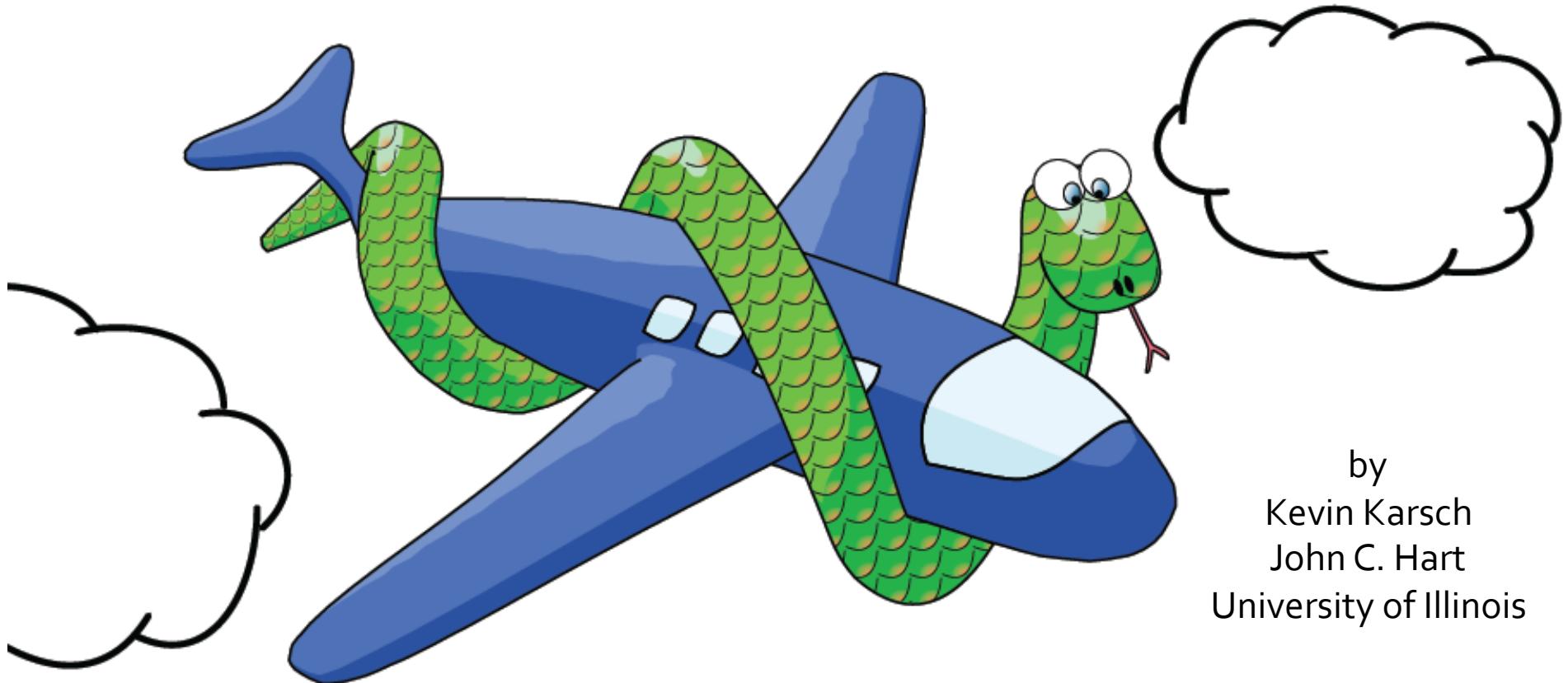


Snaxels on a Plane

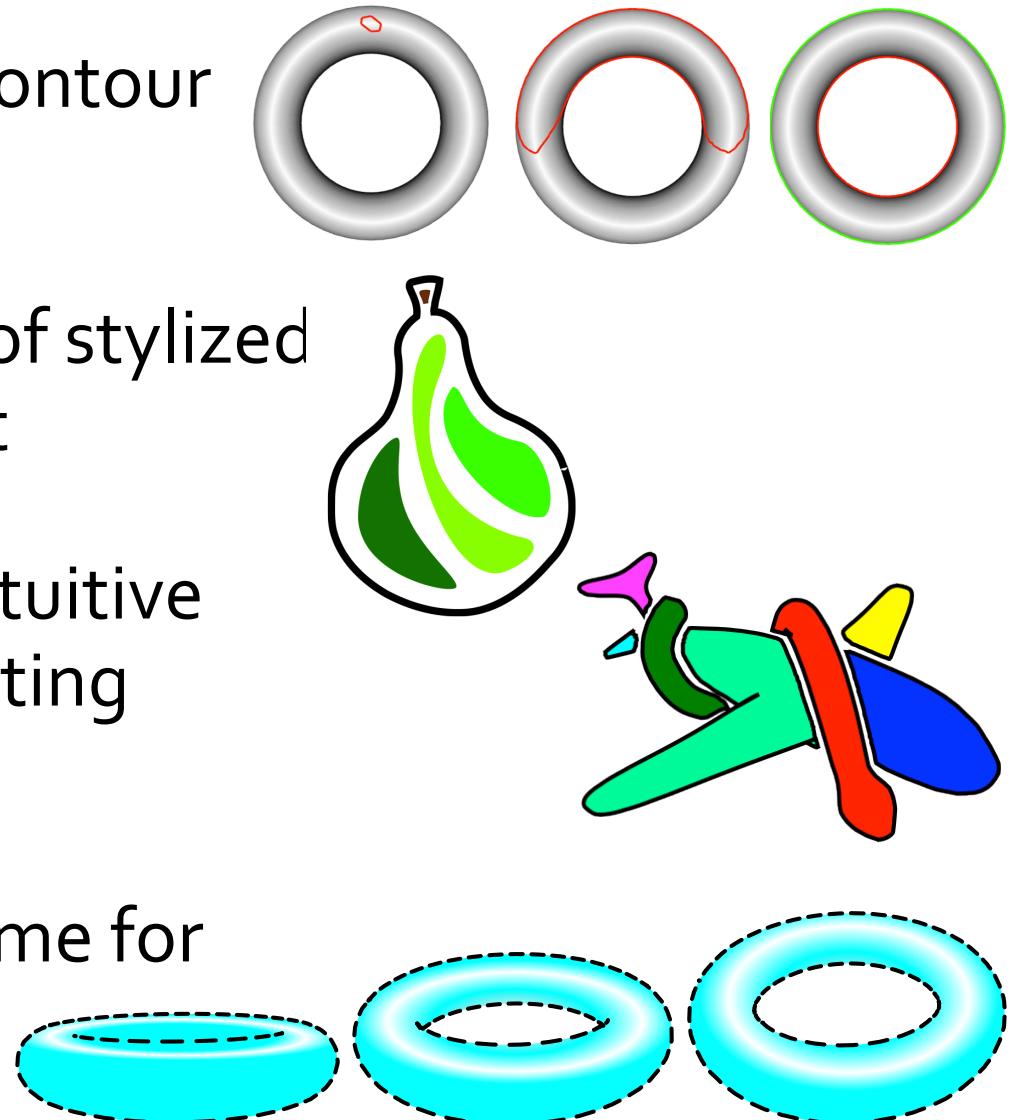


by
Kevin Karsch
John C. Hart
University of Illinois

*"I have had it with these multi-front
snakes on this meshed facet plane!"*

What can snaxels do?

- Robustly find closed contour loops on meshes
- Simplify the creation of stylized (closed region) line art
- Provide a quick and intuitive framework for generating planar maps
- Track contours over time for coherent stylization



Motivation

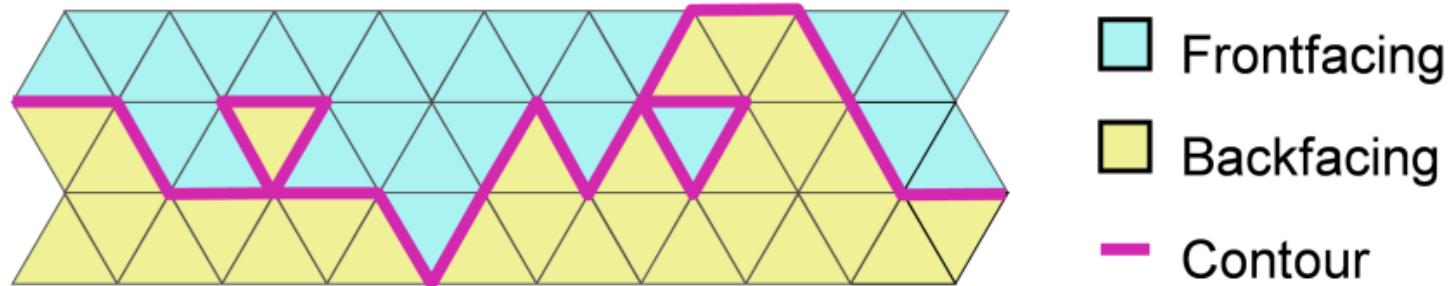
- Extract stylistic edges from meshes
 - Real-Time [Markosian et al. 97]
 - Suggestive Contours [Decarlo et al. 03]
 - Apparent Ridges [Judd & Durand 07]

- Need to link edges into closed loops
 - Hatching [Winkenbach & Salesin 94]
 - Planar maps [Asente et al. 07]
 - Stylization [Grabli et al. 04]
 - Diffusion gradients [Orzan et al. 08]



Motivation

- Tricky to assemble edges into closed loops



From Rusinkiewicz's notes on "Algorithms for Extracting Lines"

- Robust contour loop/planar map extraction is “complicated”
 - Switchbacks, slivers, etc.
 - Robustness and efficiency [Asente et al. 2007]
 - Heavyweight packages (CGAL) [Eisemann et al. 2008]
 - Entire appendix on tolerancing [Eisemann et al. 2009]

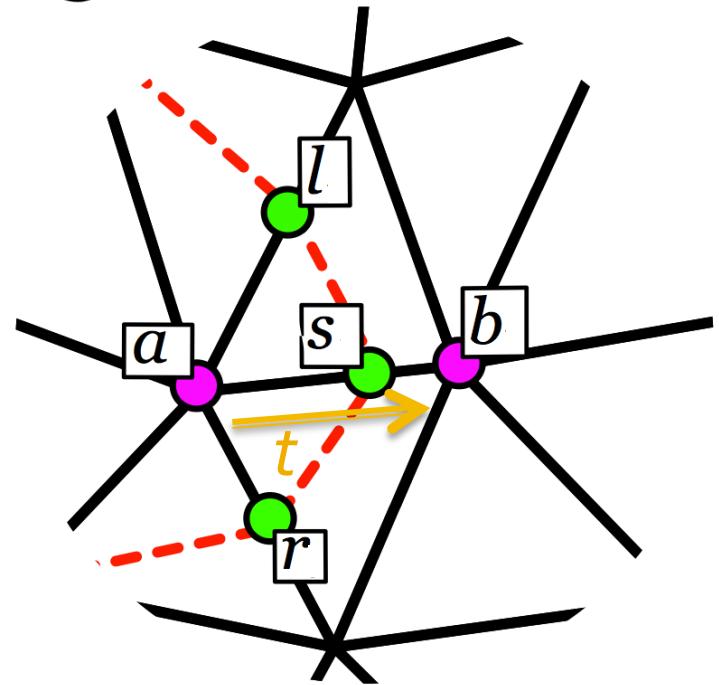
Solution: Active Surface Contours

- Represent closed loop illustration contours with closed loop surface contours
- Meshed surface “snakes”
[Kass et al. 88]
 - Segmenting mesh features
[Jung & Kim 04]
 - Detecting relief on meshes
[Lui et al. 06]
- Easy robust implementation:
“snaxels” [Bischoff et al. 05]



Snaxels [Bischoff et al. 05]

- Active contour is a chain of vertices called “snaxels”
- Each snaxel must lie on a unique mesh edge
- Each snaxel connects to neighbors across face
- Each ring of connected snaxels is called a *front*

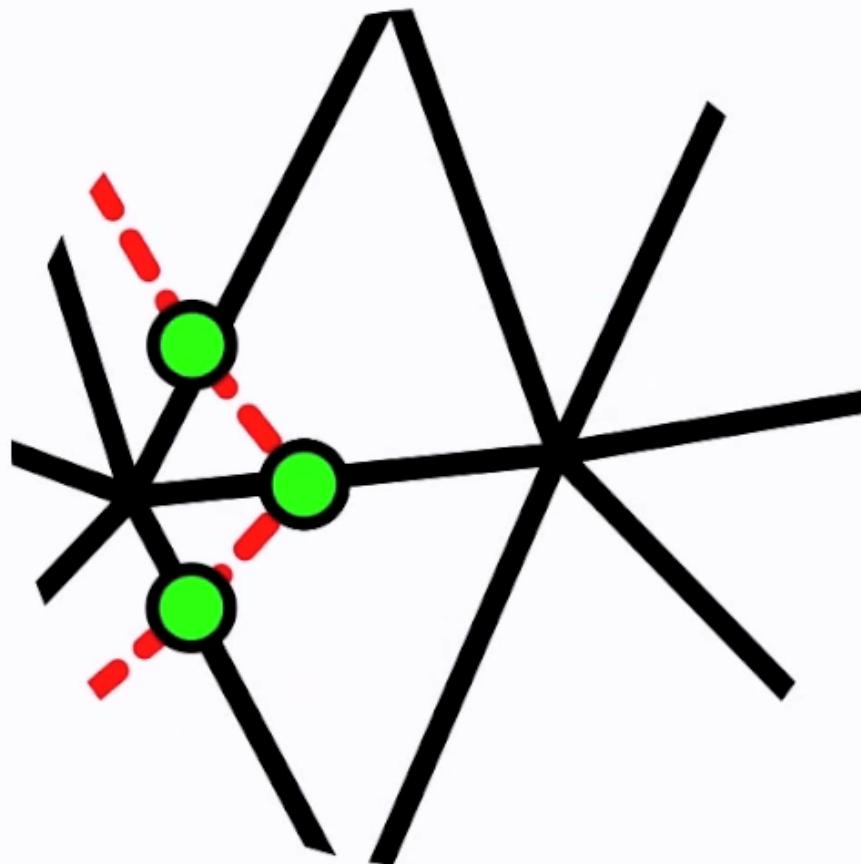


*Snaxel "s" lies
on the edge (a,b)
parameterized by $t \in [0,1]$
with neighbors l and r
in its contour*

$$s = (a, b, t, l, r)$$

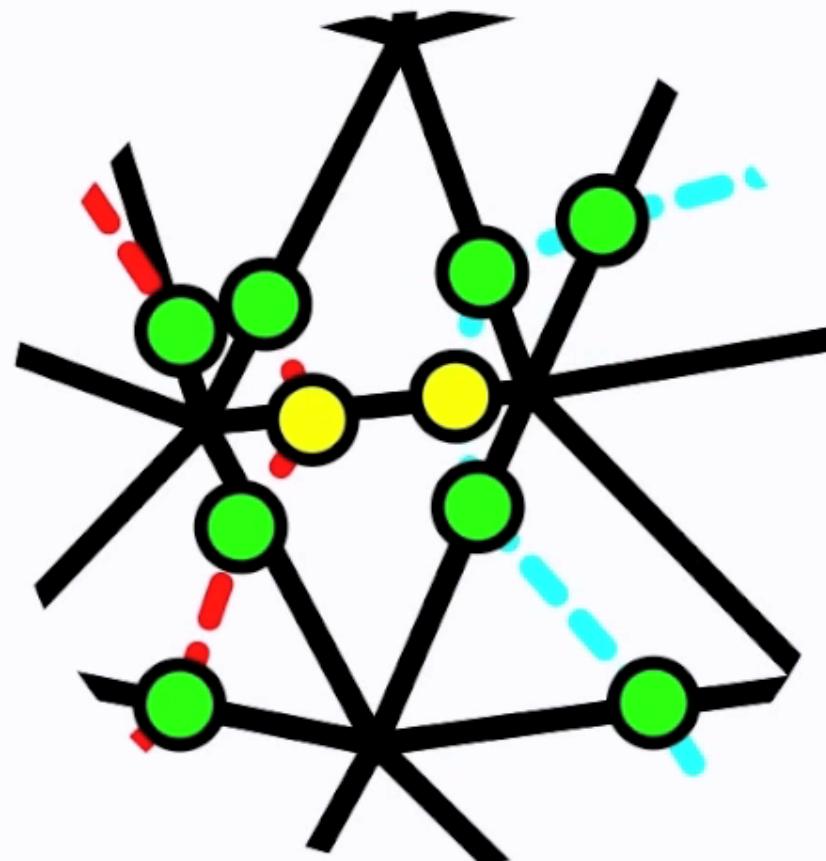
Implementation

- *Fan-out* when a snaxel reaches a vertex



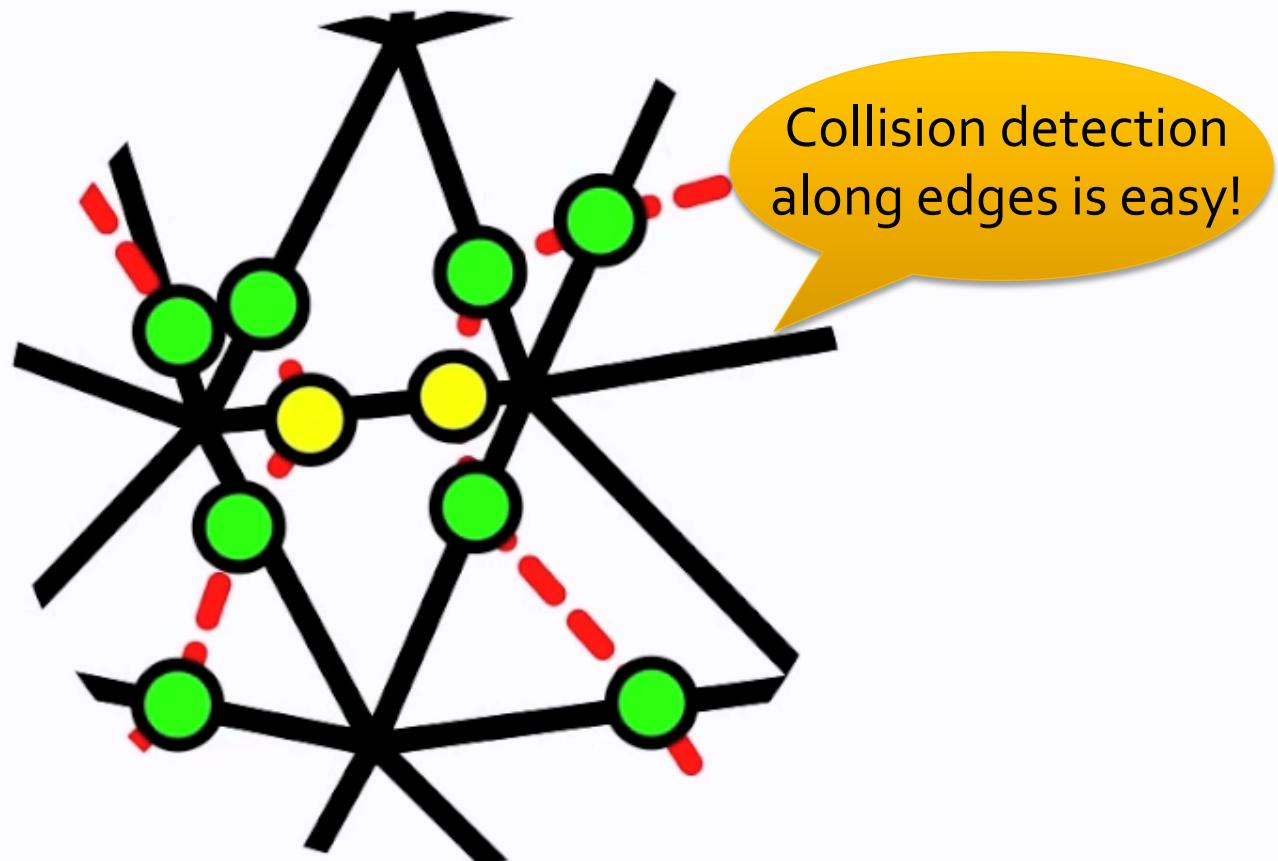
Implementation

- *Merge when two fronts collide*



Implementation

- *Split* when a front intersects itself



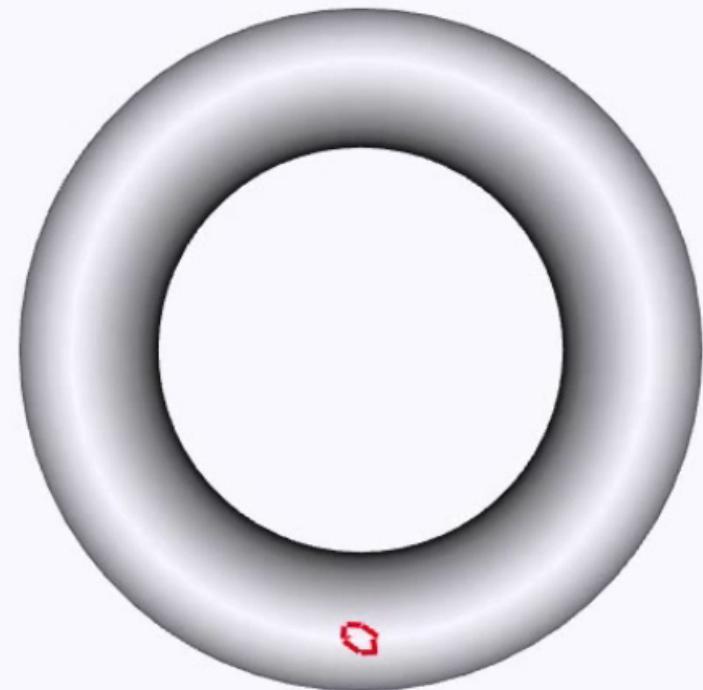
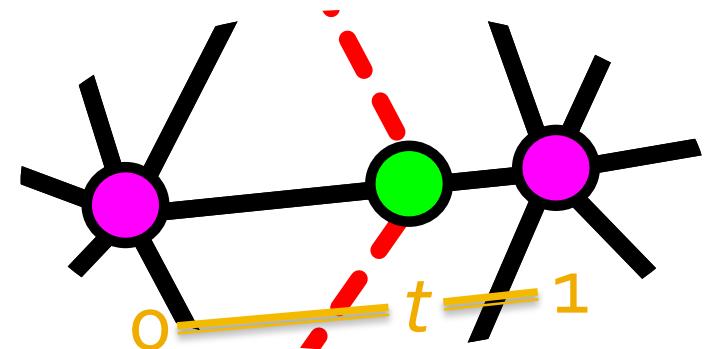
Implementation

- Snaxels minimize f

$$t_i \leftarrow t_i - \frac{\Delta t}{\|b_i - a_i\|} f(s_i)$$

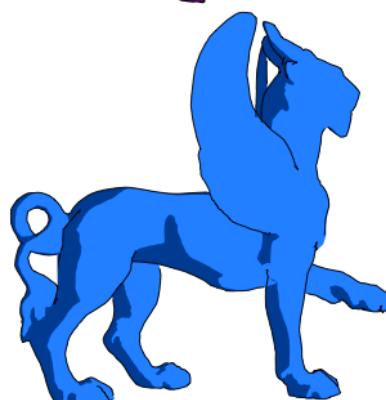
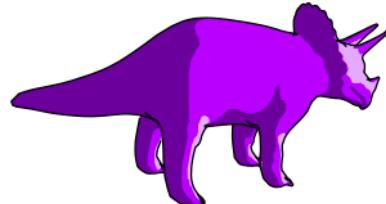
- Energy is based on the desired contour
- Visual contour generator

$$f(s_i) = N_i \cdot V_i$$



Isophotes

- We can also use snaxels to simulate diffuse lighting
 - $f(s_i) = \min(N_i \cdot L_i - k, N_i \cdot V_i)$
 - k is the isovalue of an isophote from a point light

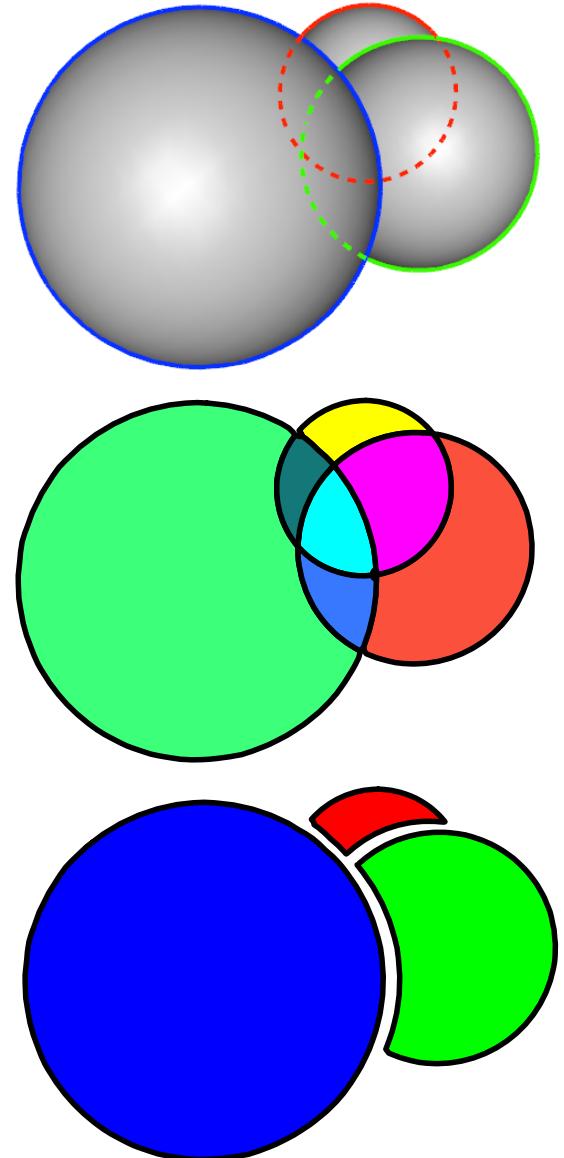


Pseudocode

```
S ← INITIALIZESNAXELS()
while ENERGY(S) > ε
    for  $s_i \in S$ 
         $s_i^p \leftarrow s_i^p - \frac{\Delta t}{\|s_i^{edge}\|} f(s_i)$ 
        Update position  
based on  $f(\cdot)$ 
    S ← HANDLECOLLISIONS( $s_i, S$ )
    PROCESSFORNPR(S)
    Stylize  
contours
    Fan-out, merge,  
split if necessary
```

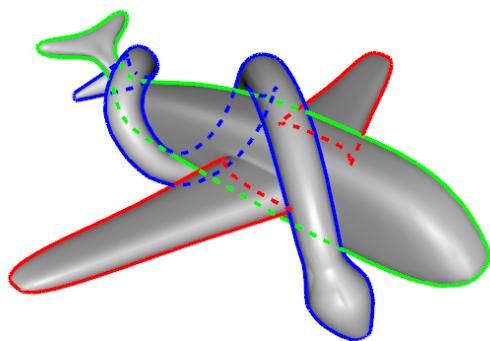
Planar Maps

- Planar graphs, i.e. edges intersect only at vertices
- Planar map organizes overlapping geometric elements into separate planar regions
- Planar map organizes 3-D projection into regions based on quantitative visibility
- NPR primarily interested in visible portions of the planar map

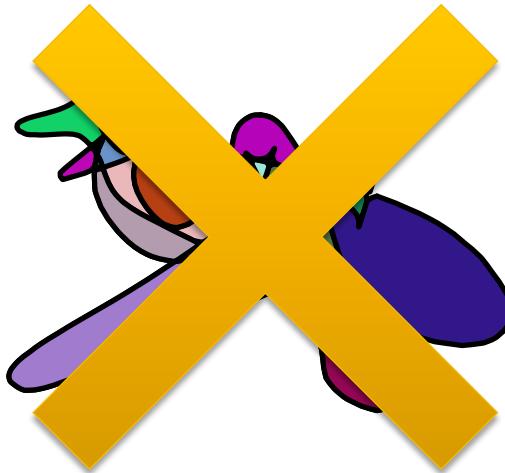


Planar Map Generation

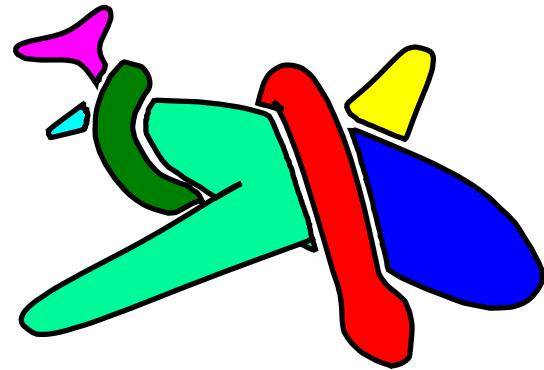
- Snaxels facilitate intuitive and easy implementation
- Avoids expensive processing and imprecise boundaries



Meshed geometry



Post-processed



Snaxel-defined

Planar Map Generation

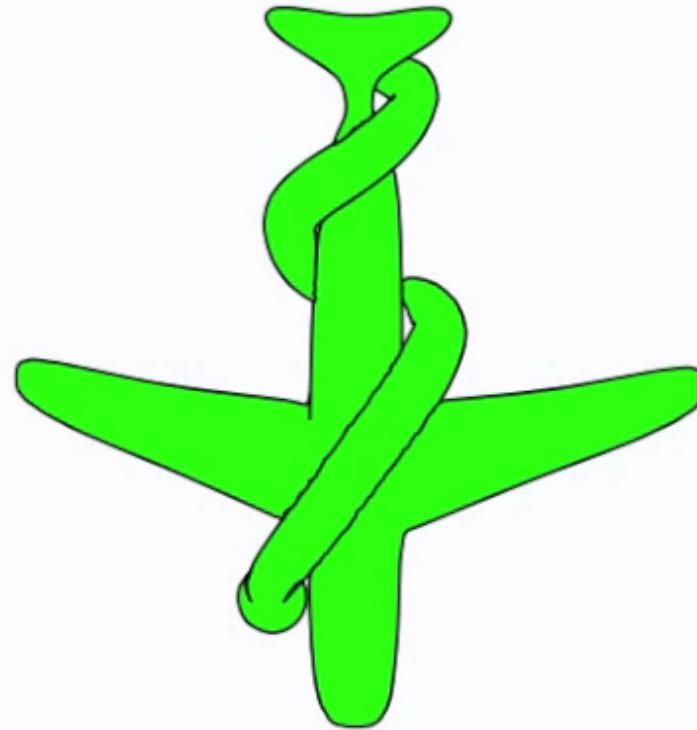
- Planar map generated by a simple addition to the existing snixel framework
 - Snixel fronts cannot overlap in view space
 - Priority given to fronts closer to camera (closer fronts push farther fronts back)

$$f_{pmap}(s_i) = \delta(s_i)f(s_i), \text{ where}$$

$$\delta(s_i) = \begin{cases} 1 & \text{if } s_i \text{ is within a closer front} \\ -1 & \text{otherwise} \end{cases}$$

Planar Map Generation

$$f_{pmap}(s_i) = \delta(s_i)f(s_i)$$



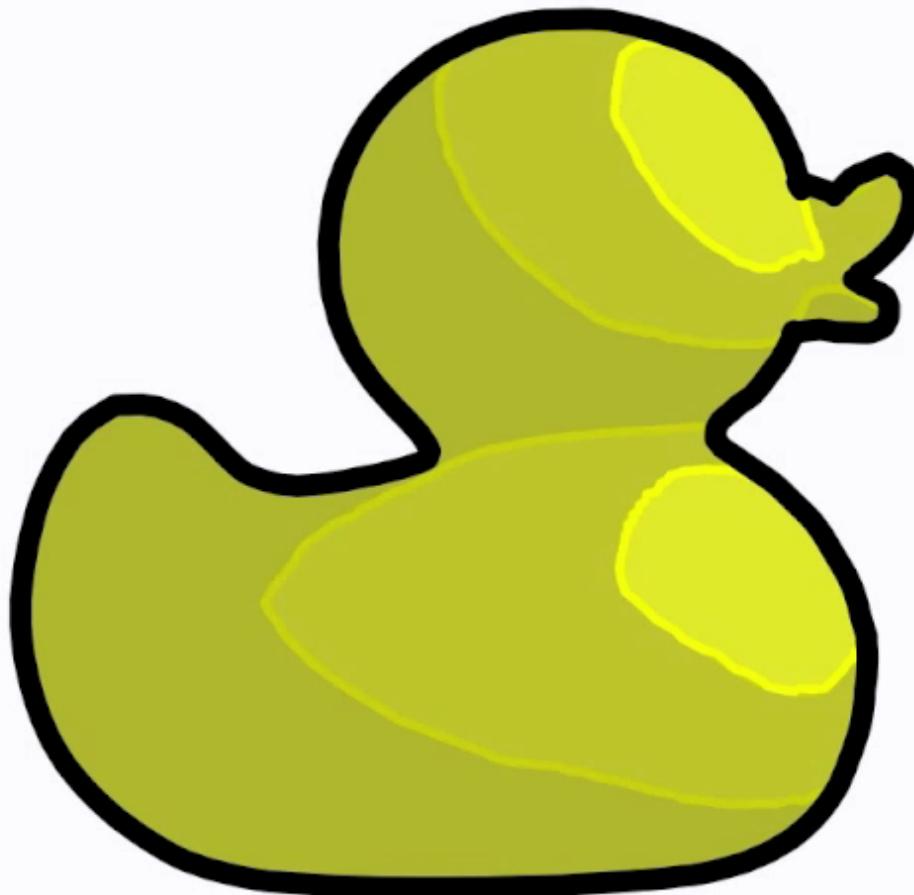
Planar Map Generation

$$f_{pmap}(s_i) = \delta(s_i)f(s_i)$$

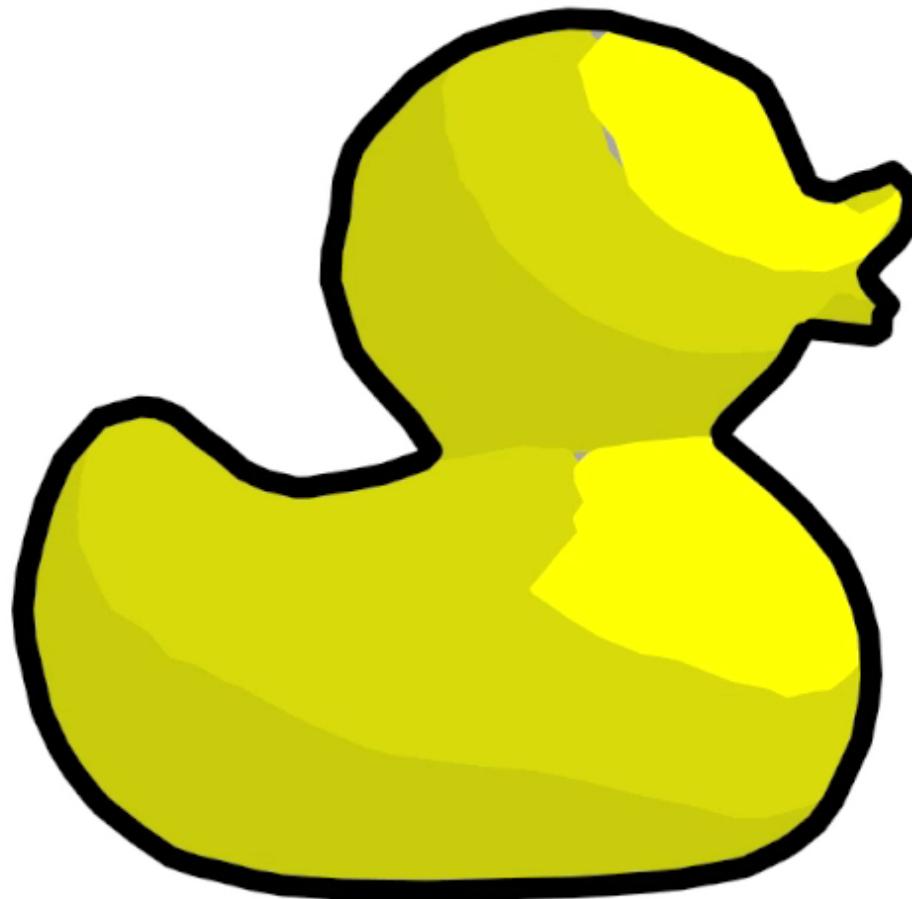


Planar Map Generation

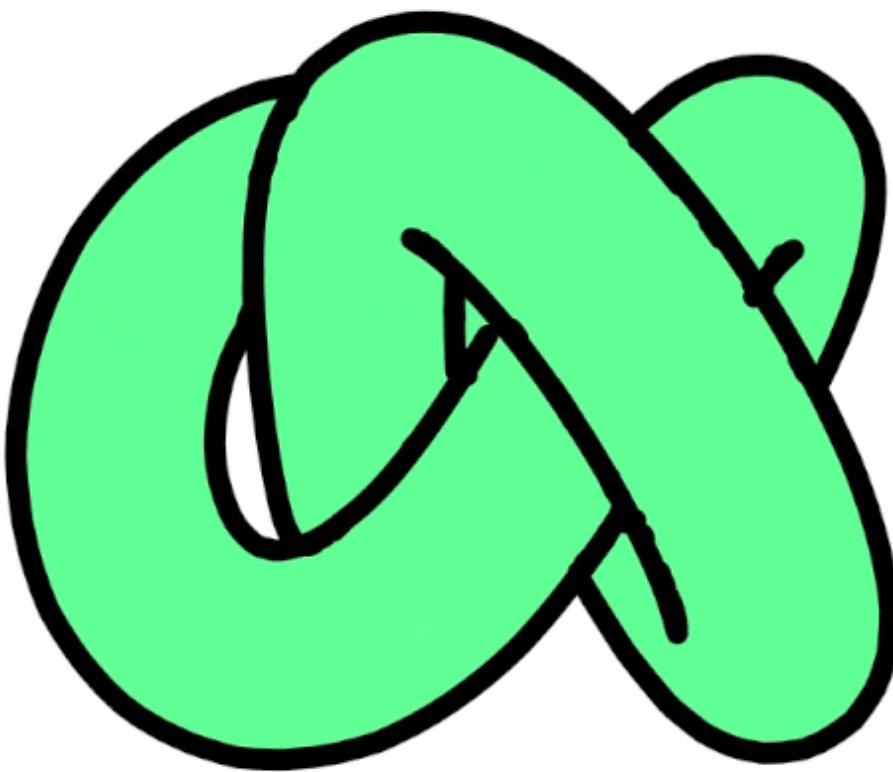
$$f_{pmap}(s_i) = \delta(s_i)f(s_i)$$



Stylized planar maps

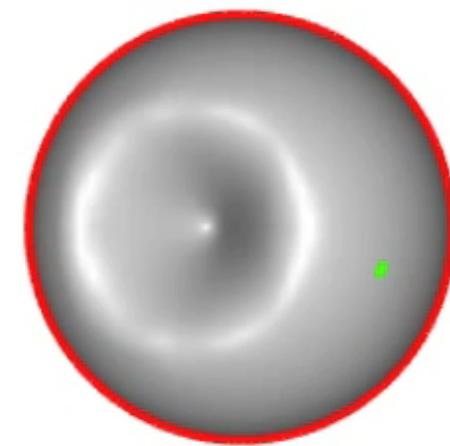


Stylized planar maps



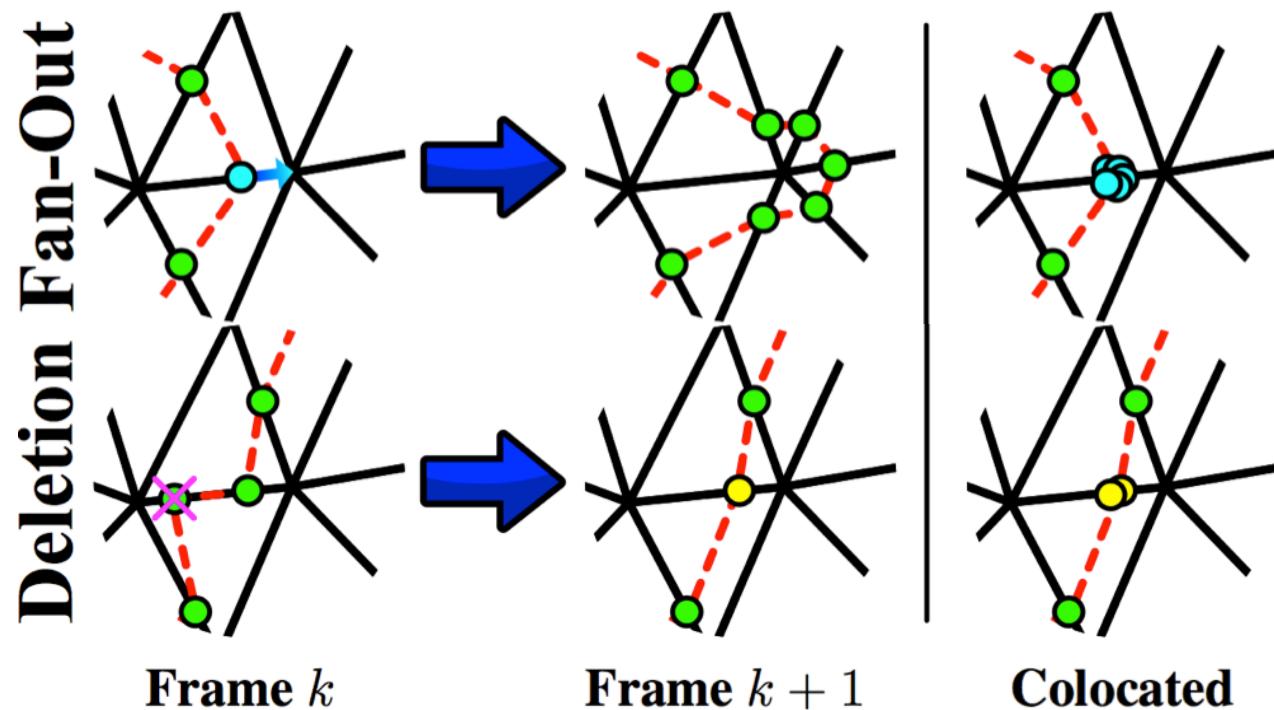
Animated Contours

- Snaxel fronts not only grow into desired surface contours...
- They also track evolving contours as a mesh moves, rotates or changes shape
 - No re-initialization
 - Robust to topology changes



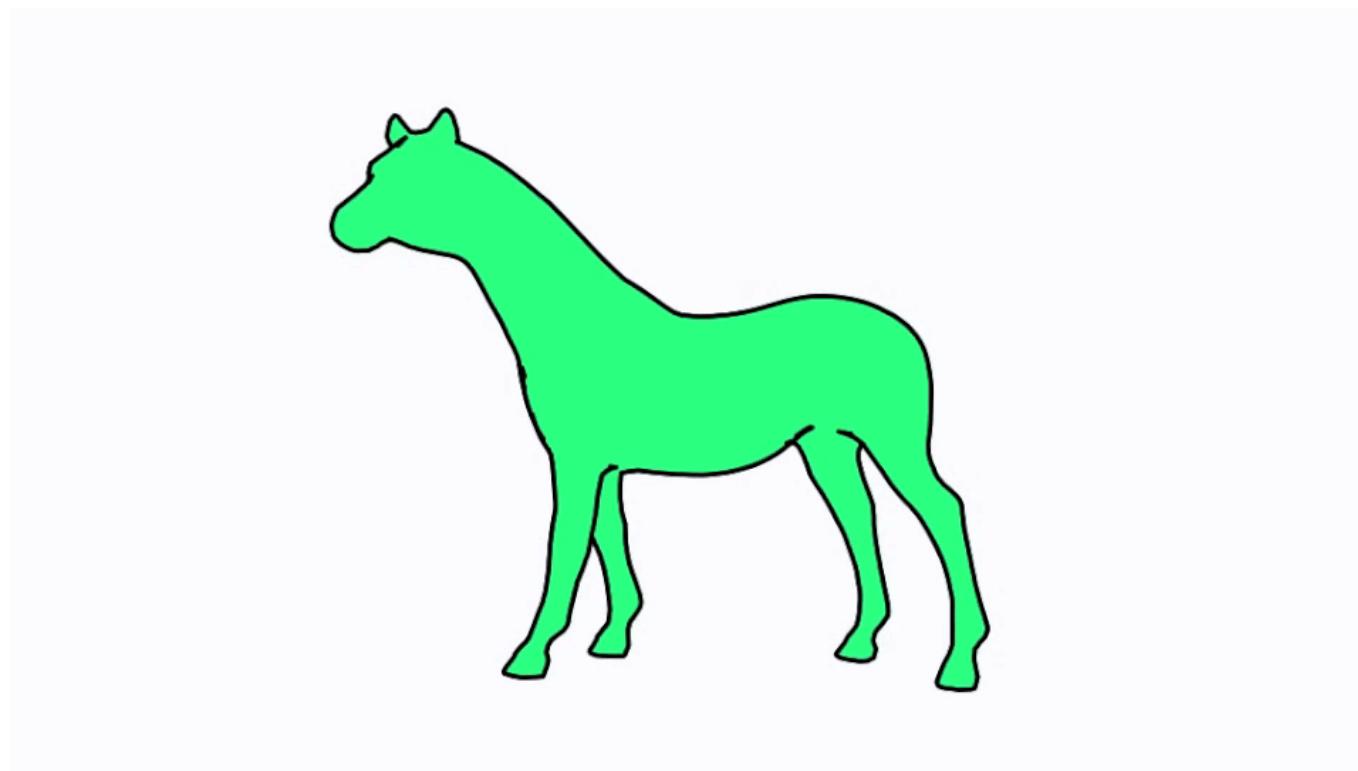
Tracking contours

- Explicit contours provide direct correspondence across frames
- For 1-1 correspondences, each contour must have same number of vertices throughout the animation
 - Changes in contour topology handled by adding colocated snaxels



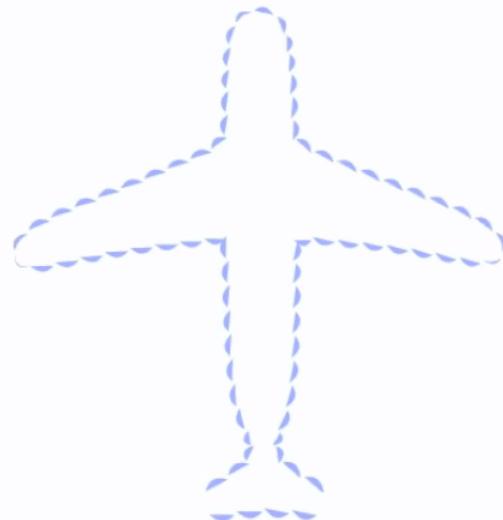
Tracking contours

- Temporal correspondences can be used to
 - Convert mesh animations to animated SVG



Tracking contours

- Temporal correspondences can be used to
 - Convert mesh animations to animated SVG
 - Temporally coherent silhouettes
 - Similar to [Kalnins et al. 2003], but with explicit, closed loop contours



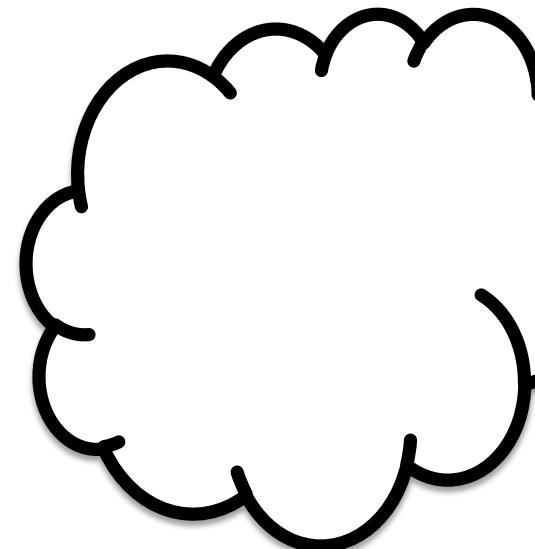
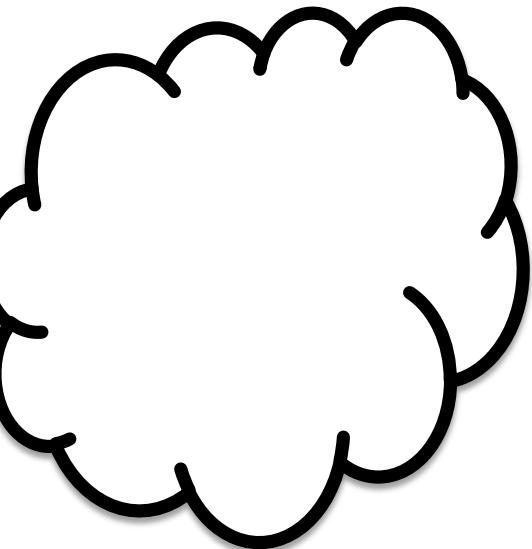
Contributions

- Snaxels for NPR
 - Supports many useful illustrative techniques
 - Easy to implement
 - Highly customizable
- Intuitive planar map scheme
 - Avoids large libraries and complex algorithms
- Efficient contour tracking
 - Useful for 2D SVG animation, coherent stylization

Future work

- Further investigate energy function
 - Curvature/shape constraints
 - Other planar map schemes
- Parallel implementation
 - Fan-out/collision events pose challenges for efficient parallelization
- Bezier contour tracking
 - Simplify/enhance curve animations with higher order curves

Questions?



Thanks!