Kevin Tracy

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Education

Carnegie Mellon University   **Pittsburgh, PA**
Ph.D. Robotics, GPA 4.0/4   *2020-Present*
Advisor: Zac Manchester,
Thesis: "Differentiable Convex Modeling for Robotic Planning and Control"

Stanford University   **Stanford, CA**
M.S. Mechanical Engineering, GPA 4.0/4   *2018-2020*
Advisor: Zac Manchester

Rice University   **Houston, TX**
B.S. Mechanical Engineering, GPA 3.91/4   *2014-2018*

Professional Experience

Gridmatic   **Cupertino, CA**
Optimization Research Scientist   *Jan 2025–Present*
- Developed custom primal-dual interior point method for scenario-based portfolio optimization
- Deployed and analyzed strategies controlling grid-scale batteries via market submissions
- Built a differentiable optimization pipeline for simulating real-time energy markets

[Google] Intrinsic   **Mountain View, CA**
PhD Resident   *June 2023–Dec 2024*
- Working with Stefan Schaal (Intrinsic), Yuval Tassa, and Tom Erez (DeepMind)
- Focusing on developing derivative-free trajectory optimization methods for contact systems
- Developed a method for sim2real learning for contact-rich assembly tasks like connector insertion

SpaceX   **Hawthorne, CA**
Associate Engineer: Guidance, Navigation, and Control   *May 2021–Aug 2021*
- Implemented a novel closed-form solar array occlusion prediction algorithm
- Wrote a primal-dual interior point solver for quadratic programs in C++
- Developed reaction wheel allocation algorithms using convex optimization

Astranis   **San Francisco, CA**
Guidance, Navigation, and Control Intern   *Jan 2020–Mar 2020*
- Implemented fuel-optimal low-thrust trajectory methods for orbit-raising
- Designed orbital relocation algorithm for moving between GEO slots

Lockheed Martin Space Systems   **Sunnyvale, CA**
Guidance, Navigation, and Control Intern   *July 2019–Sep 2019*
- Worked in GNC group for DOD Secret hypersonic and counter-hypersonic efforts
- Designed hardware-in-the-loop test setup for Multiple Object Kill Vehicle (MOKV)

Teaching Experience

Carnegie Mellon University   **Pittsburgh, PA**
Teaching Assistant, 16745: Optimal Control and Reinforcement Learning   *Spring 2022, 2023, 2024*
Teaching Assistant, 16715: Advanced Robot Dynamics and Simulation   *Fall 2021*

Stanford University   **Stanford, CA**
Teaching Assistant, AA273: State Estimation and Filtering for Robotic Perception *Spring 2020*
Teaching Assistant, ENGR205: Introduction to Control Design Techniques   *Fall 2019*

Awards

Best Paper (Avionics and Electronics for Space Applications)
IEEE Aerospace Conference   *2022*
"Ultra-Fine Pointing for Nanosatellite Telescopes With Actuated Booms"

Best Student Paper Finalist
IEEE Robotics and Automation Society *2021*
"Planning with Attitude"

Publications

Journal Papers

1. B. E. Jackson, K. Tracy, and Z. Manchester, "Planning With Attitude," en, *IEEE Robotics and Automation Letters*, 2021.

2. E. S. Douglas, K. Tracy, and Z. Manchester, "Practical Limits on Nanosatellite Telescope Pointing: The Impact of Disturbances and Photon Noise," en, *Frontiers in Astronomy and Space Sciences*, vol. 8, Aug. 2021.

Preprints

3. K. Tracy, J. Z. Zhang, J. Arrizabalaga, S. Schaal, Y. Tassa, T. Erez, and Z. Manchester, *The trajectory bundle method: Unifying sequential-convex programming and sampling-based trajectory optimization*, 2025. arXiv: `2509.26575` `[math.OC]`.

4. K. Tracy and Z. Manchester, *On the differentiability of the primal-dual interior-point method*, 2024. arXiv: `2406.11749` `[math.OC]`.

5. K. Tracy, *A Square-Root Kalman Filter Using Only QR Decompositions*, Aug. 2022. arXiv: `2208.06452` `[cs, eess]`.

6. K. Tracy, T. A. Howell, and Z. Manchester, *DiffPills: Differentiable Collision Detection for Capsules and Padded Polygons*, Jul. 2022. arXiv: `2207.00202` `[cs]`.

Conference Papers

7. K. Tracy, Z. Manchester, A. Jain, K. Go, S. Schaal, T. Erez, and Y. Tassa, "Efficient online learning of contact force models for connector insertion," in *2025 IEEE International Conference on Robotics and Automation (ICRA)*, 2025.

8. A. L. Bishop, J. Z. Zhang, S. Gurumurthy, K. Tracy, and Z. Manchester, "Relu-qp: A gpu-accelerated quadratic programming solver for model-predictive control," in *2024 IEEE International Conference on Robotics and Automation (ICRA)*, Yokohama, Japan, May 31, 2024.

9. K. Tracy and Z. Manchester, "Convex quasi-dynamic simulation of rigid point clouds with torsional friction," in *2023 IROS Workshop on Leveraging Models for Contact-Rich Manipulation*, Detroit, Michigan, Oct. 1, 2023.

10. K. Tracy, T. A. Howell, and Z. Manchester, "Differentiable Collision Detection for a Set of Convex Primitives," in *2023 IEEE International Conference on Robotics and Automation (ICRA)*, London, England, May 31, 2023.

11. K. Tracy, G. Falcone, and Z. Manchester, "Robust Entry Guidance with Atmospheric Adaptation," in *AIAA SciTech Forum and Exposition*, National Harbor, Maryland, Jan. 2023.

12. B. E. Jackson, J. H. Lee, K. Tracy, and Z. Manchester, "Data-Efficient Model Learning for Control with Jacobian-Regularized Dynamic-Mode Decomposition," in *6th Annual Conference on Robot Learning*, Dec. 2022.

13. T. A. Howell, K. Tracy, K. Le Cleac'h, and Z. Manchester, "CALIPSO: A Differentiable Solver for Trajectory Optimization with Conic and Complementarity Constraints," in *The International Symposium on Robotics Research*, Geneva, Switzerland, Sep. 2022. arXiv: `2205.09255` `[cs, eess]`.

14. M. Holliday, K. Tracy, Z. Manchester, and A. Nguyen, "The V-R3x Mission: Towards Autonomous Networking and Navigation for CubeSat Swarms," in *4S Symposium*, Vilamoura, Portugal, May 2022.

15. K. Tracy and Z. Manchester, "CPEG: A Convex Predictor-corrector Entry Guidance Algorithm," in *IEEE Aerospace Conference*, Big Sky, MT, USA, Mar. 2022.

16. K. Tracy, Z. Manchester, and E. Douglas, "Ultra-Fine Pointing for Nanosatellite Telescopes With Actuated Booms," in *IEEE Aerospace Conference*, Big Sky, MT, USA, Mar. 2022.

17. B. E. Jackson, T. Punnoose, D. Neamati, K. Tracy, R. Jitosho, and Z. Manchester, "ALTRO-C: A Fast Solver for Conic Model-Predictive Control," in *2021 IEEE International Conference on Robotics and Automation (ICRA)*, Xi'an, China, May 31, 2021.

18. K. Tracy and Z. Manchester, "Low-Thrust Trajectory Optimization Using the Kustaanheimo-Stiefel Transformation," in *AAS/AIAA Space Flight Mechanics Meeting*, Charlotte, NC, Jan. 31, 2021.

19. K. Tracy and Z. Manchester, "Model-Predictive Attitude Control for Flexible Spacecraft During Thruster Firings," in *AAS/AIAA Astrodynamics Specialist Conference*, Lake Tahoe, CA, Aug. 9, 2020.