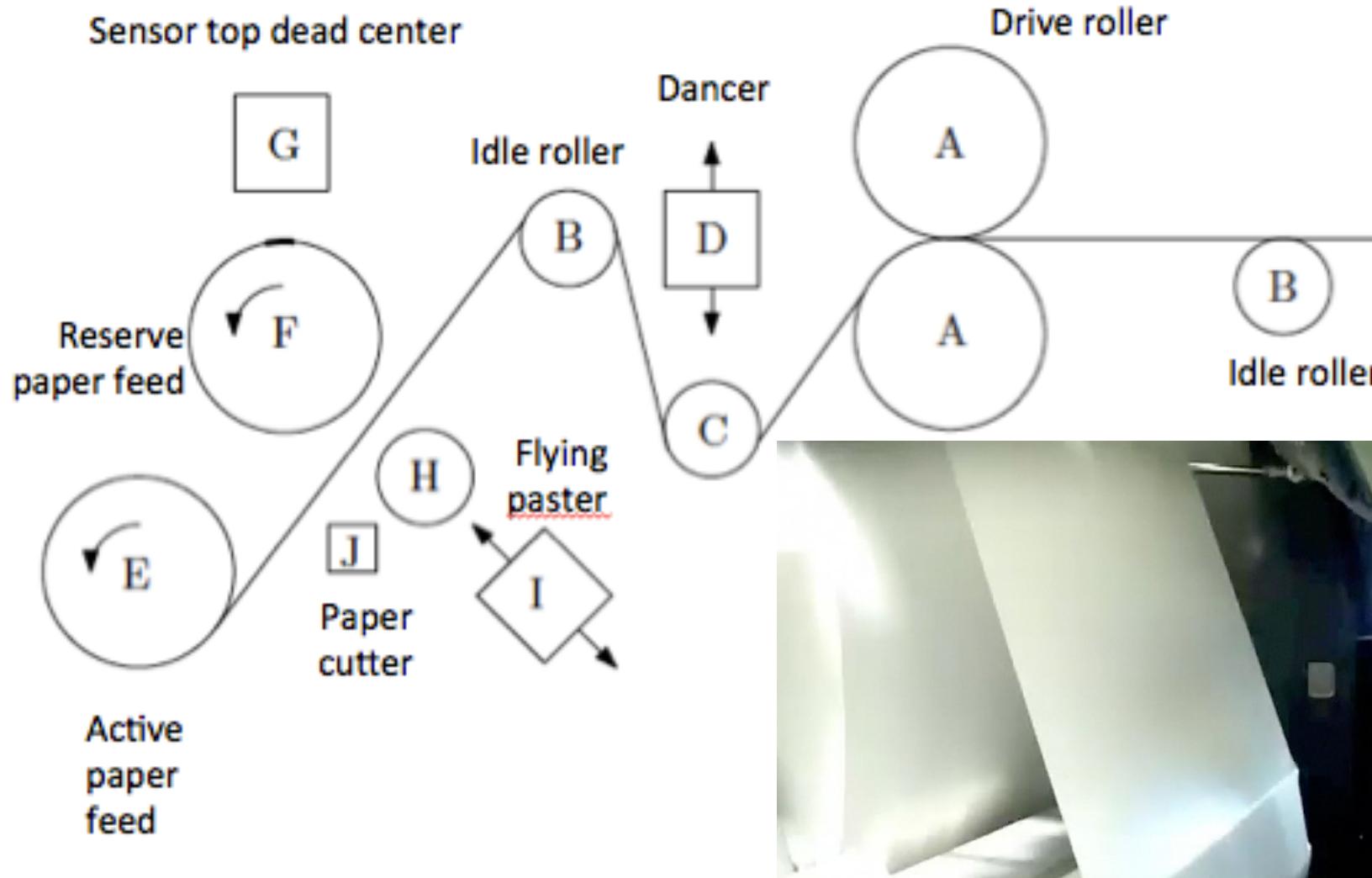
Bosch Rexroth printing press is a cyber-physical factory using Ethernet and TCP/IP with high-precision clock synchronization (IEEE 1588) on an isolated LAN.

The term “IoT” includes the technical solution “Internet technology” in the problem statement to “connect things”.



The term CPS does not.

Example – Flying Paster

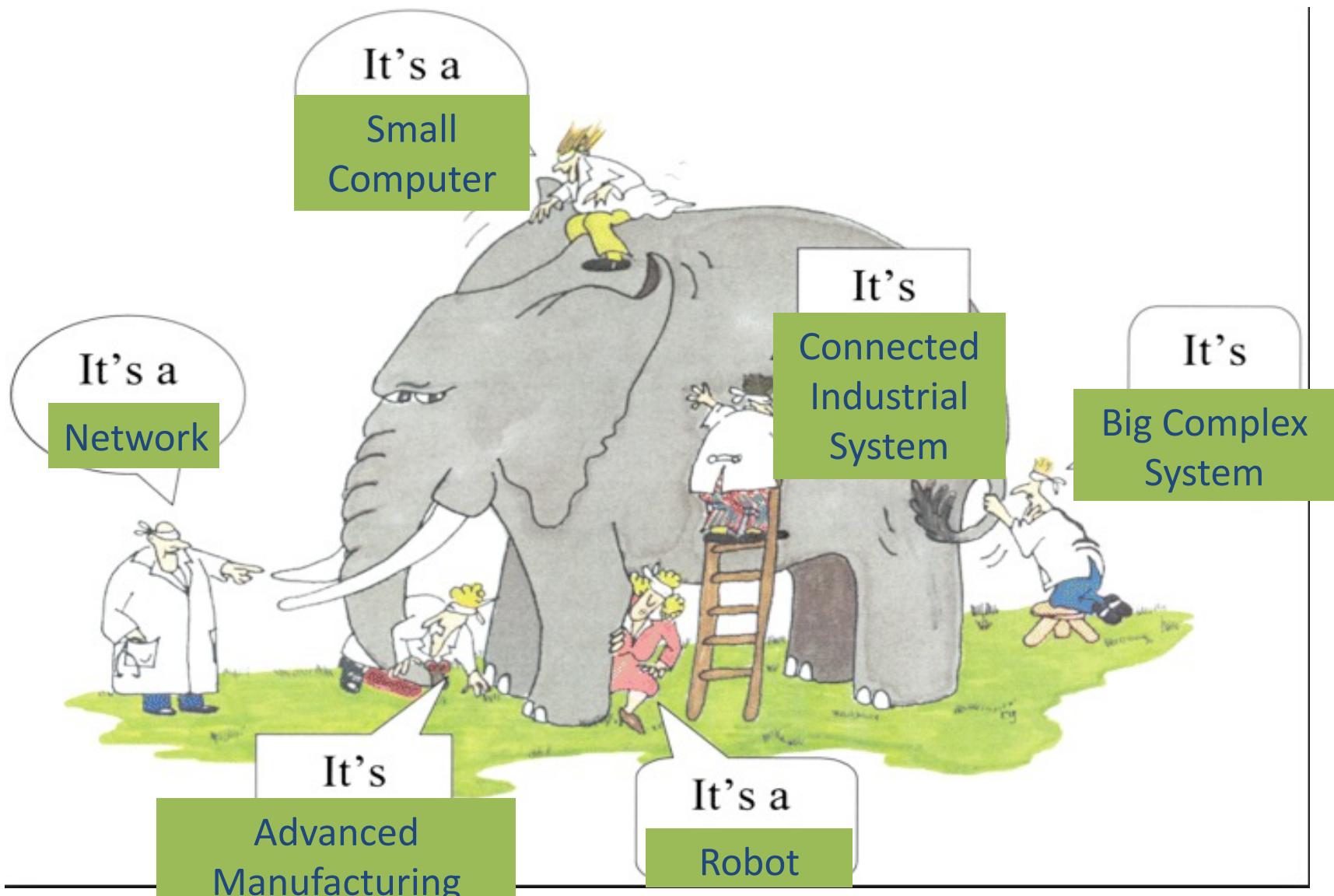


Source: <http://offsetpressman.blogspot.com/2011/03/how-flying-paster-works.html>

CPS Challenge Problem: Prevent This

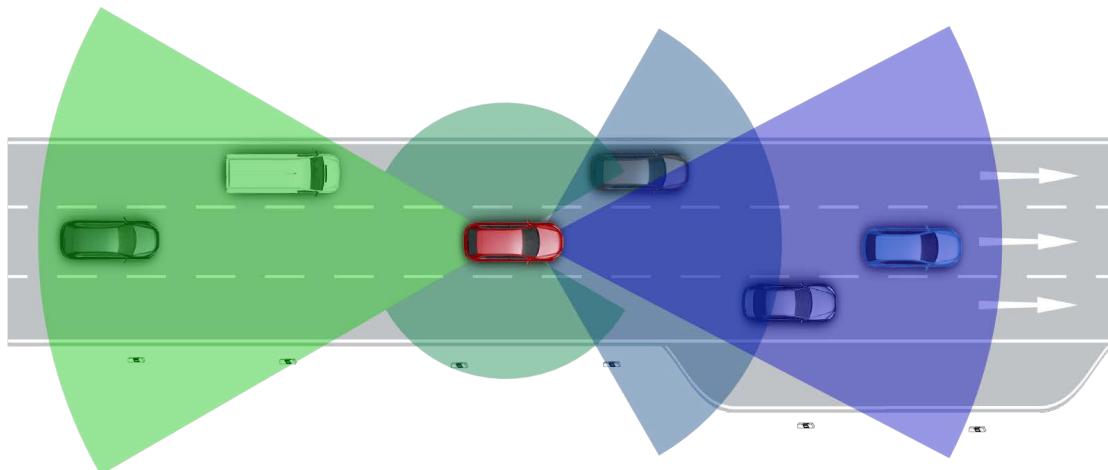
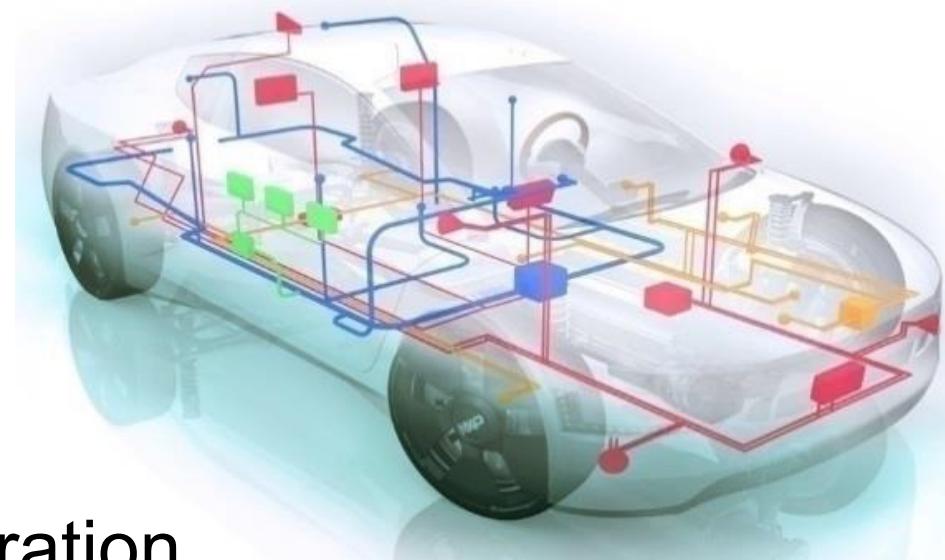


Challenges of Multidisciplinary Work



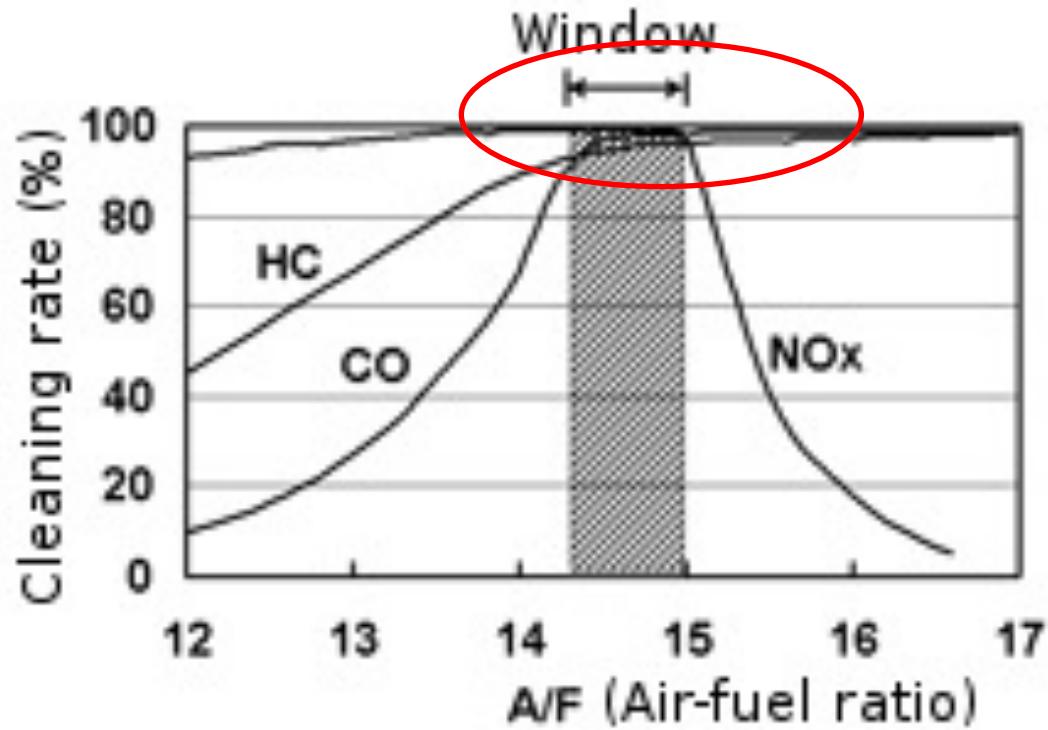
Automotive CPS and Societal Challenges

- Safer Transportation
- Reduced Emissions
- Smart Transportation
- Energy Efficiency
- Climate Change
- Human-Robot Collaboration



Example: Air-Fuel ratio control to reduce emissions

- Catalytic converters reduce CH_4 , CO_2 , and NO_x emissions
- Conversion efficiency optimal at stoichiometric value

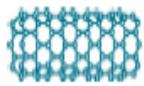


Disruptive Technologies of the Future

... with major CPS components

Twelve potentially economically disruptive technologies

	Mobile Internet	Increasingly inexpensive and capable mobile computing devices and Internet connectivity
	Automation of knowledge work	Intelligent software systems that can perform knowledge work tasks involving unstructured commands and subtle judgments
	The Internet of Things	Networks of low-cost sensors and actuators for data collection, monitoring, decision making, and process optimization
	Cloud technology	Use of computer hardware and software resources delivered over a network or the Internet, often as a service
	Advanced robotics	Increasingly capable robots with enhanced senses, dexterity, and intelligence used to automate tasks or augment humans
	Autonomous and near-autonomous vehicles	Vehicles that can navigate and operate with reduced or no human intervention

	Next-generation genomics	Fast, low-cost gene sequencing, advanced big data analytics, and synthetic biology ("writing" DNA)
	Energy storage	Devices or systems that store energy for later use, including batteries
	3D printing	Additive manufacturing techniques to create objects by printing layers of material based on digital models
	Advanced materials	Materials designed to have superior characteristics (e.g., strength, weight, conductivity) or functionality
	Advanced oil and gas exploration and recovery	Exploration and recovery techniques that make extraction of unconventional oil and gas economical
	Renewable energy	Generation of electricity from renewable sources with reduced harmful climate impact

Report: McKinsey Global Institute, *Disruptive technologies: Advances that will transform life, business, and the global economy*, May 2013

Economic Potential

	The Internet of Things	300% Increase in connected machine-to-machine devices over past 5 years 80–90% Price decline in MEMS (microelectromechanical systems) sensors in past 5 years	1 trillion Things that could be connected to the Internet across industries such as manufacturing, health care, and mining 100 million Global machine to machine (M2M) device connections across sectors like transportation, security, health care, and utilities	\$36 trillion Operating costs of key affected industries (manufacturing, health care, and mining)
	Cloud technology	18 months Time to double server performance per dollar 3x Monthly cost of owning a server vs. renting in the cloud	2 billion Global users of cloud-based email services like Gmail, Yahoo, and Hotmail 80% North American institutions hosting or planning to host critical applications on the cloud	\$1.7 trillion GDP related to the Internet \$3 trillion Enterprise IT spend
	Advanced robotics	75–85% Lower price for Baxter ³ than a typical industrial robot 170% Growth in sales of industrial robots, 2009–11	320 million Manufacturing workers, 12% of global workforce 250 million Annual major surgeries	\$6 trillion Manufacturing worker employment costs, 19% of global employment costs \$2–3 trillion Cost of major surgeries
	Autonomous and near-autonomous vehicles	7 Miles driven by top-performing driverless car in 2004 DARPA Grand Challenge along a 150-mile route 1,540 Miles cumulatively driven by cars competing in 2005 Grand Challenge 300,000+ Miles driven by Google's autonomous cars with only 1 accident (which was human-caused)	1 billion Cars and trucks globally 450,000 Civilian, military, and general aviation aircraft in the world	\$4 trillion Automobile industry revenue \$155 billion Revenue from sales of civilian, military, and general aviation aircraft

Google Strategy

CNET > Internet > Google closes \$3.2 billion purchase of Nest

Google closes \$3.2 billion purchase of Nest

The acquisition brings with it the Learning Thermostat and the Protect smoke and CO detector as Google looks to make its mark in the smart home.

by Lance Whitney @lancewhit / February 12, 2014 5:00 AM PST
/ Updated: February 12, 2014 5:19 AM PST



the guardian | The Observer

Search

Google's drive into robotics should concern us all

The company's expansion into robotics was developed in tandem with the US military. Where will its power play stop?



John Naughton
The Observer, Sunday 29 December 2013

Google's robotic cars have about \$150,000 in equipment including a \$70,000 LIDAR (laser radar) system. The range finder mounted on the top is a Velodyne 64-beam laser.

This laser allows the vehicle to generate a detailed 3D map of its environment. The car then takes these generated maps and combines them with high-resolution maps of the world, producing different types of data models that allow it to drive itself.

Google and Facebook

Wall Street Journal (Alistair Barr and Reed Albergotti , April 14, 2014)

Google acquired a maker of solar-powered drones—a startup that Facebook had also considered acquiring—as the technology giants battle to extend their influence and find new users in the far corners of the earth.



Artist's rendering of Titan's Solara 50, which in theory at least, can stay aloft for years.

What this subject is about

A principled, scientific approach to designing and implementing embedded systems

NOT HACKING!!

Hacking can be fun, but it can also be very painful when things go wrong...

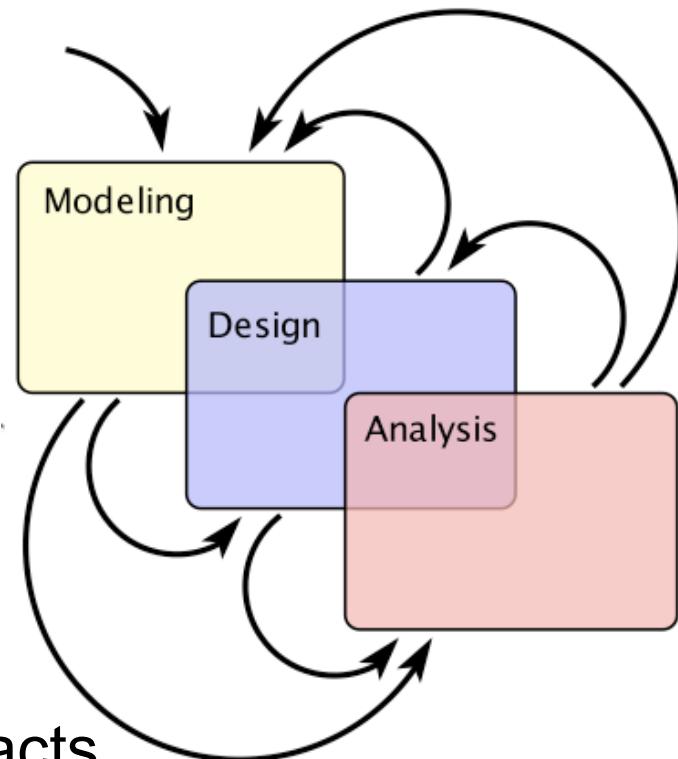
Focus on *model-based system design* and
on *embedded software*

Modeling, Design, Analysis

Modeling is the process of gaining a deeper understanding of a system through imitation. Models express **what** a system does or should do.

Design is the structured creation of artifacts. It specifies **how** a system does what it does.

Analysis is the process of gaining a deeper understanding of a system through dissection. It specifies **why** a system does what it does (or fails to do what a model says it should do).



Motivating Example of a Cyber-Physical System

(see Chapter 1 in book)



STARMAC quadrotor aircraft (Tomlin, et al.)

- Introductory Video:
<http://www.youtube.com/watch?v=rJ9r2orcaYo>
- Back-Flip Manouevre:
<http://www.youtube.com/watch?v=iD3QgGpzzIM>

Modeling:

- Flight dynamics (ch2)
- Modes of operation (ch3)
- Transitions between modes (ch4)
- Composition of behaviors (ch5)
- Multi-vehicle interaction (ch6)

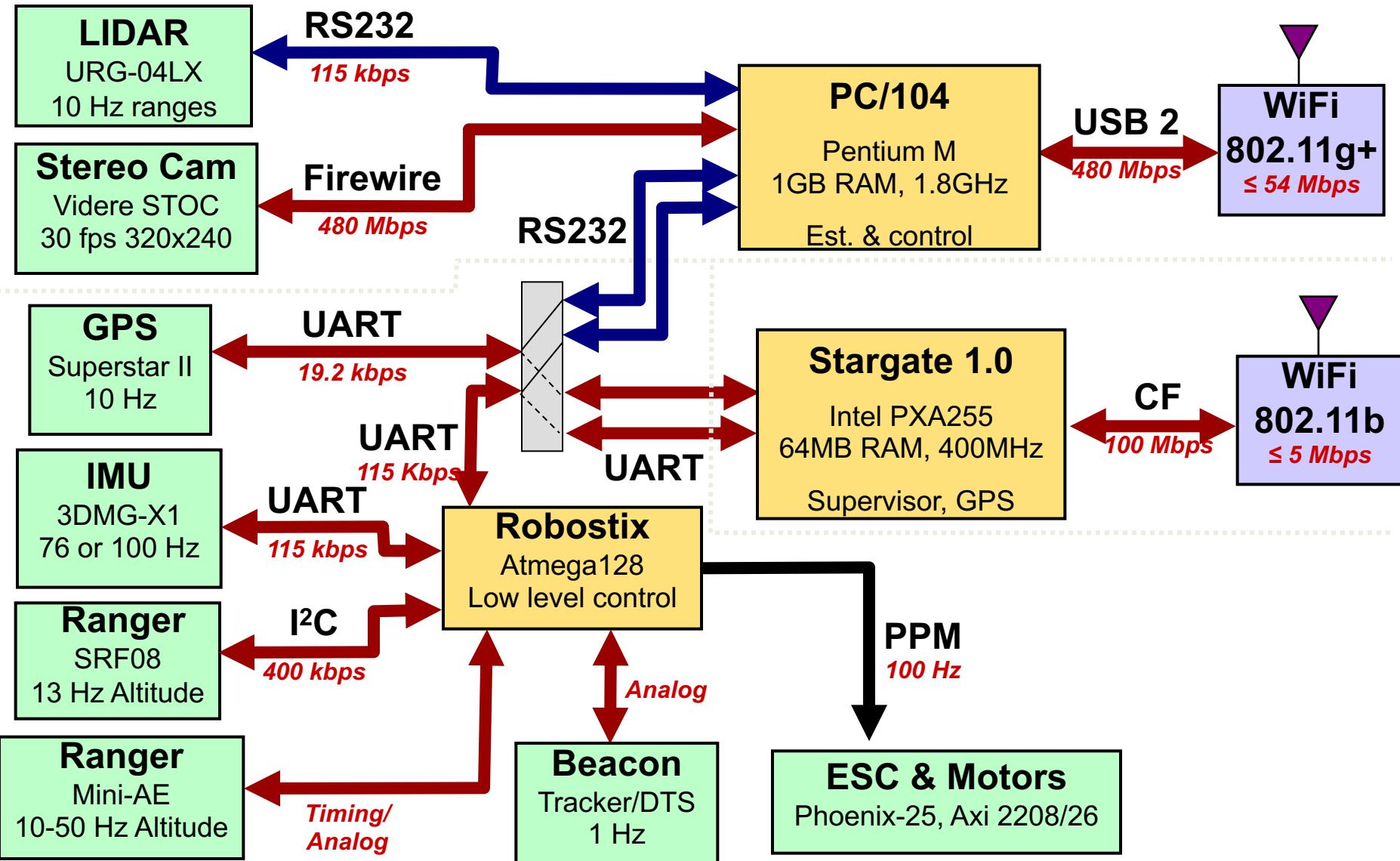
Design:

- Sensors and Actuators (ch7)
- Processors (ch8)
- Memory system (ch9)
- Sensor interfacing (ch10)
- Concurrent software (ch11)
- Real-time scheduling (ch12)

Analysis:

- Specifying safe behavior (ch13)
- Achieving safe behavior (ch14)
- Verifying safe behavior (ch15)
- Guaranteeing timeliness (ch16)
- Security and privacy (ch17)

STARMAC Design Block Diagram



A Theme in This Subject: Think Critically

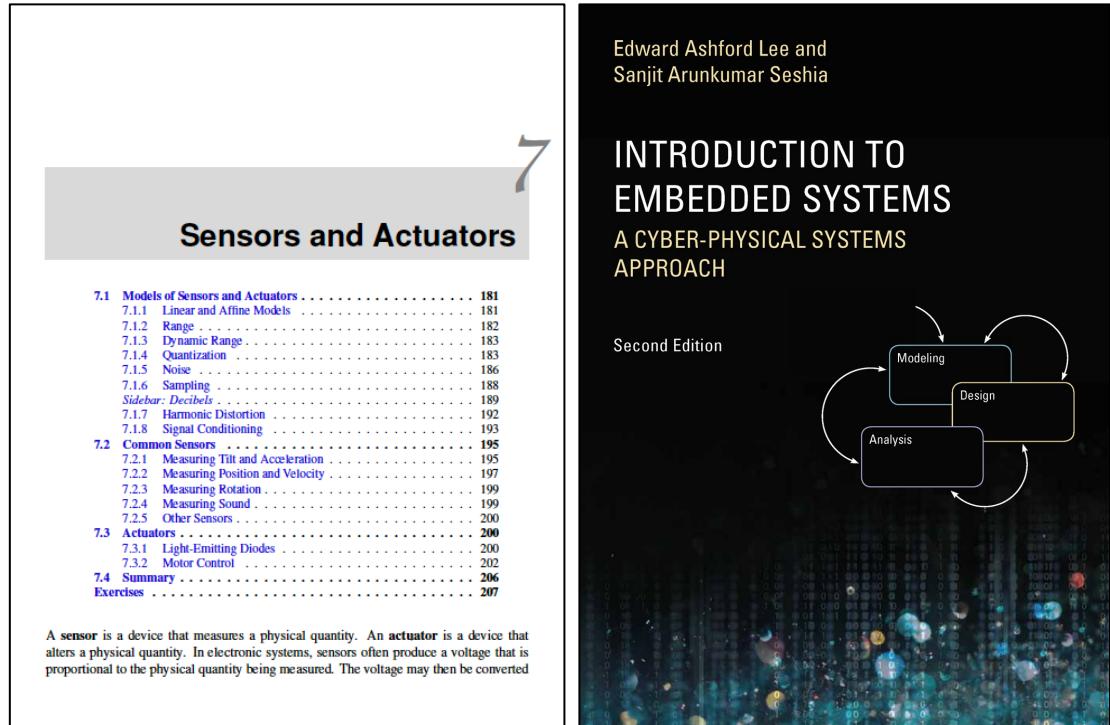
Any course that purports to teach you how to design embedded systems is misleading you.

The technology will change!

Our goal is to teach you how things are done today, and why that is not good enough. So, you will not be surprised by the changes that are coming. Also, we will introduce you to tools that enable critical thinking and are separated from specific technologies used today.

Things to do ...

- Download the textbook and [read Chapter 7](#)
- [Sign up to a group](#) in your workshop class



Next Lecture

- Sensors and actuators