

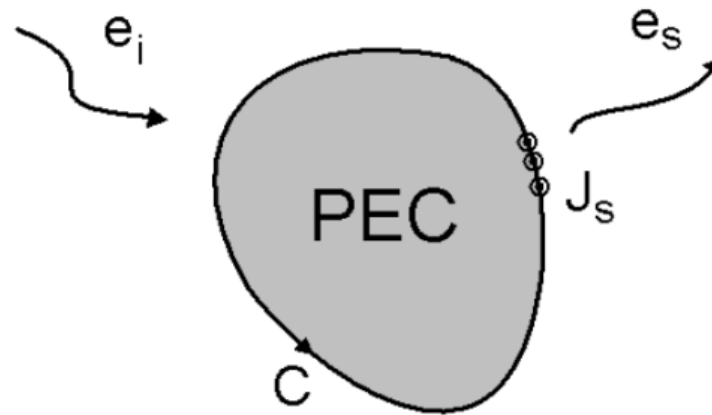
# Mortar Element Method for the Two Dimensional Transverse Electric Boundary Integral Equation

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- Electromagnetic Background
- TM Scattering Analysis
- TE Scattering Analysis
- Mortar Element Method
- Conclusion

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**Figure 1:** Scattering by a perfectly electrical conductor (PEC).

$$e^{tot}(\boldsymbol{\rho}) = [e^i(\boldsymbol{\rho}) + e^s(\boldsymbol{\rho})] = 0$$

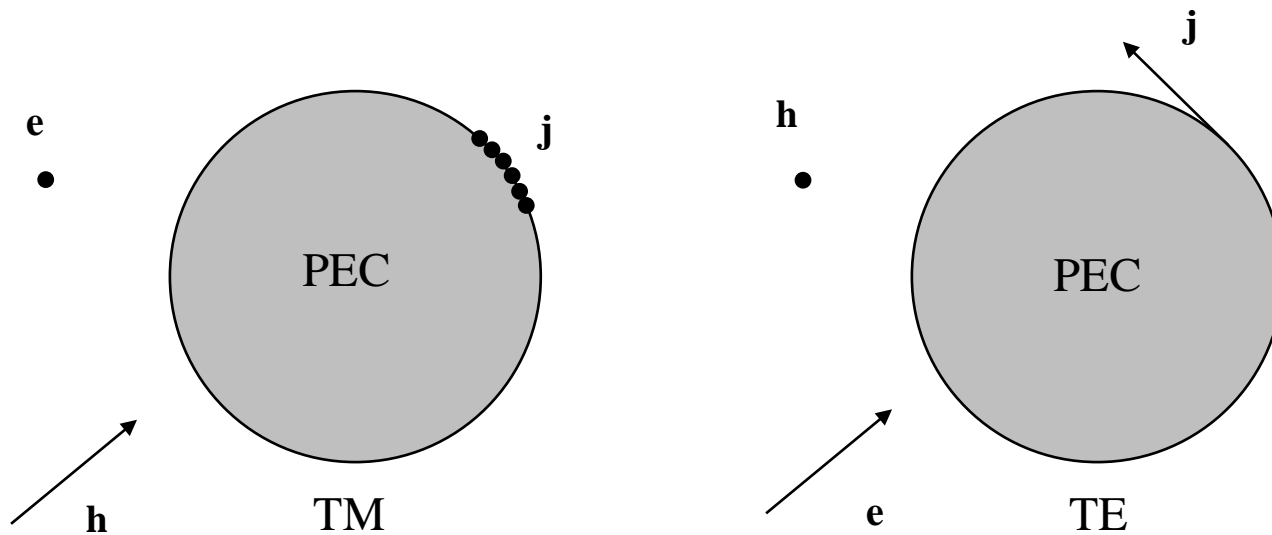
## ■ Maxwell Equations

$$\begin{array}{ccc} & \nabla \cdot \mathbf{d}(\boldsymbol{\rho}) = -\frac{1}{j\omega} \nabla \cdot \mathbf{j}(\boldsymbol{\rho}) & \\ \text{TM} \left[ & \nabla \times \mathbf{e}(\boldsymbol{\rho}) = -j\omega \mathbf{b}(\boldsymbol{\rho}) & \\ & \nabla \cdot \mathbf{b}(\boldsymbol{\rho}) = 0 & \\ & \nabla \times \mathbf{h}(\boldsymbol{\rho}) = j\omega \mathbf{d}(\boldsymbol{\rho}) + \mathbf{j}(\boldsymbol{\rho}) & \end{array} \quad \begin{array}{c} \text{TE} \end{array}$$

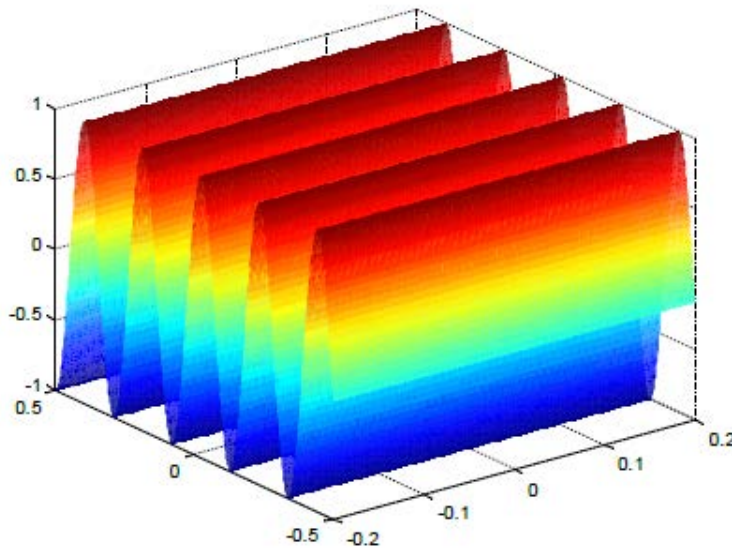
with the constitutive equations

$$\mathbf{d}(\boldsymbol{\rho}) = \varepsilon \mathbf{e}(\boldsymbol{\rho})$$

$$\mathbf{b}(\boldsymbol{\rho}) = \mu \mathbf{h}(\boldsymbol{\rho})$$



**Figure 2:** TM problem vs TE problem on the boundary of the 2D transverse.



**Figure 3:** A uniform plane wave.

$$R=0.5\text{m}$$

$$\lambda = 1.0\text{m}$$

$$c = 3 \times 10^8 \text{ m/s}$$

$$\omega = 6\pi \times 10^8 \text{ rad/s}$$

$$\mu = 4\pi \times 10^{-7} \text{ H/m}$$

$$\varepsilon = 8.85 \times 10^{-12} \text{ F/m}$$

$$\eta = 120\pi\Omega$$

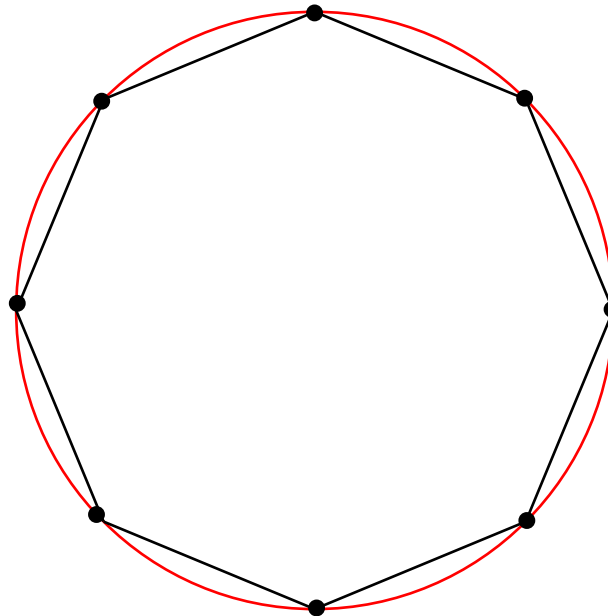
$$E_0 = 1$$

$$H_0 = \sqrt{\frac{\mu}{\varepsilon}}$$

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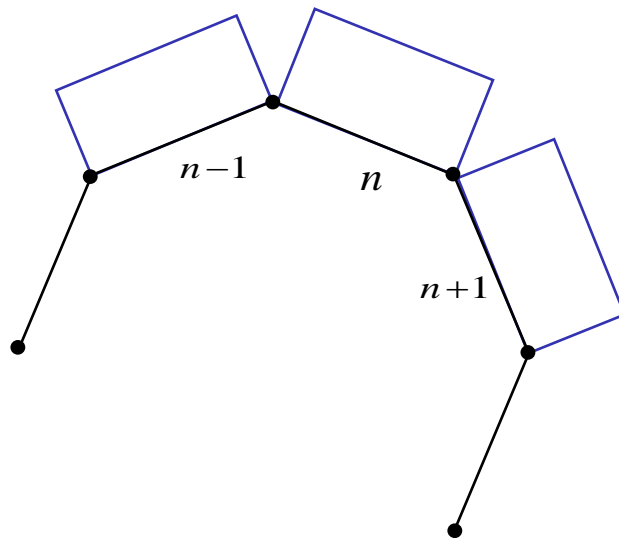


## ■ Discretization of the Electric Boundary Integral Equation



**Figure 4:** Approximation of the boundary of the scatterer by finite linear segments.

## ■ Discretization of the Electric Boundary Integral Equation



**Figure 5:** Basis functions of TM problem.

## ■ Basis Function

$$f_n(\boldsymbol{\rho}) = \begin{cases} 1, & \forall \boldsymbol{\rho} \in \text{segment } n \\ 0, & \text{elsewhere} \end{cases}$$

## ■ Current Density

$$j(\boldsymbol{\rho}) = \sum_{n=1}^N x_n f_n(\boldsymbol{\rho})$$

## ■ Electric Boundary Integral Equation

$$e^s(\boldsymbol{\rho}) = -j\omega\mu \sum_{n=1}^N x_n \int_C G(|\boldsymbol{\rho} - \boldsymbol{\rho}'|) f_n(\boldsymbol{\rho}') dc' = -e^i(\boldsymbol{\rho})$$

## ■ Multiply and integrate one test term on both sides

$$-j\omega\mu \sum_{n=1}^N x_n \int_C \int_C f_m(\boldsymbol{\rho}) G(|\boldsymbol{\rho} - \boldsymbol{\rho}'|) f_n(\boldsymbol{\rho}') dc' dc = -\int_C f_m(\boldsymbol{\rho}) e^i(\boldsymbol{\rho}) dc$$

## ■ It can be expressed as a linear system

$$\mathbf{Z}\mathbf{x} = \mathbf{L}$$

where

$$Z_{m,n} = -j\omega\mu \int_C \int_C f_m(\boldsymbol{\rho}) G(|\boldsymbol{\rho} - \boldsymbol{\rho}'|) f_n(\boldsymbol{\rho}') dc' dc$$

and

$$L_n = -\int_C f_n(\boldsymbol{\rho}) e^i(\boldsymbol{\rho}) dc$$

- Apply the numerical quadrature rule

$$\int_0^1 f(s)ds \approx \sum_{p=1}^Q w_p f(s_p)$$

- The integration can be expanded as

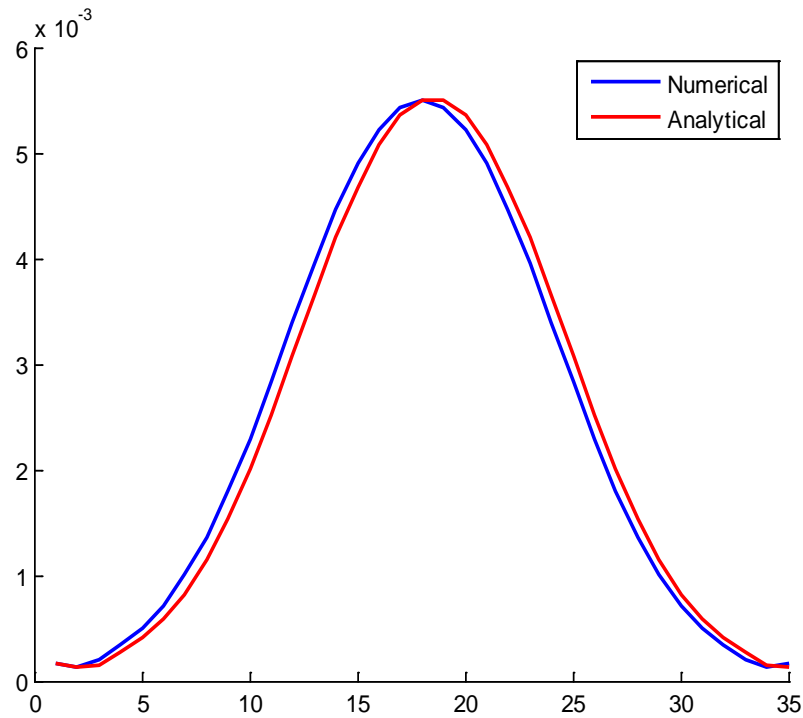
$$Z_{m,n} \approx -j\omega\mu \sum_{p=1}^Q \sum_{q=1}^Q w_p w_q l_m l_n f_m(\boldsymbol{\rho}_m(s_p)) G(|\boldsymbol{\rho}_m(s_p) - \boldsymbol{\rho}'_n(s_q)|) f'_n(\boldsymbol{\rho}'_n(s_q))$$

and

$$L_m = -\int_C f_m(\boldsymbol{\rho}) e_i(\boldsymbol{\rho}) dc = -\sum_{p=1}^Q w_p l_m f_m(\boldsymbol{\rho}_m(s_p)) e^i(\boldsymbol{\rho}_m(s_p))$$

where

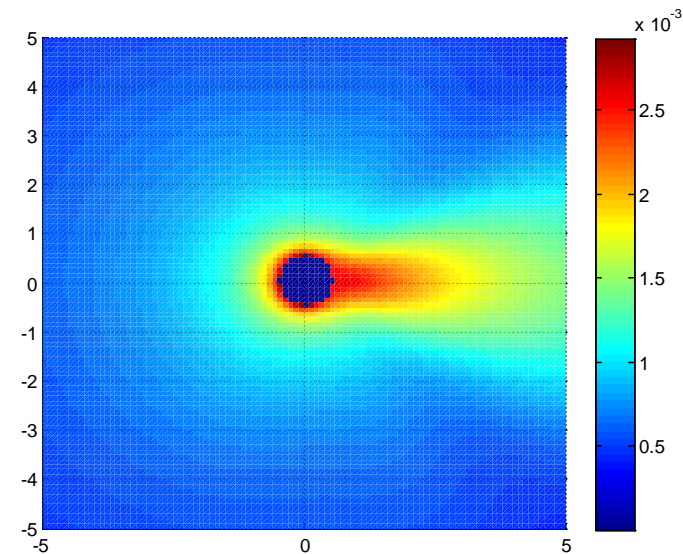
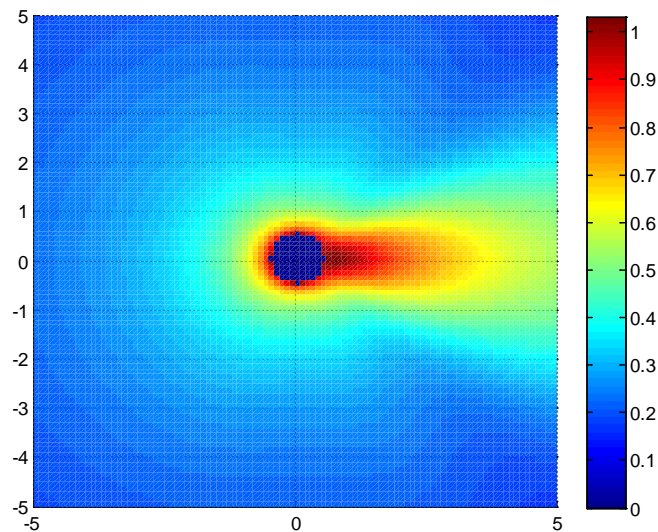
$$\boldsymbol{\rho}_m(s) = \boldsymbol{\rho}_{m,0} + s(\boldsymbol{\rho}_{m,1} - \boldsymbol{\rho}_{m,0})$$



**Figure 6:** Comparison between the numerical and analytical solution to current density in TM case.

## ■ Expression of scattered field in TM mode

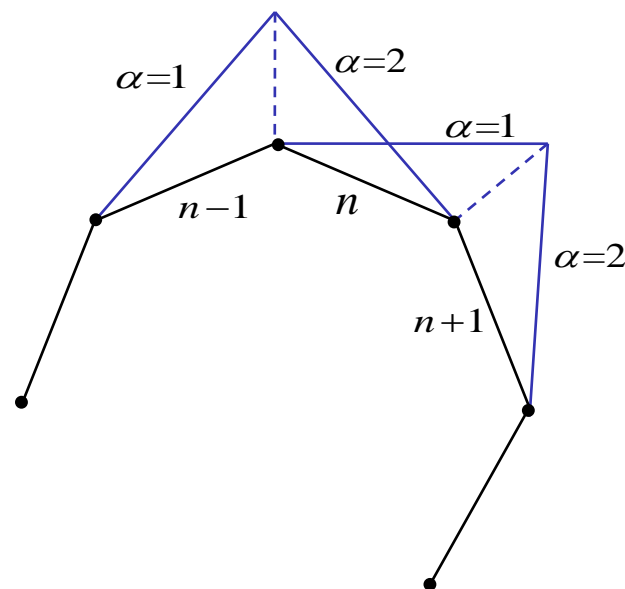
$$e^s(\boldsymbol{\rho}) = -j\omega\mu \sum_{m=1}^N x_m l_m \sum_{p=1}^Q w_p G(|\boldsymbol{\rho} - \boldsymbol{\rho}'_m(s_p)|) f_m(\boldsymbol{\rho}'_m(s_p))$$



**Figure 7:** Magnitude of scattered electric field      **Figure 8:** Magnitude of scattered magnetic field

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## ■ Discretization of the Electric Boundary Integral Equation



**Figure 9:** Basis functions of TE problem.

## ■ Basis Function

$$f_n(\mathbf{p}_\alpha(l)) = \begin{cases} 1 + \frac{l}{l_{n-1}}, & \alpha=1, n \neq N \Leftrightarrow \forall \mathbf{p} \in \text{segment } n-1 \\ 1 - \frac{l}{l_n}, & \alpha=2, n \neq N \Leftrightarrow \forall \mathbf{p} \in \text{segment } n \\ 1 - \frac{l}{l_1}, & \alpha=2, n = N \Leftrightarrow \forall \mathbf{p} \in \text{segment } 1 \\ 0, & \text{elsewhere} \end{cases}$$

## ■ Current Density

$$|\mathbf{j}(\mathbf{p})| = \sum_{\alpha=1}^2 \sum_{n=1}^N x_n f_n(\mathbf{p}_\alpha)$$



## ■ Electric Boundary Integral Equation

$$\mathbf{e}^s(\boldsymbol{\rho}) = \frac{\eta}{jk} \nabla \int_C G(|\boldsymbol{\rho} - \boldsymbol{\rho}'|) \partial_s j(\boldsymbol{\rho}') dc' - j\eta k \int_C G(|\boldsymbol{\rho} - \boldsymbol{\rho}'|) \mathbf{j}(\boldsymbol{\rho}') dc' = -\mathbf{e}^i(\boldsymbol{\rho})$$

■ After multiplying and integrating, we can expand the above equation into

$$Z_{m,n} = j \frac{\eta}{k} \sum_{\alpha=1}^2 \sum_{\beta=1}^2 \sum_{p=1}^{Q_1} \sum_{q=1}^{Q_2} [w_p w_q l_{\alpha,m} l_{\beta,n} \partial_s (f_m(\boldsymbol{\rho}_{\alpha,m}(s_p))) G(|\boldsymbol{\rho}_{\alpha,m}(s_p) - \boldsymbol{\rho}'_{\beta,n}(s_q)|) \partial'_s (f_n(\boldsymbol{\rho}'_{\beta,n}(s_q))) \\ - k^2 w_p w_q l_{\alpha,m} l_{\beta,n} f_m(\boldsymbol{\rho}_{\alpha,m}(s_p)) G(|\boldsymbol{\rho}_{\alpha,m}(s_p) - \boldsymbol{\rho}'_{\beta,n}(s_q)|) f_n(\boldsymbol{\rho}'_{\beta,n}(s_q)) \hat{\mathbf{s}}(\boldsymbol{\rho}_{\alpha,m}(s_p)) \cdot \hat{\mathbf{s}}'(\boldsymbol{\rho}'_{\beta,n}(s_q))]$$

and

$$L_m = \sum_{\alpha=1}^2 \sum_{p=1}^Q w_p l_m f_m(\boldsymbol{\rho}_{\alpha,m}(s_p)) [\mathbf{e}^i(\boldsymbol{\rho}_{\alpha,m}(s_p)) \cdot \hat{\mathbf{s}}(\boldsymbol{\rho}_{\alpha,m}(s_p))]$$

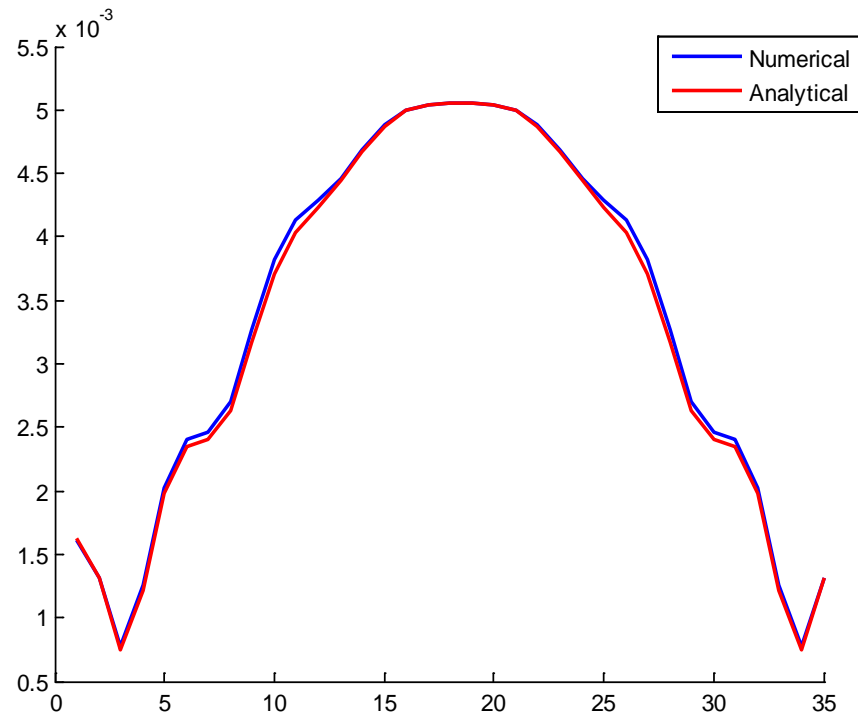
where

$$\mathbf{p}_{\alpha,m} = \begin{cases} \mathbf{p}_{m-1}, & \alpha = 1 \\ \mathbf{p}_m, & \alpha = 2 \end{cases} \quad \mathbf{p}'_{\beta,n} = \begin{cases} \mathbf{p}'_{n-1}, & \beta = 1 \\ \mathbf{p}'_n, & \beta = 2 \end{cases}$$

$$f_m(\mathbf{p}_{\alpha,m}(s_p)) = \begin{cases} s_p, & \alpha = 1 \\ 1 - s_p, & \alpha = 2 \end{cases} \quad f_n(\mathbf{p}'_{\beta,n}(s_q)) = \begin{cases} s_q, & \beta = 1 \\ 1 - s_q, & \beta = 2 \end{cases}$$

$$\partial_s(f_m(\mathbf{p}_{\alpha,m})) = \begin{cases} \frac{1}{l_{m-1}}, & \alpha = 1 \\ -\frac{1}{l_m}, & \alpha = 2 \end{cases} \quad \partial'_s(f_n(\mathbf{p}'_{\beta,n})) = \begin{cases} \frac{1}{l_{n-1}}, & \beta = 1 \\ -\frac{1}{l_n}, & \beta = 2 \end{cases}$$

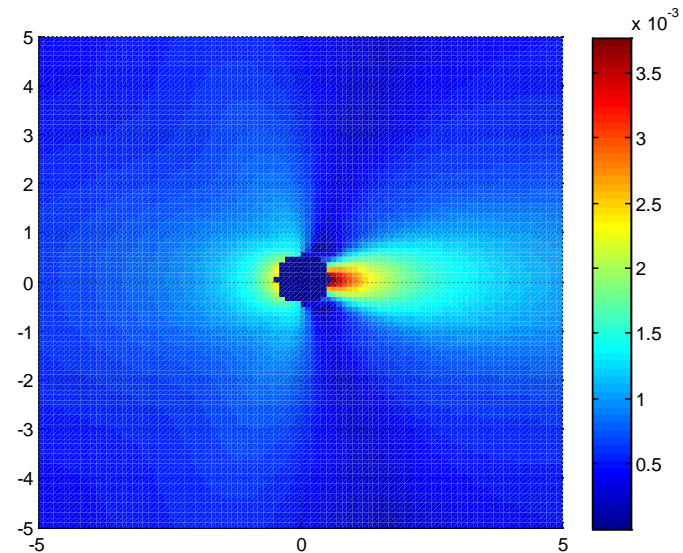
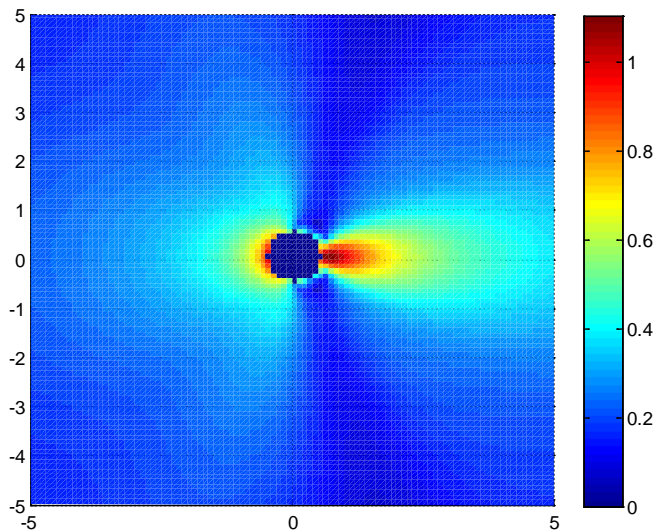
$$l_{\alpha,m} = \begin{cases} l_{m-1}, & \alpha = 1 \\ l_m, & \alpha = 2 \end{cases} \quad l_{\beta,n} = \begin{cases} l_{n-1}, & \beta = 1 \\ l_n, & \beta = 2 \end{cases}$$



**Figure 10:** Comparison between the numerical and analytical solution to current density in TE case.

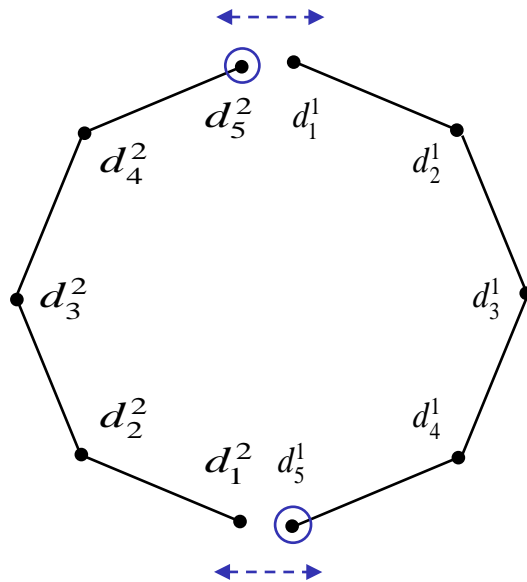
## ■ Expression of scattered field in TE mode

$$\mathbf{e}^s(\boldsymbol{\rho}) = \sum_{m=1}^N x_m \sum_{\alpha=1}^2 \sum_{p=1}^Q \left[ \frac{\eta}{jk} w_p l_{\alpha,m} (\nabla G(|\boldsymbol{\rho} - \boldsymbol{\rho}_{\alpha,m}(s_p)|)) \partial_s (f_m(\boldsymbol{\rho}_{\alpha,m}(s_p))) \right. \\ \left. - j\eta k w_p l_{\alpha,m} G(|\boldsymbol{\rho} - \boldsymbol{\rho}_{\alpha,m}(s_p)|) f_m(\boldsymbol{\rho}_{\alpha,m}(s_p)) \hat{\mathbf{s}}(f_m(\boldsymbol{\rho}_{\alpha,m}(s_p))) \right]$$

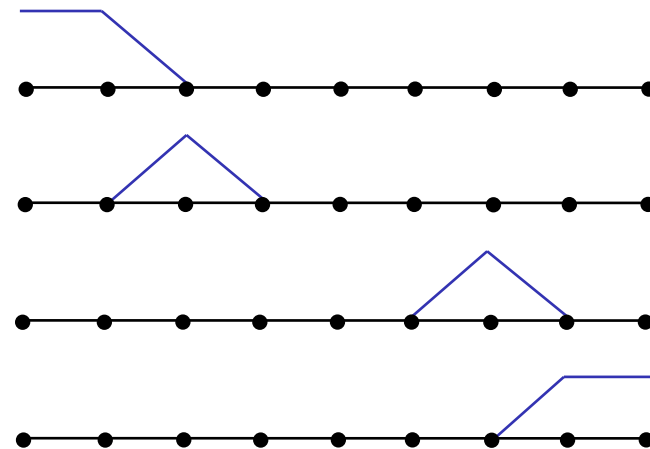


**Figure 11:** Magnitude of scattered electric field **Figure 12:** Magnitude of scattered magnetic field

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**Figure 13:** Example of choice of subcontours



**Figure 14:** Basis functions in TE problem

## ■ Constraint of Current Continuity

$$\begin{bmatrix}
 -1 & 0 & & & & \\
 & \ddots & & & & \\
 & & 0 & 1 & -1 & 0 \\
 & & & \ddots & & \\
 & & & & \ddots & \\
 & & & & & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 x_1^1 \\
 x_2^1 \\
 \vdots \\
 x_{k_1-1}^1 \\
 x_{k_1}^1 \\
 x_1^2 \\
 x_2^2 \\
 \vdots \\
 x_{k_M-1}^M \\
 x_{k_M}^M
 \end{bmatrix}
 = \mathbf{0}$$

In short,

$$\mathbf{B}\mathbf{x} = \mathbf{0}$$

- Equivalent expression of linear system

$$\begin{cases} \mathbf{Z}\mathbf{x} = \mathbf{L} \\ \mathbf{B}\mathbf{x} = \mathbf{0} \end{cases}$$

- For the same purpose, we construct a target function

$$\begin{aligned} \min_{\mathbf{x}} J(\mathbf{x}) &= \frac{1}{2} \mathbf{x}^T \mathbf{Z} \mathbf{x} - \mathbf{x}^T \mathbf{L} \\ \text{s.t. } \mathbf{B} \mathbf{x} &= \mathbf{0} \end{aligned}$$

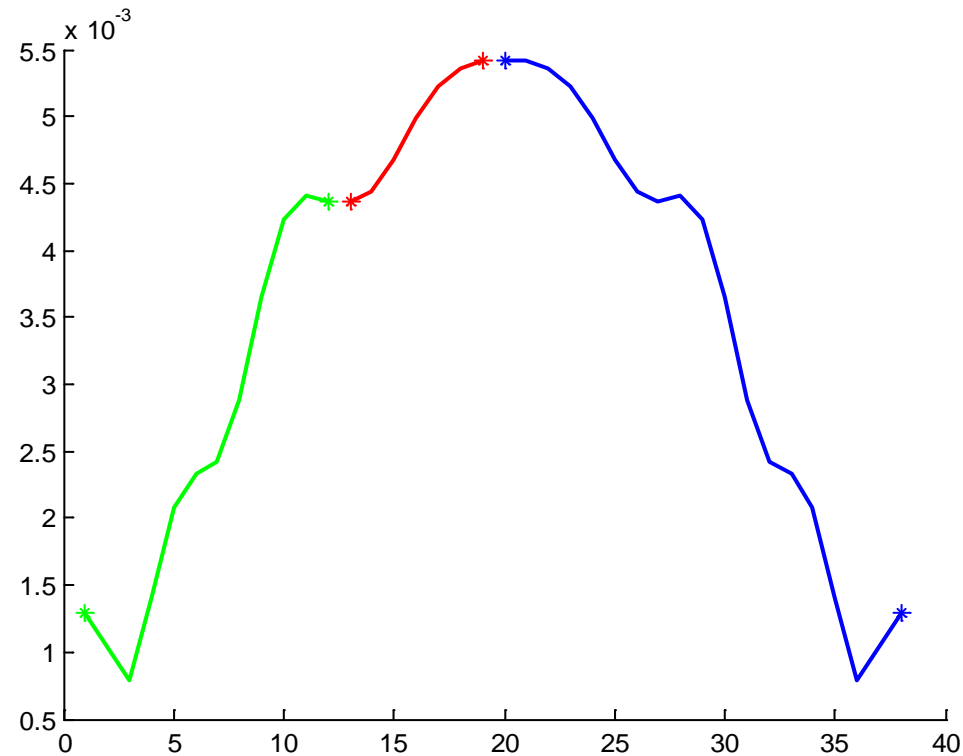
- Apply Lagrange Multiplier, we define the Lagrangian to be

$$I(\mathbf{x}, \boldsymbol{\lambda}) = J(\mathbf{x}) - \boldsymbol{\lambda}^T \mathbf{B} \mathbf{x}$$

- Set the partial derivative to be zero

$$\begin{bmatrix} \mathbf{Z} & -\mathbf{B}^T \\ -\mathbf{B} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{x} \\ \boldsymbol{\lambda} \end{bmatrix} = \begin{bmatrix} \mathbf{L} \\ \mathbf{0} \end{bmatrix}$$





**Figure 15:** Solution to current density  
on the boundary of the 2D transverse in TE problem.

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## ■ Comparison among different methods

Methods	Advantages	Disadvantages
Analytical Method	■ Simple Expression ■ Fast speed	■ Regular boundary
Numerical Method	■ Complicated boundary (e.g. piecewise boundary)	■ Slow speed
Mortar Element Method	■ Fast speed ■ Complicated boundary (e.g. piecewise boundary)	■ Increased error ■ Hardware cost (e.g. GPUs)

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**Thank You**