

1 Graph Algorithms

Traversal Visit all the nodes in the graph.

- Depth-first traversal (preorder and postorder)
- Level-order traversal

Search Given a start node, find a goal state.

- Depth-first search
- Iterative-deepening depth-first search
- Breadth-first search

Single Pair Shortest Path Given a start node, find the shortest path to a goal node.

- *Uniform cost search*
- *Greedy search*
- A* search

Single Source Shortest Path Given a start node, find the shortest paths to all other nodes.

- Dijkstra's algorithm

Minimum Spanning Tree A *spanning tree*, or cycle-free subset of edges connecting all the nodes, with the minimum possible total edge weight.

- Prim's algorithm
- Kruskal's algorithm

```
function GRAPH-SEARCH(start)
  seen ← an empty set
  fringe ← java.util.Queue interface
  ADD(start, fringe)
  while fringe is not empty do
    node ← REMOVE(fringe)
    if node is the goal then return node
    if node is not in seen then
      ADD(node, seen)
      for child in NEIGHBORS(node) do
        ADD(child, fringe)
  return failure
```

2 Dijkstra's Algorithm

- 2.1 What fringe do we use in Dijkstra's algorithm and what does it keep track of?
- 2.2 Assuming the runtime for `changePriority` is in $O(f(N))$ and `removeMin` is in $O(g(N))$ where N is the size of the priority queue, give the runtime of Dijkstra's algorithm on the simple graph $G = (V, E)$.
- 2.3 Give the runtime bound for Dijkstra's assuming the priority queue is implemented using an unordered linked list and a binary min-heap.

3 A* Search

- 3.1 What fringe do we use in A* search and what does it keep track of?
- 3.2 What is a *heuristic*? What is its correctness conditions?

4 Minimum Spanning Trees

- 4.1 Give a description of how Prim's algorithm works.
- 4.2 Give a description of Kruskal's algorithm.