

(Ex) PLM flux

$$f(u) = au$$

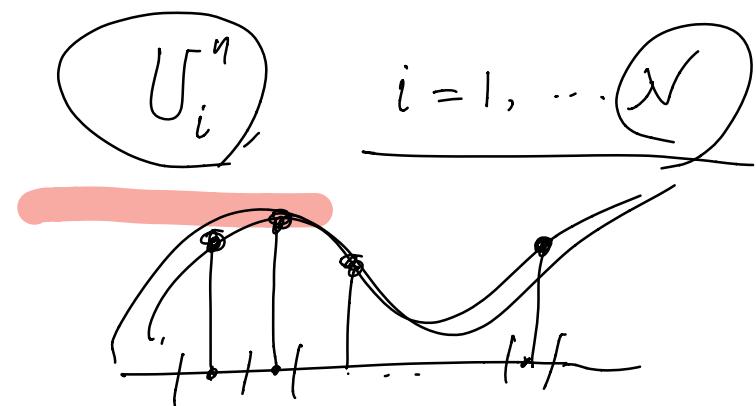
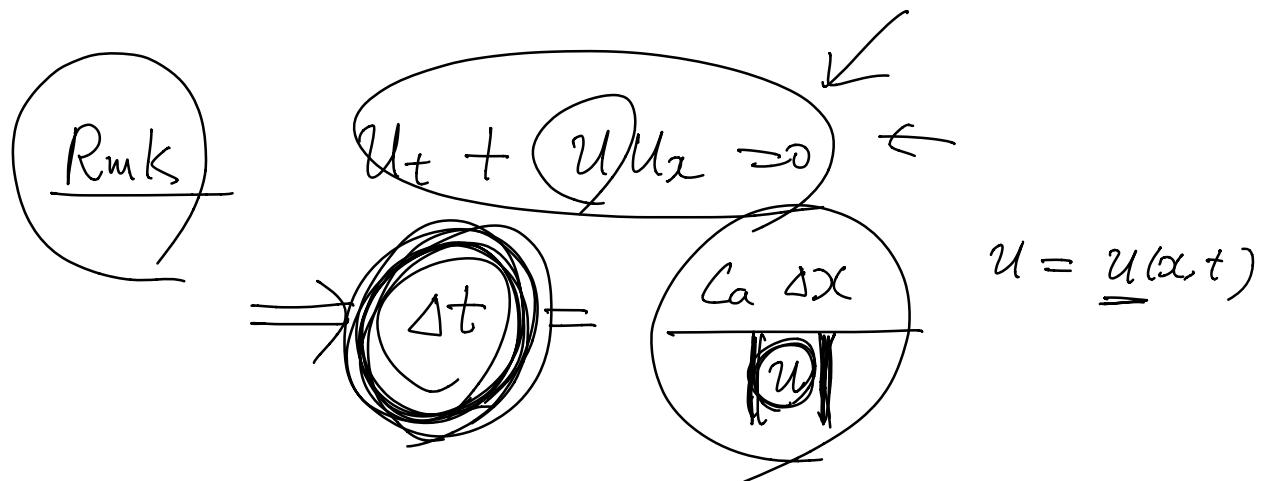
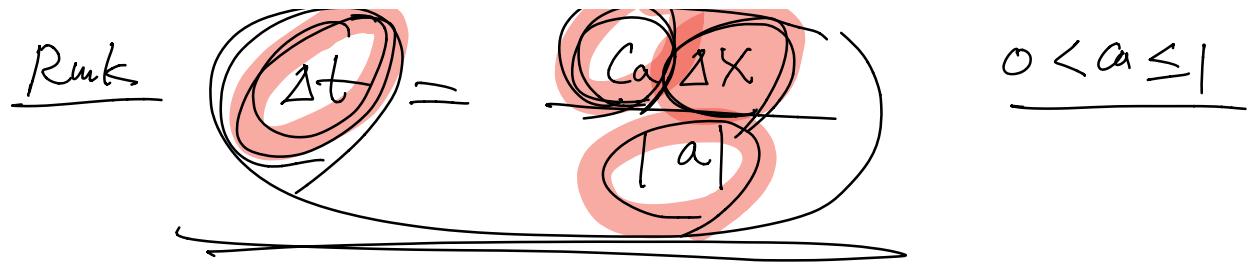
$$u_t + (a)u_x = 0$$

$$\rightarrow F_{i+\frac{1}{2}}^{\text{PLM}, n+\frac{1}{2}} = \begin{cases} f(\tilde{v}^L), & a > 0 \\ f(\tilde{v}^R), & a < 0 \end{cases}$$

$$= \begin{cases} a \tilde{v}_{i+\frac{1}{2}}^L, & a > 0 \\ a \tilde{v}_{i+\frac{1}{2}}^R, & a < 0 \end{cases}$$

$$(a) = \frac{a \Delta t}{\Delta x}$$

$$= \begin{cases} a \left(U_i^n + \frac{\Delta x}{2} \Delta_i^n (1 - (a)) \right), & a > 0 \\ a \left(U_{i+1}^n - \frac{\Delta x}{2} \Delta_{i+1}^n (1 + (a)) \right), & a < 0 \end{cases}$$



$$\Rightarrow \Delta t = \frac{Ca \Delta x}{\max_{1 \leq i \leq N} |U^n_i|}$$

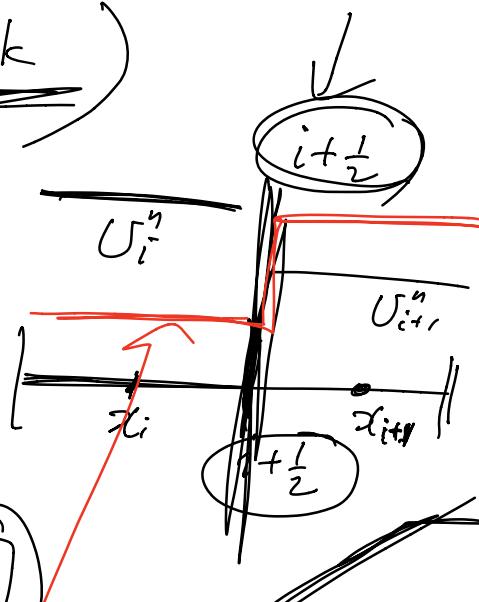
(PLM) for Burgers' Eq.



$$(i) \quad U_i^n \geq U_{i+1}^n \quad (\text{shock})$$

$$F_{i+\frac{1}{2}}^{\text{PLM}}$$

2nd order in time



$$f(u) = \frac{u^2}{2}$$

$$f(\tilde{U}_{i+\frac{1}{2}}^L) = \frac{1}{2} \left(U_i^n + \frac{\Delta x}{2} \Delta_i^n (1 - c_a) \right)^2, \quad S_{i+\frac{1}{2}} > 0$$

$$f(\tilde{U}_{i+\frac{1}{2}}^R) = \frac{1}{2} \left(U_{i+1}^n - \frac{\Delta x}{2} \Delta_{i+1}^n (1 + c_a) \right)^2, \quad S_{i+\frac{1}{2}} \leq 0$$

$$S_{i+\frac{1}{2}} = \frac{[f]}{[u]} = \frac{1}{2} (U_i^n + U_{i+1}^n)$$

$$(ii) \quad U_i^n < U_{i+1}^n \quad (\text{rarefaction})$$

$$f(\tilde{U}_{i+1}^L)$$

$$F_{i+\frac{1}{2}}^{\text{PLM}, n+\frac{1}{2}} = \frac{1}{2} \left[U_i^n + \frac{\Delta x}{2} \Delta_i^n (1 - \alpha) \right]^2, \quad 0 \leq U_i^n$$

$U_i^n < 0 \leq U_{i+1}^n$

$$f(U_{i+\frac{1}{2}}^n), \quad j, k \quad 0 > U_{i+1}^n$$

$$\frac{1}{2} \left(U_{i+1}^n - \frac{\Delta x}{2} \Delta_{i+1}^n (1 + \alpha) \right)^2$$

CFL Condition

$$x_{\max} = \max_i \{ S_{i+\frac{1}{2}} \}$$

$$\Delta t = -C_a \Delta x / x_{\max}$$

do $i = 1, \dots, N$

$t = i \Delta t$

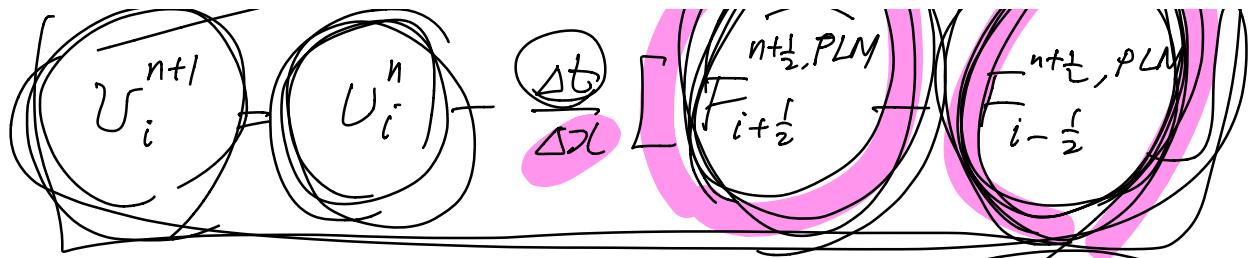
end do

while $t < t_{\max}$

$t = t_{\max}$

$n = 1 ; t_i$





Chapter 8 FVM for the Euler's Eqns.

non linear eqns

$$U_t + F(U)_x = 0$$

(i) local linearizations of the non linear flux Jacobian matrix

$$\frac{\partial F}{\partial U}_{nxn}$$

$n=3$
1D

$$U_t + \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix}_x = 0$$

conservative variable u_1, u_2, u_3

$$U_t + \frac{\partial F}{\partial U} U_x = 0$$

$$U_t + A U_x = 0$$

(ii) diagonalize

$$(A) = (R D R^{-1})$$

R

R = L

$$A \approx D$$

$$\begin{bmatrix} \lambda_1 & & 0 \\ 0 & \lambda_2 & \\ & & \lambda_3 \end{bmatrix}$$

$$\begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}_t + \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{bmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}_x = 0$$

(iii) decouple
the system

$$(u_1)_t + \lambda_1 (u_1)_x = 0$$

$$(u_3)_t + \lambda_3 (u_3)_x = 0$$

(iv) Use the linear theory for

linear scalar eqns.

$$F(u) =$$

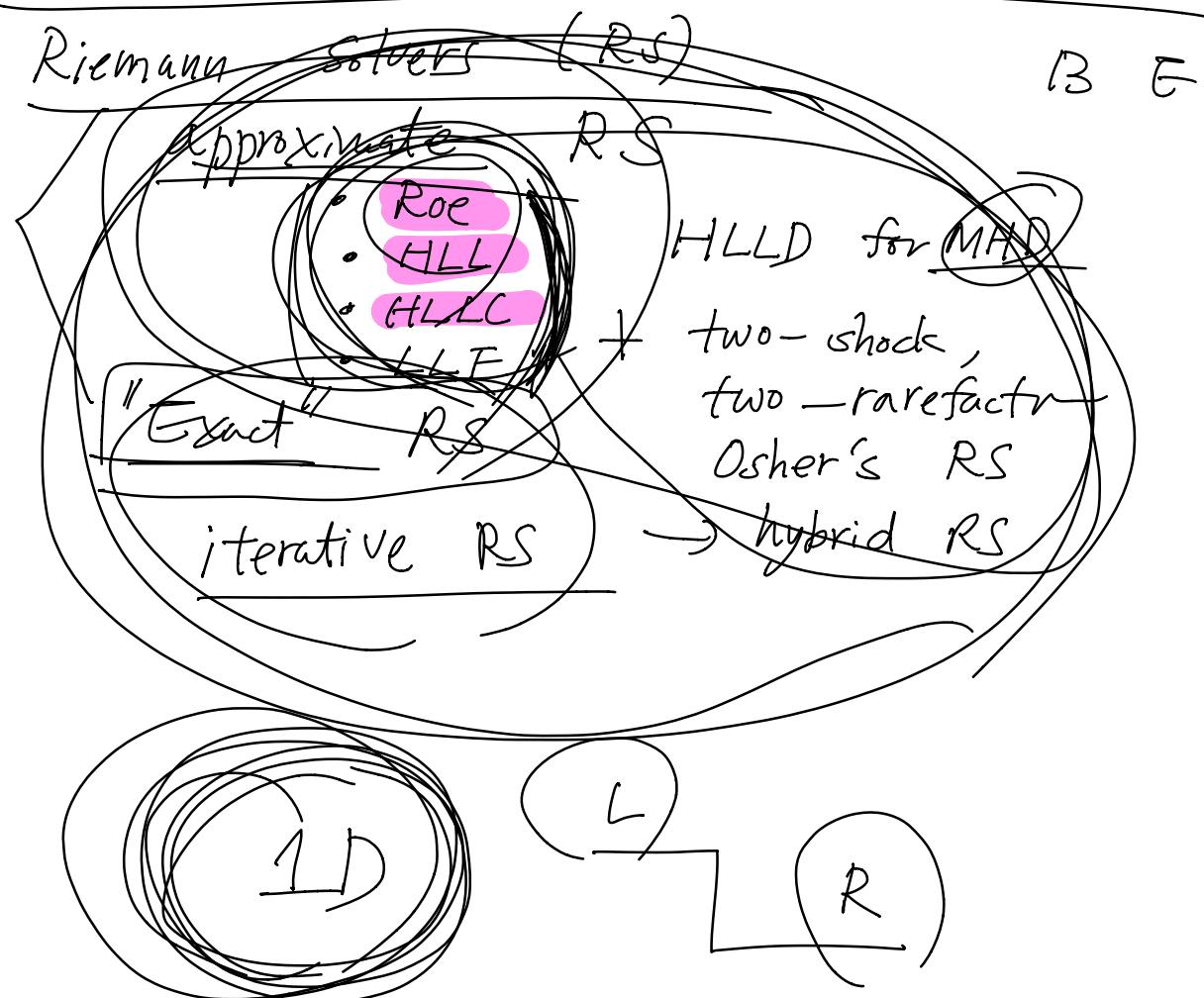
$$\begin{aligned} & \delta u \\ & \delta u^2 + p \end{aligned}$$

$$u(\delta E + p)$$

$$f_t + (gu)_x = 0$$

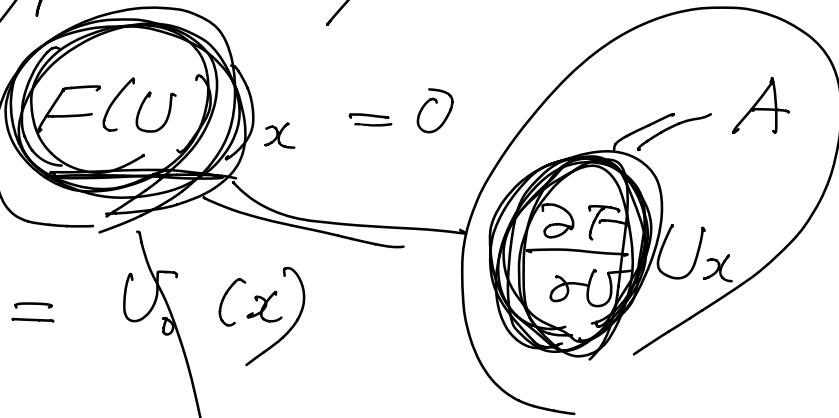
$$(gu)_t + (gu^2 + p)_x = 0$$

$$(gE)_t + (u(gE+p))_x = 0$$



Nonlinear Hyperbolic Systems

$$\left\{ \begin{array}{l} U_t + F(U)_x = 0 \\ U(x,0) = U_0(x) \end{array} \right.$$



$$A(x_{i+\frac{1}{2}}) = \tilde{A}$$

$$A(x_i) = \tilde{A}$$

(*) $\left\{ \begin{array}{l} U_t + \tilde{A} U_x = 0 \\ U(x,0) = U_0(x) \end{array} \right.$

$$\underline{F(U) = \tilde{A}U}$$

$$U = \begin{pmatrix} g_u \\ g_v \\ g_w \\ g_E \end{pmatrix}$$

↑

$$\underline{F(U)} = \begin{pmatrix} f_u \\ f_u^2 + p \\ f_{uv} \\ f_{uw} \\ u(g_E + p) \end{pmatrix}$$

flux vector

Conservative
vector

$$G(U) = \begin{pmatrix} \gamma v \\ \gamma vu \\ \gamma v^2 + p \\ \gamma vw \\ v(\gamma E + p) \end{pmatrix} \quad \underbrace{H(U)}_{\begin{matrix} \parallel \\ \vdots \end{matrix}}$$

Def. The system of conservation law $\textcircled{*}$
is called hyperbolic if

A is diagonalizable with real eigenvalues

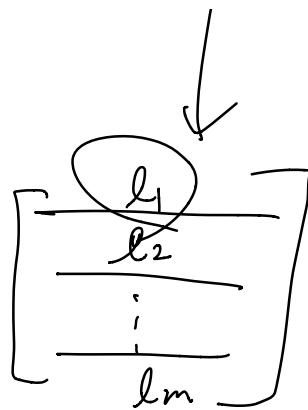
$$\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_m \text{ s.t.}$$

We can decompose

$$\tilde{A} = R \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_m \end{pmatrix} R^{-1},$$

$\begin{bmatrix} r_1 | r_2 | \dots | r_m \end{bmatrix}$

$$l_i \cdot r_j = \delta_{ij}$$



Def. strictly hyperbolic if

$$\lambda_1 < \lambda_2 < \dots < \lambda_m$$

Decoupled system: $\tilde{A} = R \Lambda R^{-1}$

$$\tilde{U}_t + \tilde{A} \tilde{U}_x = 0 \quad ; \text{ linear system}$$

$$\rightarrow R^T \tilde{U}_t + \Lambda R^T U_x = 0$$

$$\rightarrow (L U)_t + \Lambda (L U)_x = 0$$

$$\rightarrow W = (L \cup) \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{pmatrix} \quad W = \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}$$

conservative

$$\rightarrow \boxed{w_t + \lambda w_x = 0} \quad \text{variables}$$

$$\boxed{\frac{\partial w_k}{\partial t} + \lambda_k \frac{\partial w_k}{\partial x} = 0, \quad k=1, \dots, m} \quad \text{characteristic variables}$$

a decoupled system of m indep. scalar eqns.

$$w_k(x, t) = w_k(x - \lambda_k t, 0)$$

$$U = R W$$