

The Lorentz Group and Singular Lorentz Transformations

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abstract

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I. THE LORENTZ TRANSFORMATION

In this section the two null directions inherent in all Lorentz transformations, except the singular Lorentz transformations, are illustrated. The Lorentz Transform is defined by

$$(x, y, z, t) \rightarrow (x', y', z', t') \text{ such that}$$

$$x'^2 + y'^2 + z'^2 - t'^2 = x^2 + y^2 + z^2 - t^2$$

If the transformation preserves the orientation of the spatial axes then it is called a proper Lorentz transformation. This is equivalent to saying the transformation does not change the handedness of the axes. Also If $t \geq 0 \Rightarrow t' \geq 0$ then it is called an orthochronous Lorentz transformation. This ensures that the time direction is preserved. In this project the “Lorentz transformation” will refer to the proper, orthochronous Lorentz transformation.

Consider a photon moving in the x direction at the speed of light, $c = 1$, and starting at $x = 0$. The space-time for such a photon can be illustrated as follows (FIGURE). It is clear that there are two null directions in this space-time, $x = \pm t$. To see this use the standard Lorentz transformation:

$$x' = \gamma(x - vt) \text{ , where } \gamma = (1 - v^2)^{-1/2}$$

$$t' = \gamma(t - vx)$$

Rearranging:

$$x' - t' = \gamma(1 + v)(x - t)$$

$$x' + t' = \gamma(1 - v)(x + t)$$

It is clear that:

$$x = \pm t \leftrightarrow x' = \pm t'$$

Thus there are two null directions (are null directions by definition invariant??? yes) in this space-time at $x = \pm t$. It can be shown that all Lorentz transformations have two invariant null directions except the singular Lorentz transformation which has only one fixed null direction.

II. REPARAMETERISATION OF THE SCHWARZSCHILD SOLUTION

In this section the Kasner solution of the vacuum field equations is derived from the Schwarzschild solution by taking the limit as the mass goes to infinity. It is then shown that the special case of the Kasner solution with no mass is equivalent to a novel form of Minkowskian space-time. (what do we want the Kasner vacuum solution for???). Starting with the Schwarzschild Solution of the vacuum field equations:

$$\epsilon ds^2 = \left(1 - \frac{2m}{r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2) - \left(1 - \frac{2m}{r}\right) dt^2 \quad (1)$$

Now make the Eddington-Finkelstein coordinate transformation:

$$u = t - r - 2m \ln(r - 2m) \quad (2)$$

Working out the differential:

$$du = dt - dr - \frac{2m dr}{r - 2m}$$

SEE CALCULATIONS PG1

Then write Eqn.(1) in terms of u to obtain:

$$\epsilon ds^2 = r^2(d\theta^2 + \sin^2\theta d\phi^2) - 2dudr - du^2 + \frac{2m}{r}du^2$$

Note that if $m = 0$ the space-time becomes Minkowskian, as expected. Setting $r = 0$ in this Minkowskian space-time the line element becomes:

$$\epsilon ds^2 = -du^2 \Rightarrow t = -1$$

Which implies that $r = 0$ is a time-like world-line in Minkowskian space-time, with proper time u .(CHECK ITS A GEODESIC???)

We want to find the limit of the Schwarzschild solution as $m \rightarrow \infty$. In its current form, the limit cannot be calculated so first a suitable coordinate transformation must be made.

$$\begin{aligned} u &= \mu u' , \text{ where } \mu = \text{const} \\ r &= \mu^{-1} r' \end{aligned}$$

So that

$$\begin{aligned} du &= \mu du' \\ dr &= \mu^{-1} dr' \\ \Rightarrow dudr &= du' dr' \end{aligned}$$

To obtain (SEE CALCS PG3):

$$\epsilon ds^2 = r'^2 \sin^2 \theta \left\{ \frac{d\theta^2}{\mu^2 \sin^2 \theta} + \mu^{-2} d\phi^2 \right\} - 2du' dr' - \left(\mu^2 - \frac{2m\mu^3}{r'} du' \right)$$

Now set $m\mu^3 = k = \text{const} \Rightarrow m = k\mu^{-3}$ and make another transformation first done by Ivor Robinson(check this???) given by:

$$\sin \theta = \frac{1}{\cosh(\mu\xi)} , \quad \mu^{-1}\phi = \eta \quad (3)$$

Which results in (SEE CALCS PG 3):

$$\epsilon ds^2 = \frac{r^2}{\cosh^2 \mu\xi} (d\xi^2 + d\eta^2) - 2dudr - \left(\mu^2 - \frac{2k}{r} \right) du^2$$

Where the primes have been dropped for notational simplicity. This is now in an appropriate form to take the limit $m \rightarrow \infty$ which is equivalent to $\mu \rightarrow 0$. This limit gives:

$$\epsilon ds^2 = r^2(d\xi^2 + d\eta^2) - 2dudr - \frac{2k}{r} du^2 \quad (4)$$

This is still a solution of the field equations, but it is no longer the Schwarzschild solution. It is found that this is the Kasner solution. To see this (SEE CALCS PG ???):

$$\epsilon ds^2 = T^{-2/3} dX^2 + T^{4/3} (dY^2 + dZ^2) - dT^2 \quad (5)$$

By definition the Kasner solution is given by:

$$\epsilon ds^2 = T^{2p} dX^2 + T^{2q} dY^2 + T^{2r} dZ^2 - dT^2$$

With:

$$p + q + r = 1 = p^2 + q^2 + r^2$$

So it is clear that Eqn.(5) is the Kasner solution with $p = -1/3$ and $q = r = 2/3$.

A. Line Element of Minkowskian Space-Time

Minkowskian space-time reemerges again by setting $k = 0$ in Eqn.(4), which is equivalent to $m = 0$.

$$\epsilon ds^2 = r^2(d\xi^2 + d\eta^2) - 2dudr \quad (6)$$

Setting $r = 0$ it can be shown that $\epsilon ds^2 = 0$ in this case. Then $r = 0$ is a null geodesic with u an affine parameter along it. To demonstrate these properties first let $x^i = (x, y, z, t)$ be rectangular Cartesian coordinates with time in Minkowskian space-time with the usual line element:

$$\epsilon ds_0^2 = dx^2 + dy^2 + dz^2 - dt^2$$

We note that $C : x = 0, y = 0, z = t$ is a null geodesic as it will lie in the light cone of Minkowskian space-time. it we write it parametrically as $x^i = w^i(u)$ such that $w^i = (0, 0, u, u)$ then u is an affine parameter along C . The tangent to C is then computed as:

$$v^i(u) = \frac{dw^i}{du} = (0, 0, 1, 1)$$

As C is a null geodesic the first integral will be $v_i v^i = 0$ (IS THIS CALLED THE FIRST INTEGRAL?) and thus $v_i = (0, 0, 1, -1)$ where we have chosen the convention $(+, +, +, -)$.

The position vector of a point in Minkowskian space time can be written in the form(DO THE PICTURE FROM 2:1):

$$\begin{aligned} x^i &= w^i(u) = rk^i \\ \text{or } x^i &= w^i(u) + rk^i \end{aligned}$$

Thus r is a new parameter which tell us the shortest distance between C and some point x^i , and k^i is the unit vector in that direction. As k^i is a unit vector it satisfies the realtions:

$$k^i k_i = 0 \quad (7)$$

$$k^i v_i = -1 \quad (8)$$

Thus k^i is normalized so that k^i and v^i are both future pointing (HOW DOES THIS MAKE THEM BOTH FUTURE POINTING?). Making the parameterisation:

$$\begin{aligned} k^i &= (\xi, \eta, A, B) \\ \Rightarrow k_i &= (\xi, \eta, A, -B) \end{aligned}$$

We can choose any variable for the first two slots of k^i so we choose ξ and η from before for convenience. Using the relation (7) it is clear that:

$$\xi^2 + \eta^2 + A^2 - B^2 = 0$$

and using the relation (8) it is found that:

$$A - B = -1 \quad (9)$$

$$\Rightarrow A^2 - B^2 = (A + B)(A - B) = -(A + B) \quad (10)$$

Which implies:

$$\xi^2 + \eta^2 = A + B \quad (11)$$

So expressions for A and B are found using Eqn.(9) and Eqn.(11):

$$A = \frac{1}{2}(-1 + \xi^2 + \eta^2)$$

$$B = \frac{1}{2}(1 + \xi^2 + \eta^2)$$

In summary so far we have:

$$x^i = w^i(u) + rk^i \quad (12)$$

$$w^i = (0, 0, u, u) \quad (13)$$

$$k^i = (\xi, \eta, \frac{1}{2}(-1 + \xi^2 + \eta^2), \frac{1}{2}(1 + \xi^2 + \eta^2)) \quad (14)$$

$$x^i = (x, y, z, t) \quad (15)$$

Consider Eqn.(12) as a coordinate transformation from (x, y, z, t) to (ξ, η, r, u) such that:

$$x = r\xi$$

$$y = r\eta$$

$$z = u + \frac{r}{2}(-1 + \xi^2 + \eta^2)$$

$$t = u + \frac{r}{2}(1 + \xi^2 + \eta^2) \quad (16)$$

as is clear from Eqn.(12) - Eqn.(15). Now this is applied to the Minkowskian line element Eqn.(6). First, the x and y differentials are:

$$dx = rd\xi + \xi dr$$

$$dy = r d\eta + \eta dr$$

Which gives:

$$dx^2 + dy^2 = r^2(d\xi^2 + d\eta^2) + 2r\xi d\xi dr + 2r\eta d\eta dr + (\xi^2 + \eta^2)dr^2 \quad (17)$$

Next, the z and t differentials:

$$z + t = 2u + r(\xi^2 + \eta^2)$$

$$z - t = -r$$

$$dz + dt = 2du + (\xi^2 + \eta^2)dr + 2r\xi d\xi + 2r\eta d\eta$$

$$dz - dt = -dr$$

Using difference of two squares to obtain:

$$dz^2 - dt^2 = -2dudr - (\xi^2 + \eta^2)dr^2 - 2r\xi d\xi dr - 2r\eta d\eta dr \quad (18)$$

Combining Eqn.(17) and (18) to get:

$$dx^2 + dy^2 + dz^2 - dt^2 = r^2(d\xi^2 + d\eta^2) - 2dudr$$

and from this it is clear that Eqn.(6) is the line element of Minkowskian space-time with $r = 0$ a null geodesic with affine parameter u along it as before.

III. THE SINGULAR LORENTZ TRANSFORMATION

In this section a Lorentz transformation that leaves our line element Eqn.(6) invariant is constructed. This transformation is then expressed in terms of (x, y, z, t) and examined to see what for it has. First we define an arbitrary complex parameter by $\zeta = \xi + i\eta$ so that the differentials are given by:

$$\begin{aligned} d\zeta &= d\xi + i d\eta \\ d\bar{\zeta} &= d\bar{\xi} + i d\bar{\eta} \end{aligned}$$

and the line element can be rewritten as:

$$\epsilon ds^2 = r^2 d\zeta d\bar{\zeta} - 2du dr$$

In this form the transformation $\zeta \rightarrow \zeta + w$, where $w \in \mathbb{C}$, is trivial. It leaves the line element unchanged and the null geodesic $r = 0$ trivially invariant. This is a Lorentz transformation which leaves one null direction invariant. Therefore it is a two real parameter, singular Lorentz transformation, where the two parameters come from the complex variable w . With this form of the line element the transformation is obviously trivial, we now want to see what this transformation looks like in terms of the usual variables (x, y, z, t) .

First we invert the transformation (??) and use the new variable ζ :

$$\begin{aligned} x + iy &= r(\xi + i\eta) = r\zeta \\ z &= u + \frac{r}{2}(-1 + \zeta\bar{\zeta}) \\ t &= u + \frac{r}{2}(1 + \zeta\bar{\zeta}) \end{aligned}$$

From this it is clear that:

$$\begin{aligned} t - z &= r, \text{ and} \\ t + z &= 2u + r\zeta\bar{\zeta} \end{aligned}$$

So finally:

$$\begin{aligned} \zeta &= \frac{x + iy}{t - z} \\ r &= t - z \\ u &= \frac{1}{2}(t + z) - \frac{(x^2 + y^2)}{2(t - z)} \end{aligned}$$

Now make the desired transformation:

$$\begin{aligned} \zeta' &\rightarrow \zeta + w \\ \bar{\zeta}' &\rightarrow \bar{\zeta} + \bar{w} \\ r' &= r \\ u' &= u \end{aligned}$$

(SEE NOTES PG 2:6 FOR CALC)

To obtain:

$$x' + iy' = x + iy + w(t - z) \tag{19}$$

$$z' - t' = -r = z - t \tag{20}$$

$$z' + t' = z + t + w(x - iy) + w(x + iy) + w\bar{w}(t - z) \tag{21}$$

Next, it is necessary to show that this is indeed a Lorentz transformation by verifying the usual Lorentz invariant quantity. First from Eqn.(19) implies:

$$\begin{aligned} x'^2 + y'^2 &= (x + iy + w(t - z))(x - iy + \bar{w}(t - z)) \\ &= x^2 + y^2 + \bar{w}(t - z)(x + iy) + w(t - z)(x - iy) + w\bar{w}(t - z)^2 \end{aligned}$$

Then Eqn.(20) and Eqn.(21) imply:

$$\begin{aligned} (z' + t')(z' - t') &= z'^2 - t'^2 \\ &= z^2 - t^2 + (z - t)w(x - iy) + (z - t)\bar{w}(x + iy) + (z - t)w\bar{w}(t - z) \end{aligned}$$

Thus the Lorentz invariant quantity in the primed frame is the same as that of the unprimed frame:

$$x'^2 + y'^2 + z'^2 - t'^2 = x^2 + y^2 + z^2 - t^2$$

It is also clear from Eqn.(20) that the null direction $z = t$ is invariant under this Lorentz transformation.

In conclusion, this transformation involves one complex parameter and thus two real parameters. In the usual Cartesian coordinates it is described by Eqns.(19) - (21) and in the coordinates (ξ, η, r, u) (SHOULD THIS NOT BE WITH A ζ ???) derived in previous sections, it is expressed simply as:

$$\begin{aligned} \zeta' &= \zeta + w \\ r' &= r \\ u' &= u \end{aligned}$$

Note that the operation of addition of complex numbers is commutative so that:

$$\begin{aligned} \zeta' &= \zeta + w_1, \text{ and } \zeta'' = \zeta' + w_2 \\ \Rightarrow \zeta'' &= \zeta + w_1 + w_2 \end{aligned}$$

and thus these transformations form a 2-parameter abelian subgroup of the Lorentz group with the binary operation of addition of complex numbers. (SHOW ALL 2 PARAM ABELIAN SUBGROUPS OF THE LORENTZ GROUP ARE SINGULAR TRANSFORMATIONS???)

IV. SPECIAL LINEAR MATRICES OF THE LORENTZ TRANSFORMATION

Let $\vec{x} = (x, y, z, t)$ be the position vector of a point in minkowskian space-time. Knowing \vec{x} we can construct the following 2×2 hermitian matrix:

$$A = \begin{pmatrix} t - z & x + iy \\ x - iy & t + z \end{pmatrix} \quad (22)$$

with $A^\dagger(\vec{x}) = A(\vec{x})$. This is useful as its determinant is the same as the usual lorentz invariant quantity(WHAT DO WE CALL THIS???)

$$\det(A(\vec{x})) = t^2 - x^2 - y^2 - z^2$$

Consider any 2×2 hermitian matrix H .

$$H = \begin{pmatrix} p & q \\ r & s \end{pmatrix}, \quad H^\dagger = \begin{pmatrix} \bar{p} & \bar{q} \\ \bar{r} & \bar{s} \end{pmatrix}$$

It is known that $H^\dagger(\vec{x}) = H(\vec{x})$ so it is clear that $p = \bar{p}$ and $s = \bar{s}$ and thus $p, s \in \mathbb{R}$. Also $q = \bar{r}$ and then of course $\bar{q} = r$. Hence knowing p, q, r and s is equivalent to knowing 4 real numbers, two from p and two from q . From these parameters the coordinates (x, y, z, t) of a point in Minkowskian space-time can be constructed as:

$$x + iy = q = \bar{r}, t - z = p, t + z = s$$

by comparing with matrix A above. Hence it is true that there is a one to one correspondence between points in Minkowskian space-time and 2×2 hermitian matrices.

Construct the following matrix:

$$U = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$$

with $\alpha, \beta, \gamma, \delta \in \mathbb{C}$. With the condition that $\det(U) = 1$. Such matrices U form a group called the special linear group, which is denoted by $SL(2, \mathbb{C})$. Given $A(\vec{x})$ consider $UA(\vec{x})U^\dagger$. This is a 2×2 hermitian matrix since:

$$\begin{aligned} cl(UA(\vec{x})U^\dagger)^\dagger &= (U^\dagger)^\dagger A^\dagger(\vec{x})U^\dagger \\ &= UA(\vec{x})U^\dagger \end{aligned}$$

since $(U^\dagger)^\dagger = U$ and $A^\dagger = A$. Hence there exists a point $\vec{x}' = (x', y', z', t')$ in minkowskian space-time for which:

$$A(\vec{x}') = UA(\vec{x})U^\dagger \quad (23)$$

Any U involves 6 real parameters, 2 each from the four complex components, with the condition $\det(U) = 1$ supplying two constraints. One on the real parts and one on the imaginary parts of the components. Now calculate the determinant of the matrix in the primed frame

$$\begin{aligned} \det(A(\vec{x}')) &= \det(UA(\vec{x})U^\dagger) \\ &= (\det(U))(\det(A(\vec{x}))) (\det(U^\dagger)) \\ &= (\det(U))(\det(A(\vec{x}))) (\det(U)) \\ &= \det(A(\vec{x})) \end{aligned}$$

Thus we have the relation:

$$t'^2 - x'^2 - y'^2 - z'^2 = t^2 - x^2 - y^2 - z^2$$

Hence the transformation $\vec{x} \rightarrow \vec{x}'$ implicit in Eqn.(23) is a Lorentz transformation. Eqn.(23) describes the most general proper, orthochronous Lorentz transformation.

It is useful to calculate the matrix U for some examples of Lorentz transformations. First, write Eqn.(23) in terms of its components:

$$\begin{aligned} \begin{pmatrix} t' - z' & x' + iy' \\ x' - iy' & t' + z' \end{pmatrix} &= \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \begin{pmatrix} t - z & x + iy \\ x - iy & t + z \end{pmatrix} \begin{pmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{pmatrix} \\ &= \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \begin{pmatrix} (t - z)\bar{\alpha} + (x + iy)\bar{\beta} & (t - z)\bar{\gamma} + (x + iy)\bar{\delta} \\ (x - iy)\alpha + (t + z)\beta & (x - iy)\gamma + (t + z)\delta \end{pmatrix} \end{aligned}$$

Thus we have the relations:

$$t' - z' = (t - z)\alpha\bar{\alpha} + (x + iy)\alpha\bar{\beta} + (x - iy)\beta\bar{\alpha} + (t + z)\beta\bar{\beta} \quad (23a)$$

$$x' + iy' = (t - z)\alpha\bar{\gamma} + (x + iy)\alpha\bar{\delta} + (x - iy)\beta\bar{\gamma} + (t + z)\beta\bar{\delta} \quad (23b)$$

$$t' + z' = (t - z)\gamma\bar{\gamma} + (x + iy)\gamma\bar{\delta} + (x - iy)\delta\bar{\gamma} + (t + z)\delta\bar{\delta} \quad (23c)$$

A. Example 1: (NAME????)

Find U 23a23b23c corresponding to the one parameter Lorentz transformation:

$$\begin{aligned}x' &= x \cos \theta + y \sin \theta \\y' &= -x \sin \theta + y \cos \theta \\z' &= z \\t' &= t\end{aligned}$$

This implies that:

$$\begin{aligned}t' - z' &= t - z \\x' + iy' &= (x + iy)e^{-i\theta} \\t' + z' &= t + z\end{aligned}$$

Equating coefficients of x, y, z, t on both sides of Eqn.(23a) to obtain: (SEE CALS)

B. Example 2: Special Relativity Lorentz Transformation

(CALCS)

C. Example 3: Singular Lorentz Transformation

(CALCS)

It is clear that there will always be two matrices $\pm U$ corresponding to every Lorentz transformation, since if U satisfies $A(\vec{x}') = UA(\vec{x})U^\dagger$ then so does $-U$. Hence there is a 2 to 1 correspondence between the elements of $SL(2, \mathbb{C})$ and the proper orthochronous Lorentz transformation.

V. STEREOGRAPHIC PROJECTION AND THE EXTENDED COMPLEX PLANE

Stereographic projection is the mapping of points on a sphere to points on a plane. In \mathbb{R}^3 with rectangular cartesian coordinates, x, y, z , consider the unit sphere with centre $(0, 0, 0)$, defined by

$$\mathbb{S}^2 \subset \mathbb{R}^3 : x^2 + y^2 + z^2 = 1.$$

(SEE FIG PG 4:1) $Q = Q(X, Y, 0)$

The projection $P \rightarrow Q$ is a stereographic projection. A relationship between X, Y and (x, y, z) is constructed as follows. P is subdivided into the line segment NQ in some ratio, $l : m$ say. By coordinate geometry

$$\begin{aligned}x &= \frac{lX + mO}{l + m} = \frac{lX}{l + m}, \\y &= \frac{lY + mO}{l + m} = \frac{lY}{l + m}, \\z &= \frac{l \cdot 0 + m \cdot 1}{l + m} = \frac{m}{l + m}.\end{aligned}$$

This implies that

$$\begin{aligned}1 - z &= \frac{l}{l + m}, \\x &= (1 - z)X, \\y &= (1 - z)Y.\end{aligned}$$

It is also known that $x^2 + y^2 + z^2 = 1$, so using this relation it is clear that

$$\begin{aligned} x^2 + y^2 &= 1 - z^2 = (1 - z)(1 + z) \\ \Rightarrow (1 - z^2)(X^2 + Y^2) &= (1 - z)(1 + z) \end{aligned}$$

If the point N is excluded, i.e. $z \neq 1$ then dividing by $(1 - z)^2$ to obtain

$$X^2 + Y^2 = \frac{1 + z}{1 - z}.$$

Rearranging to find that

$$z = \frac{X^2 + Y^2 - 1}{X^2 + Y^2 + 1} \quad (24)$$

Define $\zeta = X + iY$ and rewrite Eqn.(24) to see that

$$z = \frac{\zeta \bar{\zeta} - 1}{\zeta \bar{\zeta} + 1},$$

Which implies that

$$1 - z = \frac{2}{\zeta \bar{\zeta} + 1}.$$

So relations for $(x, y, z) \in \mathbb{S}^2 \setminus \{N\}$ have been obtained in terms of ζ .

$$x + iy = \frac{2\zeta}{\zeta \bar{\zeta}}, \quad (25)$$

$$zz = \frac{\zeta \bar{\zeta} - 1}{\zeta \bar{\zeta} + 1}. \quad (26)$$

Hence the points on $\mathbb{S}^2 \setminus \{N\}$ are labelled by complex numbers $\zeta \in \mathbb{C}$. If a point $\zeta = \infty$, called the point at infinity of \mathbb{C} , is allowed then the following limits hold:

$$\begin{aligned} x + iy &= \frac{2/\bar{\zeta}}{1 + 1/\zeta \bar{\zeta}} \rightarrow 0, \text{ as } \zeta \rightarrow \infty \\ z &= \frac{1 - 1/\zeta \bar{\zeta}}{1 + 1/\zeta \bar{\zeta}} \rightarrow 1, \text{ as } \zeta \rightarrow \infty \end{aligned}$$

Then $N = (0, 0, 1)$ corresponds to $\zeta = \infty$. Thus in this way there is a one to one correspondence between the points of \mathbb{S}^2 and the points of the *extended complex plane* $\hat{\mathbb{C}} = \mathbb{C} \cup \infty$, which is the usual complex plane with the point at infinity added. Since \mathbb{S}^2 has finite surface area, and is therefore called a *compact manifold*, the identification of the points of $\hat{\mathbb{C}}$ with the points of \mathbb{S}^2 is called the *compactification* of $\hat{\mathbb{C}}$.

$(\zeta, \bar{\zeta})$ are called the *stereographic coordinates* on $\mathbb{S}^2 \setminus \{N\}$. How are they related to the polar angles θ and ϕ ? To investigate this write the usual spherical polar coordinates in terms of ζ . First it is known that

$$\begin{aligned} x &= \sin \theta \cos \phi, \\ y &= \sin \theta \sin \phi, \\ z &= \cos \theta. \end{aligned}$$

So using Eqn.(25) it is easy to show that

$$\begin{aligned}
\cos \theta &= \frac{\zeta \bar{\zeta} - 1}{\zeta \bar{\zeta} + 1} \\
\Rightarrow \zeta \bar{\zeta} \cos \theta + \cos \theta &= \zeta \bar{\zeta} - 1 \\
\Rightarrow \zeta \bar{\zeta} &= \frac{1 + \cos \theta}{1 - \cos \theta} = \frac{2 \cos^2(\theta/2)}{2 \sin^2(\theta/2)} \\
&\Rightarrow \zeta \bar{\zeta} = \cot^2(\theta/2).
\end{aligned}$$

Now using Eqn.(26) to obtain:

$$\begin{aligned}
\sin \theta (\cos \phi + i \sin \phi) &= \frac{2\zeta}{\cot^2(\theta/2)}, \\
2 \sin(\theta/2) \cos(\theta/2) e^{i\phi} &= 2\zeta \sin^2(\theta/2), \\
&\Rightarrow \zeta = e^{i\phi} \cot(\theta/2).
\end{aligned}$$

This makes sense as it is clear that if $\zeta = \infty$ then $\theta = 0$ as one would expect. In summary the following coordinate transformations have been constructed

$$\vec{n} = (x, y, z) = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta), \quad (27)$$

$$= \left(\frac{\bar{\zeta} + \zeta}{\zeta \bar{\zeta} + 1}, i \frac{\bar{\zeta} - \zeta}{\zeta \bar{\zeta} + 1}, \frac{\bar{\zeta} \zeta - 1}{\zeta \bar{\zeta} + 1} \right). \quad (28)$$

Where here \vec{n} is a unit vector in \mathbb{R}^3 such that $\vec{n} \cdot \vec{n} = 1$.

Let $\vec{x} = (x, y, z, t)$ be a point on the future null cone with vector $(0, 0, 0, 0)$. Denote the future null cone as N^+ (not sure??), so that

$$N^+ : x^2 + y^2 + z^2 - t^2 = 0, \text{ for } t > 0$$

as all the vectors in the null cone have a Lorentz quadratic form equal to zero by definition. (SEE FIG PG 4:5). The intersection of the space-like hypersurface $t = \text{const} > 0$ is a 2-sphere denoted by

$$\mathbb{S}^2(t) : x^2 + y^2 + z^2 - t^2 = \text{const}.$$

There is a generator of N^+ passing through each point of $\mathbb{S}^2(t)$. These generators are the null geodesics tangent to N^+ and passing through the point $(0, 0, 0, 0)$. Hence the points of $\mathbb{S}^2(t)$, denoted by (θ, ϕ) or ζ , label the *generators* of N^+ .

For any $t > 0$ it is clear that

$$\left(\frac{x}{t}\right)^2 + \left(\frac{y}{t}\right)^2 + \left(\frac{z}{t}\right)^2 = 1.$$

Hence we can write

$$\begin{aligned}
\vec{x} &= t(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta, 1), \\
&= t \left(\frac{\bar{\zeta} + \zeta}{\zeta \bar{\zeta} + 1}, i \frac{\bar{\zeta} - \zeta}{\zeta \bar{\zeta} + 1}, \frac{\bar{\zeta} \zeta - 1}{\zeta \bar{\zeta} + 1}, 1 \right).
\end{aligned} \quad (29)$$

It is shown explicitly that the direction of \vec{x} is determined by (θ, ϕ) or ζ by comparing this to Eqn.(28). All possible directions of \vec{x} on N^+ are covered if $\zeta \in \hat{\mathbb{C}}$. Now the Lorentz transformation $\vec{x} \rightarrow \vec{x}'$ is investigated. This transformation takes the form

$$\vec{x} \rightarrow \vec{x}' = t' \left(\frac{\bar{\zeta}' + \zeta'}{\bar{\zeta}' \zeta' + 1}, i \frac{\bar{\zeta}' - \zeta'}{\bar{\zeta}' \zeta' + 1}, \frac{\bar{\zeta}' \zeta' - 1}{\bar{\zeta}' \zeta' + 1}, 1 \right).$$

We say that the null direction ζ is transformed to the null direction ζ' . The relation between ζ and ζ' must also be determined. Construct the matrix $A(\vec{x})$ as in Eqn.(22).

$$A(\vec{x}) = \begin{pmatrix} \frac{2t}{\zeta\bar{\zeta}+1} & \frac{2t\zeta}{\zeta\bar{\zeta}+1} \\ \frac{2t\bar{\zeta}}{\zeta\bar{\zeta}+1} & \frac{2t\zeta\bar{\zeta}}{\zeta\bar{\zeta}+1} \end{pmatrix} = c_0 \begin{pmatrix} 1 & \zeta \\ \bar{\zeta} & \zeta\bar{\zeta} \end{pmatrix}.$$

Where $c_0 = 2t/\zeta\bar{\zeta} + 1 \in \mathbb{R}^2$. Note that as \vec{x} is a null vector $\det(A(\vec{x})) = 0$. Thus the transformed matrix $A(\vec{x}')$ is given similarly as

$$A(\vec{x}') = c_0' \begin{pmatrix} 1 & \zeta' \\ \bar{\zeta}' & \zeta'\bar{\zeta}' \end{pmatrix}.$$

Now, as in the examples in section (IV) we determine the special linear matrix U such that

$$A(\vec{x}') = UA(\vec{x})U^\dagger \quad (30)$$

As before, this matrix equation is written component wise as

$$c_0' \begin{pmatrix} 1 & \zeta' \\ \bar{\zeta}' & \zeta'\bar{\zeta}' \end{pmatrix} = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} c_0 \begin{pmatrix} 1 & \zeta \\ \bar{\zeta} & \zeta\bar{\zeta} \end{pmatrix} \begin{pmatrix} \bar{\alpha} & \bar{\beta} \\ \bar{\gamma} & \bar{\delta} \end{pmatrix}.$$

Then three separate relations between ζ and ζ' are obtained

$$c_0' = c_0(\alpha\bar{\alpha} + \alpha\bar{\beta}\zeta + \bar{\alpha}\beta\bar{\zeta} + \beta\bar{\beta}\zeta\bar{\zeta}), \quad (31)$$

$$c_0'\zeta' = c_0(\alpha\bar{\gamma} + \alpha\bar{\delta}\zeta + \bar{\gamma}\beta\bar{\zeta} + \beta\bar{\delta}\zeta\bar{\zeta}), \quad (32)$$

$$c_0'\zeta'\bar{\zeta}' = c_0(\gamma\bar{\gamma} + \gamma\bar{\delta}\zeta + \bar{\gamma}\delta\bar{\zeta} + \delta\bar{\delta}\zeta\bar{\zeta}). \quad (33)$$

$$(34)$$

Using Eqns.(31) and (32) to obtain

$$\zeta' = \frac{c_0'\zeta'}{c_0'} = \frac{\alpha(\bar{\gamma} + \bar{\delta}\zeta) + \beta\bar{\zeta}(\bar{\gamma} + \bar{\delta}\zeta)}{\alpha(\bar{\alpha} + \bar{\beta}\zeta) + \beta\bar{\zeta}(\bar{\alpha} + \bar{\beta}\zeta)}$$

Thus

$$\zeta' = \frac{(\bar{\gamma} + \bar{\delta}\zeta)}{(\bar{\alpha} + \bar{\beta}\zeta)},$$

with $\alpha\delta - \beta\gamma = 1$ as before. This is a fractional linear transformation of the extended complex plane $\hat{\mathbb{C}}$. There is a one to one correspondence here between proper, orthochronous Lorentz transformations and fractional linear transformations of the extended complex plane. This is because the matrices $\pm U$ both satisfy Eqn.(30) as in the previous section., but now both matrices give the same transformation as the signs will cancel in the fractional transformation.

A. Singular and Non-Singular Lorentz Transformations

A given Lorentz transformation is equivalent to known α, β, γ and δ parameters module a sign and therefore gives an explicit fractional linear transformation. For a given Lorentz transformation a *fixed point* of the corresponding fractional linear transformation corresponds to an invariant null direction. The fixed points ζ satisfy the relation $\zeta' = \zeta$. Thus

$$\begin{aligned} \frac{(\bar{\gamma} + \bar{\delta}\zeta)}{(\bar{\alpha} + \bar{\beta}\zeta)} &= \zeta, \\ \Rightarrow \bar{\beta}\zeta^2 + (\bar{\alpha} - \bar{\delta})\zeta - \bar{\gamma} &= 0. \end{aligned} \quad (35)$$

Clearly this is a quadratic equation over the field \mathbb{C} , thus it has two roots in general. Hence a Lorentz transformation does indeed leave two null directions invariant in general. The non-singular case is when these roots do not coincide. If Eqn.(35) has only one root then the corresponding Lorentz transformation leaves one null direction invariant, this is the singular case.

Consider Eqn.(35) again. Divide by ζ^2 to obtain

$$\bar{\beta} + (\bar{\alpha} - \bar{\delta})\zeta^{-1} - \bar{\gamma}\zeta^{-2} = 0.$$

Hence $\zeta = \infty$ is a solution of this equation if $\beta = 0$. If $\zeta = \infty$ then \vec{x} is given by $\vec{x} = t(0, 0, 1, 1)$ by Eqn.(29). Thus it is clear that this corresponds to the null direction $z = t$. Compare this to example 3, section (IV C). Here β is zero AND the null direction is $z = t$ as expected. If $\zeta = 0$ is a solution to Eqn.(35) it is required that $\gamma = 0$, thus $\vec{x} = (0, 0, -1, 1)$. So it is predicted that a Lorentz transformation with a special linear matrix of the form

$$U = \begin{pmatrix} \alpha & \beta \\ 0 & \delta \end{pmatrix},$$

will leave the $Z = -t$ null direction invariant.

B. Example: Standard Lorentz Transformation

Continuing on from Example 2, section (IV C), where α , β , γ and δ were determined. ζ' can now be expressed as

$$\zeta' = \frac{-\sqrt{\gamma_0 - 1} + \sqrt{\gamma_0 + 1}\zeta}{\sqrt{\gamma_0 + 1} - \sqrt{\gamma_0 - 1}\zeta}.$$

If the condition $\zeta' = \zeta$ is imposed then

$$\begin{aligned} \sqrt{\gamma_0 - 1}(\zeta^2 - 1) &= 0 \\ \Rightarrow \zeta &= \pm 1 \end{aligned}$$

In the $\zeta = +1$ case $\vec{x} = t(1, 0, 0, 1)$ and the invariant direction is $x = t$. Similarly in the $\zeta = -1$ case $\vec{x} = t(-1, 0, 0, 1)$ and the invariant direction is $x = -t$.

VI. ACKNOWLEDGEMENTS
