

Lecture 2-1. Math Background Review.

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1. Basic Analysis :

A. ① Norm: A fn $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is called norm if:

* (non-neg.): $f(\underline{x}) \geq 0$, $\forall \underline{x} \in \mathbb{R}^n$, $f(\underline{x}) = 0$ iff $\underline{x} = 0$.

* (homogeneity): $f(t\underline{x}) = |t|f(\underline{x})$, $\forall \underline{x} \in \mathbb{R}^n$, $t \in \mathbb{R}$.

* (triangle ineq.): $f(\underline{x} + \underline{y}) \leq f(\underline{x}) + f(\underline{y})$, $\forall \underline{x}, \underline{y} \in \mathbb{R}^n$.

If $f(\underline{x})$ is a norm, we denote it as $\|\underline{x}\|$.

2° Norm $\|\underline{x}\|$'s meaning:

* $\|\underline{x}\|$: length of \underline{x}

* $\|\underline{x} - \underline{y}\|$: dist. btwn \underline{x} and \underline{y} .

3° Unit Ball: set of vectors with $\|\underline{x}\| \leq 1$.

$$\mathcal{B} = \{\underline{x} \in \mathbb{R}^n; \|\underline{x}\| \leq 1\}.$$

Ex: * l_2 -norm (Euclidean norm): $\|\underline{x}\|_2 \triangleq (\underline{x}^\top \underline{x})^{\frac{1}{2}} = (x_1^2 + \dots + x_n^2)^{\frac{1}{2}}$.

* l_1 -norm (sum-abs-val): $\|\underline{x}\|_1 \triangleq |x_1| + |x_2| + \dots + |x_n|$.

* l_∞ -norm (Chebychev): $\|\underline{x}\|_\infty \triangleq \max \{|x_1|, \dots, |x_n|\}$.

* l_p -norm ($p \geq 1$): $\|\underline{x}\|_p \triangleq (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}$

$$\|\underline{x}\|_\infty = \lim_{p \rightarrow \infty} \|\underline{x}\|_p$$

Proof: $\|\underline{x}\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}} = \left(\frac{|x_1|^p}{\|\underline{x}\|_\infty^p} + \dots + \frac{|x_n|^p}{\|\underline{x}\|_\infty^p} \right)^{\frac{1}{p}} \|\underline{x}\|_\infty$
 $\leq (1 + \dots + 1)^{\frac{1}{p}} \|\underline{x}\|_\infty = n^{\frac{1}{p}} \cdot \|\underline{x}\|_\infty \rightarrow \|\underline{x}\|_\infty \text{ as } p \rightarrow \infty$.

Let $i^* \in \operatorname{argmax} \{|x_i|, \forall i\}$.

$$\|\underline{x}\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}} \geq (|x_{i^*}|^p)^{\frac{1}{p}} = |x_{i^*}| = \|\underline{x}\|_\infty.$$

Note $n^{\frac{1}{p}} \rightarrow 1$ as $p \rightarrow \infty$.



4^o Equivalence of Norms:

Suppose $\|\cdot\|_a$ and $\|\cdot\|_b$ are norms of \mathbb{R}^n . Then $\exists \alpha, \beta > 0$

s.t. $\forall \underline{x} \in \mathbb{R}^n, \alpha \|\underline{x}\|_a \leq \|\underline{x}\|_b \leq \beta \|\underline{x}\|_a$.

$$\text{Ex: } \|\underline{x}\|_2 \leq \|\underline{x}\|_1 \leq \sqrt{n} \|\underline{x}\|_2.$$

$$\|\underline{x}\|_\infty \leq \|\underline{x}\|_2 \leq \sqrt{n} \|\underline{x}\|_\infty$$

$$\|\underline{x}\|_\infty \leq \|\underline{x}\|_1 \leq n \|\underline{x}\|_\infty.$$

2. Convergent Sequences and Limits:

1^o Def (Convergence): A seq. of vectors $\underline{x}_1, \dots, \underline{x}_n, \dots$ are said to

be convergent to a limit pt. $\bar{\underline{x}}$ of $\forall \epsilon > 0, \exists N_\epsilon \in \mathbb{N}$

s.t. $\|\underline{x}_k - \bar{\underline{x}}\| < \epsilon, \forall k \geq N_\epsilon$. ($\{\underline{x}_k\} \rightarrow \bar{\underline{x}}$ as $k \rightarrow \infty, \lim_{k \rightarrow \infty} \underline{x}_k = \bar{\underline{x}}$).

2^o Def (Cauchy Seq.): A seq. $\{\underline{x}_k\}$ is Cauchy if

$\forall \epsilon > 0, \exists N \in \mathbb{N}$ s.t. $\|\underline{x}_m - \underline{x}_n\| < \epsilon, \forall m, n \geq N$.

Ihm: A seq. on \mathbb{R}^n has a limit iff it's Cauchy.

Ex: (p-series). $a_n = \frac{1}{n^p}$. Show $\{b_n\} \triangleq \left\{ \sum_{k=1}^n a_k \right\}$ has a limit

for $p=2$, but doesn't converge for $p=1$.

Proof: w.l.o.g., let $m, n \in \mathbb{N}$ and $m < n$.

$$\text{For } p=2, b_n - b_m = \sum_{k=1}^n \frac{1}{k^2} - \sum_{k=1}^m \frac{1}{k^2} = \sum_{k=m+1}^n \frac{1}{k^2} \leq \sum_{k=m+1}^n \frac{1}{k} \cdot \frac{1}{k-1}$$

$$= \sum_{k=m+1}^n \left(\frac{1}{k-1} - \frac{1}{k} \right) = \frac{1}{m} - \cancel{\frac{1}{m+1}} + \cancel{\frac{1}{m+1}} \cdot \cancel{\frac{1}{m+2}} + \dots + \cancel{\frac{1}{n-1}} - \frac{1}{n}$$

$$= \frac{1}{m} - \frac{1}{n} < \frac{1}{m} < \epsilon, \text{ if } m \text{ is suff. large.}$$

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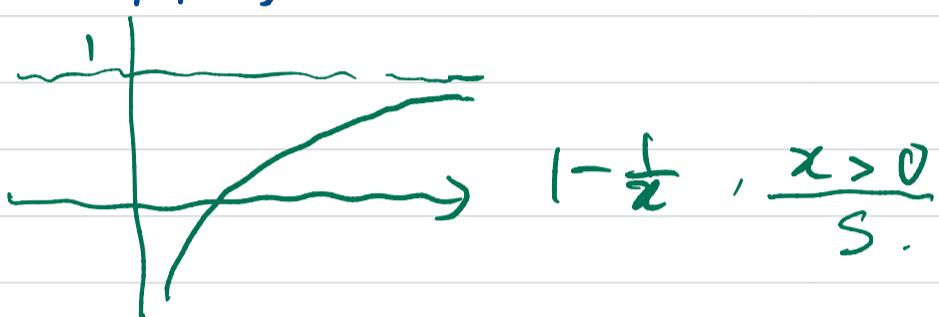
$$\text{For } p=1, b_n - b_m = \sum_{k=1}^n \frac{1}{k} - \sum_{k=1}^m \frac{1}{k} = \sum_{k=m+1}^n \frac{1}{k} = \frac{1}{m+1} + \dots + \frac{1}{n}$$

$$\geq \frac{n-m}{n} = 1 - \frac{m}{n}.$$

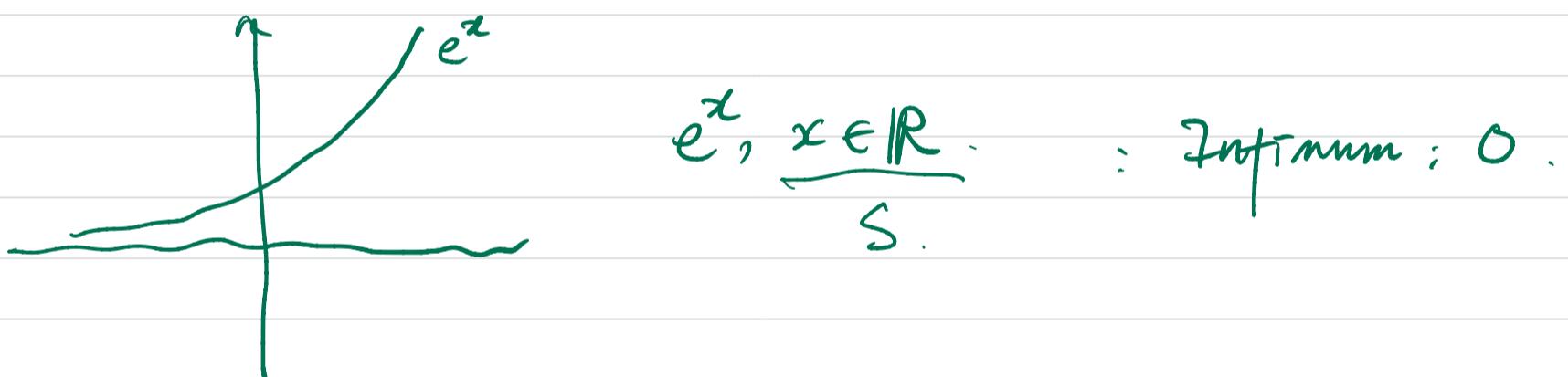
Consider any $\varepsilon > 0$, no matter how large m is, can choose

$$n \geq \left\lceil \frac{m}{1-\varepsilon} \right\rceil, \text{ so that } b_n - b_m \geq \varepsilon.$$
□

3°. Supremum of S . (least UB): Smallest possible α satisfying $\alpha \geq x, \forall x \in S$.

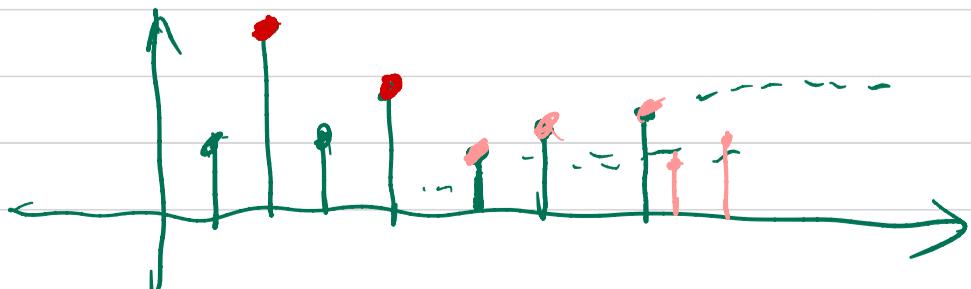
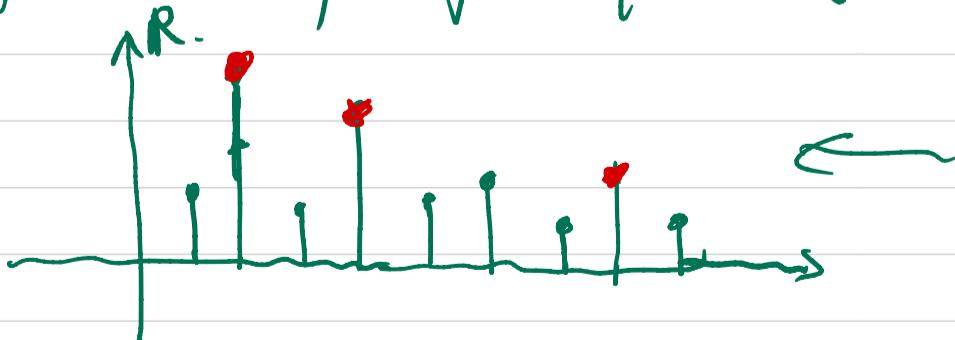


4° Infimum of S (largest LB): largest α such that $\alpha \leq x, \forall x \in S$.



Thm: (Bolzano-Weierstrass): Every bounded seq. in \mathbb{R}^n has a convergent subseq.

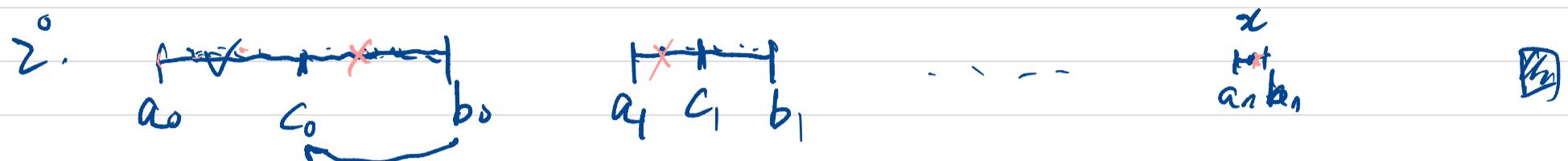
Proof: 1. Every inf. seq. $\{x_n\}$ in \mathbb{R}^1 has mono. subseq.



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2. MCT: if $\{a_n\}$ is monotonically real, then $\{a_n\}$ has a limit iff $\{a_n\}$ is bounded.

3. \mathbb{R}^n : Extract subseq. each dim. sequentially. □



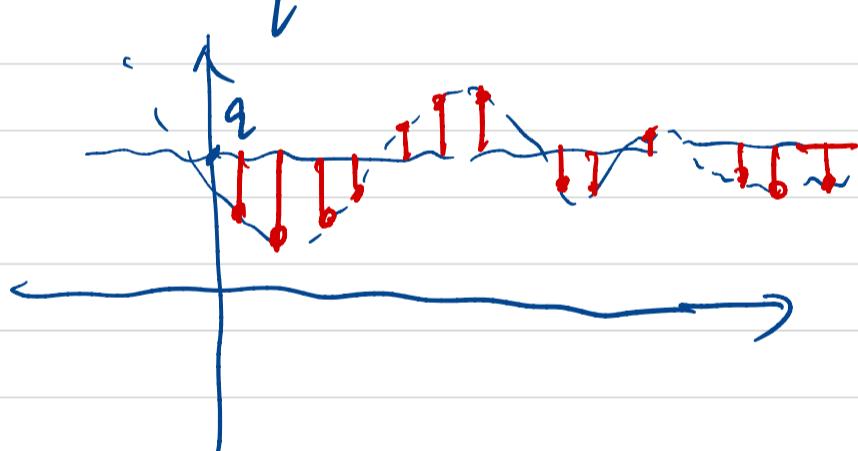
3 Maximum, Minimum. (achievable).

4 limsup, liminf:

* The compact supremum $\limsup_{k \rightarrow \infty} x_k$, is infimum of all $q \in \mathbb{R}$.

for which all but a finite # of elements in $\{x_k\}$

exceed q .



$$\limsup_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \left(\sup_{m \geq n} x_m \right).$$

* - - - limit infimum - - - $\liminf_{k \rightarrow \infty} x_k$ - - - supremum - - -

$$- - - q - - - \liminf_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \left\{ \inf_{m \geq n} x_m \right\}.$$

* limsup and liminf always exist.

$\{x_n\}$ converge iff $\limsup_{n \rightarrow \infty} x_n = \liminf_{n \rightarrow \infty} x_n$.

3. Functions:

1° Cont. fn: A fn $f: S \rightarrow \mathbb{R}$ is cont. at $\bar{x} \in S$ if $\forall \varepsilon > 0$, $\exists \delta > 0$, s.t. $x \in S$ with $\|x - \bar{x}\| < \delta \rightarrow |f(x) - f(\bar{x})| < \varepsilon$.

write: $f(x) \rightarrow f(\bar{x})$, as $x \rightarrow \bar{x}$.

Fact: Cont. fn achieves both maximum & minimum over a non-empty compact set.
closed & bounded.

2° Differentiable fn:



(1) S nonempty set in \mathbb{R}^n , $x \in \text{int } S$, and $f: S \rightarrow \mathbb{R}$.

f is diff'ble at \bar{x} if \exists a vector (called gradient).

$$\nabla f(\bar{x}) \triangleq \left[\frac{\partial f(\bar{x})}{\partial x_1}, \dots, \frac{\partial f(\bar{x})}{\partial x_n} \right]^T \text{ at } \bar{x} \text{ and fn } \beta(x, \bar{x}) \rightarrow 0.$$

as $x \rightarrow \bar{x}$, such that:

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T(x - \bar{x})}_{\text{FO-approx.}} + \underbrace{\|x - \bar{x}\| \beta(x, \bar{x})}_{O(\|x - \bar{x}\|)}, \quad \forall x \in S$$

(2). f is called twice diff'ble at \bar{x} if, in addition to grad., \exists symmetric matrix $\underline{H}(\bar{x})$ (called Hessian matrix) of f at \bar{x} , and $\beta(x, \bar{x}) \rightarrow 0$ as $x \rightarrow \bar{x}$, such that:

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T(x - \bar{x})}_{\text{FO-approx.}} + \underbrace{\frac{1}{2}(x - \bar{x})^T \underline{H}(\bar{x})(x - \bar{x})}_{\text{SO-approx.}} + \underbrace{\|x - \bar{x}\|^2 \beta(x, \bar{x})}_{O(\|x - \bar{x}\|^2)}.$$

$$\underline{H}(x) \triangleq \begin{bmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \cdots & \frac{\partial^2 f(x)}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f(x)}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 f(x)}{\partial x_n^2} \end{bmatrix} \in \mathbb{R}^{n \times n}$$

3° A vector-valued fn f is diff'ble if each component is diff'ble.
(twice).

A diff'ble vector-valued fn $h: \mathbb{R}^m \rightarrow \mathbb{R}^n$, the Jacobian, denoted by $\nabla h(\underline{x})$, is given by the $n \times m$ matrix.

$$\underline{J}(\underline{x}) = \nabla \underline{h}(\underline{x}) = \begin{bmatrix} \nabla h_1(\underline{x})^T \\ \vdots \\ \nabla h_n(\underline{x})^T \end{bmatrix}_{n \times m}.$$

~~$\underline{x}_1, \underline{x}_2$~~

4° (MVT): S non-empty open convex set in \mathbb{R}^n , let $f: S \rightarrow \mathbb{R}$ be diff'ble. For every $\underline{x}_1, \underline{x}_2 \in S$, we have:

$$f(\underline{x}_2) = f(\underline{x}_1) + \nabla f(\underline{x})^T (\underline{x}_2 - \underline{x}_1), \text{ where } \underline{x} = \lambda \underline{x}_1 + (1-\lambda) \underline{x}_2$$

for some $\lambda \in (0, 1)$.

5° Taylor's Thm. S non-empty, open, convex set in \mathbb{R}^n .
 $f: S \rightarrow \mathbb{R}$, twice diff'ble. For every $\underline{x}_1, \underline{x}_2 \in S$, we have:

$$f(\underline{x}_2) = f(\underline{x}_1) + \nabla f(\underline{x})^T (\underline{x}_2 - \underline{x}_1) + \frac{1}{2} (\underline{x}_2 - \underline{x}_1)^T H(\underline{x}) (\underline{x}_2 - \underline{x}_1), \text{ where } H(\underline{x})$$

is Hessian at \underline{x} , and $\underline{x} = \lambda \underline{x}_1 + (1-\lambda) \underline{x}_2$; for some $\lambda \in (0, 1)$.

Linear Algebra:

- Linear indep.: $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n$ are lin. indep. if $\sum_{i=1}^k \lambda_i \underline{x}_i = \underline{0} \Rightarrow \lambda_i = 0, \forall i = 1, \dots, k$.

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2. linear comb.: $y \in \mathbb{R}^n$ is a lin. comb. of $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n$ if

$$y = \sum_{i=1}^k \lambda_i \underline{x}_i \text{ for some } \lambda_1, \dots, \lambda_k.$$

* $\sum_{i=1}^k \lambda_i = 1$: y is an affine comb. of $\underline{x}_1, \dots, \underline{x}_k$.

* $\sum_{i=1}^k \lambda_i = 1, \lambda_i \geq 0, \forall i$: y is a convex comb. of $\underline{x}_1, \dots, \underline{x}_k$.

The linear, affine, convex hull of $S \subseteq \mathbb{R}^n$ are, resp., the set of all lin., affine, convex combs. of pts. in S .

3. Spanning vectors: $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n, k \geq n$, said to be spanning \mathbb{R}^n if any vector in \mathbb{R}^n can be represented as lin. comb. of $\underline{x}_1, \dots, \underline{x}_k$.

The cone spanned by $\underline{x}_1, \dots, \underline{x}_k$ is the set of non-neg. lin. combs.



4. Basis: A set of $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n$ spans \mathbb{R}^n and if the deletion of any of $\underline{x}_1, \dots, \underline{x}_k$ prevents remaining vectors from spanning \mathbb{R}^n . (Basis $\underline{x}_1, \dots, \underline{x}_k$ spans \mathbb{R}^n iff $k=n$).

5. Cauchy-Schwartz Ineq.: $|\langle \underline{x}, \underline{y} \rangle| = |\underline{x}^T \underline{y}| \leq \|\underline{x}\|_2 \cdot \|\underline{y}\|_2$,

with equality achieved iff $\underline{x}, \underline{y}$ are lin. dep.

(unsigned) angle btwn $\underline{x}, \underline{y} \in \mathbb{R}^n$.

$$\angle(\underline{x}, \underline{y}) \triangleq \cos^{-1} \left(\frac{\underline{x}^T \underline{y}}{\|\underline{x}\|_2 \cdot \|\underline{y}\|_2} \right) \in [0, \pi]$$

($\underline{x}, \underline{y}$ are orthogonal, $\underline{x} \perp \underline{y}$, if $\langle \underline{x}, \underline{y} \rangle = 0$)

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6. Young's Ineq: $a > 0, b > 0$, and any $p, q > 0$ s.t. $\frac{1}{p} + \frac{1}{q} = 1$.
 we have $ab \leq \frac{a^p}{p} + \frac{b^q}{q}$, with eq. achieved iff $a^p = b^q$.
 (special case, $p=q=2$).

7. Holder's Ineq: For any pair of vectors \underline{x} and $\underline{y} \in \mathbb{C}^n$, and
 for any p, q satisfying $\frac{1}{p} + \frac{1}{q} = 1$, we have:

$$\sum_{i=1}^n |x_i y_i| \leq \|\underline{x}\|_p \cdot \|\underline{y}\|_q.$$

 (special case : $p=q=2, p=1, q=\infty$).

8. Orthogonal matrix: $\underline{Q} \in \mathbb{R}^{m \times n}$: $\underline{Q}^T \underline{Q} = \underline{\underline{I}}_n$ or $\underline{Q} \underline{Q}^T = \underline{\underline{I}}_m$.
 If \underline{Q} is square: $\underline{Q}^{-1} = \underline{Q}^T$.

9. Rank of matrix: For $\underline{\underline{A}} \in \mathbb{R}^{m \times n}$, $\text{rank}(\underline{\underline{A}}) \triangleq \max \# \text{ of lin. indep. rows (or equivalently cols)} \text{ of } \underline{\underline{A}}$.

If $\text{rank}(\underline{\underline{A}}) = \min \{m, n\}$, $\underline{\underline{A}}$ is full row/col rank.

10. Eigenvalues and eigenvectors: $\underline{\underline{A}} \in \mathbb{R}^{n \times n}$. If λ and $\underline{x} \neq \underline{0}$
 satisfy $\underline{\underline{A}}\underline{x} = \lambda \underline{x}$, then λ and \underline{x} are eigenvalue & eigenvector.

- * λ can be computed by solving $\det(\underline{\underline{A}} - \lambda \underline{\underline{I}}) = 0$ (^{characteristic} eqn.).
- * $\underline{\underline{A}}$ is symmetric $\Rightarrow n$ (possibly non-distinct) real eigenvalues.
- * Eigenvectors assoc. with distinct eigenvalues are orthogonal.
- * Given some symmetric $\underline{\underline{A}}$ \Rightarrow can construct a orthogonal basis $\underline{\underline{B}} \in \mathbb{R}^{n \times r}$ ^{rank}, where each col in $\underline{\underline{B}}$ is an eigenvector of $\underline{\underline{A}}$.

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* Normalize \underline{B} to have unit L₂ norm, s.t. $\underline{B}^T \underline{B} = \underline{I}$ ($\underline{B}^T = \underline{B}^{-1}$).

Then, \underline{B} is called orthonormal matrix.

* Let $\lambda_1, \dots, \lambda_n$ be real eigenvalues of symmetric \underline{A}

$$\text{Let } \underline{\Lambda} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}. \quad \underline{A}\underline{B} = \underline{B}\underline{\Lambda}$$

$$\underline{A} \begin{bmatrix} | & | \\ v_1 & \dots & v_n \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ v_1 & \dots & v_n \\ | & | \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\stackrel{\underline{B}^T = \underline{B}^{-1}}{\Rightarrow} \underline{A} = \underline{B}\underline{\Lambda}\underline{B}^T = \sum_{i=1}^n \lambda_i b_i b_i^T$$

II. Singular - Value Decomp. (SVD).

Let $\underline{A} \in \mathbb{R}^{m \times n}$. Then $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$, where $\underline{U} \in \mathbb{R}^{m \times m}$ orthonormal,

$\underline{V} \in \mathbb{R}^{n \times n}$ orthonormal, and $\underline{\Sigma} \in \mathbb{R}^{m \times n}$, $(\underline{\Sigma})_{ij} = 0$ for $i \neq j$.

$$(\underline{\Sigma})_{ii} \geq 0, \in \mathbb{R}$$

* Cols of \underline{U} : Normalized eigenvectors of $\underline{A} \underline{A}^T$

* Cols of \underline{V} : -- - of $\underline{A}^T \underline{A}$

* $(\underline{\Sigma})_{ii}$: Abs square root of eigenvalues of $\underline{A}^T \underline{A}$ if $m \leq n$

or $\underline{A} \underline{A}^T$ if $m \geq n$.

12. Definite & Semidefinite Matrices: $\underline{A} \in \mathbb{R}^{n \times n}$ symmetric.

$$\text{PD} \quad \underline{x}^T \underline{A} \underline{x} > 0, \quad \forall \underline{x} \neq 0, \underline{x} \in \mathbb{R}^n$$

$$\underline{A} \text{ is PSD if } \underline{x}^T \underline{A} \underline{x} \geq 0, \quad \forall \underline{x} \in \mathbb{R}^n$$

$$\text{ND} \quad \underline{x}^T \underline{A} \underline{x} < 0, \quad \forall \underline{x} \neq 0, \underline{x} \in \mathbb{R}^n$$

$$\text{NSD} \quad \underline{x}^T \underline{A} \underline{x} \leq 0, \quad \forall \underline{x} \in \mathbb{R}^n.$$

\underline{A} is indef. if neither PSD nor NSD.

PD	pos.
\underline{A} is PSD	if eigenvalues are non-neg., resp.
ND	neg.
NSD	non-pos.

13. If \underline{A} is PSD, $\underline{A}^\frac{1}{2}$ is the matrix satisfying

$$\underline{A}^\frac{1}{2} \cdot \underline{A}^\frac{1}{2} = \underline{A}, \text{ and } \underline{A}^\frac{1}{2} = \underline{B} \underline{\Lambda}^\frac{1}{2} \underline{B}^T$$

$$\begin{bmatrix} \lambda_1^\frac{1}{2} & & \\ 0 & \ddots & \\ & & \lambda_n^\frac{1}{2} \end{bmatrix}$$