MSAI3105 Exam Preparation: Questions & Answers

Lecture 1: Introduction to AI

Q: Who proposed the Turing Test? A: Alan Turing (1950).
Q: What does AI stand for? A: Artificial Intelligence.
Q: Which of the following is *not* one of the four AI definitions? (a) Thinking humanly (b) Thinking rationally (c) Acting mechanically (d) Acting humanly A: c) Acting mechanically.
Q: What is the main idea of the Turing Test? A: If a machine can imitate human responses so well that a human interrogator cannot reliably distinguish it from a person, it is considered intelligent.
Q: The Dartmouth Conference in officially coined the term 'Artificial Intelligence.' A: 1956.
Q: What are the four main approaches to defining AI? A: Systems that (1) think like humans, (2) think rationally, (3) act like humans, (4) act rationally.
Q: Cognitive science emerged in which decade? A: 1960s.
Q: What is a rational agent? A: An entity that chooses actions expected to maximize its performance measure, given its percept history.
Q: Al can be broadly divided into Al and Al. A: Narrow Al (Weak Al) and General Al.
Q: Give two examples of risks of AI. A: Autonomous weapons, biased decision making, surveillance, cybersecurity threats.
Q: Which of the following is considered an early AI milestone? (a) Samuel's checkers program (b) Kasparov vs. Deep Blue (c) GPT-4 passing a Turing test (d) ImageNet challenge A: a) Samuel's checkers program.
Q: What is the 'gorilla problem' analogy in AI risk? A: Just as humans control gorillas despite evolving together, AI might surpass and control humans.
Q: Aristotle's *laws of thought* inspired the approach to AI. A: Rational thinking / logic-based.
Q: List three disciplines that influenced the development of AI.A: Philosophy, mathematics, neuroscience, psychology, linguistics, economics.
Q: What is the main limitation of the Turing Test? A: It is not reproducible, constructive, or mathematically rigorous.
A: Rational thinking / logic-based. Q: List three disciplines that influenced the development of AI. A: Philosophy, mathematics, neuroscience, psychology, linguistics, economics. Q: What is the main limitation of the Turing Test?

Lecture 2: Agents & Problem Solving

Q: What is an agent? A: Anything that perceives its environment through sensors and acts upon it with actuators.
Q: The agent function maps to actions. A: Percept histories.
Q: What does PEAS stand for? A: Performance measure, Environment, Actuators, Sensors.
Q: In the vacuum cleaner world, the agent's actions are,, and A: Left, Right, Suck, NoOp.
Q: What is the difference between simple reflex agents and model-based agents? A: Simple reflex agents act on current percepts only, while model-based agents maintain internal state.
Q: Which of these is a goal-based agent? Automated taxi agent. A: Yes, because it considers goals.
Q: Define rationality in agents.A: Choosing actions that maximize expected performance based on percepts and knowledge.
Q: Rational ≠ and Rational ≠ A: Omniscient; Clairvoyant.
Q: Give an example of an environment property. A: Observable vs. partially observable, deterministic vs. stochastic, static vs. dynamic, episodic vs. sequential.
Q: What is a utility-based agent? A: One that chooses actions to maximize an internal utility function.
Q: Example of Internet shopping agent PEAS? A: Performance: price/quality; Environment: WWW; Actuators: display, form-fill; Sensors: HTML pages.
Q: Which environment type is Solitaire? A: Observable and Deterministic.
Q: What is the main limitation of BFS in search? A: High space complexity (O(b^d)).
Q: The Romania problem starts in and ends in A: Arad \rightarrow Bucharest.
Q: What is the difference between nodes and states in search? A: States describe the world; nodes are data structures in the search tree containing state, parent, and path cost.

Lecture 3: Search Strategies & Heuristics

Q: What are the four evaluation criteria for search strategies? A: Completeness, Optimality, Time complexity, Space complexity.
Q: BFS is complete if? A: Branching factor is finite and step cost is uniform.
Q: Why is DFS not optimal? A: It may return a longer path if it encounters a non-optimal solution first.
Q: Time complexity of BFS? A: O(b^d).
Q: Space complexity of DFS? A: O(bm).
Q: What problem does UCS solve that BFS cannot? A: Handles varying edge/path costs.
Q: UCS uses a queue ordered by path cost g(n). A: Priority queue.
Q: What is a heuristic? A: An estimate of the cost from the current state to the goal.
Q: Example of admissible heuristic for 8-puzzle? A: Manhattan distance, misplaced tiles.
Q: Greedy Best-First Search uses evaluation function? A: h(n).
Q: A* evaluation function $f(n) = \underline{\hspace{1cm}}$. A: $g(n) + h(n)$.
Q: Condition for heuristic admissibility?A: h(n) ≤ true cost from n to goal.
Q: What happens if heuristic is inconsistent? A: A* may not guarantee optimality.
Q: Manhattan distance heuristic is used for A: Grid problems like 8-puzzle.
Q: Advantage of A* over Greedy search? A: A* is both complete and optimal with admissible heuristics.

Lecture 4: Advanced Search & Local Optimization

Q: Two heuristic functions for the 8-puzzle? A: h1 = misplaced tiles; h2 = Manhattan distance. Q: What does dominance of heuristics mean? A: If $h2 \ge h1$ and both admissible, h2 dominates. Q: Typical nodes expanded by A*(h2) at depth 24 in 8-puzzle? A: ~1,641 nodes. Q: What is local search used for? A: Optimization problems where the goal matters, not the path. Q: Example of local search problem? A: N-Queens, TSP. Q: Hill climbing can get stuck in _____ and ____. A: Local maxima, plateaus. Q: How does simulated annealing differ from hill climbing? A: It accepts worse moves with a probability. Q: What is the probability function in simulated annealing? A: $P = e^{-\Delta E} / T$). Q: What is a genetic algorithm inspired by? A: Biological evolution (selection, crossover, mutation). Q: Which search is guaranteed complete? A: Random restart hill climbing. Q: Example of real-world use of simulated annealing? A: VLSI layout, airline scheduling. Q: What is a pattern database heuristic? A: Precomputed exact costs for subproblems.

Lecture 5: Game Playing

Q: Who first described the minimax algorithm?

A: Ernst Zermelo (1912). Q: What is a zero-sum game? A: One player's gain equals the other's loss. Q: Example of stochastic game? A: Backgammon. Q: Branching factor in chess? A: About 35. Q: What is the minimax value of a node? A: Utility for MAX assuming optimal play. Q: Optimality of minimax? A: Optimal against an optimal opponent. Q: Alpha-beta pruning reduces search complexity to _____ A: O(b^(m/2)) with perfect ordering. Q: What is the horizon effect? A: Mis-evaluating because key events are beyond cutoff depth. Q: What is quiescence search? A: Extend search in unstable positions to avoid horizon effect. Q: Which program defeated Kasparov in 1997? A: Deep Blue. Q: What is an evaluation function? A: Function estimating utility of a state. Q: Example feature in chess evaluation? A: Piece values (pawn=1, queen=9). Q: What is Expectiminimax used for? A: Games with chance nodes. Q: Which AI milestone won checkers (1994)? A: Chinook. Q: Why was Go difficult for AI? A: Branching factor > 300.

Lecture 6: Constraint Satisfaction Problems (CSPs)

Q: Define a CSP. A: Assign values to variables subject to constraints.
Q: Map coloring requires that regions get different colors. A: Adjacent.
Q: Two examples of CSPs? A: Sudoku, N-Queens.
Q: What does backtracking search do? A: DFS assigning one variable at a time, undoing when constraints fail.
Q: What is forward checking? A: Eliminates values that would violate constraints with current assignment.
Q: Heuristic choosing variable with fewest values? A: MRV (Minimum Remaining Values).
Q: What is the least constraining value heuristic?A: Value that rules out fewest options for other variables.
Q: What is arc consistency? A: Every value in one variable's domain must be consistent with some value in another.
Q: CSPs are generally problems. A: NP-complete.
Q: What is SAT problem? A: Check if Boolean formula is satisfiable.
Q: Unary, binary, and n-ary constraints? A: Single variable; pairs; multiple variables.
Q: Example scheduling CSP constraint? A: Class A before Class B.
Q: Why heuristics make CSP efficient? A: Reduce branching, detect failures earlier.
Q: What does MCV stand for? A: Most Constraining Variable.
Q: Which algorithm enforces arc consistency? A: AC-3.