

STL CONTAINER METHODS

- The following methods are defined for STL **vectors**, STL **lists**, and STL **deques**:

`vector(p,q)` or `list(p,q)` or `deque(p,q)`: **Construct** the container **by iterating** the range `[p,q)` and **copying** each of these elements into the new container.

Example:

```
vector<int> x;  
...  
vector<int> y( x.begin(), x.end() );
```

This way, `y` is assigned a new vector containing copies of the elements in `x`.
Of course, `x` must have the same base type as `y`.

- Note that the method operates on **the range `[p,q)`**, i.e., from `p` to `q-1`. However, since `x.end()` returns an imaginary element that lies just after the end of the container, then `y(x.begin(), x.end())` would copy **all** elements of `x`.

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`vector(p,q)` or `list(p,q)` or `deque(p,q)`: **Construct** the container **by iterating** the range `[p,q)` and **copying** each of these elements into the new container.

`assign(p,q)`: **Delete** the contents, and **assigns its new contents by iterating** the range `[p,q)` and **copying** each of these elements into the container.

Example:

```
vector<int> x;  
...  
y.assign( x.begin(), x.end() );
```

This way, the content of `y` will be deleted, and then `y` will be assigned a new vector containing copies of the elements in `x`. Of course, `x` must have the same base type as `y`.

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vector(p,q) or **list(p,q)** or **deque(p,q)**: **Construct** the container **by iterating** the range $[p,q)$ and **copying** each of these elements into the new container.

assign(p,q): **Delete** the contents, and **assigns its new contents by iterating** the range $[p,q)$ and **copying** each of these elements into the container.

insert(p,e): **Insert a copy** of e just prior to the position given by iterator p and **shift** the subsequent elements one position to the right. (except for STL lists, where no shifting occurs, since it is **implemented as a doubly-linked list**)

erase(p): **Remove and destroy** the element at the position given by p and **shift** the subsequent elements one position to the left. (except for STL lists)

erase(p,q): Iterate the range $[p,q)$, **removing and destroying** all these elements and **shifting** subsequent elements to the left to fill the gap. (except for STL lists)

clear(): **Delete** all elements of the container.

STL CONTAINER METHODS

- The following methods are defined for STL **vectors**, STL **lists**, and STL **deque**s:

`sort(p,q)`: **Sort** the elements in the range $[p,q)$ in **ascending order**. It is assumed that (" $<$ ") is defined for the base type. (**sort is not supported by STL lists**)

Example:

```
vector<int> v;  
...  
v.sort( v.begin(), v.end() ); // this sorts the vector  
v.sort( v.begin(), v.begin()+10 ); // this sorts the first 10  
                                // elements of the vector
```

STL CONTAINER METHODS

- The following methods are defined for STL **vectors**, STL **lists**, and STL **deques**:

sort(p, q): **Sort** the elements in the range $[p, q)$ in **ascending order**. It is assumed that (" $<$ ") is defined for the base type. (**sort is not supported by STL lists**)

random_shuffle(p, q): **Rearrange** the elements in the range $[p, q)$ in **random order**. (**random_shuffle is not supported by STL lists**)

reverse(p, q): **Reverse** the elements in the range $[p, q)$.

find(p, q, e): Return an iterator to **the first element** in the range $[p, q)$ **that is equal to e** ; if e is not found, q is returned.

min_element(p, q): Return an iterator to **the minimum element** in the range $[p, q)$.

max_element(p, q): Return an iterator to **the maximum element** in the range $[p, q)$.

for_each(p, q, f): **Apply the function f** to the elements in the range $[p, q)$.

EXAMPLE

```
int a[ ] = {17, 12, 33, 15, 62, 45};
vector<int> v(a, a + 6);
cout << v.size();
v.pop_back();
cout << v.size();
v.push_back(19);
cout << v.front() << " " << v.back();
sort(v.begin(), v.begin() + 4);
v.erase(v.end() - 4, v.end() - 2);
cout << v.size();
```

```
char x[ ] = {'b', 'r', 'a', 'v', 'o'};
vector<char> w(x, x + 5);
```

```
// #include <algorithm> to use random_shuffle
```

```
random_shuffle(w.begin(), w.end());
```

```
w.insert(w.begin(), 's');
```

```
for (vector<char>::iterator p = w.begin(); p != w.end(); ++p)
```

```
    cout << *p << " ";
```

```
return EXIT_SUCCESS;
```

```
}
```

Write the output of each line here

```
// v: 17 12 33 15 62 45
```

```
// outputs: 6
```

```
// v: 17 12 33 15 62
```

```
// outputs: 5
```

```
// v: 17 12 33 15 62 19
```

```
// outputs: 17 19
```

```
// v: (12 15 17 33) 62 19
```

```
// v: 12 15 62 19
```

```
// outputs: 4
```

```
// w: b r a v o
```

```
// w: o v r a b
```

```
// w: s o v r a b
```

```
// outputs: s o v r a b
```



SEQUENCES



SEQUENCES

- A **sequence** is an **ADT** that:
 - Supports all the functions of the **List ADT**
 - Provides functions for accessing elements by their **index** (as in the **Vector ADT**)

More specifically, the **Sequence ADT** consists of the operations of the List ADT, plus the following two functions:

- **atIndex(i)**: Return the **position/iterator** of the element at **index i**
- **indexOf(p)**: Return the **index** of the element at **position/iterator p**

- A **sequence** can be implemented using either a **linked list**, or an **array**.

SEQUENCES – LIST IMPLEMENTATION



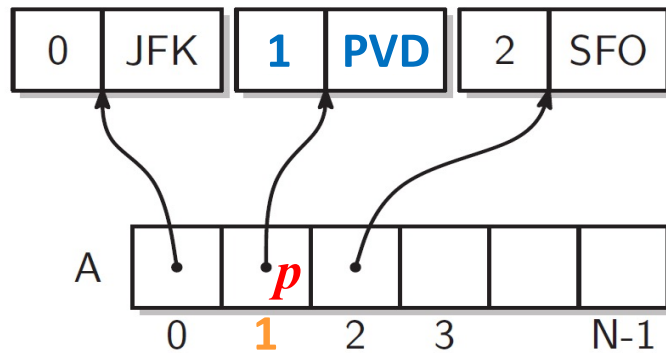
```
// get index from position
int indexOf(const Iterator& p) const {
    Iterator q = begin();
    int j = 0;
    while (q != p) // until finding p
        {++q; ++j;} // advance and count hops
    return j;
}
```

```
// get position from index
Iterator atIndex(int i) const {
    Iterator p = begin();
    for (int j = 0; j < i; j++)
        ++p; // advance
    return p;
}
```

- **Disadvantage:** `atIndex(i)` and `indexOf(p)` run in $O(n)$; they may perform n iterations!
- **Advantage:** `insert(p, e)` and `erase(p)` run in $O(1)$; no need to shift elements!

SEQUENCES – ARRAY IMPLEMENTATION

- Recall that a sequence is an ADT that supports "**indexOf(p)**" and "**atIndex(i)**"
- If implemented as an array**, we must have an **array of positions**, each of which points to a **pair** consisting of an element, and the index of that element.



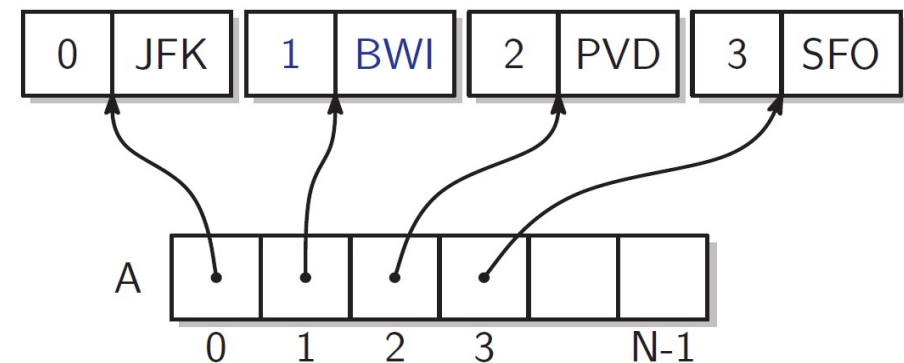
$A[1]$ is a **position**, p , pointing to a pair consisting of:

- An **element**, which is **PVD**
- The **index** of that element, which is **1**

To **insert** an element at index 1, we must:

- **Shift** all the positions whose index is ≥ 1
- **Update the indices** of all the positions whose index is ≥ 1

What is the time complexity? $O(n)$

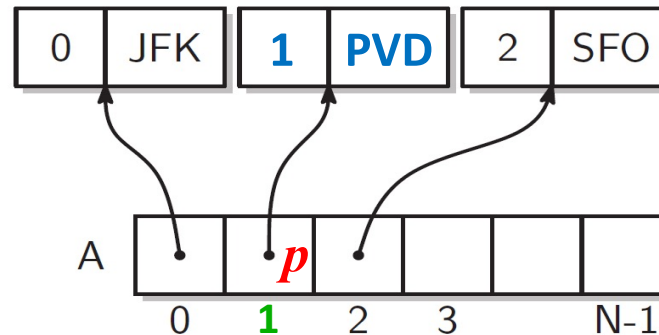


LIST VS. ARRAY IMPLEMENTATION

List:



- **Disadvantage:** $\text{atIndex}(i)$ and $\text{indexOf}(p)$ run in $O(n)$; they may perform n iterations!
- **Advantage:** $\text{insert}(p, e)$ and $\text{erase}(p)$ run in $O(1)$; no need to shift elements!



Array:

- **Disadvantage:** $\text{insert}(p, e)$ and $\text{erase}(p)$ run in $O(n)$; we must shift elements!
- **Advantage:** $\text{atIndex}(i)$ and $\text{indexOf}(p)$ run in $O(1)$, because:
 - Given an index i , the position at i is stored in $A[i]$.
 - Given a position p , the index of p is stored in the object that p points to.



BUBBLE SORT



BUBBLE SORT

- “Bubble Sort” is a **sorting algorithm** that performs a series of passes over a **sequence**.
- In each pass, it compares each element to the one after it, and swaps them if needed!

1st pass:

initial array: 5, 7, 2, 6, 9, 3

Swap? No! 5, 7, 2, 6, 9, 3

Swap? Yes 5, 7, 2, 6, 9, 3

Swap? Yes 5, 2, 7, 6, 9, 3

Swap? No! 5, 2, 6, 7, 9, 3

Swap? Yes 5, 2, 6, 7, 9, 3

After 1st pass: 5, 2, 6, 7, 3, 9

2nd pass:

initial array: 5, 2, 6, 7, 3, 9

Swap? Yes 5, 2, 6, 7, 3, 9

Swap? No! 2, 5, 6, 7, 3, 9

Swap? No! 2, 5, 6, 7, 3, 9

Swap? Yes 2, 5, 6, 7, 3, 9

Swap? No! 2, 5, 6, 3, 7, 9

After 2nd pass: 2, 5, 6, 3, 7, 9

3rd pass:

initial array: 2, 5, 6, 3, 7, 9

Swap? No! 2, 5, 6, 3, 7, 9

Swap? No! 2, 5, 6, 3, 7, 9

Swap? Yes 2, 5, 6, 3, 7, 9

Swap? No! 2, 5, 3, 6, 7, 9

Swap? No! 2, 5, 3, 6, 7, 9

After 3rd pass: 2, 5, 3, 6, 7, 9

4th pass:

initial array: 5, 7, 2, 6, 9, 3

Swap? No! 2, 5, 3, 6, 7, 9

Swap? Yes 2, 5, 3, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

After 4th pass: 2, 3, 5, 6, 7, 9

BUBBLE SORT

- “Bubble Sort” has the following properties:
 - In 1st pass, once the **largest element** is reached, it keeps on being swapped until it gets to the **last position**
 - In 2nd pass, once the **second largest element** is reached, it keeps on being swapped until it gets to the **second-to-last position**
 - At the end of the i^{th} pass, the **last i elements** (i.e., those at indices $n-i$ to $n-1$) are **sorted**.
- The last property implies that
 - It suffices to **stop after n passes**.
 - The i^{th} pass can be limited to **the first $n-i+1$ elements**.

1st pass:

initial array: 5, 7, 9, 6, 2, 3

Swap? No! 5, 7, 9, 6, 2, 3

Swap? No! 5, 7, 9, 6, 2, 3

Swap? Yes 5, 7, 9, 6, 2, 3

Swap? Yes 5, 7, 6, 9, 2, 3

Swap? Yes 5, 7, 6, 2, 9, 3

After 1st pass: 5, 7, 6, 7, 3, 9

BUBBLE SORT

- In the example we saw earlier, we can see how:
 - At the end of the i^{th} pass, the **last i elements are sorted**, implying that the i^{th} pass can be limited to **the first $n-i+1$ elements**.

1st pass:

initial array: 5, 7, 2, 6, 9, 3

Swap? No! 5, 7, 2, 6, 9, 3

Swap? Yes 5, 7, 2, 6, 9, 3

Swap? Yes 5, 2, 7, 6, 9, 3

Swap? No! 5, 2, 6, 7, 9, 3

Swap? Yes 5, 2, 6, 7, 9, 3

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Swap? No! 2, 5, 6, 7, 3, 9

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After 2nd pass: 2, 5, 6, 3, 7, 9

3rd pass:

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Swap? Yes 2, 5, 6, 3, 7, 9

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Swap? No! 2, 5, 3, 6, 7, 9

After 3rd pass: 2, 5, 3, 6, 7, 9

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Swap? No! 2, 5, 3, 6, 7, 9

Swap? Yes 2, 5, 3, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

Swap? No! 2, 3, 5, 6, 7, 9

After 4th pass: 2, 3, 5, 6, 7, 9

BUBBLE SORT

- What is the complexity of Bubble Sort?

The number of comparisons is $\approx n + (n-1) + (n-2) + \dots + 2 + 1 = \frac{n(n+1)}{2}$ which is $O(n^2)$

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After 1st pass: 5, 2, 6, 7, 3, 9

2nd pass:

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The number of comparisons is $\approx n + (n-1) + (n-2) + \dots + 2 + 1 = \frac{n(n+1)}{2}$ which is $O(n^2)$

- Clearly, Bubble Sort requires accessing elements at different indices. The above analysis assumes that an **element at index i can be accessed in $O(1)$ time.**
- Now, suppose we are sorting a sequence. Then:
 - If we use an **array-based implementation**, where **atIndex(i)** runs in $O(1)$, the total runtime of BubbleSort is indeed $O(n^2)$
 - On the other hand, if we use a **list-based implementation**, where **atIndex(i)** runs in $O(n)$ time, the total runtime becomes $O(n^3)$
- Thus, **choosing the appropriate implementation of the ADT matters!**