

# An Artificial Science for System Value Engineering and Assurance

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# Problems

- ▶ The space of system properties is not flat
- ▶ Stakeholders have conflicting property preferences
- ▶ Properties can be coupled in complex ways
- ▶ Lacking foundations for rigorous engineering of properties

# Consequences

- ▶ Projects canceled after consuming billions of dollars
- ▶ Projects overrun their budgets and deadlines
- ▶ Delivered systems have less capability than required
- ▶ Systems experience serious operational failures
- ▶ System developers game the slack

# Causes

- ▶ Lacking focus on multi-property, value-driven engineering
- ▶ Related research have been lacking in rigor and precision

# Contributions

- ▶ Formalizing and improving Boehm's informal taxonomy
- ▶ Producing general but also specializable formal theories
- ▶ Integrating Boehm's taxonomy with Ross's approach
- ▶ Testing two propositions through the integration effort
- ▶ Unifying definition, specification and assurance cases
- ▶ A theory that supports formal reasoning about properties
- ▶ An example of applying the theory to a specific system

# Purpose

To provide an approach for:

- ▶ Making accessible of the theories to practitioners
- ▶ Evolving the theories with the needs of practitioners

# State of The Art

Ross's Semantic Approach (?, ?)

- ▶ **Problem:**

No precise understanding of particular system properties

- ▶ **Key Idea:**

A semantic approach for defining change-related ility terms

- ▶ **Main Contributions:**

- ▶ *Informal grammar* for changeability requirements
- ▶ Rules for *classifying statements* by *ility*
- ▶ Providing *semantics* to ility terms





# Ross's semantic basis approach

- **Pros:**

- Defining change-related ilities requirements statements

- **Cons:**

- Informal, not computable, hard to evaluate and evolve

# State of The Art

Boehm's top-down Taxonomy (?, ?)

- ▶ **Problem:**

System designs are deficient in balancing system ilities

- ▶ **Key Ideas:**

- ▶ Defining language grammer for full range of ilities
- ▶ Balancing ility values for the system's stakeholders

- ▶ **Main Contributions:**

- ▶ Proposing a stakeholder-value based property hierarchy
- ▶ An ontology for reasoning about a system's ilities
- ▶ Studied Synergies and Conflicts among key properties

# Boehm's top-down Taxonomy <sup>2</sup>

Stakeholder Value-Based QA Ends	Contributing QA Means
Mission Effectiveness	Stakeholders-satisfactory balance of Physical Capability, Cyber Capability, Human Usability, Speed, Endurability, Maneuverability, Accuracy, Impact, Scalability, Versatility, Interoperability
Resource Utilization	Cost, Duration, Key Personnel, Other Scarce Resources; Manufacturability, Sustainability
Dependability	Security, Safety, Reliability, Maintainability, Availability, Survivability, Robustness
Flexibility	Modifiability, Tailorability, Adaptability
Composite QAs	
Affordability	Mission Effectiveness, Resource Utilization
Resilience	Dependability, Flexibility

Figure : Stakeholder-value based property means-ends hierarchy

<sup>2</sup>Figure from (?, ?)

# Boehm's top-down Taxonomy

## ► Pros:

- Clarifying the nature of system ilities
- Reasoning about the tradeoffs among ilities
- Addressing stakeholder value conflicts

## ► Cons:

Informal, difficult to validate, hard to apply

# State of The Art

## Assurance Cases

- ▶ Claim - Assertion about key requirements and properties
- ▶ Evidence
  - ▶ Testing, Proofs, Process and people, Review and analyses
- ▶ Argument - How the evidences support the claims
  - ▶ Inference rules: deterministic, probabilistic, qualitative
- ▶ Inductive reasoning
  - ▶ Providing evidence, not proof that the claim is certain

## 3

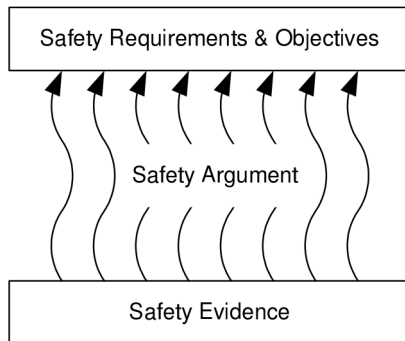


Figure : The relationship among safety case elements

<sup>3</sup>Figure from ( ?, ? )

# State of The Art

Kelly's Goal Structuring Notation (?, ?)

## ► Problem:

Safety arguments are often poorly communicated

## ► Key Idea:

Develop safety cases in a reader-friendly manner

## ► Main Contributions:

- Using graphical notations to annotate the assurance cases
- Applying *inductive* argumentation to safety cases

# Kelly's Goal Structuring Notation

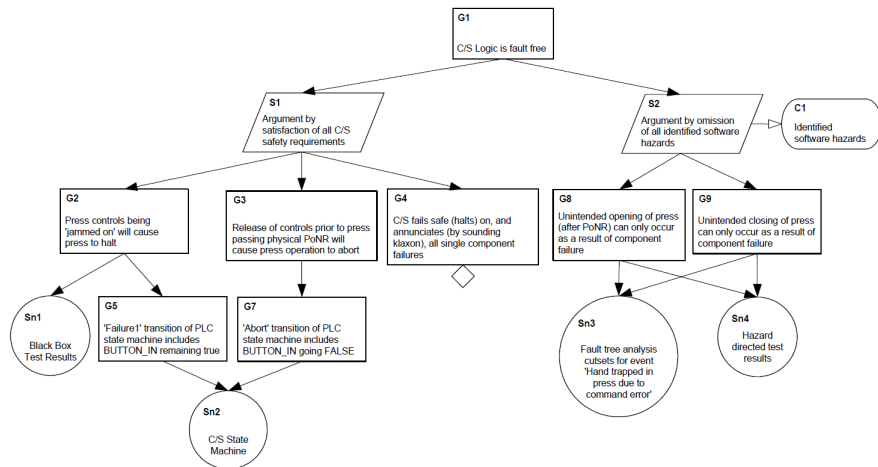


Figure : Example GSN (Figure from (?, ?))



# Kelly's GSN safety argument notation

- **Pros:**

- Facilitate comprehension and communication of arguments

- **Cons:**

- Informal, syntax rules are defined in prose text, not scale

# State of The Art

Rushby's Theory (?, ?)

## ► Problem:

Increasing confidence in the soundness of a given case

## ► Key Ideas:

- Applying formalism to safety cases
- Eliminating logic doubt and focusing on epistemic logic

## ► Main Contributions:

- Formalizing parts of a safety argument into deductive logic
- Providing mechanized support for assurance case argument
- Helping engineers focus on evidence instead of argument

# Rushby's Theory

- ▶ **Pros:**

Improving efficiency and cost of safety argument checking

- ▶ **Cons:**

No empirical evidence

# State of The Art

Knight's Assurance Based Development (?, ?)

- ▶ **Problem:**

Assurance cases often fail to guide developers' decisions

- ▶ **Key Idea:**

Co-developing the software system and its assurance case

- ▶ **Main Contributions:**

- ▶ Integrating assurance into development process.
- ▶ Assurance requirements drive development decisions

# Knight's Assurance Based Development

- ▶ **Pros:**

Detecting the assurance difficulties from the earliest stages

- ▶ **Cons:**

Hard to validate that their approach is optimal

# State of The Art

Basir's Automatically Generated Argument (?, ?)

- **Problem:**

Formal proofs are complex and machine-oriented

- **Key Idea:**

Automatically generating a safety argument by converting natural deduction style proofs

- **Main Contributions:**

- helps human understand the formal proofs

# Basir's Automatically Generated Argument

- **Pros:**

- Providing easier-to-understand proofs

- **Cons:**

- No benefit over an hand-generated, informal argument
  - Far from satisfactory as the proofs contain too many details

# State of The Art

## Bosch's Mobile Service Oriented Architectures (?, ?)

- ▶ **Problem:**

It's hard to achieve success in realizing mobile services

- ▶ **Key Idea:**

Defining the architecture drivers that make success

- ▶ **Main Contributions:**

- ▶ Identified the goals for mobile service oriented architectures
- ▶ Identified ilities that influence the success of mobile services
- ▶ Predicted future trends of mobile service



# State of The Art

## Lundberg's Architecture Design Guidelines (?, ?)

### ► **Problem:**

There are conflicts between modifiability and performance

### ► **Key Idea:**

Providing guidelines in software architecture design

### ► **Main Contributions:**

- A taxonomy for performance and modifiability related QA
- Four software architecture design evaluation approaches
- Four architecture design transformation strategies
- Eight guidelines in software architecture design

# Lundberg's Architecture Design Guidelines

## ► Pros:

- Revealed the relationships among architecture, quality attributes, and implementation
- The guidelines are extracted from real industry experience

## ► Cons:

- Only focus on performance and modifiability
- Such studies may not fit domains other than software design

# State of The Art

## Knight's Success Arguments (?, ?)

### ► **Problem:**

Failure rate of software development efforts is high

### ► **Key Idea:**

Defining success argument to establish confidence

### ► **Main Contributions:**

- Structuring and documenting the argument
- Recording the argument and exposing it to examinations

# Knight's Success Arguments

## ► Pros:

- Helps structure the reasoning and expose it to criticism
- Helps explain the evidence to the reviewers

## ► Cons:

- Informal, Hard to validate

# Our approach

- ▶ Combining Bosch's innovation experiment systems theory
- ▶ Integrating Boehm's theory and Ross's approach
- ▶ Using rigorous formal specification and software synthesis
- ▶ Refining and expressing quality theories using Coq
- ▶ Building web-based tools to implement the theory concepts
- ▶ Driving theory testing, evolution, and validation with tools



# Top-Most System Value – Satisfactory

```

Class Satisfactory (System: Set) (Stakeholder: Set) (Context: Set) := {
  sys: System

  ; physicalCapability : System → Stakeholder → Context → Prop
  ; cyberCapability : System → Stakeholder → Context → Prop
  ; humanUsability : System → Stakeholder → Context → Prop
  .....
  ; adaptability : System → Context → Prop

  ; me: MissionEffective System Stakeholder Context sys physicalCapability cyberCapability
humanUsability speed endurance maneuverability accuracy impact scalability versatility interoperability
  ; ru: ResourceUtilization System Context sys cost duration keyPersonnel otherScareResources
manufacturability sustainability
  ; dp: Dependable System Context sys security safety reliability maintainability availability survivability
robustness
  ; fl: Flexible System Context sys modifiability tailorability adaptability

```

# Top-Most System Value – Satisfactory

```

Class Satisfactory (System: Set) (Stakeholder: Set) (Context: Set) (Phase: Set):= {
  sys: System

  ; physicalCapability : System → Stakeholder → Context → Phase → Prop
  ; cyberCapability : System → Stakeholder → Context → Phase → Prop
  ; humanUsability : System → Stakeholder → Context → Phase → Prop
  .....
  ; exchangeability: System → Stakeholder → Context → Phase → Prop
  .....
  ; affordable: Affordable System Stakeholder Context Phase sys
    physicalCapability cyberCapability humanUsability speed endurance
    maneuverability accuracy impact scalability versatility interoperabilitycost
    duration keyPersonnel otherScareResources manufacturability sustainability
  ; resilient: Resilient System Stakeholder Context Phase sys
    security safety reliability maintainability availability survivability robustness
    modifiability tailorability adaptability valueRobustness valueSurvivability
    ross_robustness classicalPassiveRobustness ross_survivability evolvability
    ross_adaptability ross_flexibility ross_scalability ross_modifiability extensibility
    agility reactivity formReconfigurability operationalReconfigurability
    functionalVersatility operationalVersatility exchangeability

  }.

```



# *Mission Effectiveness* in QA Taxonomy [Boehm, to app]

Mission Effectiveness: a System has achieved a  
 Stakeholders-satisfactory balance of  
 Physical Capability, Cyber Capability, Human Usability,  
 Speed, Endurability, Maneuverability, Accuracy, Impact,  
 Scalability, Versatility, and Interoperability.

# Second-Level Property – Mission Effective

```

Inductive MissionEffective (System: Set) (Stakeholder: Set) (Context: Set) (sys: System)
  (physical_capable: System → Stakeholder → Context → Prop)
  (cyber_capable: System → Stakeholder → Context → Prop)
  (human_usable: System → Stakeholder → Context → Prop)
  (speed: System → Stakeholder → Context → Prop)
  (endurable: System → Stakeholder → Context → Prop)
  .....
  (interoperable: System → Stakeholder → Context → Prop)
  : Prop :=

```

```

mk_mission_eff:

```

```

  PhysicalCapable System Stakeholder Context sys physical_capable →

```

```

  CyberCapable System Stakeholder Context sys cyber_capable →

```

```

  HumanUsable System Stakeholder Context sys human_usable →

```

```

  Speed System Stakeholder Context sys speed →

```

```

  Endurable System Stakeholder Context sys endurable →

```

```

  Maneuverable System Stakeholder Context sys maneuverable →

```

```

  .....

```

```

  MissionEffective System Stakeholder Context sys mission_effective physical_capable

```

```

  cyber_capable human_usable speed endurable maneuverable accurate impact scalable versatile
  interoperable.

```

## Second-Level Property – Flexible

Inductive ***Flexible*** (*System*: Set) (*Context*: Set) (*sys*: *System*)  
 (*flexible*: *System* → *Context* → Prop)  
 (*modifiable*: *System* → *Context* → Prop)  
 (*tailorable*: *System* → *Context* → Prop)  
 (*adaptable*: *System* → *Context* → Prop)  
 : Prop :=

*mk\_flexibility*:

***Modifiable*** *System Context sys modifiable* →

***Tailorable*** *System Context sys tailorable* →

***Adaptable*** *System Context sys adaptable* →

***Flexible*** *System Context sys flexible modifiable tailorable adaptable*.

# Leaf Property – Adaptable

Inductive ***Adaptable*** (*System*: Set) (*Context*: Set) (*sys*: System)  
 (*adaptable*: System → Context → Prop)  
 : Prop :=

*mk\_adaptability*:

(∀ *cx*: Context, *adaptable sys cx*) →  
***Adaptable System Context sys adaptable***.

# Example – Smart Home

Define System, Stakeholder, and Context for a Smart Home

Require Import Satisfactory.

Require Import Changeable.

Definition Smart\_Home\_System := **Datatypes.unit**.

Inductive **Smart\_Home\_Stakeholder** := investor | end\_user |  
developer | maintainer | public.

Inductive **Smart\_Home\_Context** := normal.

# Example – Smart Home

Create a Specific Adaptability Requirement using Ross's Approach

Definition smart\_home\_system\_adaptability\_requirement :

**changeStatement** :=

mk\_changeStatement

(perturbation\_shift "low temperature")

(context\_circumstantial "late at night")

phase\_preOps

(agent\_internal "controller")

(mk\_change direction\_increase (parameter\_level "knob angle")

(origin\_one "degree") (destination\_one "degree") aspect\_function)

(mechanism\_description "regulating the airflow")

(mk\_change direction\_increase (parameter\_level "temperature")

(origin\_one "degree") (destination\_one "degree") aspect\_function)

(abstraction\_architecture " ")

valuable\_simple

# Example – Smart Home

## Corresponding requirement statement:

In response to (Perturbation\_shift) *low temperature* (Context\_circumstantial) *late at night*, during (Phase\_preOps) of system, desire (Agent\_internal) *controller* to be able to (Direction\_increase) the (Parameter\_level) of *knob angle* from (Origin\_one) state(s) to (Destination\_one) state(s) in the system (Aspect\_function) through (Mechanism\_description) *regulating the airflow* that results in the effect of (Direction\_increase) the (Parameter\_level) of *temperature* from (Origin\_one) state(s) to (Destination\_one) state(s) in the system (Aspect\_function) for a (Abstraction\_architecture) that is (Valuable\_simple).

# Example – Smart Home

Check a given system meets the adaptability requirement

Inductive **systemMeetsSpecificAdaptabilityRequirement**:

$\text{Smart\_Home\_System} \rightarrow \text{changeStatement} \rightarrow \text{Prop} :=$

$\text{systemMeetsSpecificAdaptabilityRequirement\_proof}:$

$\forall s: \text{Smart\_Home\_System}, \forall c: \text{changeStatement},$

**In** adaptability (typeAssignment  $c$ )  $\rightarrow$

**systemMeetsSpecificAdaptabilityRequirement**  $s\ c$ .



# Example – Smart Home

Check a given system has adaptability quality

Inductive **adaptability** (*sys*: Smart\_Home\_System) (*cx*:  
**Smart\_Home\_Context**): Prop :=  
 adaptability\_proof:  
**systemMeetsSpecificAdaptabilityRequirement** *sys*  
 smart\_home\_system\_adaptability\_requirement →  
**adaptability** *sys cx*.

# Example – Smart Home

Formalize two properties with trivial proofs

Inductive **systemCanControlFurnaceOnOffSwitch**:

Smart\_Home\_System  $\rightarrow$  Prop :=

systemCanControlFurnaceOnOffSwitch\_proof:  $\forall s$ :

Smart\_Home\_System, **systemCanControlFurnaceOnOffSwitch**  $s$ .

Inductive **systemCanControlGarageDoorOpener**:

Smart\_Home\_System  $\rightarrow$  Prop :=

systemCanControlGarageDoorOpener\_proof:  $\forall s$ :

Smart\_Home\_System, **systemCanControlGarageDoorOpener**  $s$ .

# Example – Smart Home

Check a given system has Physical Capability quality

Inductive **physicalCapability** (*sys*: Smart\_Home\_System) (*sh*:  
**Smart\_Home\_Stakeholder**) (*cx*: **Smart\_Home\_Context**): Prop :=  
    physicalCapability\_proof: **systemCanControlFurnaceOnOffSwitch**  
*sys*  $\wedge$  **systemCanControlGarageDoorOpener** *sys*  $\rightarrow$   
**physicalCapability** *sys sh cx*.

# Example – Smart Home

Define an instance of Satisfactory for a smart home project

```
Instance Smart_Home_Instance: Satisfactory Smart_Home_System
Smart_Home_Stakeholder Smart_Home_Context := {
    sys := tt

    ; physicalCapability := physicalCapability
    ; cyberCapability := cyberCapability
    ; humanUsability := humanUsability
    .....
    ; tailorability := tailorability
    ; adaptability := adaptability
}
```

# Our Contributions

- ▶ A parameterizable hierarchy of qualities and relationships
- ▶ Quality-specific languages for expressing requirements
- ▶ Integration of the distinct, previously conflicting theories.
- ▶ Web-based software implementations of the theory concepts
- ▶ An approach for theory testing, evolution, and validation

The overall contribution of this work is a novel, rigorous, and promising new approach to developing, promulgating, testing, evolving, and validating the scientific theory that is needed to underpin rigorous new approaches to comprehensive system quality engineering.

# Why do we think it will work?

- ▶ Replaces vague prose with *verifiable propositions*
- ▶ Every proposition has corresponding *assurance case*
- ▶ Practitioners never have to see formal specifications
- ▶ Web-based tools provide for *broad accessibility*
- ▶ Evolution of theory driven by *feedback from use*
- ▶ Social process of learning, testing, *theory validation*

# Conclusion

- To be added

# Bibliography