CS420 Assignment 1

Question 1

- 1. A ⊥ E | {D}
 - $A \rightarrow B \rightarrow D \rightarrow E$
 - Blocked due to cascade on D, it is observed.
 - $A \rightarrow B \leftarrow C \rightarrow F \leftarrow E$
 - Blocked due to v-structure on F, neither F nor its its descendants are observed.
 - $A \rightarrow B \rightarrow D \rightarrow G \rightarrow H \leftarrow F \leftarrow E$
 - Blocked due to cascade on D, it is observed.
 - $A \rightarrow D \rightarrow E$
 - Blocked due to cascade on D, it is observed.
 - $A \rightarrow D \rightarrow G \rightarrow H \rightarrow F \rightarrow E$
 - Blocked due to cascade on D, it is observed.

Since all the trails are blocked, the statement is true.

- 2. A ⊥ H | {B, G}
 - $A \rightarrow D \rightarrow G \rightarrow H$
 - Blocked due to cascade on D, it is observed.
 - $A \rightarrow D \rightarrow E \rightarrow F \rightarrow H$
 - Blocked due to cascade on D, it is observed.
 - $A \rightarrow D \leftarrow B \leftarrow C \rightarrow F \rightarrow H$
 - Active trail
 - $A \rightarrow B \leftarrow C \rightarrow F \rightarrow H$
 - Active trail

- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow H$
 - Blocked due to cascade on B, it is observed.
- $A \rightarrow B \rightarrow D \rightarrow E \rightarrow F \rightarrow H$
 - Blocked due to cascade on B, it is observed.
- $A \rightarrow B \leftarrow C \rightarrow F \leftarrow E \leftarrow D \rightarrow G \rightarrow H$
 - Blocked due to cascade on G, it is observed.

Since there are active trails, the statement is false.

3. A ⊥ C

- $A \rightarrow B \leftarrow C$
 - Blocked due to v-structure on B, neither B nor its descendants are observed.
- $A \rightarrow B \rightarrow D \rightarrow E \rightarrow F \leftarrow C$
 - Blocked due to v-structure on F, neither F nor its descendants are observed.
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow H \leftarrow F \leftarrow C$
 - Blocked due to v-structure on H, neither H nor its descendants are observed.
- $A \rightarrow D \rightarrow E \rightarrow F \leftarrow C$
 - Blocked due to v-structure on F, neither F nor its descendants are observed.
- $A \rightarrow D \leftarrow B \leftarrow C$
 - Blocked due to v-structure on D, neither D nor its descendants are observed.
- $A \rightarrow D \rightarrow G \rightarrow H \leftarrow F \leftarrow C$
 - Blocked due to v-structure on H, neither H nor its descendants are observed.

Since all the trails are blocked, the statement is true.

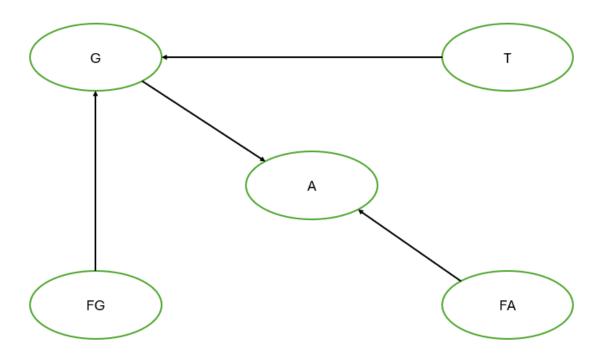
4. $\{D\} \perp \{C, F\} \mid \{A, B, E, G\}$

- $D \rightarrow E \rightarrow F \leftarrow C$
 - Blocked due to cascade on E, it is observed.
- $D \leftarrow B \leftarrow C \leftarrow F$
 - Blocked due to cascade on B, it is observed.
- $D \leftarrow A \rightarrow B \rightarrow C \rightarrow F$
 - Blocked due to common cause on A, it is observed.
- $D \rightarrow G \rightarrow H \rightarrow F \rightarrow C$
 - Blocked due to cascade on G, it is observed.

Since all the trails are blocked, the statement is true.

Question 2

A)



B)

Variable Name	Domain (list all the entries of the domain)
Т	{Low actual temperature = 0, High actual temperature = 1}
G	{Low measured temperature = 0, High measured temperature = 1}
FG	{Gauge not faulty = 0, Gauge is faulty = 1}
FA	{Alarm not faulty = 0, Alarm is faulty = 1}
Α	{Alarm does not sound = 0, Alarm sounds = 1}

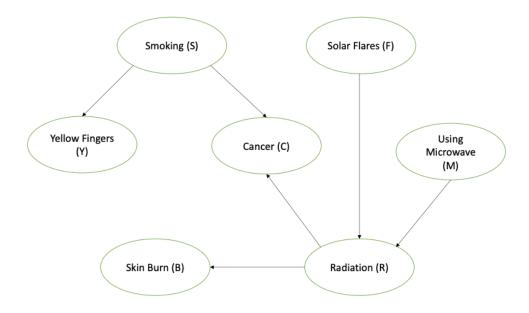
C)

FG	Т	P (G = 1 FG, T)	P (G = 0 FG, T)
1	1	0.2	0.8
1	0	0.8	0.2
0	1	0.9	0.1
0	0	0.1	0.9

D)

FA	G	P (A = 1 FA, G)	P (A = 0 FA, G)
0	0	1	0
0	1	1	0
1	0	0	1
1	1	0	1

Question 3



1.

```
[25] # Import relevant packages
    from pgmpy.models import BayesianModel
    from pgmpy.factors.discrete import TabularCPD
    import sys

[26] # We first create a model which containts edges of the graph
    model = BayesianModel([('Smoking', 'Yellow Fingers'), ('Smoking', 'Cancer'), ('Solar Flares', 'Radiation'), ('Using Microwave', 'Radiation'), ('Radiation',
    # Enter conditional probability distribution for each variable

# Prior probability for Smoking P(S)
    cpd_S = TabularCPD(variable='Smoking', variable_card=2, values=[[0.8], [0.2]])

# Prior probability for Solar Flares', variable_card=2, values=[[0.999], [0.001]])

# Prior probability for Using Microwave P(M)
    cpd_M = TabularCPD(variable='Using Microwave', variable_card=2, values=[[0.1], [0.9]])

WARNING:pgmpy:BayesianModel has been renamed to BayesianNetwork. Please use BayesianNetwork class, BayesianModel will be removed in future.
```

```
from pgmpy.inference import VariableElimination

# Going to do variable elimination
infer = VariableElimination(model)

# Compute probability of Radiation given Cancer = 1
phh_query = infer.query(['Radiation'], evidence=('Cancer':1), joint = False)
factor = phi_query(['Radiation']
print('Probability of Radiation given Cancer = 1')
print('Probability of Radiation given Cancer = 1')
print('Probability of Cancer given Skin Burn = 1
phi_query = infer.query(['Cancer'], evidence=('Skin Burn':1), joint = False)
factor = phi_query('Cancer']
print('Probability of Cancer given Skin Burn = 1')
print('factor)

# Compute probability of Cancer given Using Microwave = 0
phi_query = infer.query(['Cancer'], evidence=('Using Microwave':0), joint = False)
factor = phi_query('Cancer']
print('Probability of Cancer given Using Microwave = 0')
```

```
Probability of Radiation given Cancer = 1
                    phi(Radiation)
  Radiation
  {\sf Radiation(0)}
                             0.6438
  Radiation(1)
                             0.3562
Probability of Cancer given Skin Burn = 1
                 phi(Cancer)
  Cancer
  Cancer(0)
                       0.6092
  Cancer(1)
                      0.3908
Probability of Cancer given Using Microwave = 0
                 phi(Cancer)
  Cancer
  Cancer(0)
                       0.8744
  Cancer(1)
                       0.1256
```

4. Trails between Smoking and Using Microwave:

a.
$$S \rightarrow C \leftarrow R \leftarrow M$$

Since Cancer is observed, the trail is active. Therefore Smoking and Using Microwave are independent.

5.
$$P(C = 1 | M = 0) = 0.1256$$

Question 4

• Code and answers is submitted in zip file.

Question 5

a and b)

```
➤ Download MobileNetV2 model

➤ #
# Load the MobileNetV2 model pre-trained on ImageNet
base_model = MobileNetV2(weights='imagenet', include_top=False, input_shape=(minSize, minSize, 3))

# Freeze the pre-trained layers
for layer in base_model.layers:
layer.trainable = False

**Trainable = False**

**Trainab
```

c)

Add custom layers at the end of downloaded model

```
[ ] #<Write code for adding custom layers>
    from tensorflow.keras.layers import GlobalAveragePooling2D, Dense
    from tensorflow.keras.models import Sequential
    # Create a new Sequential model
    model = Sequential()

# Add the pre-trained base model
    model.add(base_model)

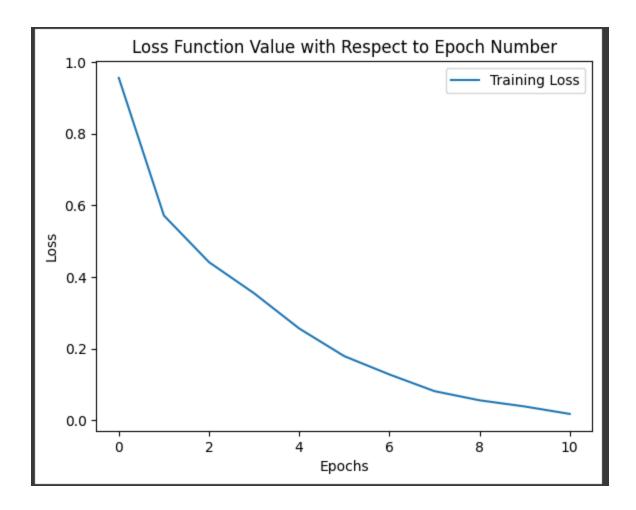
# Add the rest of the layers
    model.add(GlobalAveragePooling2D())
    model.add(Dense(512, activation='relu'))
    model.add(Dense(10, activation='softmax')) # 10 classes for CIFAR-10
```

d)

```
Add loss function, compile and train the model, and check accuracy on test data
▶ from tensorflow.keras.optimizers import Adam
    from tensorflow.keras.callbacks import EarlyStopping
    limited_train_images = resized_train_images
    limited_train_labels = train_labels[:10000]
    # Compile the model with sparse categorical crossentropy
model.compile(optimizer=Adam(learning_rate=0.001), loss='sparse_categorical_crossentropy', metrics=['accuracy'])
    # Define early stopping criteria
    early_stopping = EarlyStopping(monitor='val_loss', patience=8, restore_best_weights=True)
    history = model.fit(limited_train_images, limited_train_labels, batch_size=64, epochs=50,
                       validation_data=(resized_test_images, test_labels), callbacks=[early_stopping])
    # Evaluate the model
    test_loss, test_accuracy = model.evaluate(resized_test_images, test_labels, verbose=1)
    print(f"Test accuracy: {test_accuracy * 100:.2f}%")
Epoch 1/50
                                :=======] - 20s 78ms/step - loss: 0.9554 - accuracy: 0.6790 - val_loss: 0.7351 - val_accuracy: 0.7427
                                        ===] - 6s 38ms/step - loss: 0.5715 - accuracy: 0.7978 - val_loss: 0.7501 - val_accuracy: 0.7443
    Epoch 3/50
                                        ===] - 6s 40ms/step - loss: 0.4413 - accuracy: 0.8450 - val_loss: 0.6973 - val_accuracy: 0.7705
    157/157 [===
Epoch 4/50
                                         ==] - 8s 53ms/step - loss: 0.3546 - accuracy: 0.8785 - val_loss: 0.7296 - val_accuracy: 0.7607
    157/157 [==
                                        ===] - 9s 55ms/step - loss: 0.2564 - accuracy: 0.9164 - val_loss: 0.7614 - val_accuracy: 0.7579
    157/157 [==
    Epoch 6/50
                                         ==] - 6s 40ms/step - loss: 0.1791 - accuracy: 0.9472 - val_loss: 0.7866 - val_accuracy: 0.7666
    .
157/157 [==
                                         ==] - 6s 38ms/step - loss: 0.1281 - accuracy: 0.9646 - val_loss: 0.8054 - val_accuracy: 0.7637
    Epoch 8/50
                                :=======] - 8s 54ms/step - loss: 0.0815 - accuracy: 0.9820 - val_loss: 0.8337 - val_accuracy: 0.7691
    157/157 [===
    Fnoch 9/50
    157/157 [=
                                         ==] - 8s 53ms/step - loss: 0.0560 - accuracy: 0.9904 - val_loss: 0.8981 - val_accuracy: 0.7639
    Epoch 10/50
                                      :=====] - 9s 56ms/step - loss: 0.0388 - accuracy: 0.9949 - val_loss: 0.9108 - val_accuracy: 0.7711
    Epoch 11/50
                              157/157 [===:
    313/313 [===
    Test accuracy: 77.05%
```

1) I extended the MobileNetV2 model by adding 1 GlobalAveragePooling2D layer, 1 dense layer with 512 nodes and ReLU activation and 1 dense output layer with 10 nodes and Softmax activation. Initially I added a MaxPool2D layer instead, but it was giving me very low training accuracy.

2)



- a. As seen from the screenshot for part (d), I added an EarlyStopping callback to the training process. This avoids overfitting and stops training as soon as val_loss stops improving. I set the patience parameter to 8 after experimenting with a few values and since the model reaches the required accuracy (≥ 70%) in a few epochs, I set it to a relatively low number. I also set restore_best_weights = True so that when training is stopped, the model's weights will be rolled back to the state when it achieved the best performance on the validation loss.
- b. For the mini batch size, I experimented with a few values such as 32, 64 and 128 and decided on 64 as it gave me the highest training accuracy and a relatively smooth loss function with respect to epoch number graph.
- c. Similarly for learning rate, I experimented with different values ranging from 0.1 to 0.00001. I eventually settled on 0.001 as it gave me the necessary training accuracy when combined with the other set parameters.

```
Add loss function, compile and train the model, and check accuracy on test data
▶ from tensorflow.keras.optimizers import Adam
    from tensorflow.keras.callbacks import EarlyStopping
    limited_train_images = resized_train_images
    limited_train_labels = train_labels[:10000]
    model.compile(optimizer=Adam(learning_rate=0.001), loss='sparse_categorical_crossentropy', metrics=['accuracy'])
    # Define early stopping criteria
    early_stopping = EarlyStopping(monitor='val_loss', patience=8, restore_best_weights=True)
    history = model.fit(limited_train_images, limited_train_labels, batch_size=64, epochs=50,
                      validation_data=(resized_test_images, test_labels), callbacks=[early_stopping])
    test_loss, test_accuracy = model.evaluate(resized_test_images, test_labels, verbose=1)
    print(f"Test accuracy: {test_accuracy * 100:.2f}%")
Epoch 1/50
                         Epoch 2/50
    157/157 [===
Epoch 3/50
                            ========] - 6s 40ms/step - loss: 0.4413 - accuracy: 0.8450 - val_loss: 0.6973 - val_accuracy: 0.7705
    Epoch 4/50
                           ========] - 8s 53ms/step - loss: 0.3546 - accuracy: 0.8785 - val_loss: 0.7296 - val_accuracy: 0.7607
    Epoch 5/50
    .
157/157 [==
                                      ===] - 9s 55ms/step - loss: 0.2564 - accuracy: 0.9164 - val loss: 0.7614 - val accuracy: 0.7579
    Epoch 6/50
                                      :==] - 6s 40ms/step - loss: 0.1791 - accuracy: 0.9472 - val_loss: 0.7866 - val_accuracy: 0.7666
                                      ===] - 6s 38ms/step - loss: 0.1281 - accuracy: 0.9646 - val_loss: 0.8054 - val_accuracy: 0.7637
    Epoch 8/50
    157/157 [=
                                       ==] - 8s 54ms/step - loss: 0.0815 - accuracy: 0.9820 - val_loss: 0.8337 - val_accuracy: 0.7691
    Epoch 9/50
    157/157 [==
                                =======] - 8s 53ms/step - loss: 0.0560 - accuracy: 0.9904 - val_loss: 0.8981 - val_accuracy: 0.7639
                            =========] - 9s 56ms/step - loss: 0.0388 - accuracy: 0.9949 - val_loss: 0.9108 - val_accuracy: 0.7711
    157/157 [===
Epoch 11/50
    157/157 [====
313/313 [====
                           ========] - 9s 56ms/step - loss: 0.0180 - accuracy: 0.9993 - val_loss: 0.9346 - val_accuracy: 0.7729 ========] - 4s 12ms/step - loss: 0.6973 - accuracy: 0.7705
    Test accuracy: 77.05%
```

Note: I have added the Q3 code file in the zip folder as well in case the screenshot is not clear.