



GRAPH PROPERTIES



GRAPHS – PROPERTIES

Proposition: If G is a graph with m edges, then:

$$\sum_{v \in G} \deg(v) = 2m$$

Justification:

- An edge (u,v) is counted twice in the summation above:
 - once by its endpoint u when considered an origin
 - once by its endpoint v when considered an origin
- Thus, the total contribution of the edges to the degrees of the vertices is twice the number of edges.

GRAPHS – PROPERTIES

Proposition: If G is a **directed** graph with m edges, then:

$$\sum_{v \in G} \text{indeg}(v) = \sum_{v \in G} \text{outdeg}(v) = m$$

Justification:

- In a **directed** graph, an edge (u,v) contributes:
 - One unit to the **out-degree** of its origin u
 - One unit to the **in-degree** of its destination v
- Based on this:
 - The total **contribution of the edges to the in-degrees** equals the **number of edges**
 - The total **contribution of the edges to the out-degrees** equals the **number of edges**

GRAPHS – PROPERTIES

Proposition: Let G be a graph with n vertices and m edges. If G is a **simple undirected**, then $m \leq n(n - 1)/2$, and if G is **simple directed**, then $m \leq n(n - 1)$

Justification:

- If G is a **simple undirected** graph:
 - Since G is **simple**, then for each vertex v we have: $\deg(v) \leq n - 1$, implying that:

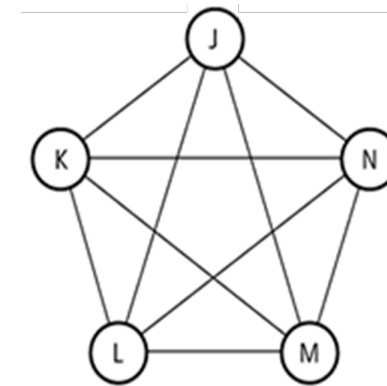
$$\sum_{v \in G} \deg(v) \leq n(n - 1)$$

- Since G is **undirected**, then we already proved that

$$\sum_{v \in G} \deg(v) = 2m$$

- The above two equations imply that:

$$2m \leq n(n - 1) \equiv m \leq n(n - 1)/2$$



Example: Given a simple undirected graph of 5 vertices, the **maximum** possible degree of a vertex is 4

GRAPHS – PROPERTIES

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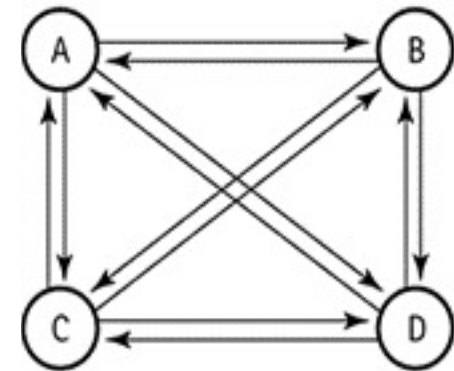
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- Since G is **directed**, then we already proved that

$$\sum_{v \in G} \text{indeg}(v) = m$$

- The above two equations imply that:

$$m \leq n(n - 1)$$



Example: Given a simple directed graph of 4 vertices, the **maximum** possible in-degree of a vertex is 3

THE GRAPH ADT

- The abstract data type has a **position** for **each vertex**, and a **position** for **each edge**.
- Each **Vertex** object, ***u***, supports at least the following operations:
 - operator**(*)***: Return the **element** associated with ***u***.
 - incidentEdges*(*)***: Return an **edge list** of all the edges incident on ***u***.
 - isAdjacentTo*(*v*)**: Test whether vertices ***u*** and ***v*** are **adjacent**.
- Each **Edge** object ***e*** supports at least the following operations:
 - operator**(*)***: Return the **element** associated with ***e*** (e.g., it could be the weight of ***e***)
 - endVertices*(*)***: Return a **vertex list** containing ***e***'s **end vertices**.
 - opposite*(*v*)**: Return the **end vertex** of edge ***e*** distinct from vertex ***v*** (an error occurs if ***e*** is not incident on ***v***).
 - isAdjacentTo*(*f*)**: Test whether edges ***e*** and ***f*** are **adjacent**.
 - isIncidentOn*(*v*)**: Test whether ***e*** is **incident** on ***v***.

THE GRAPH **ADT**

- The **Graph ADT** itself supports at least the following operations:

vertices(): Return a **vertex list** of all the vertices of the graph.

edges(): Return an **edge list** of all the edges of the graph.

insertVertex(*x*): **Insert** and return a new **vertex** storing element *x*.

insertEdge(*v*,*w*,*z*): **Insert** and return a new **undirected edge** with end vertices *v* and *w* and storing element *z*.

eraseVertex(*v*): **Remove vertex** *v* and all its incident edges.

eraseEdge(*e*): **Remove edge** *e*.



DATA STRUCTURES FOR GRAPHS

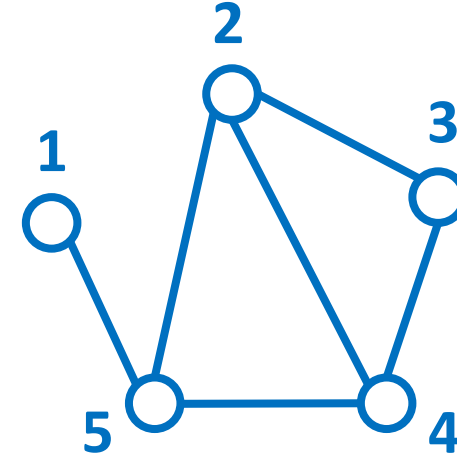


DATA STRUCTURES FOR GRAPHS

How would you represent such a graph in memory?

We can use an **EDGE LIST**, which simply lists all the edges one by one:

- (1, 5)
- (2, 3)
- (2, 4)
- (2, 5)
- (3, 4)
- (4, 5)

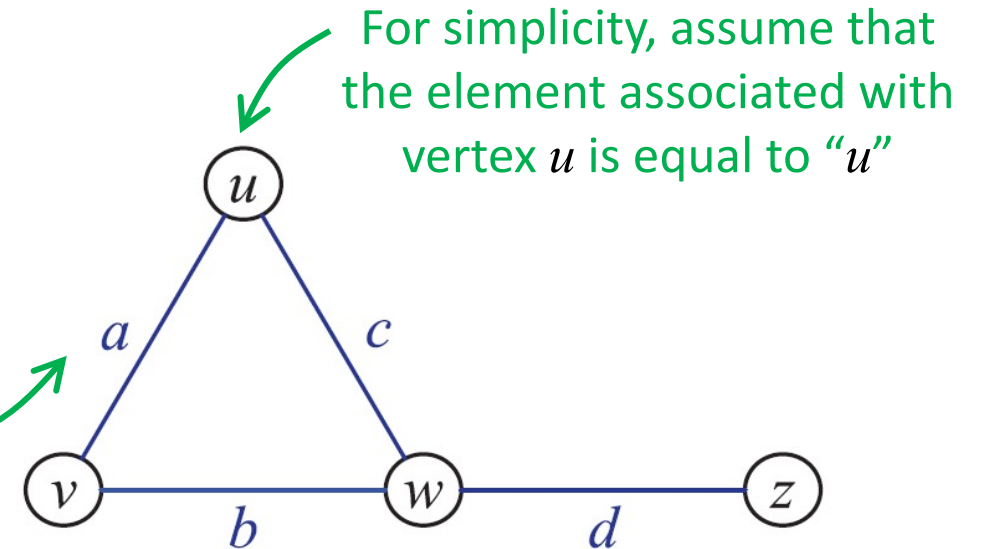


EDGE LIST

Here is the **edge list** of this graph:

- (v, u)
- (v, w)
- (u, w)
- (w, z)

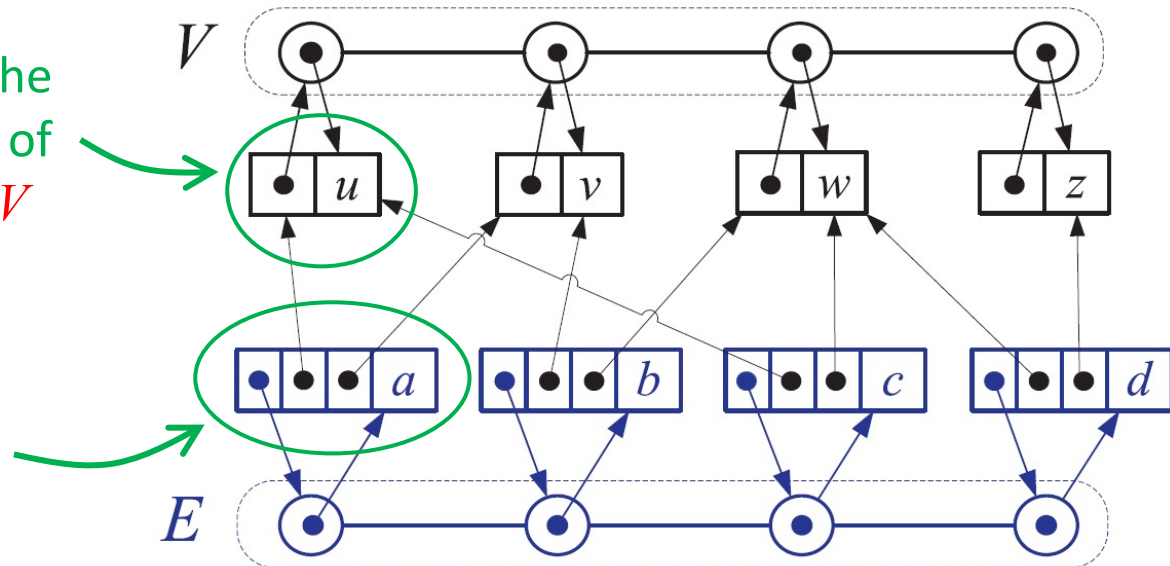
a is the element associated with (u, v) (e.g., it represents the edge's weight)



Here is how to represent this **edge list**:

A **vertex object** consists of the **element** u and the **position** of the object in the collection V

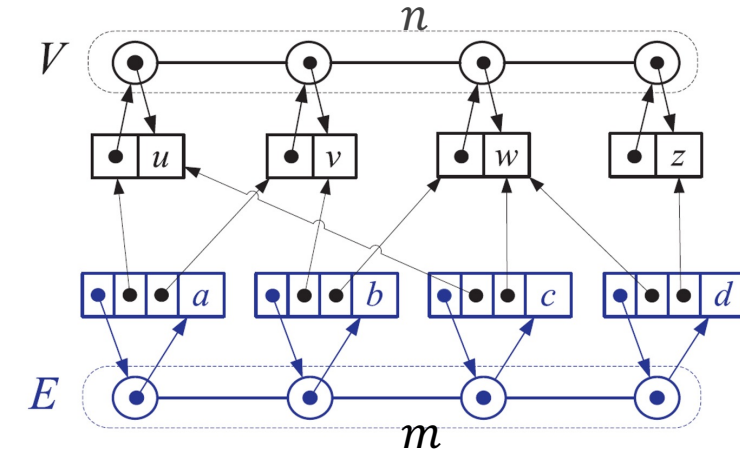
An **edge object** consists of the **element** a and the object's **position** in the collection E as well as **positions** associated with its two endpoints, u and v



EDGE LIST – COMPLEXITY

- Given an **Edge List**, what is the complexity of these operations?

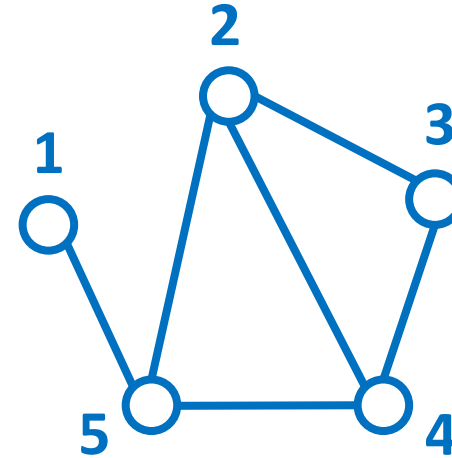
$O(n)$	vertices: Return a list of all vertices
$O(m)$	edges: Return a list of all edges
$O(1)$	insertVertex: Inserts a new vertex
$O(1)$	insertEdge: Insert a new edge
$O(m)$	eraseVertex: Remove a vertex and all its incident edges
$O(1)$	eraseEdge: Remove an edge
$O(m)$	incidentEdges: Return a list of all edges incident on a vertex
$O(m)$	isAdjacentTo: Test whether two vertices are adjacent
$O(1)$	endVertices: Return the two endpoints of an edge
$O(1)$	opposite: Given an endpoint of an edge, return the other endpoint
$O(1)$	isIncidentOn: Test whether an edge is incident on given vertex



ADJACENCY LIST

We discussed how this graph can be represented as an **edge list**, which simply **lists the edges**:

- (1, 5)
- (2, 3)
- (2, 4)
- (2, 5)
- (3, 4)
- (4, 5)



An alternative is an **ADJACENCY LIST**, which **lists the vertices that are adjacent to each vertex**

- **1:** 5
 - **2:** 3, 4, 5
 - **3:** 2, 4,
 - **4:** 2, 3, 5
 - **5:** 1, 2, 4
- ← This is called the “**incidence collection**” of vertex **2**, denoted by $I(2)$

ADJACENCY LIST

Here is the **adjacency list** of this graph:

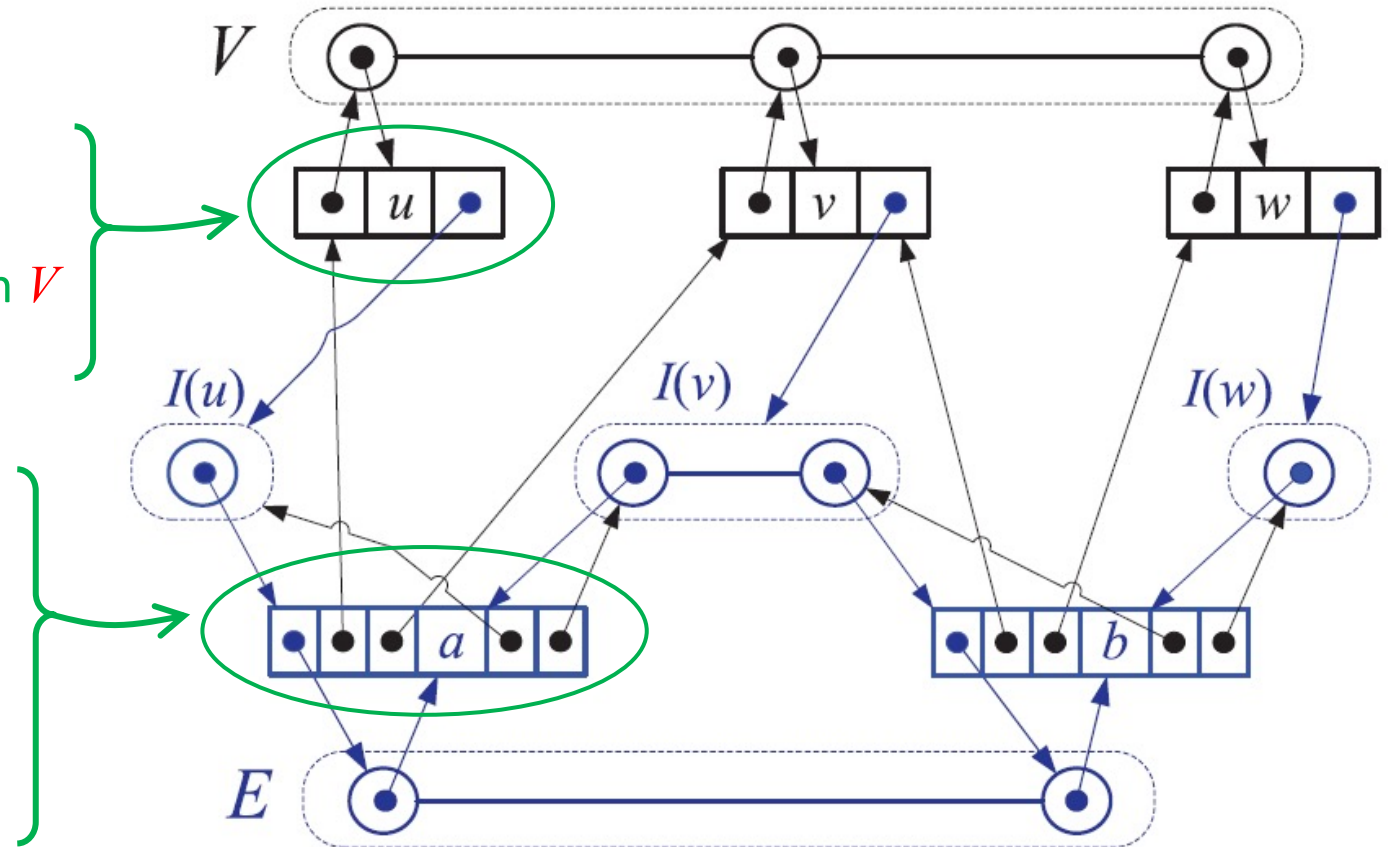
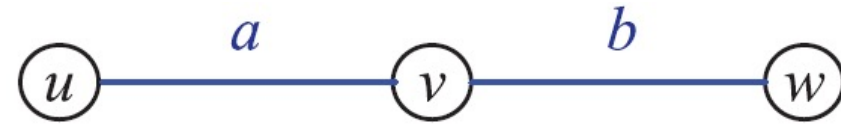
- u : v
- v : u, w
- w : v

A **vertex object** consists of:

- The **element** u
- The object's **position** in collection V
- A **reference** to $I(u)$

An **edge object** consists of:

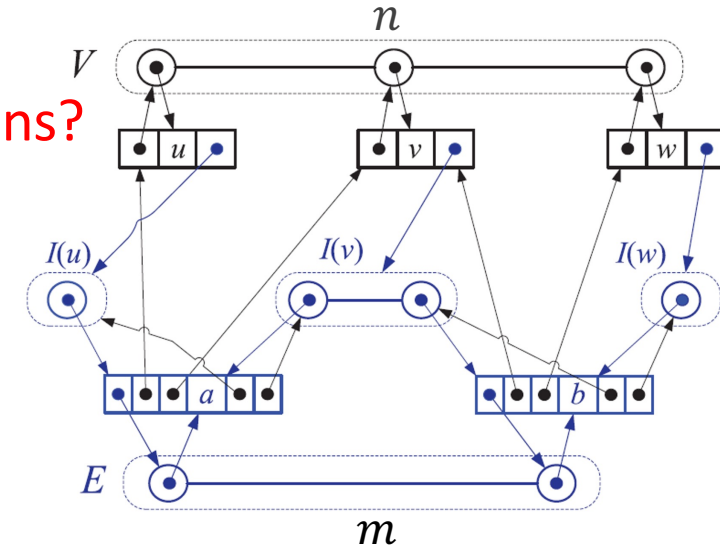
- The **element** a
- The object's **position** in the collection E
- The **positions** associated with u and v
- **References** to the edge's position in $I(u)$ and the edge's position in $I(v)$



ADJACENCY LIST – COMPLEXITY

- Given an **adjacency list**, what is the complexity of these operations?

- $O(n)$ **vertices**: Return a list of **all vertices**
- $O(m)$ **edges**: Return a list of **all edges**
- $O(1)$ **insertVertex**: Inserts a **new vertex**
- $O(1)$ **insertEdge**: Insert a **new edge**
- $O(\deg(v))$ **eraseVertex(v)**: **Remove a vertex** and all its incident edges
- $O(1)$ **eraseEdge**: **Remove an edge**
- $O(\deg(v))$ **v .incidentEdges()**: Return a list of **all edges incident** on a vertex
- $O(\min(\deg(v), \deg(w)))$ **v .isAdjacentTo(w)**: Test whether v and w are **adjacent**
- $O(1)$ **endVertices**: Return the two **endpoints** of an edge
- $O(1)$ **opposite**: Given an endpoint of an edge, **return the other endpoint**
- $O(1)$ **isIncidentOn**: Test whether **an edge is incident** on given vertex



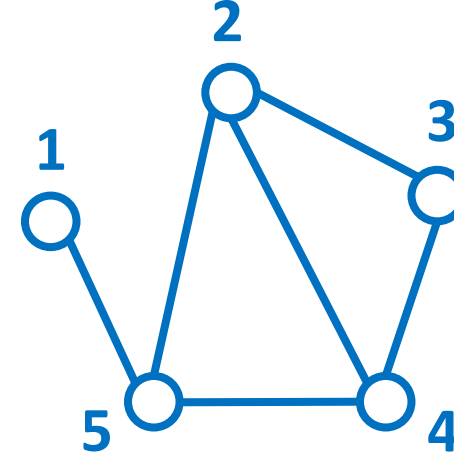
ADJACENCY MATRIX

An **edge list** simply lists **the edges**:

- (1, 5)
- (2, 3)
- (2, 4)
- (2, 5)
- (3, 4)
- (4, 5)

An **adjacency list** specifies the **vertices** that are adjacent to each vertex:

- **1:** 5
- **2:** 3, 4, 5
- **3:** 2, 4,
- **4:** 2, 3, 5
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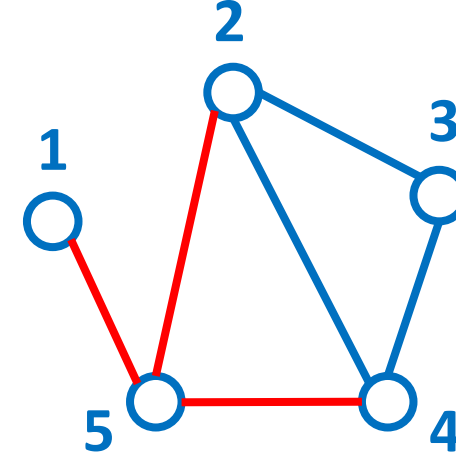
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An **adjacency list** specifies the **vertices** that are adjacent to each vertex:

- **1:** 5
- **2:** 3, 4, 5
- **3:** 2, 4,
- **4:** 2, 3, 5
- **5:** 1, 2, 4



We can use an **ADJACENCY MATRIX**, where:

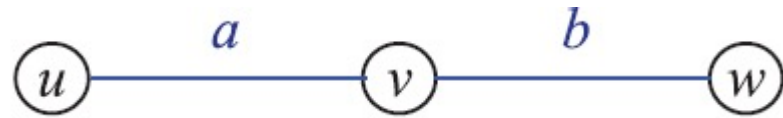
- $A[i, j] = 1$ means j is adjacent to i
- $A[i, j] = 0$ means j is not adjacent to i

	1	2	3	4	5
1	0	0	0	0	1
2	0	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

ADJACENCY MATRIX

$A[i, j]$ holds a **reference** to the edge between the vertices whose indices are i and j (if such an edge exists)

Here is the **adjacency Matrix** of this graph:



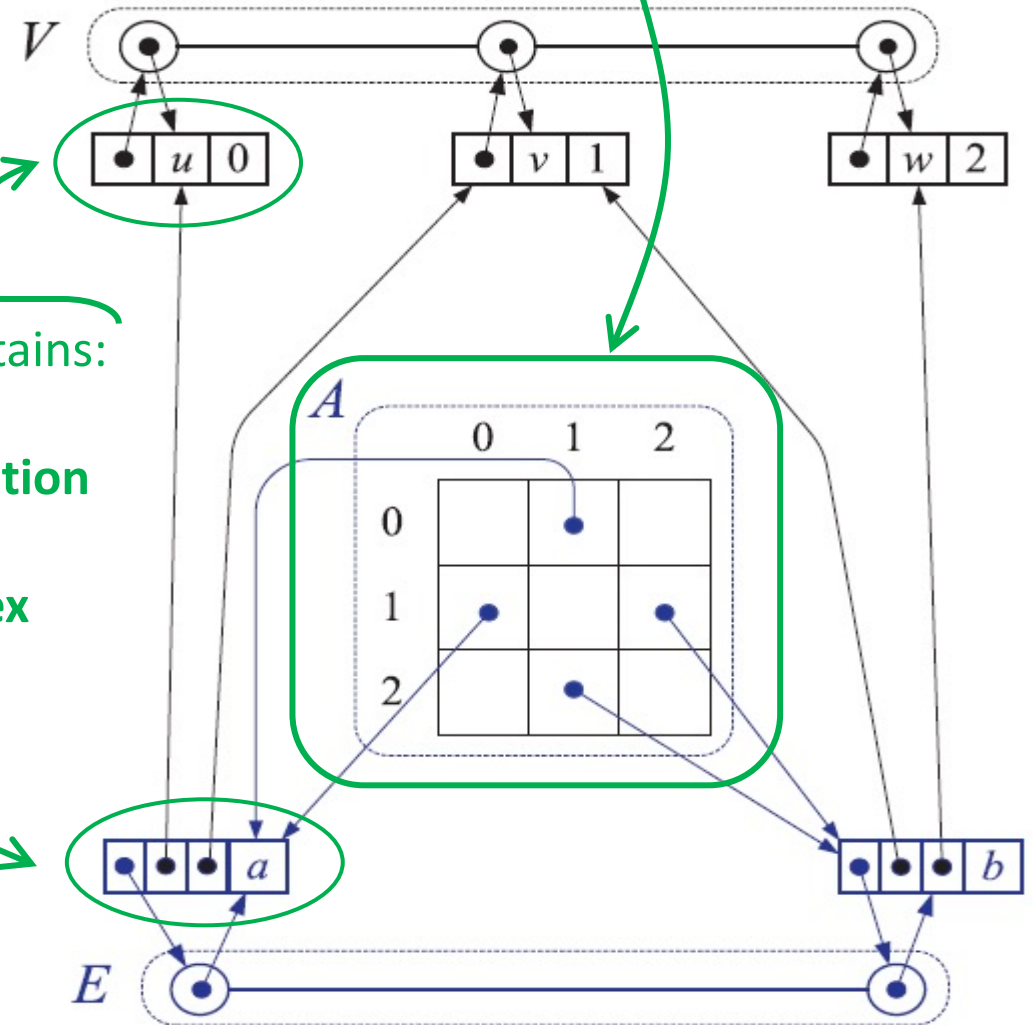
	u	v	w
u	0	1	0
v	1	0	1
w	0	1	0

A **vertex object** contains:

- The **element** u
- The object's **position** in collection V
- The vertex's **index**

An **edge object** consists of:

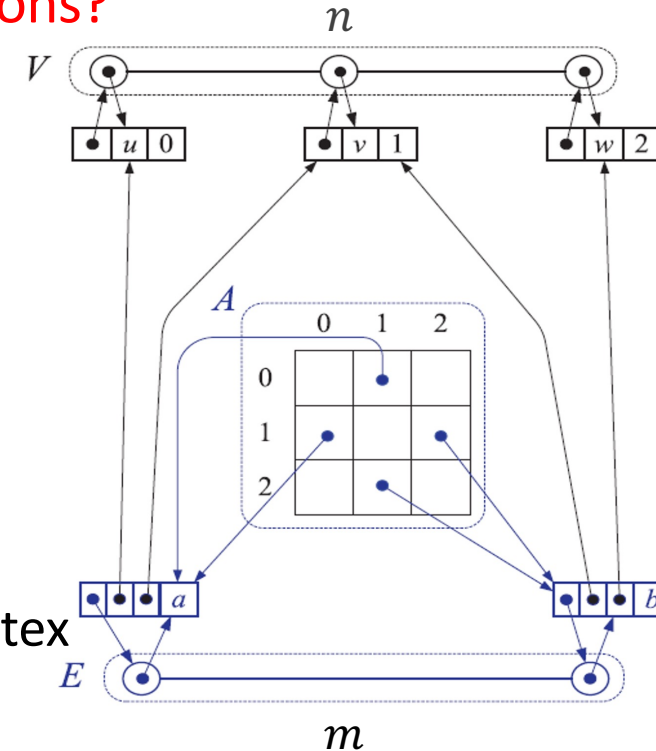
- The **element** a
- The object's **position** in the collection E
- The **positions** associated with the endpoints u and v



ADJACENCY MATRIX – COMPLEXITY

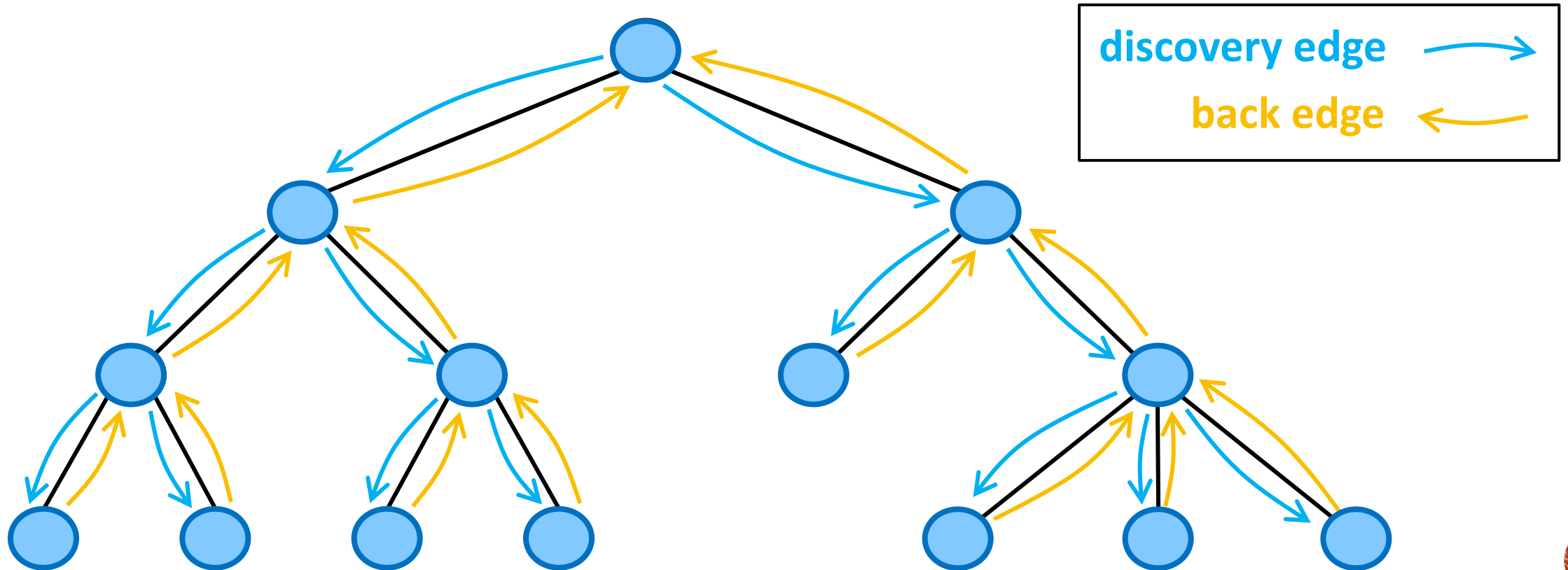
- Given an **adjacency matrix**, what is the complexity of these operations?

$O(n)$	vertices: Return a list of all vertices
$O(n^2)$	edges: Return a list of all edges
$O(n^2)$	insertVertex: Inserts a new vertex
$O(1)$	insertEdge: Insert a new edge
$O(n^2)$	eraseVertex: Remove a vertex and all its incident edges
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DEPTH-FIRST SEARCH (DFS)

- How to **traverse** a **tree**, i.e., visit all of its vertices one by one?
- One way to do this is to use the “**depth-first search**” algorithm:



BREADTH-FIRST SEARCH (BFS)

- An alternative to **depth-first search** is to call it “**breadth-first search**”, which works in trees as follows:

