Operational earthquake forecasting during the M6.4 Searles Valley and M7.1 Ridgecrest sequence using the UCERF3-ETAS model—evaluation and lessons learned

Kevin Milner (USC), Ned Field (USGS), Bill Savran (USC), Tom Jordan (USC), Morgan Page (USGS), Max Werner (Bristol)

Background

By 11:07 am on July 4, 2019 (33 minutes after the M6.4 Searles Valley earthquake), the first UCERF3-ETAS aftershock simulations were running at the University of Southern California's High-Performance Computing Center. UCERF3-ETAS (Field et al., 2017), an extension to the Third Uniform California Earthquake Rupture Forecast, is the first comprehensive fault-based epidemic-type aftershock sequence model. It produces ensemble simulations of aftershock sequences both on and between explicitly modeled UCERF3 faults to answer a key question in earthquake forecasting: What are the chances that an earthquake that just occurred will turn out to be the foreshock of an even bigger event? Standard short-term forecasting models in current use by the USGS and CEPEC do not explicitly consider the proximity of seismic activity to major faults like the Garlock.

Development of the UCERF3-ETAS code base during the past year allowed us to rapidly prepare Ridgecrest simulations. Moreover, new tools were quickly developed in the weeks following the M7.1 event, including the incorporation of 3-D finite rupture models, which allowed us to account explicitly for the distance between the observed rupture surfaces and neighboring faults. As various finite fault models were generated, sensitivity to rupture geometry became apparent, though the differences between all of the finite sources are much smaller than the difference between using our best finite source and point source. This suggests that, while sensitivities exist, inclusion of an uncertain finite source is still preferred over a point source model.

M7.1 Preferred Model Results (Finite Source)

A detailed finite rupture geometry was posted ComCat on Thursday, July 11, at 6:32 pm. This geometry was developed through analysis of coseismic deformation from INSAR. We developed the capability to scrape these sources for use in UCERF3-ETAS simulations on Tuesday, July 16, and have used that rupture geometry as our preferred model since.
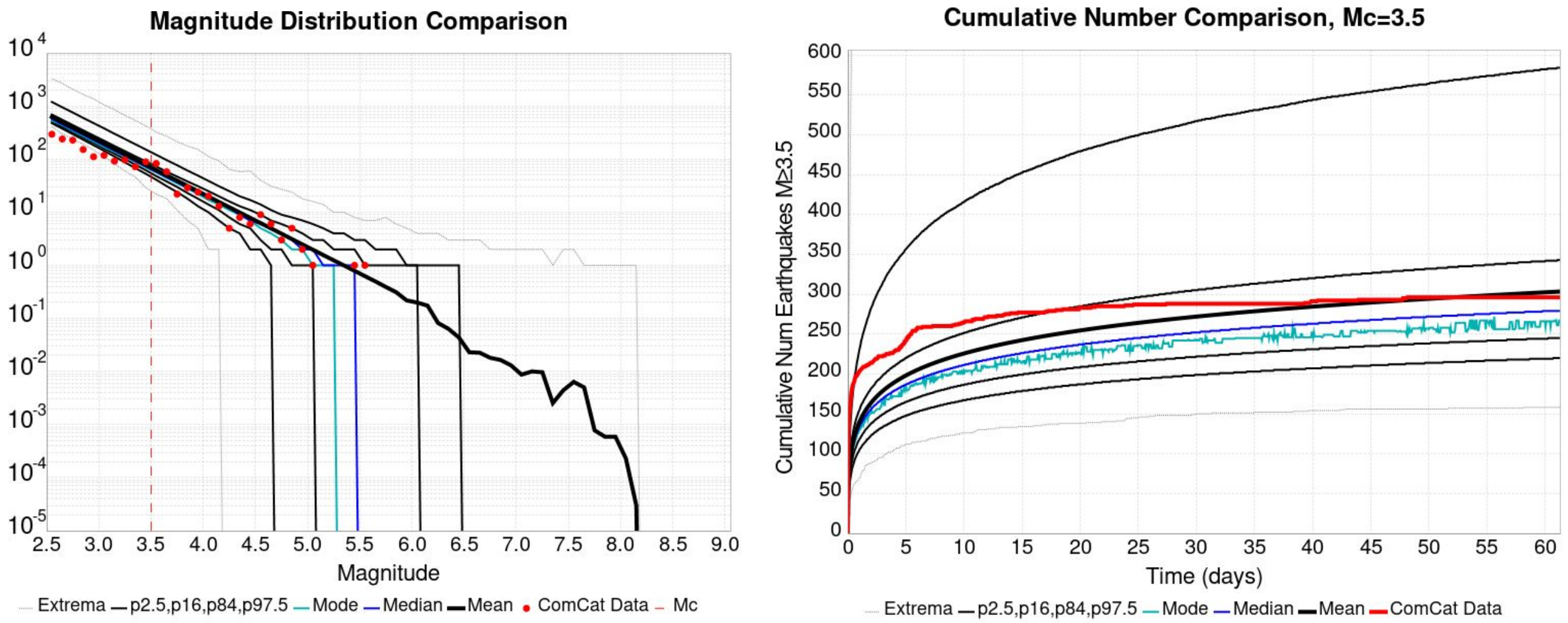

Figure 1: Magnitude-Number Comparison
Comparison of UCERF3-ETAS preferred model predicted incremental magnitude number distribution (solid lines) and actual aftershocks reported by ComCat (M7.1). Simulation mean expectation is plotted with a thick black line, median in blue, percentiles as thin black lines.
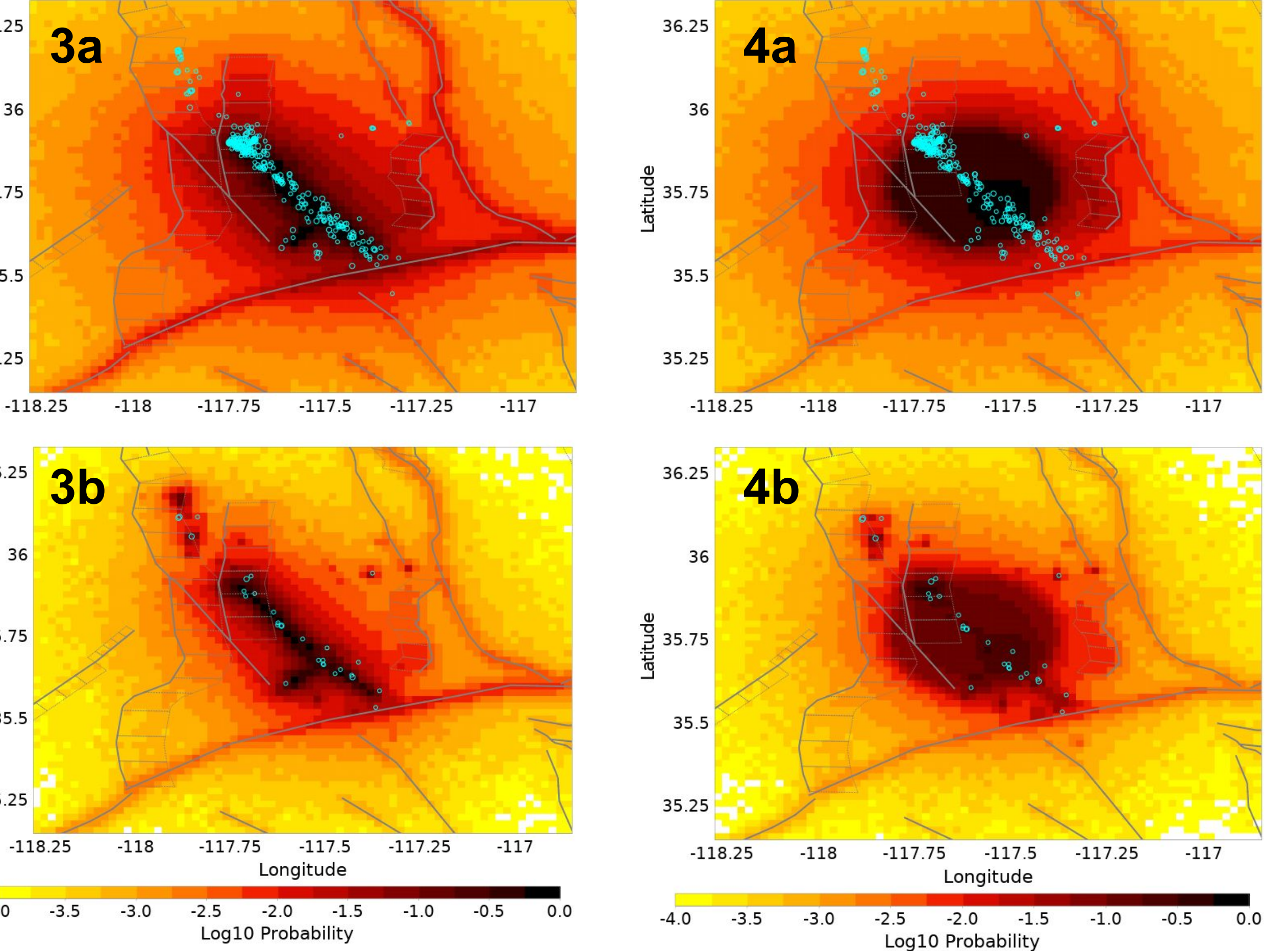
Figure 2: Cumulative Number M≥3.5 Comparison
Comparison of UCERF3-ETAS cumulative number of M≥3.5 events as a function of time with ComCat data. While the actual sequence has a different shape (higher mainshock productivity, lower aftershock productivity), the overall fit after 2 months is good.

Figure 3: Spatial Distribution of M≥3.5 Events
Comparison of UCERF3-ETAS preferred model predicted spatial distribution of M≥3.5 aftershocks with ComCat data (cyan circles). Probabilities are highest along the input rupture surface, and near previously mapped active neighboring faults (gray lines). Both panels show one month probabilities, (a) beginning immediately after the M7.1, and (b) beginning one week later.

Figure 4: Point Source Spatial Distribution
Same as Figure 3, except with a point source rupture model instead of the finite rupture source. Failure to include the finite source model results in a generic, spherical falloff from the epicenter (most probabilities are higher in the vicinity of previously mapped faults). Even when the first week of aftershocks are used as input to the model in (b), resultant spatial probabilities are still spherical.
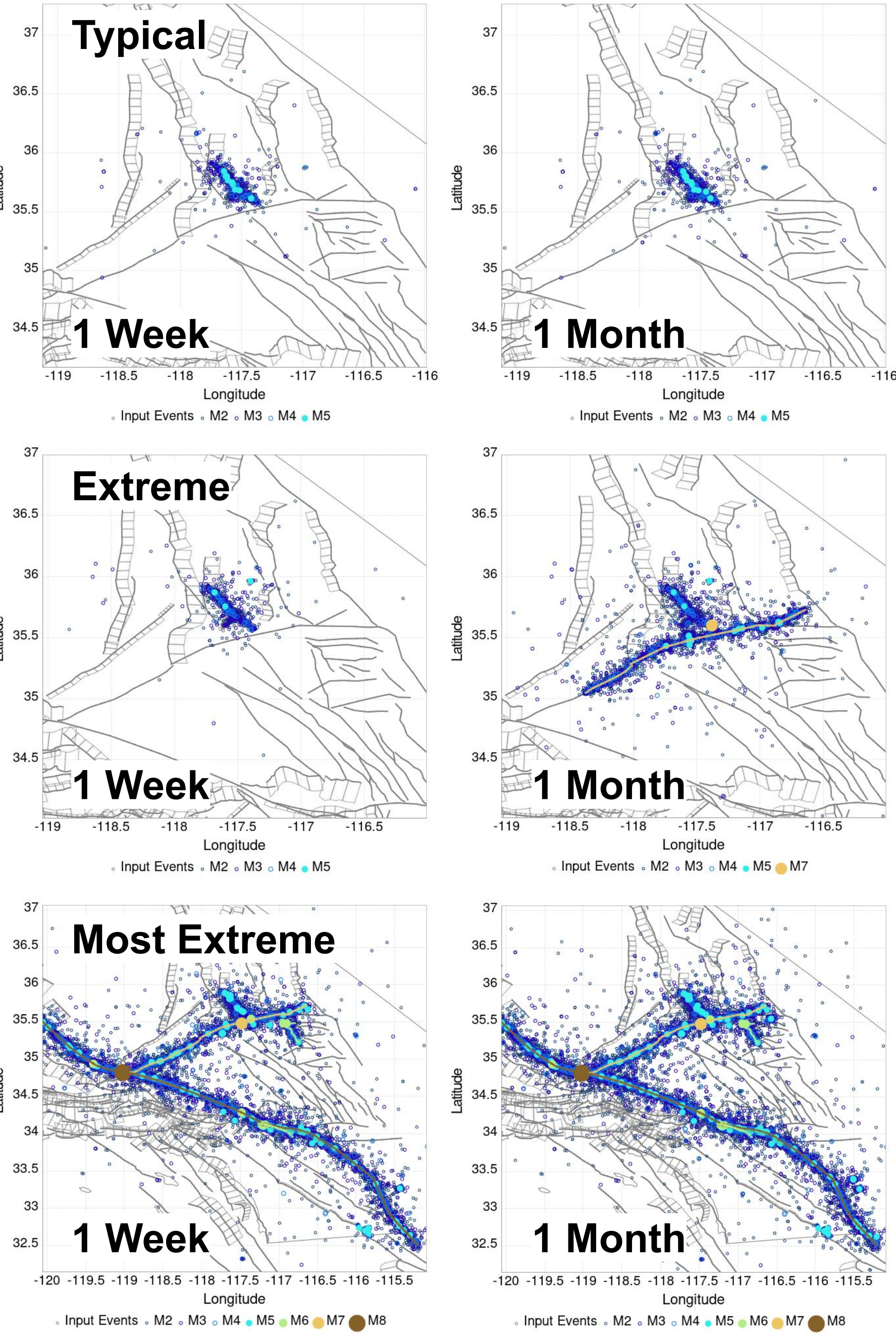
Figure 5: Individual Simulated Catalogs
We ran 100,000 UCERF3-ETAS simulations for each parameterization. The plots on the above show "typical" (50th percentile, top row), "extreme" (97.5th percentile, middle row), and "most extreme" (bottom row) sequences. The left column shows the progression of each simulated sequence as of 1 week from the M7.1, and the right column 1 month. Note that the "extreme" sequence looked very similar to the "typical" sequence as of the one month mark, before a supra-seismogenic Garlock fault rupture was triggered. The most extreme simulation had both large Garlock and San Andreas aftershocks within the first week of the M7.1.
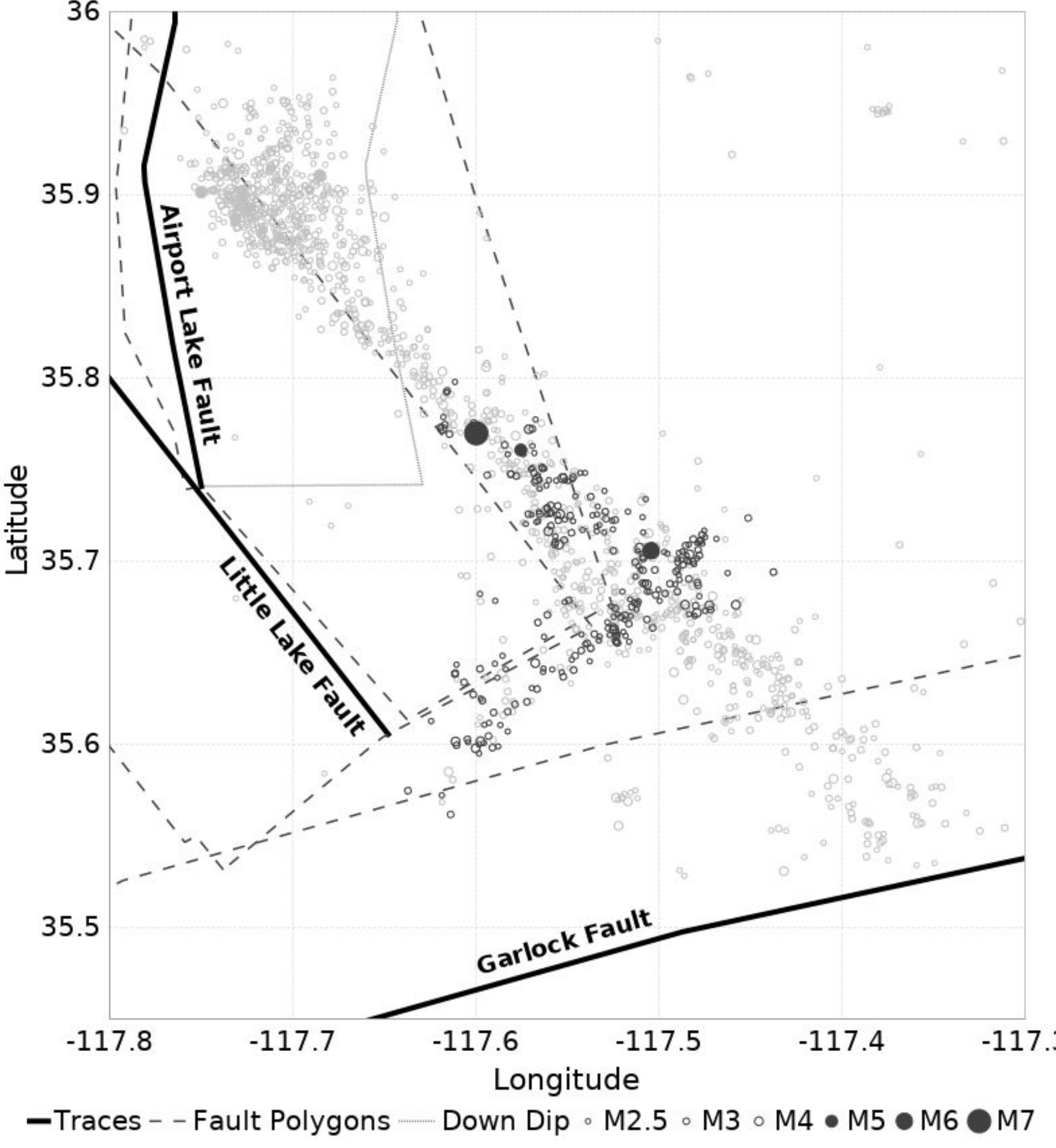
Figure 6: Relationship to Previously Mapped UCERF3 Faults
Map view of model input events from ComCat (M≥2.5, accessed 9/4/2019) from one week preceding to one week following the M7.1 earthquake (circles). Events which occurred up to and including the M7.1 are plotted as dark circles, and those which occurred in the week following are light circles. UCERF3 faults traces are drawn as thick black lines, and the extent of dipping fault surfaces (e.g. Airport Lake) are outlined in dotted gray lines. UCERF3 polygons for each fault are drawn with thin dashed dark lines. The M7.1 epicenter (largest dark circle) occurred inside the polygon for the Airport Lake fault, while the M6.4 (second largest dark circle) occurred outside of all UCERF3 fault polygons.

Typical — 1 Week — 1 Month
Extreme — 1 Week — 1 Month
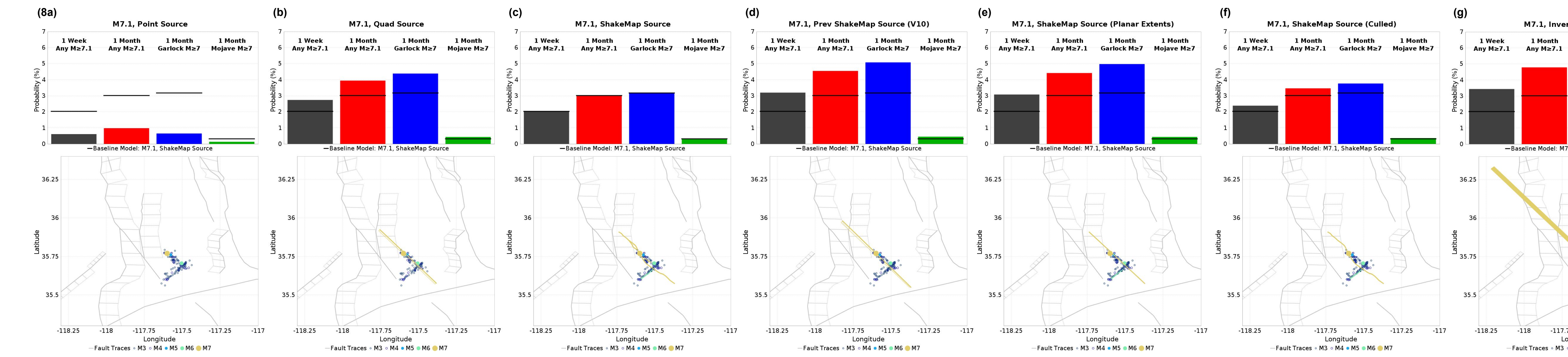**Most Extreme** — 1 Week — 1 Month

UCERF3-ETAS provides useful information about fault probabilities after Ridgecrest, but can be sensitive to inputs

- Assesses probability of Ridgecrest triggering neighboring faults (e.g. Garlock)
- Such probabilities are sensitive to poorly constrained rupture geometry
- Still better to include a poorly constrained rupture surface than completely ignore finite fault extents (if interested in fault probabilities or spatial probability distribution)
- Having a real event (Ridgecrest) was extremely valuable for learning about these sensitivities and motivating development of tools to improve response to future events

Model Sensitivities

Sensitivity of various probabilities (bar charts) to different UCERF3-ETAS configurations. Simulation input fault geometry is shown on the bottom map view panels, with the M7.1 surface in gold. Probabilities are in the top chart panels, with the preferred model (ShakeMap finite source, default parameters) annotated with a black line.

Figure 7 (right): Sensitivity to different model parameters. Probabilities are higher for this parameterization than for the no-faults version (b). Areas without explicitly mapped faults in regular UCERF3-ETAS are anti-characteristic (as faults are, on average, characteristic and the model is Gutenberg-Richter statewide by construction), which results in lower probabilities of triggering large ruptures (a) than when faults are excluded. The reverse would be true if the event had occurred on a mapped fault. Results for sequence specific ETAS parameters are shown in (c).

Figure 8 (below): Sensitivity to different input fault geometries. The default model (c) is the ShakeMap finite fault source. Point source (a) simulations have much lower probabilities. Triggering probabilities are sensitive to the distance to faults, and the overall squirliness of the surface. Because surfaces are discretized evenly, with each point on the surface assigned an equal triggering potential, linear surfaces (with fewer points) give higher probability to the point at the end of the rupture nearest Garlock. The last panel (g) shows the finite source surface from the ComCat USGS finite fault event page, which is overly large and unsuitable for use as input to UCERF3-ETAS.

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