Kevin Tracy

Education

Carnegie Mellon University

Pittsburgh, PA

Ph.D. Robotics, GPA 4.14/4

Advisor: Zac Manchester

2020-Present

Stanford University

Stanford, CA

M.S. Mechanical Engineering, GPA 4.05/4
Advisor: Zac Manchester

Rice University
B.S. Mechanical Engineering, GPA 3.91/4

2014-2018

Professional Experience

[Google] Intrinsic Mountain View, CA

PhD Resident June 2023–Present

o Working with Stefan Schaal (Intrinsic), Yuval Tasaa, and Tom Erez (DeepMind)

Developed a method for sim2real learning for contact-rich assembly tasks like connector insertion
 SpaceX

SpaceX
Associate Engineer: Guidance, Navigation, and Control
Hawthorne, CA
May 2021—Aug 2021
May 2021—Aug 2021

o Implemented a novel closed-form solar array occlusion prediction algorithm

o Wrote a primal-dual interior point solver for quadratic programs in C++

o Developed reaction wheel allocation algorithms using convex optimization

Astranis San Francisco, CA

Guidance, Navigation, and Control Intern

Jan 2020–Mar 2020

o Built high-fidelity orbital simulation environment from scratch in Julia o Implemented fuel-optimal low-thrust trajectory methods for orbit-raising

o Designed orbital relocation algorithm for moving between GEO slots

Lockheed Martin Space Systems

Guidance, Navigation, and Control Intern

July 2019–Sep 2019

o Worked in GNC group for DOD Secret hypersonic and counter-hypersonic efforts o Designed hardware-in-the-loop test setup for Multiple Object Kill Vehicle (MOKV)

o Contributed to 6-DOF hypersonic missile simulation tools

o Published a paper internally on attitude parameterization conventions at LM Space

Maxar TechnologiesPalo Alto, CASpacecraft Systems InternMay 2016–Sep 2018

o Completed three internships in the spacecraft systems engineering organization

o Created subsystem models for attitude control, solar array, and electric power subsystem sizing in Matlab for Monte Carlo optimization of spacecraft architecture

o Redesigned equipment list system for bus subsystems and provided relevant training for engineers

Teaching Experience

Carnegie Mellon UniversityTeaching Assistant, 16745: Optimal Control and Reinforcement Learning

Pittsburgh, PA
Spring 2022, 2023, 2024

Teaching Assistant, 16715: Advanced Robot Dynamics and Simulation

Stanford University
Teaching Assistant AA273: State Estimation and Filtering for Robotic Percention
Spring 2020

Teaching Assistant, AA273: State Estimation and Filtering for Robotic PerceptionSpring 2020Teaching Assistant, ENGR205: Introduction to Control Design TechniquesFall 2019

Rice UniversityTeaching Assistant, ENGI120: Introduction to Engineering Design
Teaching Assistant, STAT305: Statistics for Biosciences

Houston, TX
Fall 2016, 2017
Fall 2015

Fall 2021

Sunnyvale, CA

Awards

Best Paper (Avionics and Electronics for Space Applications)

IEEE Aerospace Conference

2022

"Ultra-Fine Pointing for Nanosatellite Telescopes With Actuated Booms"

Best Student Paper Finalist

IEEE Robotics and Automation Society

2021

"Planning with Attitude"

Publications

Journal Papers

- 1. B. E. Jackson, K. Tracy, and Z. Manchester, "Planning With Attitude," en, *IEEE Robotics and Automation Letters*, 2021.
- 2. E. S. Douglas, K. Tracy, and Z. Manchester, "Practical Limits on Nanosatellite Telescope Pointing: The Impact of Disturbances and Photon Noise," en, *Frontiers in Astronomy and Space Sciences*, vol. 8, Aug. 2021.

Preprints

- 3. K. Tracy and Z. Manchester, *On the differentiability of the primal-dual interior-point method*, 2024. arXiv: 2406.11749 [math.OC].
- 4. K. Tracy, Z. Manchester, A. Jain, K. Go, S. Schaal, T. Erez, and Y. Tassa, Efficient online learning of contact force models for connector insertion, 2023. eprint: arXiv:2312.09190.
- 5. K. Tracy, A Square-Root Kalman Filter Using Only QR Decompositions, Aug. 2022. arXiv: 2208.06452 [cs, eess].
- 6. K. Tracy, T. A. Howell, and Z. Manchester, *DiffPills: Differentiable Collision Detection for Capsules and Padded Polygons*, Jul. 2022. arXiv: 2207.00202 [cs].

Conference Papers

- 7. A. L. Bishop, J. Z. Zhang, S. Gurumurthy, K. Tracy, and Z. Manchester, "Relu-qp: A gpu-accelerated quadratic programming solver for model-predictive control," in *2024 IEEE International Conference on Robotics and Automation (ICRA)*, Yokohama, Japan, May 31, 2024.
- 8. K. Tracy and Z. Manchester, "Convex quasi-dynamic simulation of rigid point clouds with torsional friction," in 2023 IROS Workshop on Leveraging Models for Contact-Rich Manipulation, Detroit, Michigan, Oct. 1, 2023.
- 9. K. Tracy, T. A. Howell, and Z. Manchester, "Differentiable Collision Detection for a Set of Convex Primitives," in 2023 IEEE International Conference on Robotics and Automation (ICRA), London, England, May 31, 2023.
- 10. K. Tracy, G. Falcone, and Z. Manchester, "Robust Entry Guidance with Atmospheric Adaptation," in *AIAA SciTech Forum and Exposition*, National Harbor, Maryland, Jan. 2023.
- 11. B. E. Jackson, J. H. Lee, K. Tracy, and Z. Manchester, "Data-Efficient Model Learning for Control with Jacobian-Regularized Dynamic-Mode Decomposition," in 6th Annual Conference on Robot Learning, Dec. 2022.
- 12. T. A. Howell, K. Tracy, K. Le Cleac'h, and Z. Manchester, "CALIPSO: A Differentiable Solver for Trajectory Optimization with Conic and Complementarity Constraints," in *The International Symposium on Robotics Research*, Geneva, Switzerland, Sep. 2022. arXiv: 2205.09255 [cs, eess].
- 13. M. Holliday, K. Tracy, Z. Manchester, and A. Nguyen, "The V-R3x Mission: Towards Autonomous Networking and Navigation for CubeSat Swarms," in *4S Symposium*, Vilamoura, Portugal, May 2022.
- 14. K. Tracy and Z. Manchester, "CPEG: A Convex Predictor-corrector Entry Guidance Algorithm," in *IEEE Aerospace Conference*, Big Sky, MT, USA, Mar. 2022.
- 15. K. Tracy, Z. Manchester, and E. Douglas, "Ultra-Fine Pointing for Nanosatellite Telescopes With Actuated Booms," in *IEEE Aerospace Conference*, Big Sky, MT, USA, Mar. 2022.
- 16. B. E. Jackson, T. Punnoose, D. Neamati, K. Tracy, R. Jitosho, and Z. Manchester, "ALTRO-C: A Fast Solver for Conic Model-Predictive Control," in *2021 IEEE International Conference on Robotics and Automation (ICRA)*, Xi'an, China, May 31, 2021.
- 17. K. Tracy and Z. Manchester, "Low-Thrust Trajectory Optimization Using the Kustaanheimo-Stiefel Transformation," in AAS/AIAA Space Flight Mechanics Meeting, Charlotte, NC, Jan. 31, 2021.

| 18. | K. Tracy and Z. Manchester, "Model-Predictive Attitude Control for Flexible Spacecraft During Thruster Firings," in <i>AAS/AIAA Astrodynamics Specialist Conference</i> , Lake Tahoe, CA, Aug. 9, 2020. |
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