

# Machine Learning and Data Mining

Basic Matrix Analysis and Singular Value Decomposition

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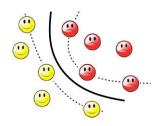
## What is Machine Learning?



Informally: Making predictions from data

Formally: The construction of a statistical model that is an underlying distribution from which the data is drawn from, or using which we can classify the data into different categories.

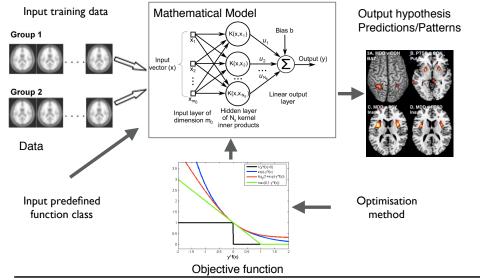




### Review

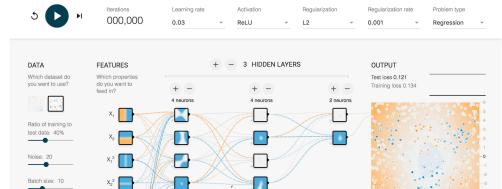
## Elements of Machine Learning





#### Neural Networks





Source: http://playground.tensorflow.org/

REGENERATE

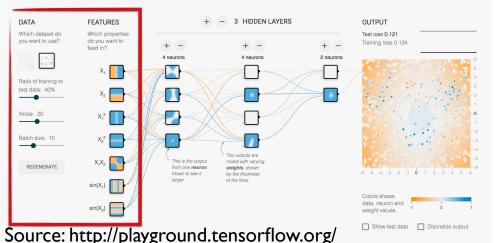
This is the output

from one **neuro** Hover to see it

#### **Neural Networks**





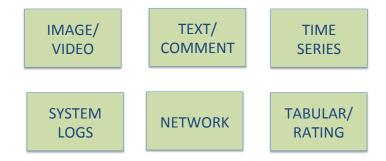


## Common representation



data, neuron and

☐ Show test data ☐ Discretize output



Is there a common way to represent data of different modalities?

#### Text to matrix



- Document-Word Matrix
- Document I: "AACCBBAAA"
- Document 2:"CCAABBDD"

$$\left[\begin{array}{ccccc} A & B & C & D \\ 5 & 2 & 2 & 0 \\ 2 & 2 & 2 & 2 \end{array}\right]$$

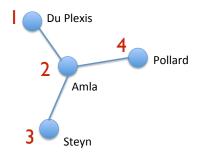
#### Network data



## Image data







	[ 0	1	0	0
Nodes	1	0	1	1
Š	0	1	0	0
	0	1	0	0

						700 x 500			
						4	45	6	
					$\Longrightarrow$	6	12	33	
						22	17	44	
ww	w.sydney.visito	rsbureau.com.au							
	4	45	6	6	12	33	22	17	44

## Similarity Computation

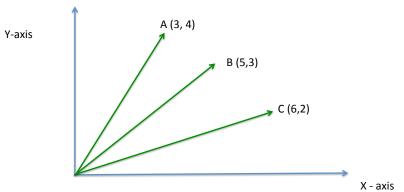


- We can now represent most data types as a matrix.
- A special case of a matrix is a vector.
- Now lets compute similarities with these objects.

## Similarity Computation



How can we quantify similarity between A, B and C?



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## Similarity Computation



## Similarity Computation



Dot product

$$x = (x_1, x_2, ..., x_n);$$
  $y = (y_1, y_2, ..., y_n);$   
 $x.y = (x_1y_1 + x_2y_2 + ... + x_ny_n);$ 

• Norm (length) of a vector

$$||x|| = (x.x)^{1/2} = (x_1.x_1 + x_2.x_2 + x_n.x_n)^{1/2}$$

 The similarity between two vectors x and y is given by

$$sim(x, y) = x.y/(||x|| ||y||)$$

13

## Similarity Computation

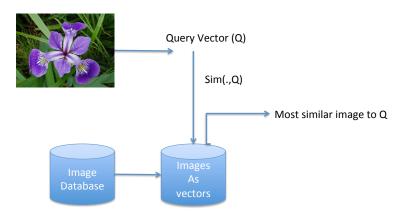


- Can sim(x,y) > 1?  $sim(x,y) = x.y/(\|x\| \|y\|)$
- No! Because of Cauchy-Schwarz inequality:

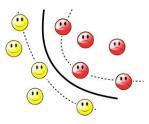
$$|x \cdot y| \le ||x|| ||y||.$$

## Image search engine









## Matrix Algebra

## Why Matrix Algebra?



- In database management, the fundamental entity is a *relation*.
  - SQL (relational algebra) is a collection of operations on relations – Select, project, join, group-by
- In machine learning and data mining, the fundamental entity is a matrix
  - We therefore need to know the basic operations on matrices
  - One important application is to summarise data or extract patterns from data or compress data
  - In SIT several people apply data mining for different domains: Chinese medicine, bioinformatics, student learning, multimedia, image processing, quality of cloud computing service, text analysis, medical imaging, robotics

## Why Matrix Algebra?

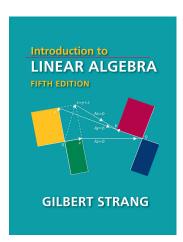


- Data Mining: Computation for large data sets
- Key idea: Data Reduction leads to "Knowledge Discovery"
- Matrix algebra provides simple algorithms with great power for data management, e.g., data reduction or data summarisation.

18

## Suggested book





http://math.mit.edu/~gs/linearalgebra/

#### Numbers vs Matrices



#### **Numbers**

- Can add and subtract numbers
- Multiply numbers
- Divide two numbers a/b as long as b is not equal to 0.
- Can factorise positive numbers into product of primes

#### **Matrices**

- Can add and subtract compatible metrics
- Multiply and divide matrices
- Division of matrices is complicated
- Can factorise any matrix to get data patterns (using a technique called Singular Value Decomposition)

#### Linear Algebra



- Area in maths that deals with vector spaces and linear mappings between these spaces
- The generalisation of LA to infinite dimensions is known as functional analysis

Linear algebra

Functional analysis

21

#### Definition for vector space: 8 Axioms



- Associativity of addition: (u+v)+w=u+(v+w)
- Commutativity of addition: u+v=v+u
- Identity element of addition:  $\exists 0, v+0=v$
- Inverse elements of addition:  $\forall v,\exists -v,v+(-v)=0$
- ullet Compatibility of scalar multiplication with field multiplication: (a and b are scalars) a(bv)=(ab)v
- Identity element of scalar multiplication:  $\exists 1, 1v = v$
- Distributivity of scalar multiplication with respect to vector addition: (a is a scalar) a(u+v)=au+av
- Distributivity of scalar multiplication with respect to field addition: (a and b are scalers)

$$(a+b)v = av + bv$$

#### **Basics** I



$$S = \left[ \begin{array}{rrr} 3 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

- This is a 3 x 3 matrix.
- In general  $m \times n$ .
  - m rows and n columns
  - Square matrix when m=n
- Each row or column could represent one object. If rows are objects then columns are features/attributes/components

#### Basics II



• Identity matrix *I* 

$$\left[\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array}\right]$$

- If A is a square matrix, AI = IA = A
- *I* is an example of a **diagonal** matrix.
- ullet If  $A=[a_1,...a_m]$  is matrix where  $a_i$  are the columns, then
  - A is <u>orthogonal</u> if  $a_i.a_j = 0$  for  $i \neq j$
  - A is orthonormal if above and  $a_i.a_i = 1$

25

27

## Linear independence



- Intuitively, a set of vectors is linearly independent if any element of the set cannot be expressed as a linear combination of the others.
- The columns are not linearly independent:

$$S = \left[ \begin{array}{rrr} 3 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

#### **Basics III**



- Every vector can be written as a linear combination of some finitely many "special" vectors.
- These are called basis-vectors.

$$S = \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$



Exercise

Given v = (1, 2, 3), calculate:

- I. The length of  $\it v$
- 2. A unit vector in the same direction as v
- 3. A set orthogonal bases for  $\boldsymbol{v}$
- 4. A vector perpendicular to v

## Solution



Given v = (1, 2, 3), calculate:

- I. The length of v is  $\sqrt{14}$
- 2. A unit vector in the same direction  $(1/\sqrt{14}, 2/\sqrt{14}, 3/\sqrt{14})$
- 3. A set orthogonal bases: (1, 0, 0); (0, 1, 0), (0, 0, 1)
- 4. A vector perpendicular to v = (-1, -1, 1)

29

#### Rank of a matrix I



- Given a matrix M, the **rank** of a matrix is the maximum number of linearly independent columns.
- A rank 2 matrix:  $S = \left[ \begin{array}{ccc} 3 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$

#### **Determinant**



- Matrix A maps the unit n-cube to the ndimensional parallelotope defined by the column vectors
- The determinant gives the signed n-dimensional volume of this parallelotope
- For 2 by 2 matrix

$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$$|A| = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

$$= aei + bfg + cdh - ceg - bdi - afh.$$



#### Rank of a matrix II

• Can we automatically determine the rank of a matrix

$$S = \left[ \begin{array}{rrr} 3 & 1 & 3.5 \\ 2 & 2 & 3 \\ 4 & 2 & 5 \end{array} \right]$$

• Why is rank important anyways...?

## Transpose of a matrix



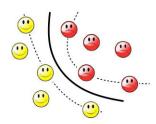
- The transpose of a matrix A, denoted  $A^T$  is another matrix B such that B(i, j) = A(j, i)(just flip the matrix)
- The transpose of S is  $S^T$

$$S = \begin{bmatrix} 3 & 3 & 1 \\ 0 & 2 & 4 \\ 0 & 0 & 0 \end{bmatrix} \qquad S^T = \begin{bmatrix} 3 & 0 & 0 \\ 3 & 2 & 0 \\ 1 & 4 & 0 \end{bmatrix}$$

$$S^T = \begin{bmatrix} 3 & 0 & 0 \\ 3 & 2 & 0 \\ 1 & 4 & 0 \end{bmatrix}$$

33





## Matrix Decompositions

#### Exercise



• What is the rank of the following matrix:

$$\begin{bmatrix}
1 & 2 & 3 \\
3 & 4 & 5 \\
5 & 4 & 3 \\
0 & 2 & 4 \\
1 & 3 & 5
\end{bmatrix}$$

## Eigen Decomposition



ullet For any square matrix A we say that  $\lambda$  is an eigenvalue and u is its eigenvector if

$$A\mathbf{u} = \lambda \mathbf{u}, \quad \mathbf{u} \neq 0.$$

• Stacking up all eigenvectors/values gives

$$AU = U\Lambda = \begin{bmatrix} & | & & & & | \\ \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_n \\ & | & & & | \end{bmatrix} \begin{bmatrix} \lambda_1 & & & & \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & \lambda_n \end{bmatrix}$$

## Eigen Decomposition



- If A is symmetric, all its eig-vals are real, and all its eig-vecs are orthonormal,  $\mathbf{u}_i^T \mathbf{u}_j = \delta_{ij}$
- $\bullet \ \ \text{Hence} \quad U^TU=UU^T=I, \quad |U|^2=1.$
- and  $A = U\Lambda U^T = \sum_{i=1}^n \lambda_i \mathbf{u}_i \mathbf{u}_i^T$

$$A = \begin{bmatrix} & | & & & | & \\ \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_n \\ & | & & | \end{bmatrix} \begin{bmatrix} & \lambda_1 & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} & & \mathbf{u}_1^T & \dots \\ & & \mathbf{u}_2^T & \dots \\ & & \vdots & \\ & & & \mathbf{u}_n^T & \dots \end{bmatrix}$$

$$= \lambda_1 \begin{bmatrix} & | & \\ \mathbf{u}_1 & & \\ & | & \end{bmatrix} \begin{bmatrix} & & \mathbf{u}_1^T & \dots \end{bmatrix} + \dots + \lambda_n \begin{bmatrix} & | & \\ & \mathbf{u}_n & \\ & | & \end{bmatrix} \begin{bmatrix} & & \mathbf{u}_n^T & \dots \end{bmatrix}$$

# Principal component

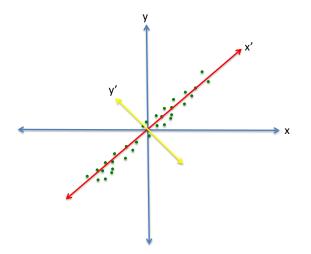


- Given a data matrix  $X \in \mathbb{R}^{n \times d}$ , the principle components of X are the eigenvectors of  $X^{\top}X$
- Principal component analysis (PCA) for X is to find the eigenvectors and eigenvalues of the matrix  $X^{\top}X$ .

37

#### Geometric intuition





#### Exercise



 Find the eigenvectors and eigenvalues for the following matrix

$$\begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix}$$

50

## Singular Value Decomposition



• Given any real matrix X of size (m, n) it can be expressed as:

$$X = U\Sigma V^{T}$$

$$m \times r \qquad r \times r \qquad r \times n$$

- r is the rank of matrix X
- U is a (m, r) column-orthonormal matrix
- V is a (n, r) column-orthonormal matrix
- $\Sigma$  is diagonal  $r \times r$  matrix

## SVD in Python



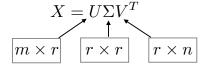
• One line command:

>>> U, s,V = np.linalg.svd(a, full matrices = True)

$$X = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0.58 & 0.58 & 0.58 & 0.71 & 0.71 \end{bmatrix}$$

## Singular Value Decomposition

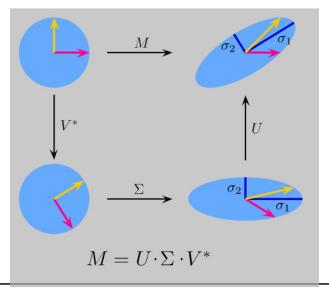




$$X = \lambda_1 \mathbf{u}_1 \times \mathbf{v}_1^t + \lambda_2 \mathbf{u}_2 \times \mathbf{v}_2^t + \dots + \lambda_r \mathbf{u}_r \times \mathbf{v}_r^t$$

SVD as a sequence of operations THE UNIVERSITY OF SYDNEY





#### Qualitative use of SVD



$$X = \begin{bmatrix} 0.18 & 0 \\ 0.36 & 0 \\ 0.18 & 0 \\ 0.90 & 0 \\ 0 & 0.53 \\ 0 & 0.80 \\ 0 & 0.27 \end{bmatrix} \times \begin{bmatrix} 9.64 & 0 \\ 0 & 5.29 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \\ 0 & 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

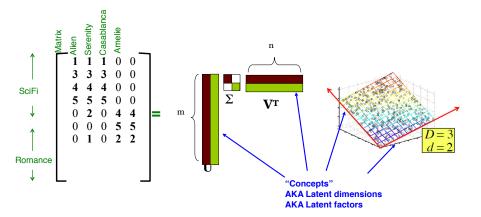
- Two kinds of customers (businesses and individuals)
- Two kinds of days (weekday and weekends)
- *U* is a customer-pattern matrix
- V is a day-pattern matrix
- V(1,2) = 0 means Wednesday has zero similarity with the "weekend pattern."

45

## Example: Users to Movies



•  $A = U\Sigma V^T$ - example: Users to Movies



#### Data reduction with SVD



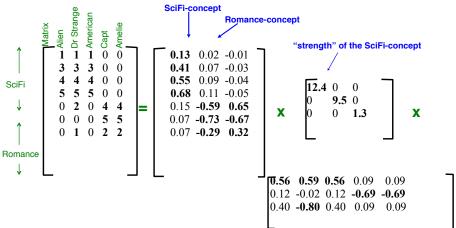
- Now how can we use an SVD decomposition...
- The first way is **qualitative**...
  - Customer-day pattern; or Customer-Pattern-day matrix...
- The second way is **quantitative**...
  - When X is very large, we can compress X into a smaller matrix but still retain important information...

Example: Users to Movies



ullet  $A=U\Sigma V^T$ - example: Users to Movies

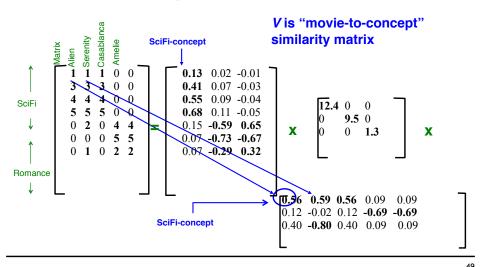
*U* is "user-to-concept" similarity matrix



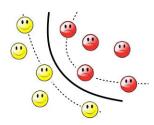
## Example: Users to Movies



•  $A = U\Sigma V^T$  - example:







# Data Reduction and Matrix compression

### Interpretation



'movies', 'users' and 'concepts':

- **U**: user-to-concept similarity matrix
- V: movie-to-concept similarity matrix
- Σ: its diagonal elements: 'strength' of each concept

50

## Spectral representation



• Matrix *X* can also be written as:

$$X = \lambda_1 \mathbf{u}_1 \times \mathbf{v}_1^t + \lambda_2 \mathbf{u}_2 \times \mathbf{v}_2^t + \dots + \lambda_r \mathbf{u}_r \times \mathbf{v}_r^t$$

• The above is called **spectral** representation.

$$X = 9.64 \times \begin{bmatrix} 0.18 \\ 0.36 \\ 0.18 \\ 0.90 \\ 0 \\ 0 \\ 0 \end{bmatrix} \times \begin{bmatrix} 0.58 & 0.58 & 0.58 & 0 & 0 \end{bmatrix} + 5.29 \times \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0.53 \\ 0.80 \\ 0.27 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0.71 & 0.71 \end{bmatrix}$$

## Example: compression of X



$$X = U \Sigma V^{T}$$

$$m \times r$$

$$r \times r$$

$$r \times n$$

- Size of X = mn
- Size of  $U + \Sigma + V$  is mr + r + nr
- Thus compression ratio is

$$\frac{mr+r+nr}{mn} = \frac{r(m+1+n)}{mn} \approx \frac{rm}{mn} = \frac{r}{n}$$

• Can we do better?

#### 53

## Example: compression of X



• Now a compact way of writing the spectral representation is:

$$X = \sum_{i=1}^{r} \lambda_i \mathbf{u}_i \times \mathbf{v}_i^t$$

• However, can approximate it as:

$$\hat{X} = \sum_{i=1}^{k} \lambda_i \mathbf{u}_i \times \mathbf{v}_i^t$$

• This new compression ratio is:

$$\frac{mk+k+nk}{mn} = \frac{k(m+1+n)}{mn} \approx \frac{km}{mn} = \frac{k}{n} \leqslant \frac{r}{n}$$

## Example: compression of X



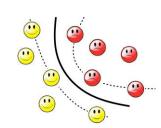
- To get better compression we should look at the  $\lambda$  values.
  - These are called **singular values**.
- We can arrange them in descending order:

$$\lambda_1 \geqslant \lambda_2 \geqslant \cdots \geqslant \lambda_r > 0$$

Now recall....

$$X = \lambda_1 \mathbf{u}_1 \times \mathbf{v}_1^t + \lambda_2 \mathbf{u}_2 \times \mathbf{v}_2^t + \dots + \lambda_r \mathbf{u}_r \times \mathbf{v}_r^t$$





## Thanks!