

1.

VWBP = unpause wait button press

PWBR = pause wait button release

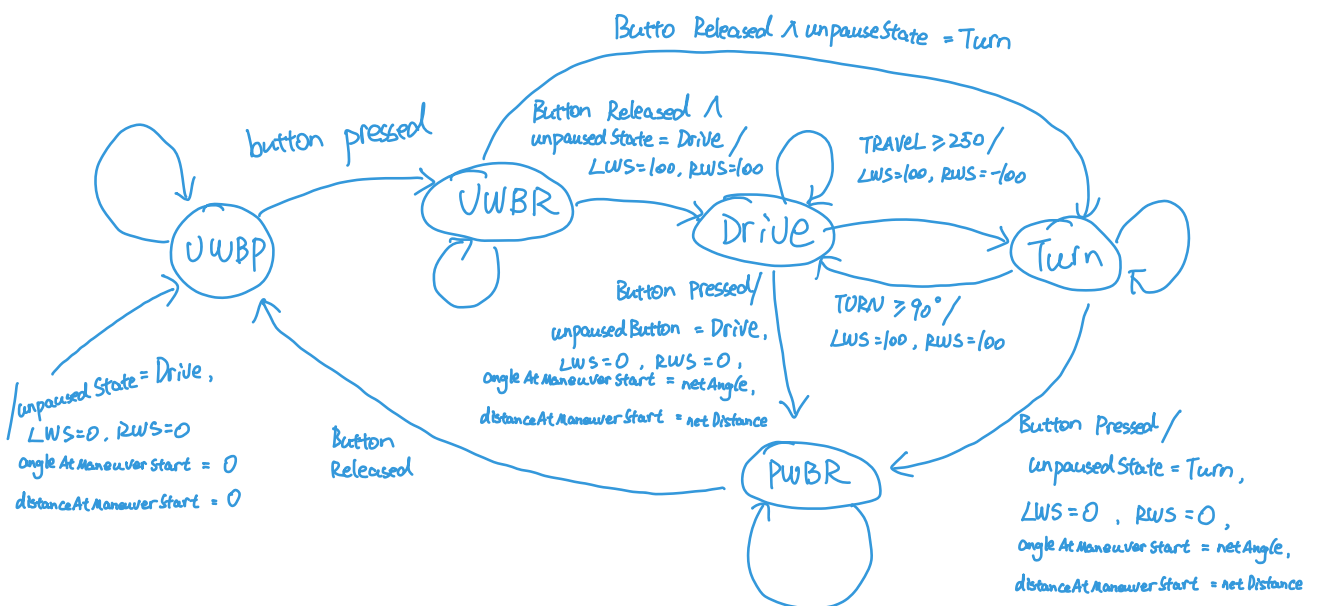
VWBR = unpause wait button release

LWS = Left wheel speed

RWS = Right wheel speed

TRAVEL = netDistance - distanceAtManeuverStart

TURN = netAngle - angleAtManeuverStart



2.

The template code uses polling,

but the protocol uses interrupts.

3.

Set a time triggered interrupts for
5 seconds as a timer to run
that commands.