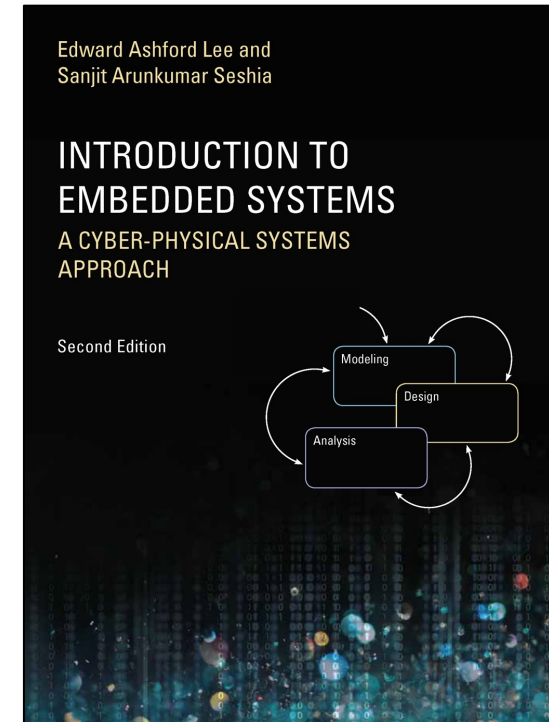
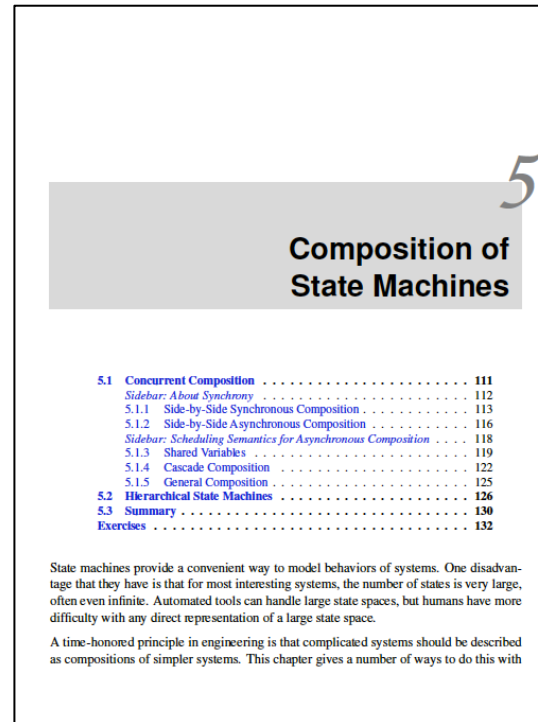


# Lecture 11: Concurrent Composition

Slides adapted from Edward A. Lee

# Outline

- Temporal composition
  - Sequential
  - Concurrent
- Spatial composition
  - Side-by-side composition
  - Cascade composition
  - Feedback composition



# Composition of State Machines

- How do we construct complex state machines out of simpler “building blocks”?
- Two kinds of composition:
  1. **Spatial**: how do the components communicate between each other?
  2. **Temporal**: when do the components execute, relative to each other?

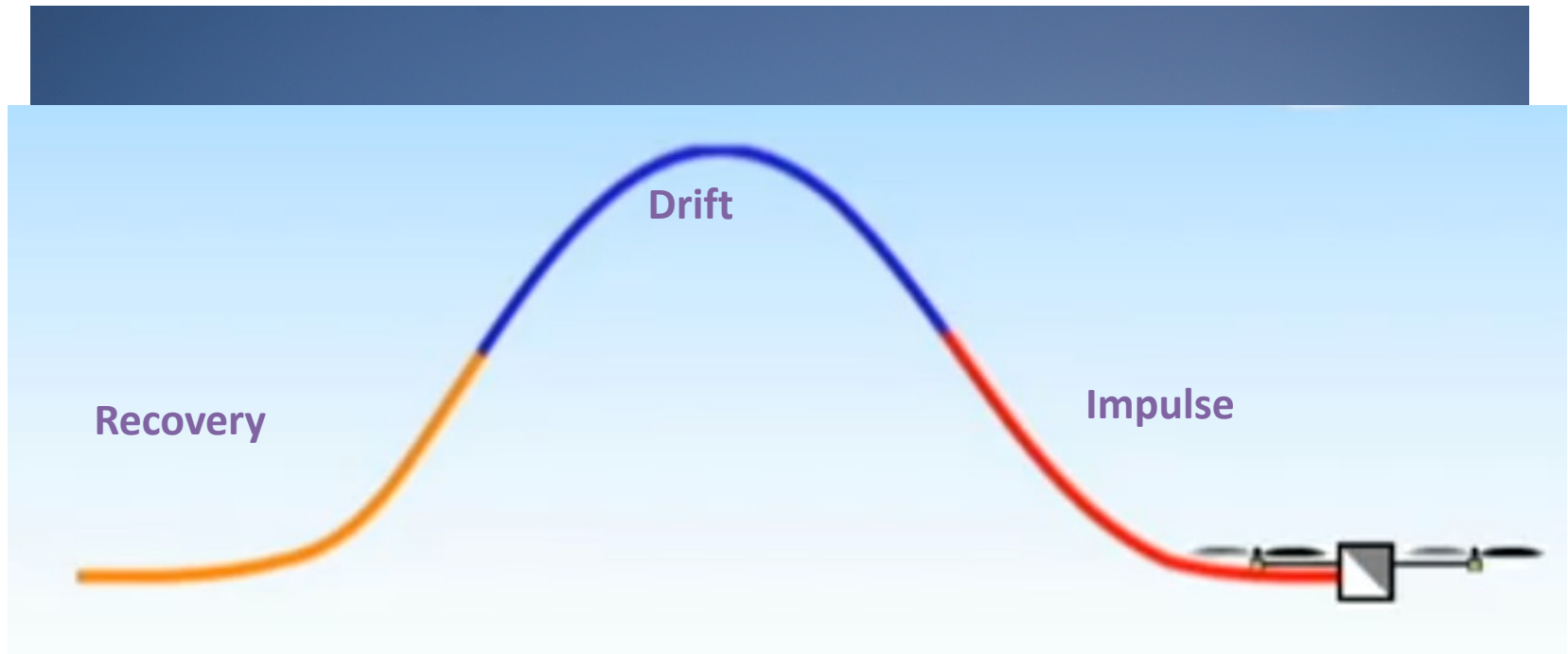
# Temporal Composition of State Machines

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- Sequential vs. Concurrent
- If Concurrent, Asynchronous vs. Synchronous

# Hybrid Systems Provide *Sequential* Composition

## Modal models: Sequencing between modes

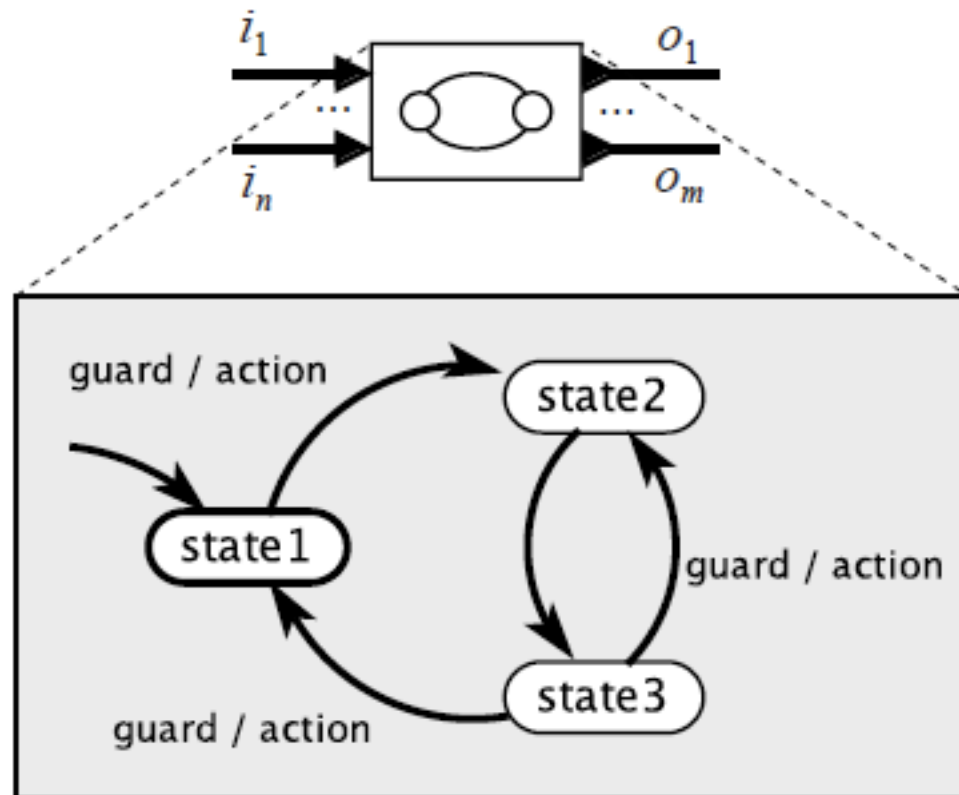


[Tomlin et al.]

# For concurrent composition, we need an interface.

## Actor Model for State Machines

- Expose inputs and outputs, enabling **concurrent composition**:



# Set-theoretic definition

- State machine is a 5-tuple:

$$(S, I, O, u, i), \quad i \in S$$

$$u : S \times I \rightarrow S \times O$$

Where

- $S$  is a set of states
  - $I$  is a set of input symbols
  - $O$  is a set of output symbols
  - $u$  is an update function
  - $i$  is an initial state
- To apply the update function, if  $s \in S$  and  $c \in I$   
$$(s', o) = u(s, c)$$

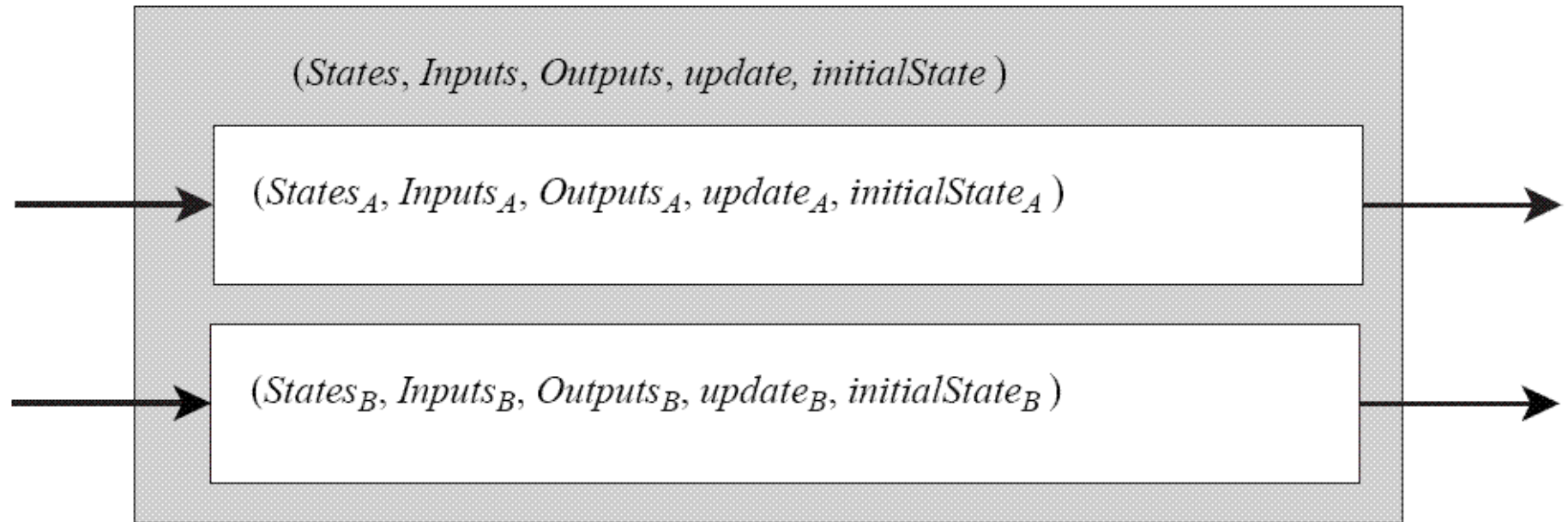
# Spatial Composition of State Machines

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- Side-by-side composition
- Cascade composition
- Feedback composition



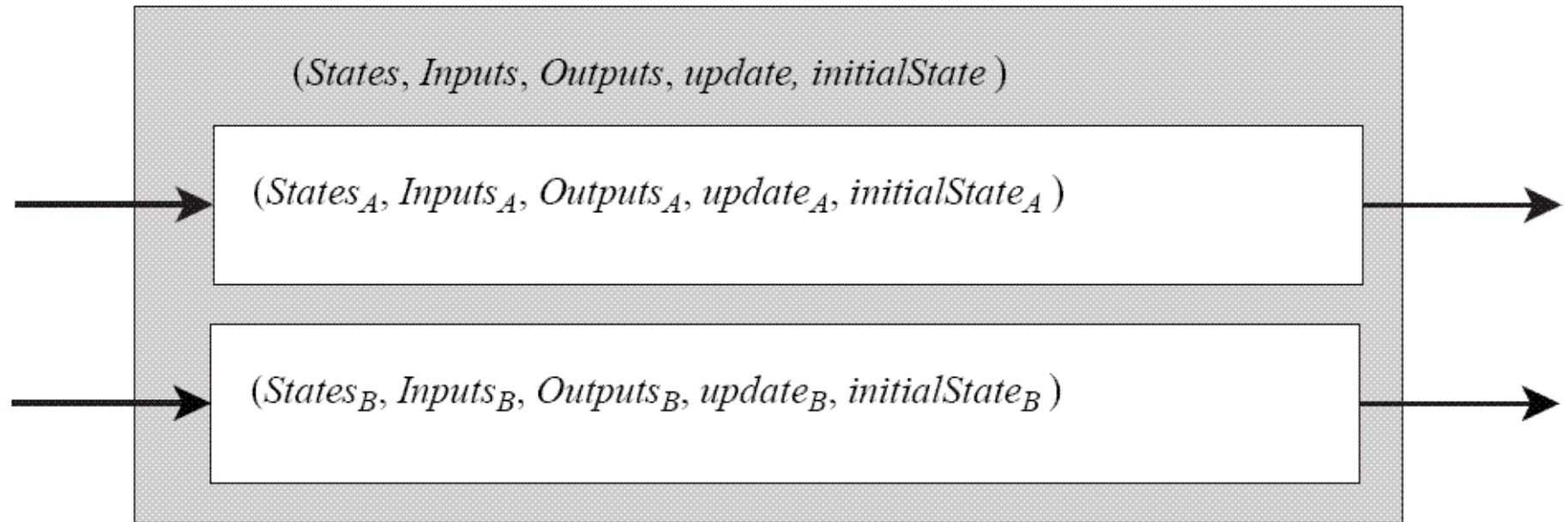
# Side-by-Side Composition



A key question: When do these machines react?

How the reactions of composed machines is coordinated is called a “**Model of Computation**” (MoC).

# Side-by-Side, Parallel Composition

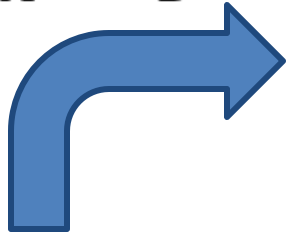


When do these machines react? Two of many possibilities:

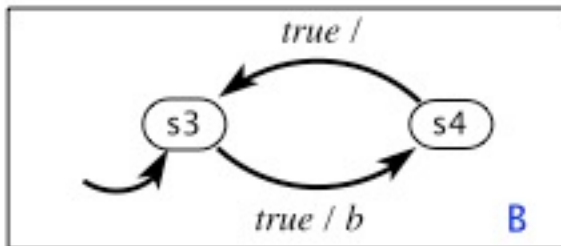
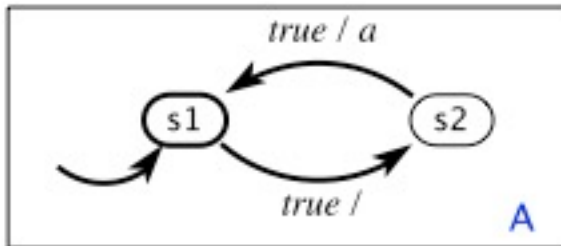
- **Together**, in lock step (synchronous, concurrent composition)
- **Independently** (asynchronous, concurrent composition)

# Synchronous Composition

$$S_C \subseteq S_A \times S_B$$

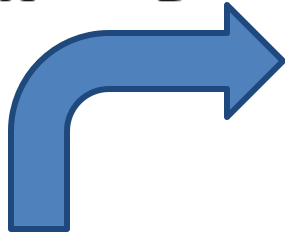


outputs:  $a, b$  (pure)

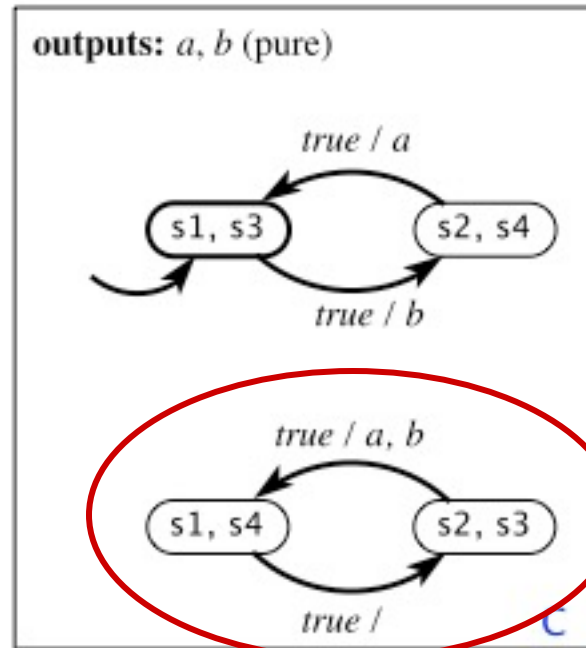
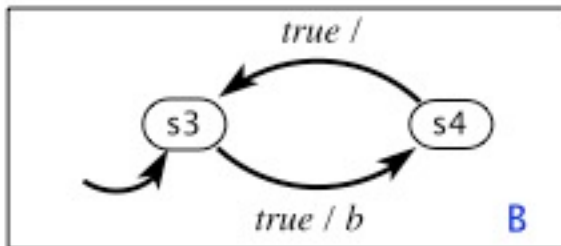
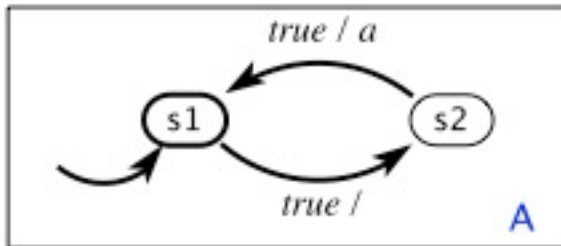


# Synchronous Composition

$$S_C \subseteq S_A \times S_B$$



outputs:  $a, b$  (pure)



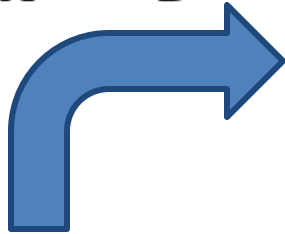
Synchronous composition

Note that these two states are not reachable.

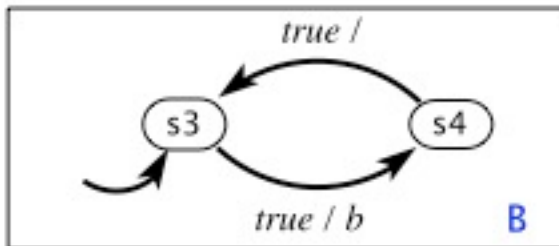
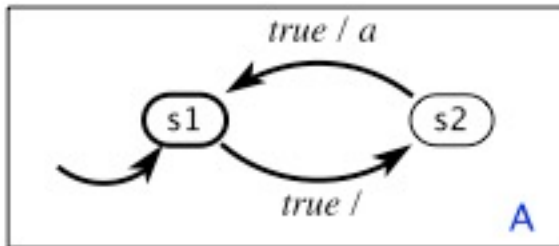
Composition multiplies the state space

# Asynchronous Composition

$$S_C \subseteq S_A \times S_B$$



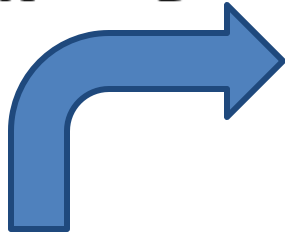
outputs:  $a, b$  (pure)



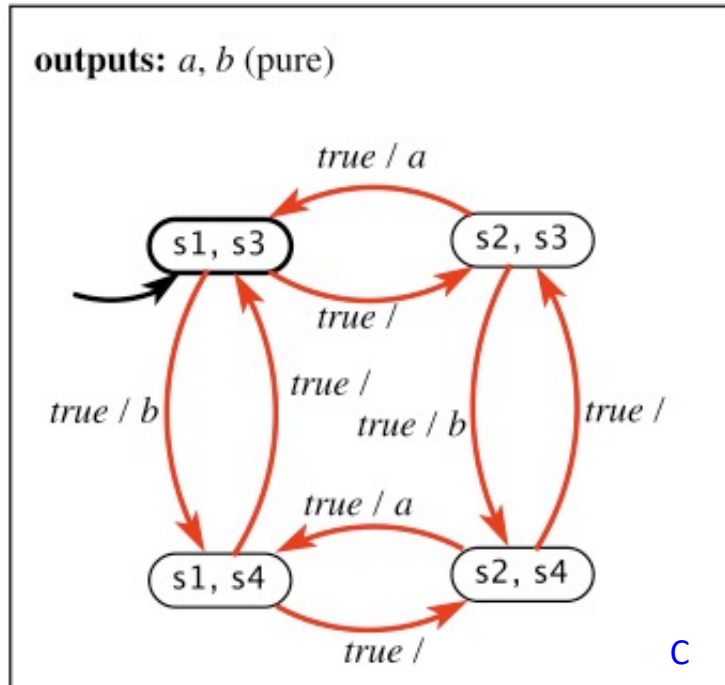
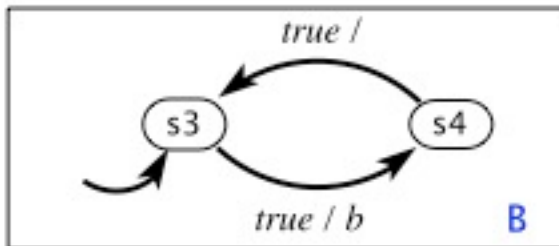
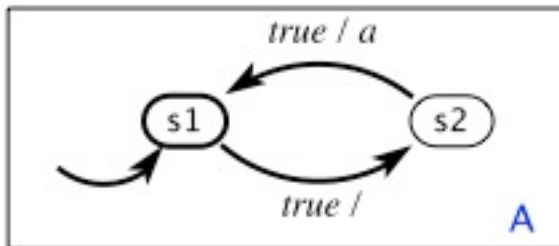
Asynchronous composition  
using interleaving semantics

# Asynchronous Composition

$$S_C \subseteq S_A \times S_B$$



outputs:  $a, b$  (pure)

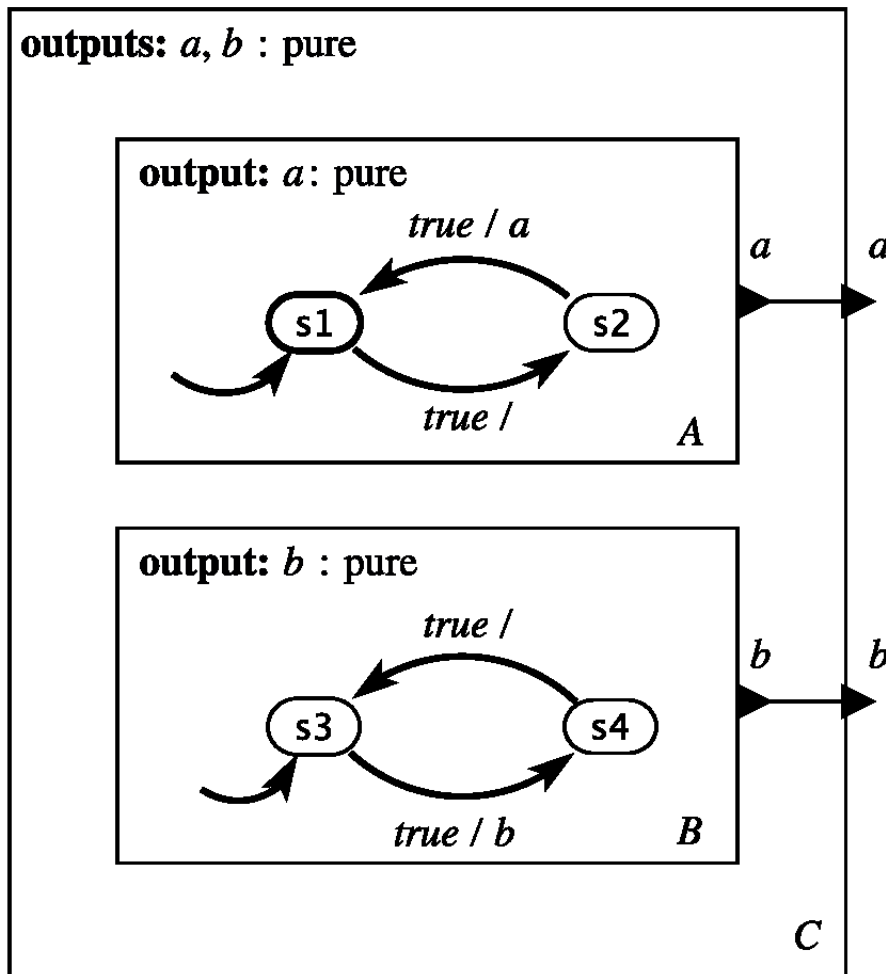


Note that now all states are reachable.

Asynchronous composition using interleaving semantics

# Syntax vs. Semantics

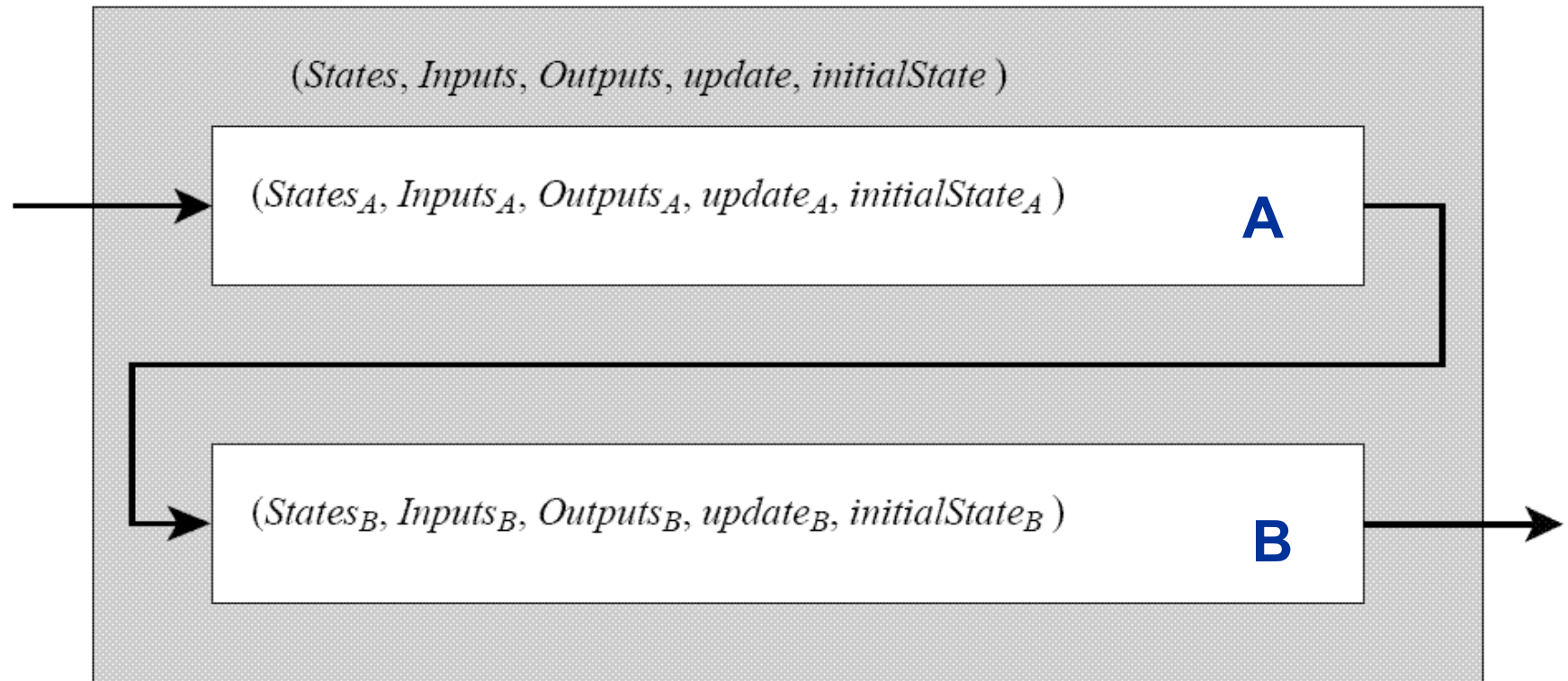
The answers to these questions defines the MoC being used.



Synchronous or Asynchronous composition?

If asynchronous, does it allow simultaneous transitions in A & B? How to choose whether A or B reacts when C reacts?

# Cascade Composition



Output port(s) of A connected to input port(s) of B

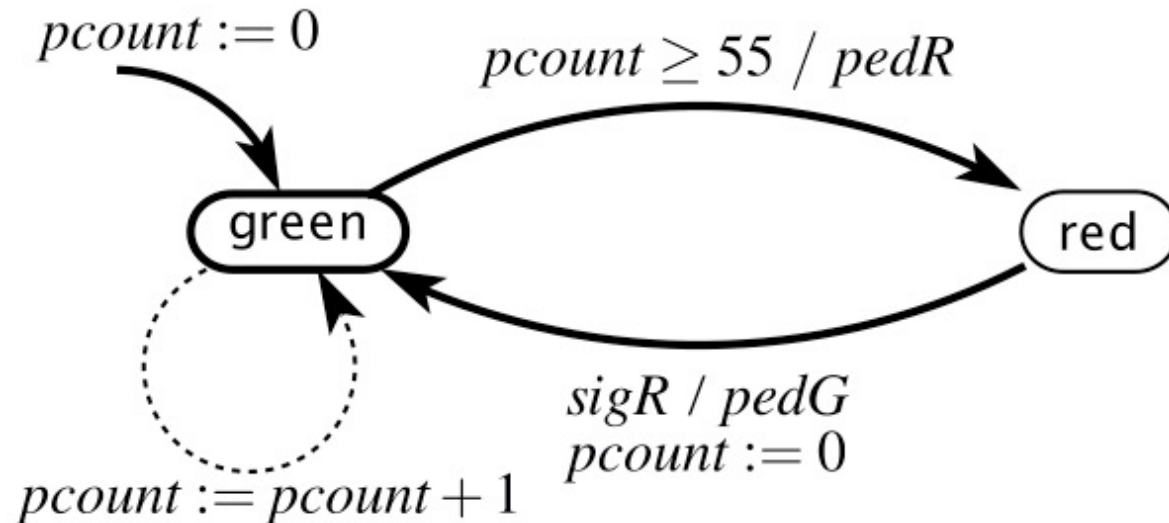


# Example: Time-Triggered Pedestrian Light

**variable:**  $pcount: \{0, \dots, 55\}$

**input:**  $sigR$ : pure

**outputs:**  $pedG, pedR$ : pure



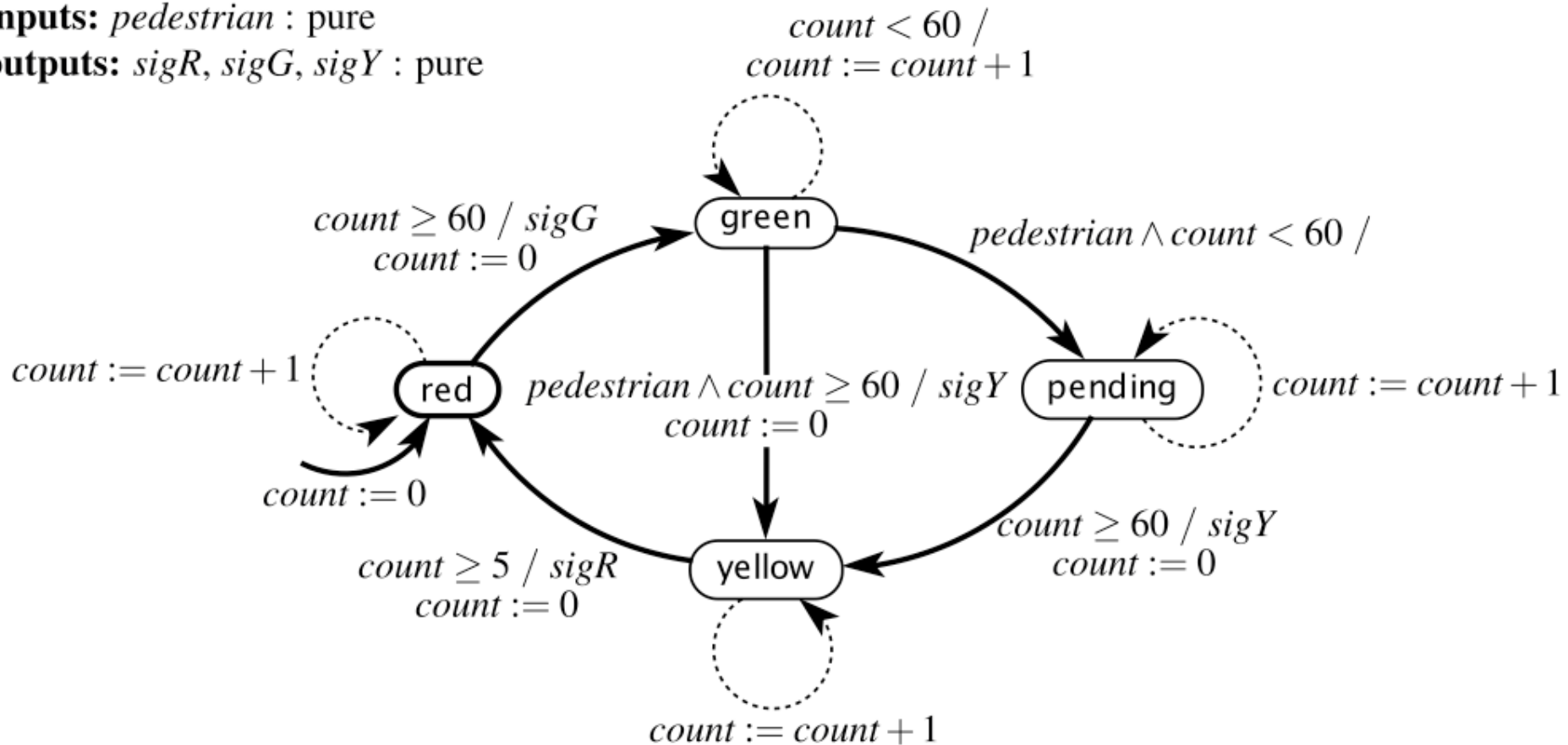
This light stays green for 55 seconds, then goes red. Upon receiving a  $sigR$  input, it repeats the cycle.

# Example: Time-Triggered Car Light

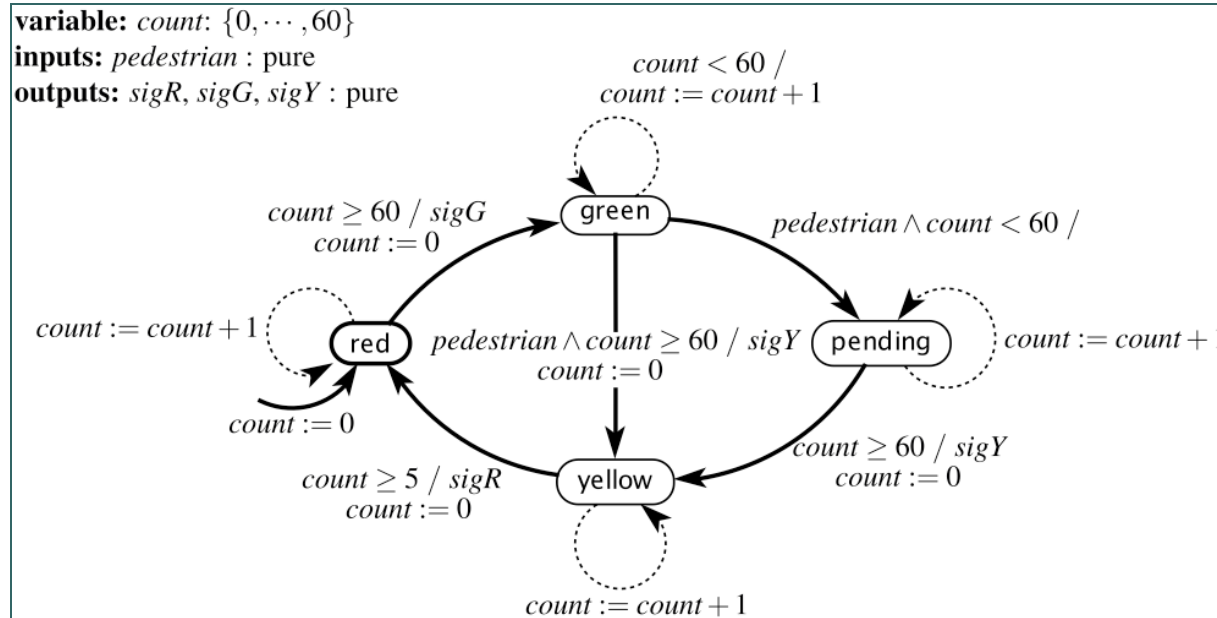
**variable:**  $count: \{0, \dots, 60\}$

**inputs:**  $pedestrian : \text{pure}$

**outputs:**  $sigR, sigG, sigY : \text{pure}$



# Pedestrian Light with Car Light



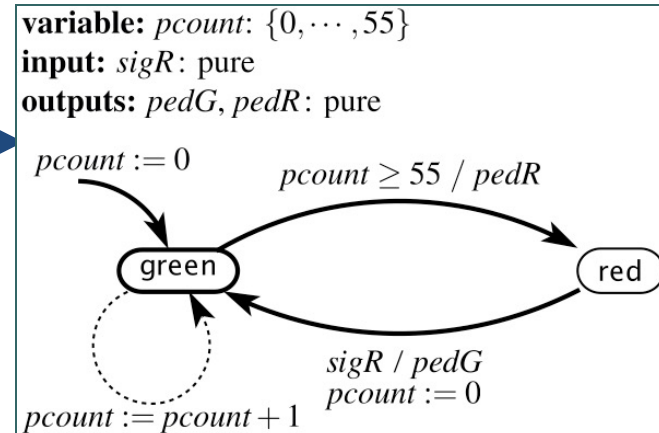
sigY

sigG

sigR

What is the size of the state space of the composite machine?

sigR

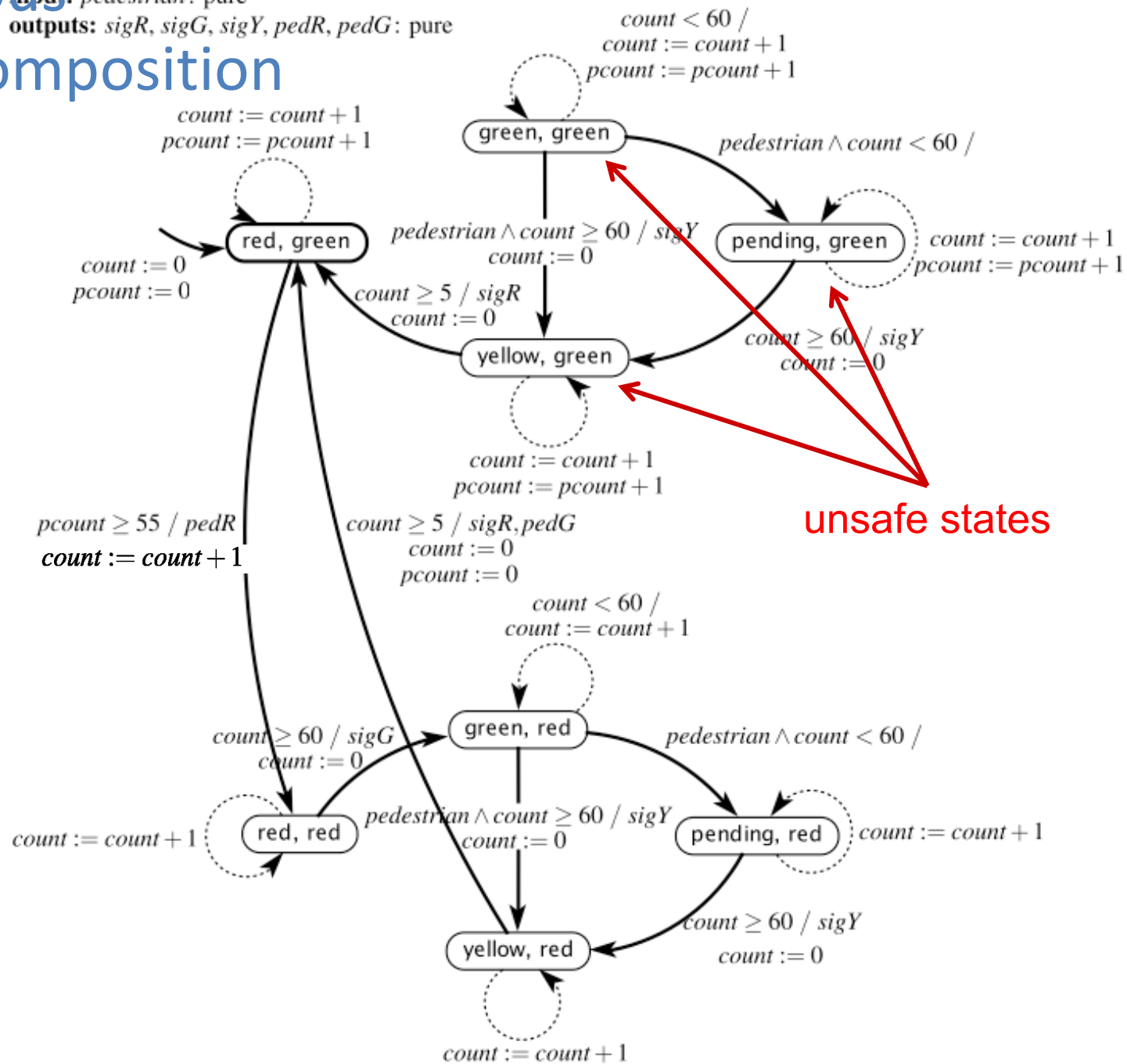


pedG

pedR

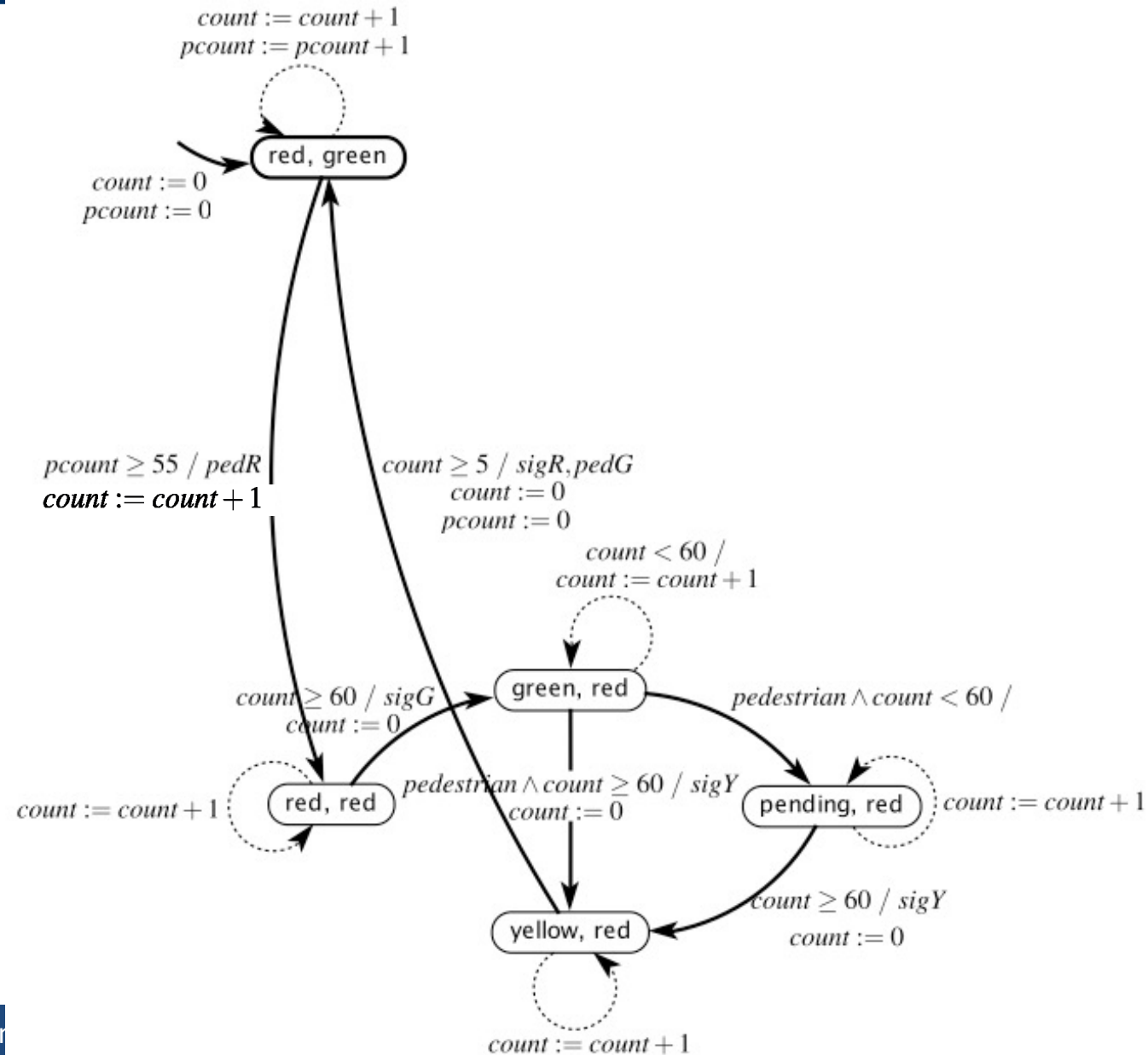
# Synchronous cascade composition

variables:  $count: \{0, \dots, 60\}, pcount: \{0, \dots, 55\}$   
 input:  $pedestrian: pure$   
 outputs:  $sigR, sigG, sigY, pedR, pedG: pure$

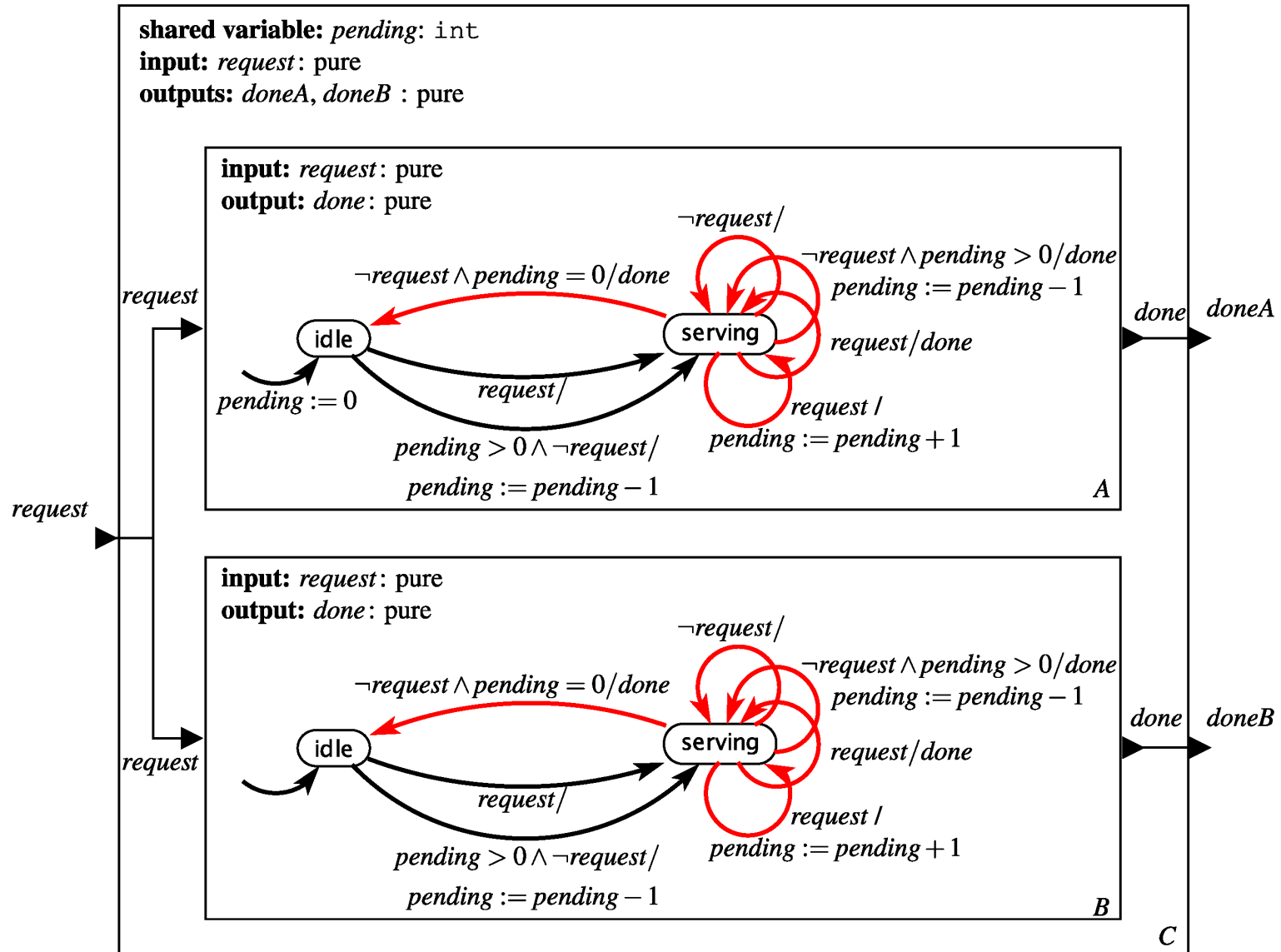


# Unreachable states removed

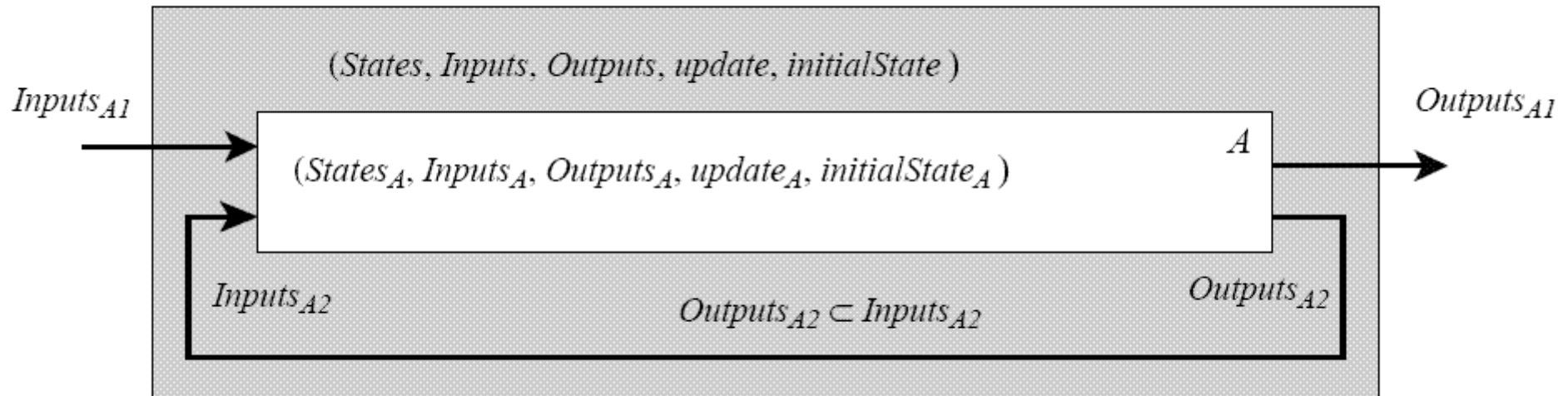
**variables:**  $count: \{0, \dots, 60\}, pcount: \{0, \dots, 55\}$   
**input:**  $pedestrian: \text{pure}$   
**outputs:**  $sigR, sigG, sigY, pedR, pedG: \text{pure}$



# Shared Variables: Two Servers



# Feedback Composition



Reasoning about feedback composition can be very subtle.  
(more about this later)

# Things to do ...

- If you haven't already done, [read Chapter 5](#)

