

VOLUME = 9.7698795e+06 MM^3
SURFACE AREA = 4.5454505e+06 MM^2
AVERAGE DENSITY = 2.1672039e-06 KILOGRAM / MM^3
MASS = 2.1173321e+01 KILOGRAM

CENTER OF GRAVITY with respect to BODY_SYS coordinate frame:
X Y Z -2.4530316e-01 1.1726402e+00 2.6549449e+02 MM

INERTIA with respect to BODY_SYS coordinate frame: (KILOGRAM * MM^2)

INERTIA TENSOR:
Ixx Ixy Ixz 3.3546678e+06 -5.5712339e+02 -1.3427256e+04
Iyx Iyy Iyz -5.5712339e+02 3.1933458e+06 -2.2806672e+03
Izx Izy Izz -1.3427256e+04 -2.2806672e+03 2.1998895e+05

INERTIA at CENTER OF GRAVITY with respect to BODY_SYS coordinate frame: (KILOGRAM * MM^2)

INERTIA TENSOR:
Ixx Ixy Ixz 1.8621879e+06 -5.6321395e+02 -1.4806203e+04
Iyx Iyy Iyz -5.6321395e+02 1.7008938e+06 4.3112127e+03
Izx Izy Izz -1.4806203e+04 4.3112127e+03 2.1995856e+05

PRINCIPAL MOMENTS OF INERTIA: (KILOGRAM * MM^2)
I1 I2 I3 2.1981256e+05 1.7009040e+06 1.8623236e+06

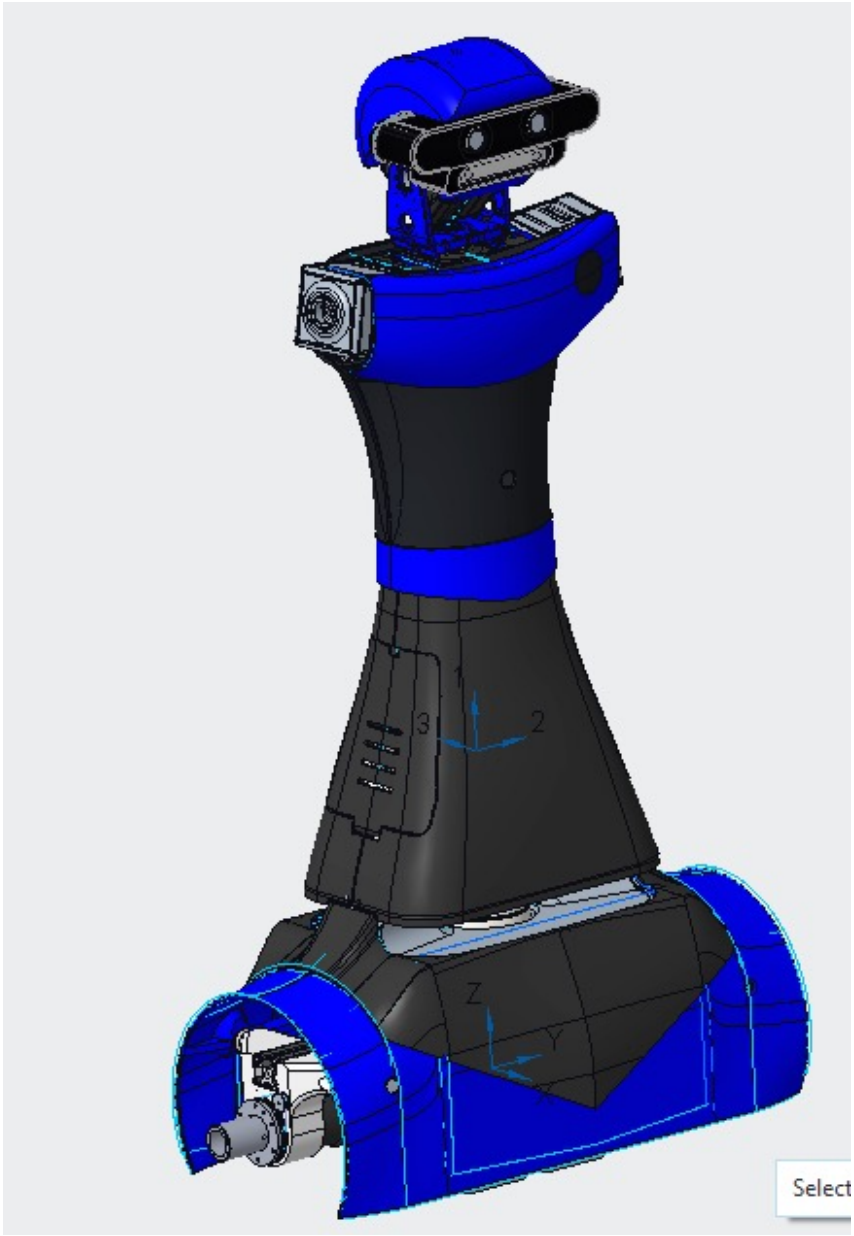
ROTATION MATRIX from BODY_SYS orientation to PRINCIPAL AXES:
0.00901 0.00376 -0.99995
-0.00291 0.99999 0.00373
0.99996 0.00287 0.00902

ROTATION ANGLES from BODY_SYS orientation to PRINCIPAL AXES (degrees):
angles about x y z -22.455 -89.441 -22.620

RADII OF GYRATION with respect to PRINCIPAL AXES:
R1 R2 R3 1.0189005e+02 2.8342974e+02 2.9657400e+02 MM

MASS PROPERTIES OF COMPONENTS OF THE ASSEMBLY
(in assembly units and the BODY_SYS coordinate frame)

DENSITY	MASS	C.G.: X	Y	Z
EGO2_MBASE MATERIAL: UNKNOWN				
1.88027e-06	1.42456e+01	-1.32698e+00	1.71417e+00	8.25453e+01
MTEG100_TORSO MATERIAL: UNKNOWN				
3.15826e-06	6.92772e+00	1.97897e+00	5.90742e-02	6.41696e+02



Advanced Measure Results

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BODY_SYS:F5(CSYS)

X = 0.0000000000

Y = 0.0000000000

Z = 0.0000000000

ARM_L_SYS:F9(CSYS)

X = -145.290

Y = 668.027

Z = -15.2252

All References

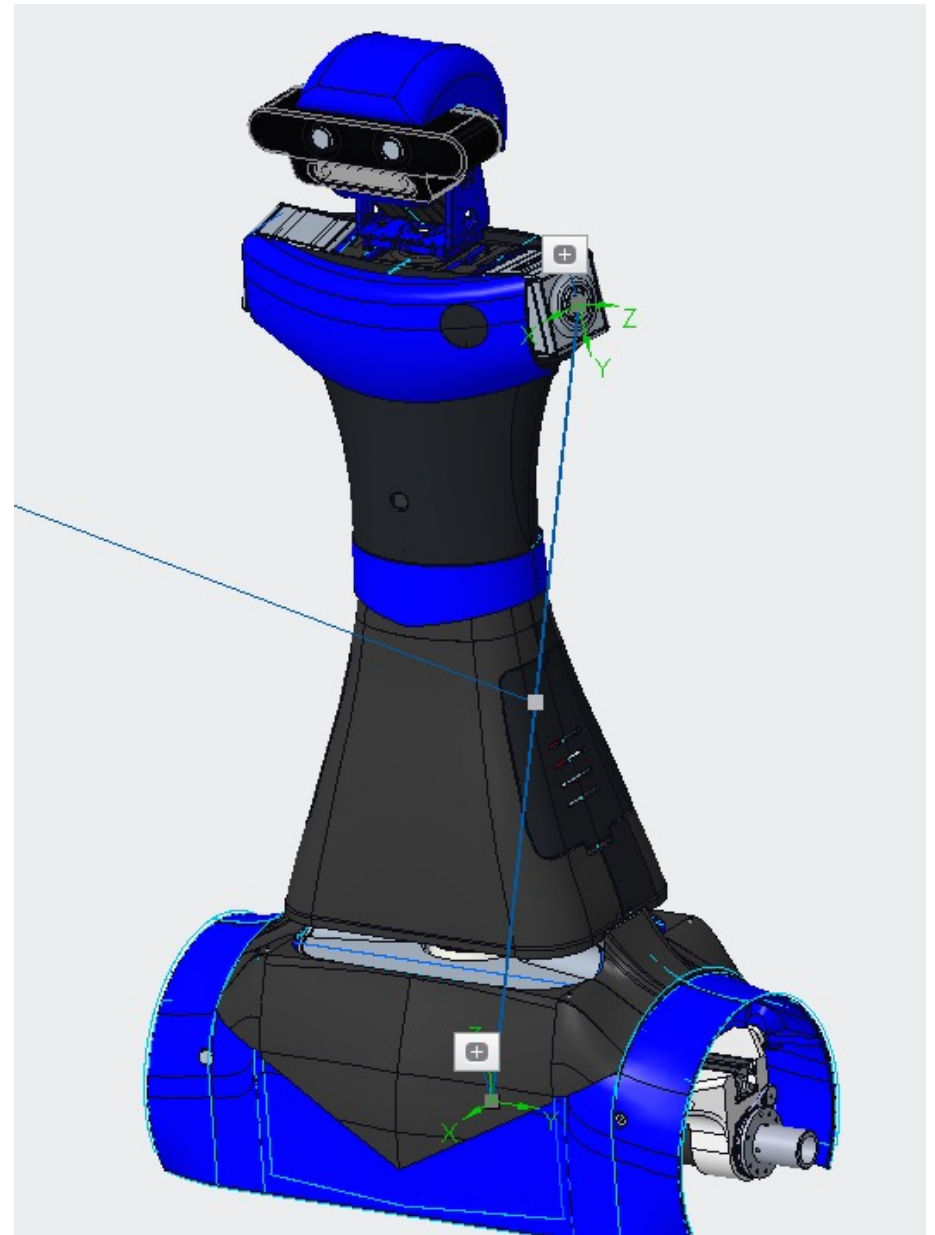
Distance = 683.814 mm

Transformation matrix =

0.984808 0.000000 0.173648 15.225205

-0.171010 0.173648 0.969846 145.290291

-0.030154 -0.984808 0.171010 668.026953



Advanced Measure Results

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BODY_SYS:F5(CSYS)

X = 0.0000000000

Y = 0.0000000000

Z = 0.0000000000

ARM_R_SYS:F10(CSYS)

X = 145.290

Y = 668.027

Z = -15.2252

All References

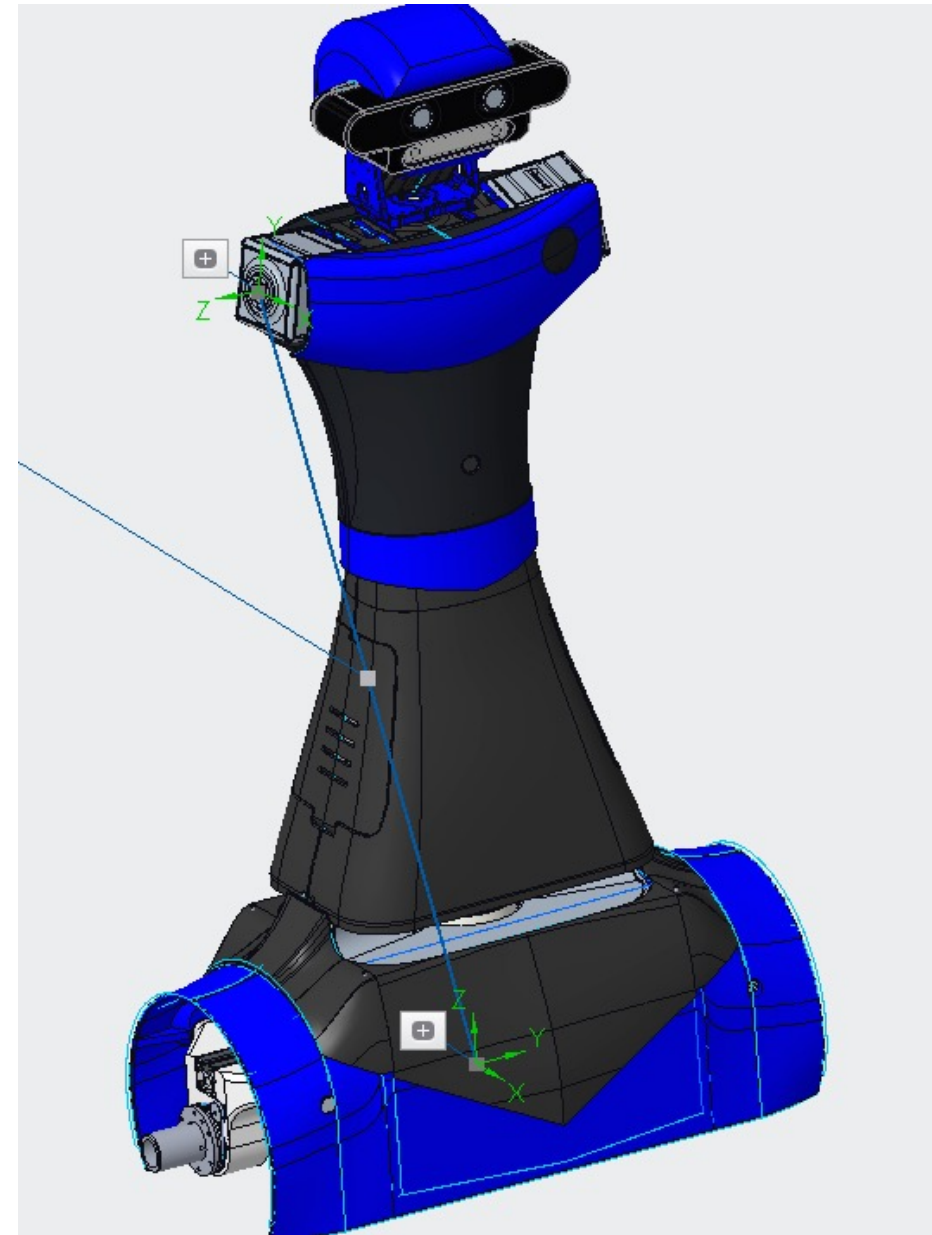
Distance = 683.814 mm

Transformation matrix =

0.984808 -0.000000 0.173648 15.225205

0.171010 0.173648 -0.969846 -145.290291

-0.030154 0.984808 0.171010 668.026953



Advanced Measure Results

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BODY_SYS:F5(CSYS)

X = 0.0000000000

Y = 0.0000000000

Z = 0.0000000000

HEAD_INTERFACE:F11(CSYS)

X = 0.0000000000

Y = 698.500

Z = 0.0000000000

All References

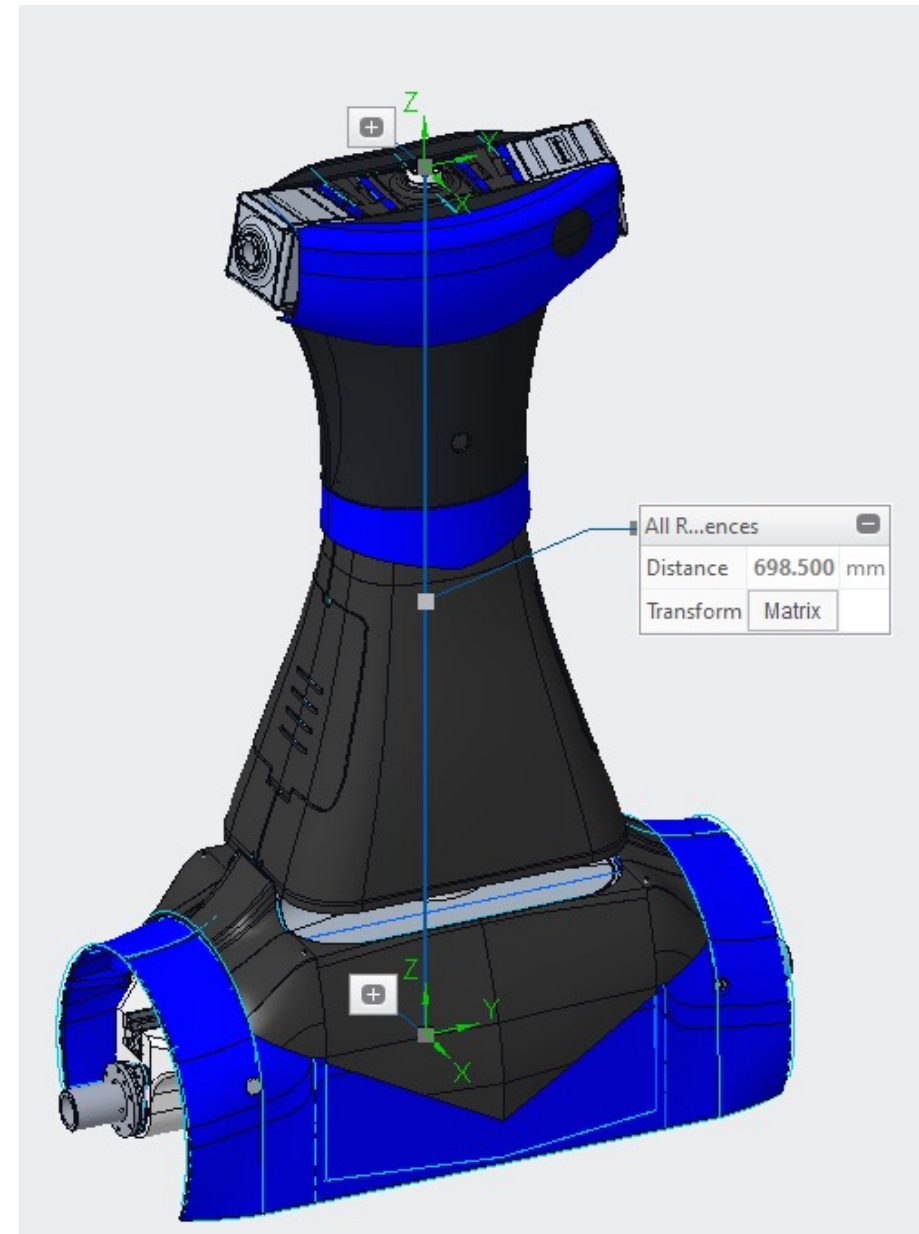
Distance = 698.500 mm

Transformation matrix =

1.000000 0.000000 0.000000 0.000000

0.000000 1.000000 0.000000 0.000000

0.000000 0.000000 1.000000 698.500000



Advanced Measure Results

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BODY_SYS:F5(CSYS)

X = 0.0000000000

Y = 0.0000000000

Z = 0.0000000000

HEAD_INTERFACE:F43(CSYS):MTEG102_HEAD

X = 0.0000000000

Y = 753.477

Z = 0.0000000000

All References

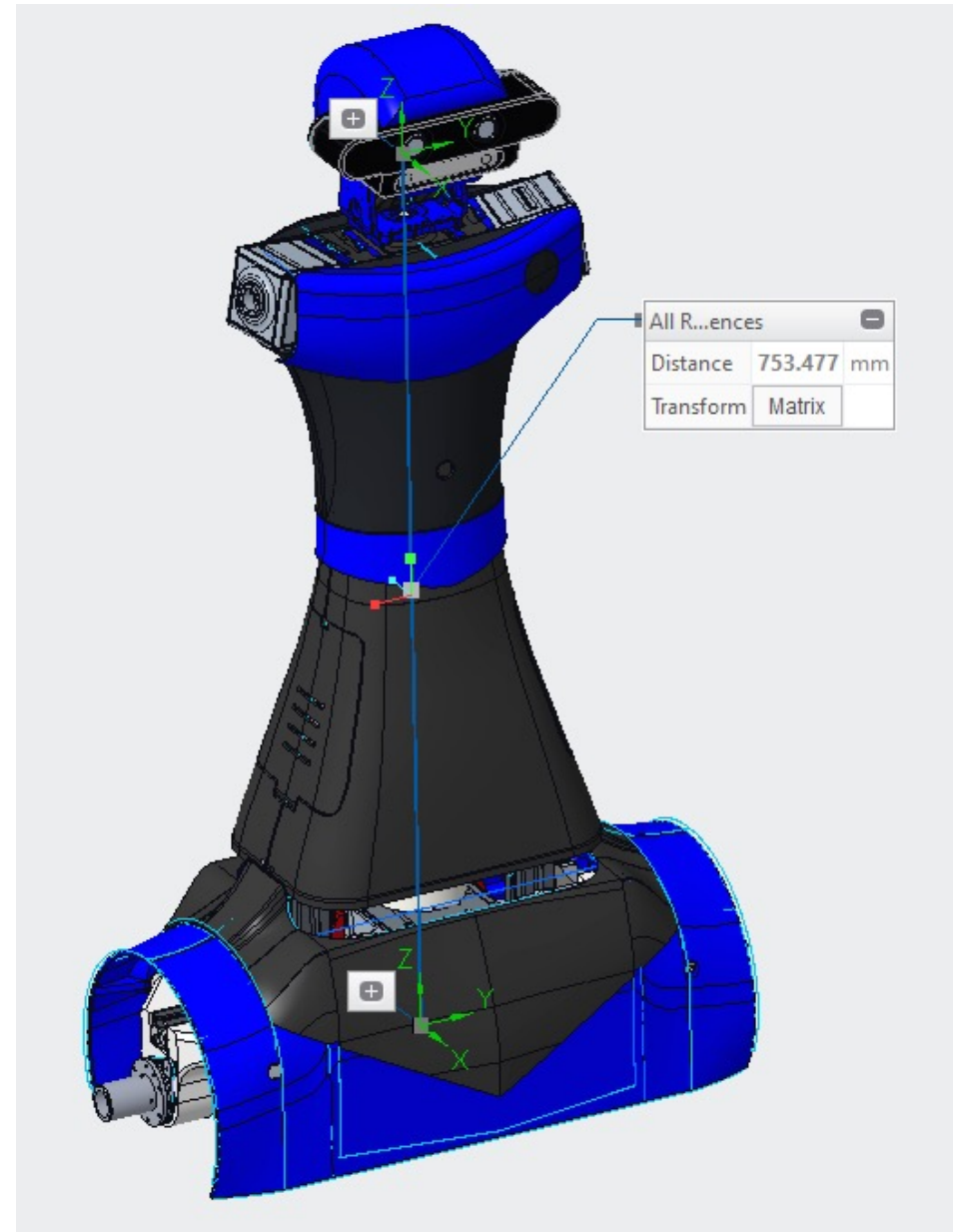
Distance = 753.477 mm

Transformation matrix =

1.000000 0.000000 -0.000000 -0.000000

-0.000000 1.000000 -0.000000 0.000000

-0.000000 0.000000 1.000000 753.476858



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BODY_SYS:F5(CSYS)

X = 0.0000000000

Y = 0.0000000000

Z = 0.0000000000

LIDAR_INTERFACE:F7(CSYS):RPLIDAR_A2_SLAMTEC

X = 0.0000000000

Y = 116.000

Z = 0.0000000000

All References

Distance = 116.000 mm

Transformation matrix =

1.000000 0.000000 0.000000 -0.000000

0.000000 1.000000 0.000000 -0.000000

0.000000 0.000000 1.000000 116.000000

