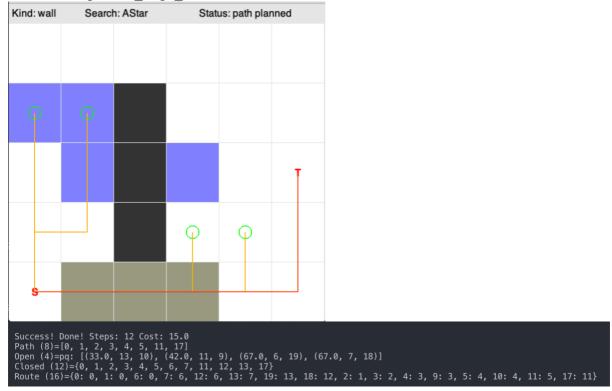
Before change: min_edge_cost = 10.0



After change:



By changing the value to the min value, more routes are discovered. This means that the path finding algorith is more optimal to find more available solutions.

```
def reset_navgraph(self):
     self.path = None # invalid so remove if present
     self.graph = SparseGraph()
     self.graph.cost_h = self._manhattan
     self.graph.cost_h = self._hypot
     self.graph.cost_h = self._max
     nx, ny = self.nx, self.ny
     for i, box in enumerate(self.boxes):
       box.pos = (i % nx, i // nx) #tuple position
       box.node = self.graph.add_node(Node(idx=i))
     for i, box in enumerate(self.boxes):
       if box.kind in no_edge:
       if (i+nx) < len(self.boxes):</pre>
          self._add_edge(i, i+nx)
       if (i-nx) \ge 0:
          self._add_edge(i, i-nx)
       if (i\%nx + 1) < nx:
          self._add_edge(i, i+1)
          self._add_edge(i, i-1)
       if (j-1) < len(self.boxes) and (j\%nx - 1) >= 0:
          self._add_edge(i, j-1, 1.4142) # sqrt(1+1)
       if (j+1) < len(self.boxes) and (j\%nx + 1) < nx:
          self._add_edge(i, j+1, 1.4142)
```

```
# DOWN LEFT(i - nx - 1)

j = i - nx

if (j-1) >= 0 and (j%nx - 1) >= 0:

print( i, j, j%nx)

self._add_edge(i, j-1, 1.4142)

# DOWN RIGHT (i - nx + 1)

j = i - nx

if (j+1) >= 0 and (j%nx +1) < nx:

self._add_edge(i, j+1, 1.4142)
```

Code needed to add diagonal edges is uncommented and fixed. The use of Manhattan distance calculation is altered.