

# Computer Vision HW1

Part1: write a program to generate

- (a) upside-down lena.im
- (b) right-side-left lena.im
- (c) diagonally mirrored lena.im

這個部分的程式，我是使用python3.7.0的版本，圖片的部分使用OpenCV去做基本的I/O，程式碼的部分如下圖，三個函式都是利用for迴圈去實作。

upside-down和right-side-left是長和寬分別減去當前的座標去達到上下交換和左右交換的圖像，diagonally mirrored則是交換xy座標達成鏡射的效果。

執行時的指令為 `python3 cv_hw1.py`

```

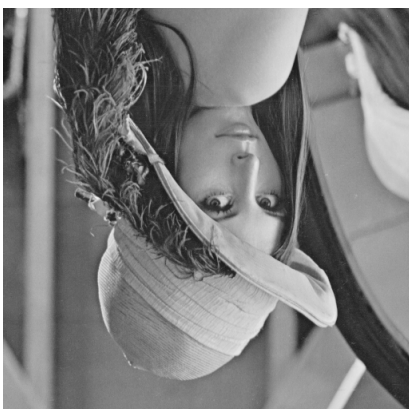
1 import sys
2 import numpy as np
3 import cv2
4
5
6
7 def upside_down(img):
8     ans = np.zeros((img.shape[0],img.shape[1],img.shape[2]),np.int)
9     for x in range(img.shape[0]):
10         ans[x,:]=img[img.shape[0]-x-1,:]
11     return ans
12
13 def right_side_left(img):
14     ans = np.zeros((img.shape[0],img.shape[1],img.shape[2]),np.int)
15     for y in range(img.shape[1]):
16         ans[:,y]=img[:,img.shape[1]-y-1]
17     return ans
18
19 def diagonally_mirrored(img):
20     ans = np.zeros((img.shape[0],img.shape[1],img.shape[2]),np.int)
21     for x in range(img.shape[1]):
22         for y in range(img.shape[0]):
23             ans[x,y] = img[y,x]
24     return ans
25
26 img = cv2.imread('lena.bmp')
27 cv2.imwrite('upside_down.bmp', upside_down(img))
28 cv2.imwrite('right_side_left.bmp', right_side_left(img))
29 cv2.imwrite('diagonallymirrored.bmp', diagonally_mirrored(img))

```

lena.bmp



(a)upside-down



b)right-side-left



(c)diagonally mirrored



## Part2: Use Photoshop to

- (a) rotate lena.im 45 degrees clockwise
- (b) shrink lena.im in half
- (c) binarize lena.im at 128 to get a binary image

註：(a)和(b)都有先在圖片加上背景

- (a) 影像 -> 影像調整 -> 任意 -> 45度
- (b) 影像 -> 影像尺寸 -> 將長寬改成256\*256
- (c) 影像 -> 調整 -> 臨界值 -> 改成128

(a) rotate 45 degrees



(b) shrink in half



(c) binarize at 128

