

Project 2 – Spatial Data Structure

CSE 168: Rendering Algorithms, Spring 2014

Description

Add a spatial data structure (such as an AABB tree) to your renderer. It should be derived off of the Object base class and be instance-able. Also, add cast shadows to the renderer. It should be able to run the code listed below in the *Project 2 Function* section, and generate the image in the *Sample Image* section.

In addition, add some timing functions to both the BoxTree::Construct() and Camera::Render() functions and output the resulting times to the console. For the sample data provided, it should only take a few seconds to generate the data structure and a few more seconds to render.

Mesh Format and Sample Data

You can use the dragon.ply file from the Stanford model library. A simple PLY file loader is also provided below.

Project 2 Function

Project 2 should be able to be run with the following sample code (or something very similar):

```
void project2() {
    // Create scene
    Scene scn;
    scn.SetSkyColor(Color(0.8f, 0.8f, 1.0f));

    // Create ground
    MeshObject ground;
    ground.MakeBox(5.0f, 0.1f, 5.0f);
    scn.AddObject(ground);

    // Create dragon
    MeshObject dragon;
    dragon.LoadPLY("dragon.ply");
    dragon.Smooth();

    BoxTreeObject tree;
    tree.Construct(dragon);
    scn.AddObject(tree);

    // Create instance
    InstanceObject inst(tree);
    Matrix34 mtx;
    mtx.MakeRotateY(PI);
    mtx.d.Set(-0.05f, 0.0f, -0.1f);
    inst.SetMatrix(mtx);
}
```

```

scn.AddObject(inst);

// Create lights
DirectLight sunlgt;
sunlgt.SetBaseColor(Color(1.0f, 1.0f, 0.9f));
sunlgt.SetIntensity(1.0f);
sunlgt.SetDirection(Vector3(2.0f, -3.0f, -2.0f));
scn.AddLight(sunlgt);

PointLight redlgt;
redlgt.SetBaseColor(Color(1.0f, 0.2f, 0.2f));
redlgt.SetIntensity(0.02f);
redlgt.SetPosition(Vector3(-0.2f, 0.2f, 0.2f));
scn.AddLight(redlgt);

PointLight bluelgt;
bluelgt.SetBaseColor(Color(0.2f, 0.2f, 1.0f));
bluelgt.SetIntensity(0.02f);
bluelgt.SetPosition(Vector3(0.1f, 0.1f, 0.3f));
scn.AddLight(bluelgt);

// Create camera
Camera cam;
cam.LookAt(Vector3(-0.1f,0.1f,0.2f),Vector3(-0.05f,0.12f,0.0f));
cam.SetFOV(40.0f);
cam.SetAspect(1.33f);
cam.SetResolution(800,600);

// Render image
cam.Render(scn);
cam.SaveBitmap("project2.bmp");
}

```

Sample Image

The sample code above should generate the following image:



Grading

This project is worth 12 points:

- Write code to build & traverse data structure	2
- Image renders correctly using data structure	4
- Construction & render time displayed	1
- Render with correct shadows	2
- Total runtime under 1 minute	3
- Total	12

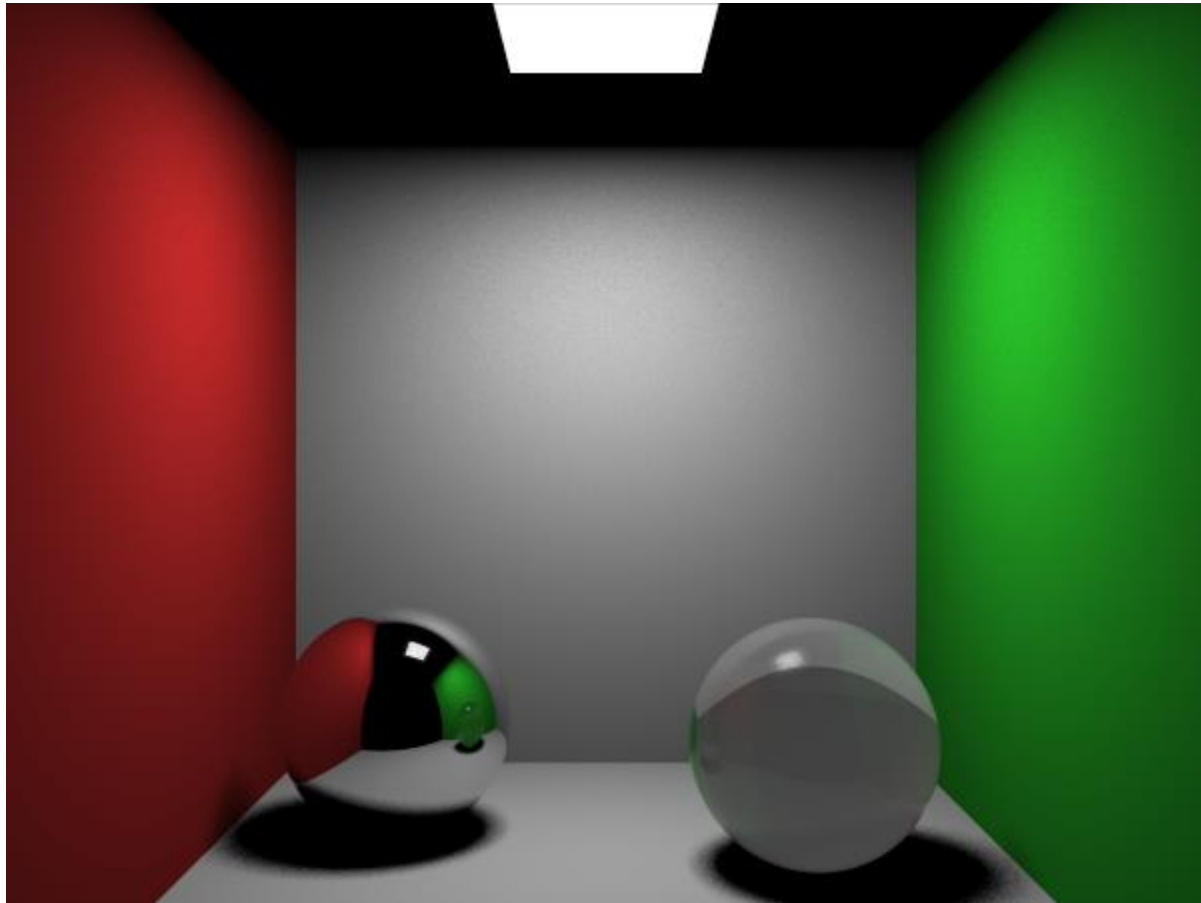
Extra Credit

For 1 extra credit point total, you must do *all* of the following:

- Add area lights

- Add Fresnel dielectrics and metals
- Add pixel supersampling for antialiasing

And then render an image something like this:



PLY File Loader

Here is a basic PLY file loader. It compiles in VisualStudio but hasn't been tested on other systems. You may need to move the #define line above any other #include's at the top of the file.

```
#define _CRT_SECURE_NO_WARNINGS

bool MeshObject::LoadPLY(const char *filename, Material *mtl) {
    // Open file
    FILE *f=fopen(filename,"r");
    if(f==0) {
        printf("ERROR: MeshObject::LoadPLY()- Can't open '%s'\n",filename);
        return false;
    }

    // Read header
    char tmp[256];
    int numverts=0,numtris=0;
```

```

int posprop=-99,normprop=-99;
int props=0;
while(1) {
    fgets(tmp,256,f);
    if(strncmp(tmp,"element vertex",14)==0)
        numverts=atoi(&tmp[14]);
    if(strncmp(tmp,"element face",12)==0)
        numtris=atoi(&tmp[12]);
    if(strncmp(tmp,"property",8)==0) {
        int len=strlen(tmp);
        if(strncmp(&tmp[len-3]," x",2)==0) posprop=props;
        if(strncmp(&tmp[len-3],"nx",2)==0) normprop=props;
        props++;
    }
    if(strcmp(tmp,"end_header\n")==0) break;
}
if(posprop==-1) {
    printf("ERROR: MeshObject::LoadPLY()- No vertex positions found\n");
    fclose(f);
    return false;
}

// Read verts
int i=0;
if(numverts>0) {
    NumVertexes=numverts;
    Vertexes=new Vertex[NumVertexes];

    for(i=0;i<NumVertexes;i++) {
        fgets(tmp,256,f);
        char *pch=strtok(tmp," ");
        int prop=0;
        while(pch) {
            if(prop==posprop) Vertexes[i].Position.x=float(atof(pch));
            if(prop==posprop+1) Vertexes[i].Position.y=float(atof(pch));
            if(prop==posprop+2) Vertexes[i].Position.z=float(atof(pch));
            if(prop==normprop) Vertexes[i].Normal.x=float(atof(pch));
            if(prop==normprop+1) Vertexes[i].Normal.y=float(atof(pch));
            if(prop==normprop+2) Vertexes[i].Normal.z=float(atof(pch));
            pch=strtok(0," ");
            prop++;
        }
    }
}

// Read tris
if(numtris>0) {
    if(mtl==0) mtl=new LambertMaterial;
    NumTriangles=numtris;
    Triangles=new Triangle[numtris];
    for(i=0;i<numtris;i++) {
        int count,i0,i1,i2;
        fscanf(f,"%d %d %d %d\n",&count,&i0,&i1,&i2);
        if(count!=3) {
            printf("ERROR: MeshObject::LoadPLY()- Only triangles are
supported\n");
            fclose(f);
            return false;
        }
    }
}

```

```

        }
        Triangles[i].Init(&Vertexes[i0],&Vertexes[i1],&Vertexes[i2],mtl);
    }
}

// Smooth
if(normprop<0) Smooth();

// Close file
fclose(f);
printf("Loaded %d triangles from file '%s'\n",numtris,filename);
return true;
}

void MeshObject::Smooth() {
    int i,j;
    for(i=0;i<NumVertexes;i++)
        Vertexes[i].Normal.Zero();
    for(i=0;i<NumTriangles;i++) {
        Triangle &tri=Triangles[i];
        Vector3 e1=tri.GetVtx(1).Position-tri.GetVtx(0).Position;
        Vector3 e2=tri.GetVtx(2).Position-tri.GetVtx(0).Position;
        Vector3 cross;
        cross.Cross(e1,e2);
        for(j=0;j<3;j++)
            tri.GetVtx(j).Normal.Add(cross);
    }
    for(i=0;i<NumVertexes;i++)
        Vertexes[i].Normal.Normalize();
}

```