















Meet the team Apollo





Ziwen Tan

Backend Developer



Zhuo (Kyle) Chen

Frontend Developer



Yilin (Kevin) Ren

Frontend Developer & Scrum Manager



Kecheng Yu

Al Developer & Presentation Hoster



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Why?





Vehicle is part of our life



Hard to find a parking spot when occur in a heavy traffic time



Even find a parking spot but far away from the destination



No indoor navigation



What sets us apart?





Simplicity

In just three simple steps, this project fulfills the users' requirements



Flexibility

The waypoint map can be customized by administrators as per their requirements

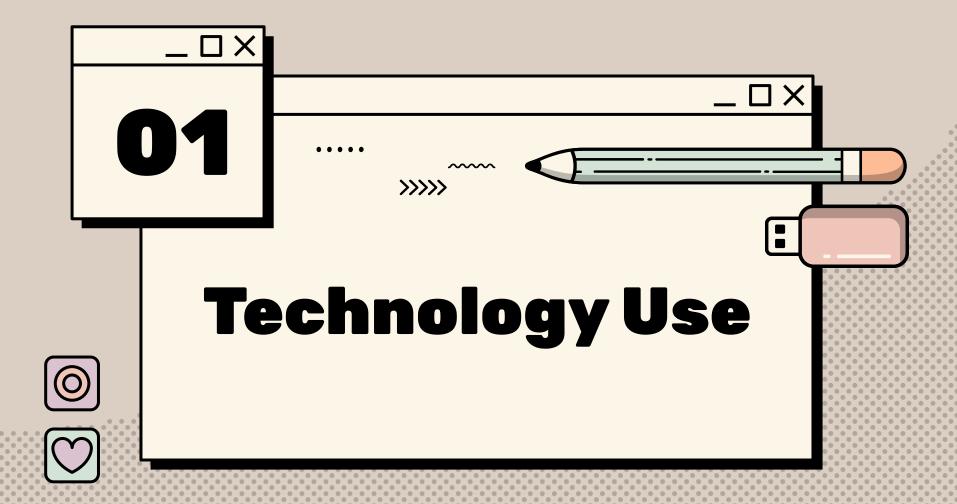


Reliability

The system offers up to five recommended alternative parking lots that are optimal

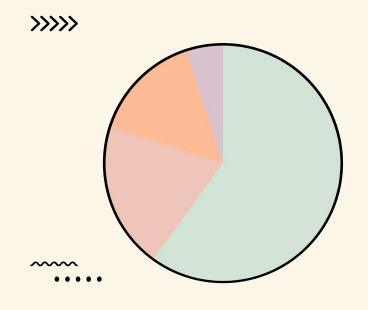
Project commercial







Tech Stack





Python

Al Detector

20%

Java

Backend services



JavaScript

Frontend, React and Redux

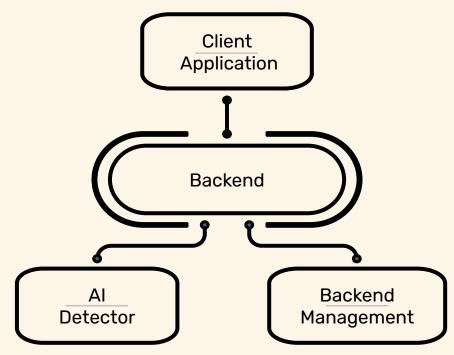
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Other

HTML, TypeScript, Shell, etc.



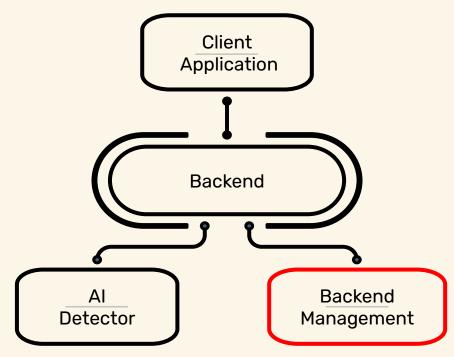




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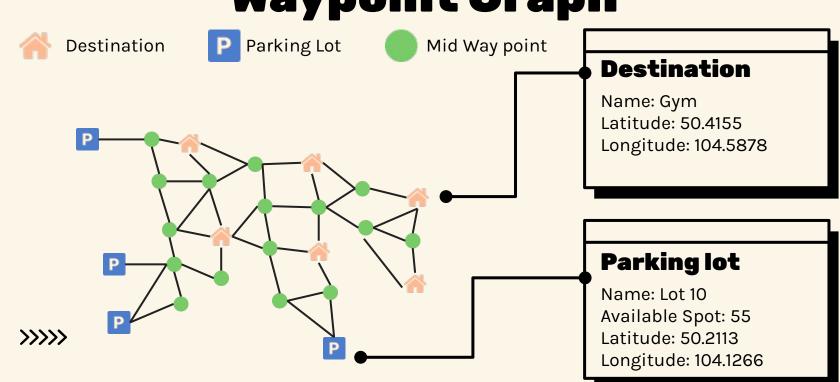


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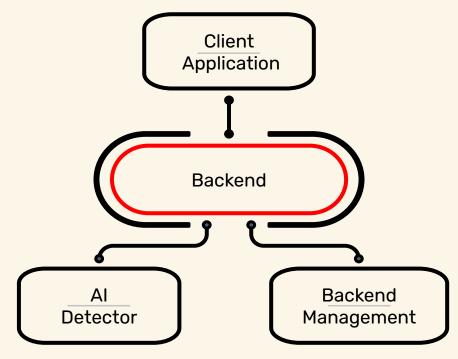


Waypoint Graph









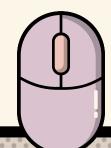
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Dijkstra's algorithm

- Why Ezparking use dijkstra's algorithm?
- What problem does the dijkstra's algorithm help EzParking solve?









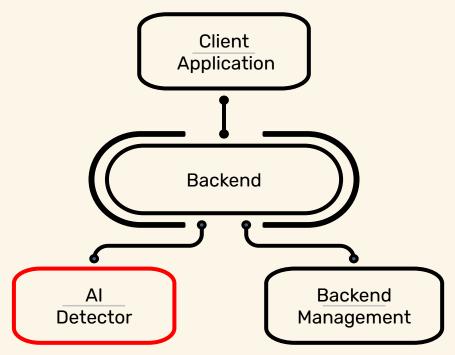












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Al Vehicle Detection





- Camera Detect

Easy to place and more versatile than sensors



- YOLO v5

The best choice of both performance and requirements

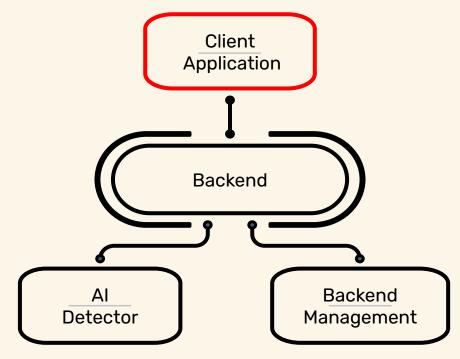


Multi-process APIs Call

No pausing issue anymore, won't miss any frame in the video

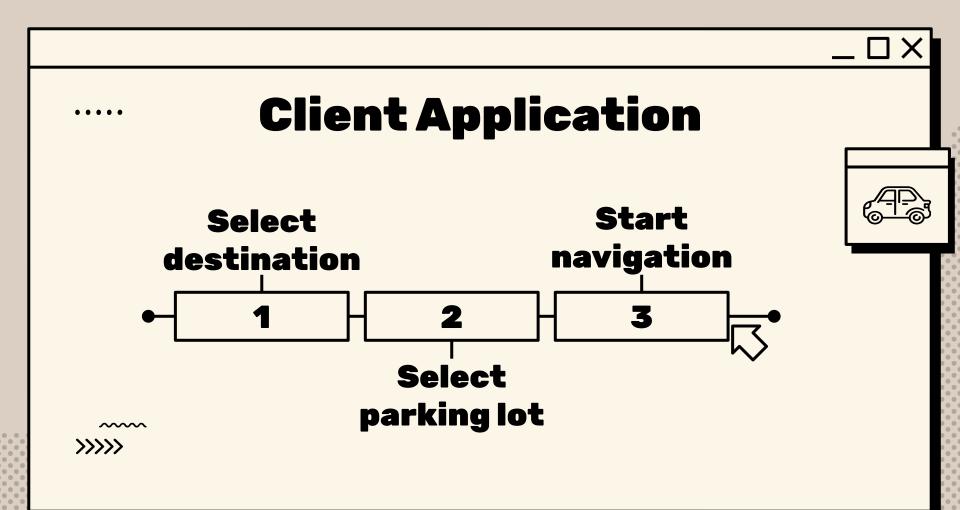


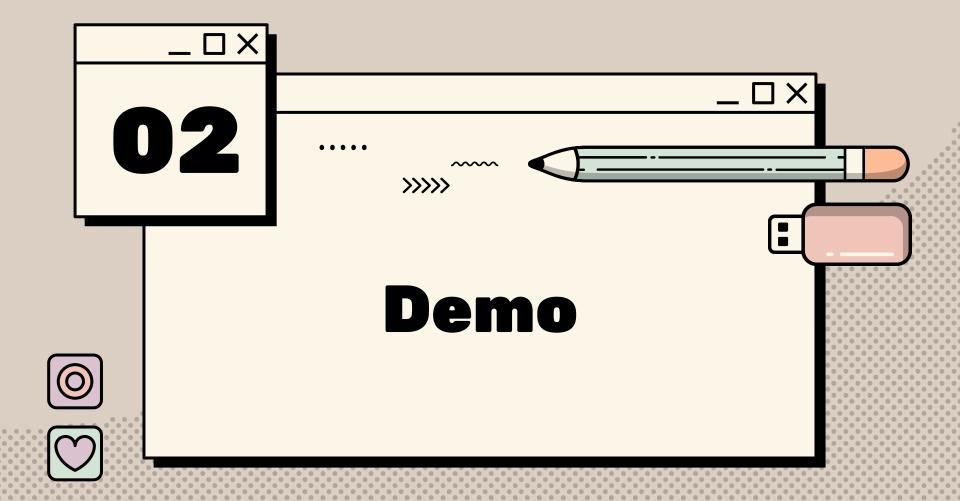




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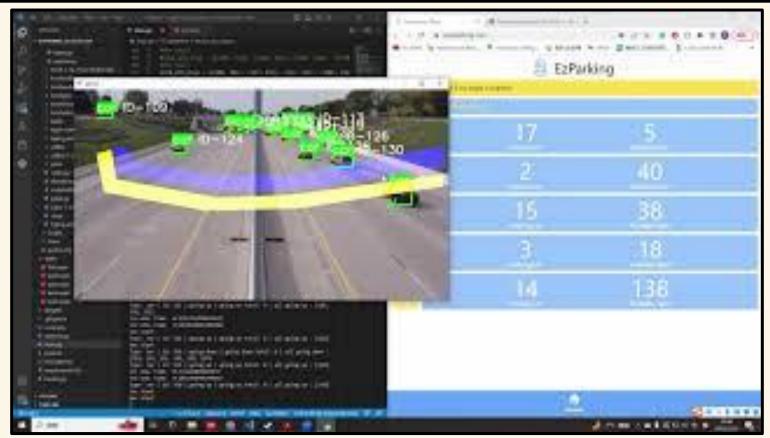
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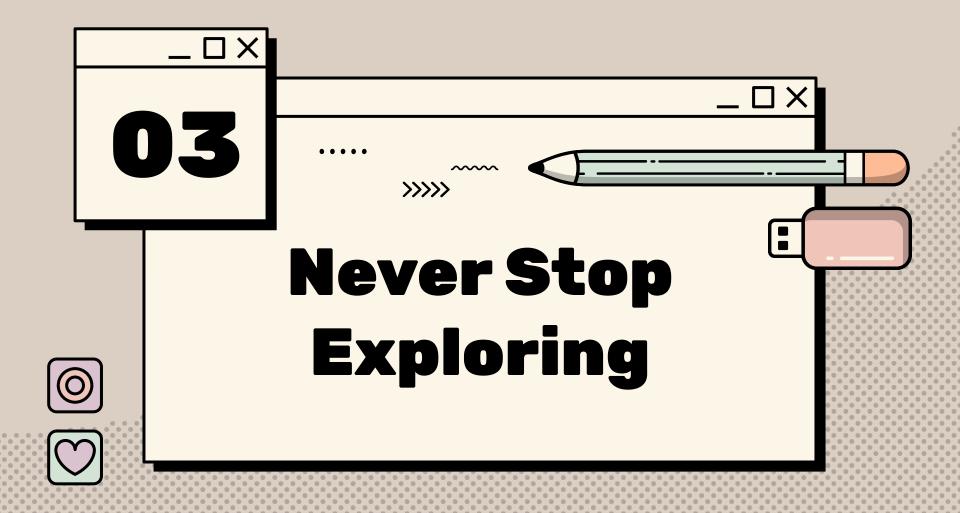




Al Demo











Future

Implemente advanced analytics

• More personalized recommendations

>>>>>

Develop additional features

Additional features



Improving the performance





Acknowledgement

We would like to thank the following people for their involvement with our project:

- Project Advisor:Dr. Timothy Maciag
- Project Mentor:Dr. Christine Chan







