Design Document (Assignment 2)

Process Status

```
typedef enum process_status {
  RUNNING = 0,
     # Add the READY state
  READY = 1,
     # Add the STOPPED state
  STOPPED = 2,
  TERMINATED = 3
} process_status;
```

Process Record

```
typedef struct process_record {
   pid_t pid;
   process_status status;
   int total_runtime; # Total expected runtime of the process
   int remaining_runtime; # Remaining runtime of the process
} process_record;
enum {
        # Set to 64 as per requirements
        MAX_PROCESSES = 64
};
process_record process_records[MAX_PROCESSES];
```

Process Management Functions

```
void scheduler(void) {
       \# Iterate through process_records and identify the process with the least
       # remaining run time from all the READY processes and change its status to RUNNING.
}
void perform_run(char* args[], int runtime) {
   # New processes are added to the READY queue and scheduler() is called
   scheduler();
}
void perform_stop(char* args[]) {
   # Change status of specified PID to STOPPED and call scheduler()
   scheduler();
}
void perform_kill(char* args[]) {
   # Search for process with given PID, and send a SIGTERM signal to terminate it. # Set its status to TERMINATED
       # Call scheduler function to decide which function should be running.
   scheduler();
void perform_list(char* args[]) {
   \# Loop through all processes and print out PID and status code for each process
void perform_resume(char* args[]) {
   # Search for process with given PID, and changes status from STOPPED to READY
       # Call scheduler() to decide which function should be running.
   scheduler();
}
void perform_exit(void) {
   printf("bye!\n");
```

Main

```
int main(void) {
    # Enters into an infinite while loop, processes user input and calls the appropriate function
    # based on the command entered (run, stop, resume, list, kill, exit). The program terminates
    # when the exit command is entered.
}
```