Introduction

# An Artificial Science for System Value Engineering and Assurance

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### Problems

- ► The space of system properties is not flat
- ► Stakeholders have conflicting property preferences
- ▶ Properties can be coupled in complex ways
- ► Lacking foundations for rigorous engineering of properties

## Consequences

- ▶ Projects canceled after consuming billions of dollars
- ▶ Projects overrun their budgets and deadlines
- ▶ Delivered systems have less capability than required
- ► Systems experience serious operational failures
- ► System developers game the slack

### Causes

- ► Lacking focus on multi-property, value-driven engineering
- ▶ Related research have been lacking in rigor and precision

### Contributions

- ► Formalizing and improving Boehm's informal taxonomy
- $\blacktriangleright$  Producing general but also specializable formal theories
- ► Integrating Boehm's taxonomy with Ross's approach
- ► Testing two propositions through the integration effort
- ▶ Unifying definition, specification and assurance cases
- ▶ A theory that supports formal reasoning about properties
- ► An example of applying the theory to a specific system

## Purpose

To provide an approach for:

- ▶ Making accessible of the theories to practitioners
- ► Evolving the theories with the needs of practitioners

Ross's Semantic Approach (?, ?)

#### ▶ Problem:

No precise understanding of particular system properties

### ► Key Idea:

A semantic approach for defining change-related ility terms

- ► Main Contributions:
  - ► Informal grammar for changeability requirements
  - ▶ Rules for *classifying statements* by *ility*
  - ▶ Providing *semantics* to ility terms

# Ross's semantic basis approach <sup>1</sup>

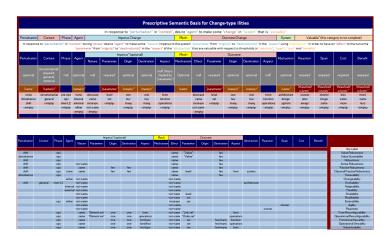


Figure: Ross's prescriptive semantic basis for change-type ilites



<sup>&</sup>lt;sup>1</sup>Figures from (?, ?)

# Ross's semantic basis approach

- ► Pros:
  Defining change-related ilities requirements statements
- ► Cons:
  Informal, not computable, hard to evaluate and evolve

Boehm's top-down Taxonomy (?, ?)

#### ▶ Problem:

System designs are deficient in balancing system ilites

### ► Key Ideas:

- ► Defining language grammer for full range of ilities
- ▶ Balancing ility values for the system's stakeholders

#### ► Main Contributions:

- ▶ Proposing a stakeholder-value based property hierarchy
- ► An ontology for reasoning about a system's ilities
- Studied Synergies and Conflicts among key properties

# Boehm's top-down Taxonomy $^{2}$

Introduction

Stakeholder Value-Based OA Ends	Contributing QA Means
Mission Effectiveness	Stalrahaldara satisfactory, balance, of Dhysical Canability
Mission Effectiveness	Stakeholders-satisfactory balance of Physical Capability,
	Cyber Capability, Human Usability, Speed, Endurability,
	Maneuverability, Accuracy, Impact, Scalability, Versatility,
	Interoperability
Resource Utilization	Cost, Duration, Key Personnel, Other Scarce Resources;
	Manufacturability, Sustainability
Dependability	Security, Safety, Reliability, Maintainability, Availability,
	Survivability, Robustness
Flexibility	Modifiability, Tailorability, Adaptability
Composite QAs	
Affordability	Mission Effectiveness, Resource Utilization
Resilience	Dependability, Flexibility

Figure: Stakeholder-value based property means-ends hierarchy

# Boehm's top-down Taxonomy

#### ▶ Pros:

- ► Clarifying the nature of system ilities
- ► Reasoning about the tradeoffs among ilities
- ► Addressing stakeholder value conflicts

#### ► Cons:

Informal, difficult to validate, hard to apply

Assurance Cases

- ► Claim Assertion about key requirements and properties
- ► Evidence
  - ► Testing, Proofs, Process and people, Review and analyses
- ► Argument How the evidences support the claims
  - ► Inference rules: deterministic, probabilistic, qualitative
- ► Inductive reasoning
  - ▶ Providing evidence, not proof that the claim is certain

Introduction

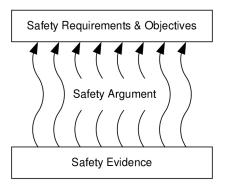


Figure: The relationship among safety case elements

Kelly's Goal Structuring Notation (?, ?)

#### ► Problem:

Safety arguments are often poorly communicated

- ► Key Idea:
  - Develop safety cases in a reader-friendly manner
- ► Main Contributions:
  - ▶ Using graphical notations to annotate the assurance cases
  - ► Applying *inductive* argumentation to safety cases

## Kelly's Goal Structuring Notation

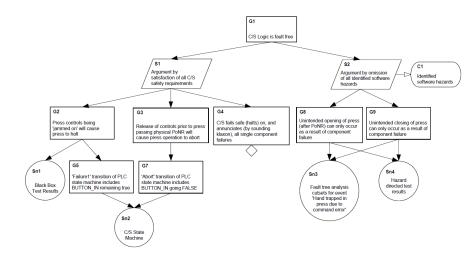


Figure: Example GSN (Figure from (?, ?))

# Kelly's GSN safety argument notation

▶ Pros:

Facilitate comprehension and communication of arguments

► Cons:

Informal, syntax rules are defined in prose text, not scale

Rushby's Theory (?, ?)

#### ▶ Problem:

Increasing confidence in the soundness of a given case

### ► Key Ideas:

- ► Applying formalism to safety cases
- ► Eliminating logic doubt and focusing on epistemic logic

#### ► Main Contributions:

- ► Formalizing parts of a safety argument into deductive logic
- ▶ Providing mechnized support for assurance case argument
- ► Helping engineers focus on evidence instead of argument

# Rushby's Theory

- ► Pros: Improving efficiency and cost of safety argument checking
- ► Cons:
  No empirical evidence

Knight's Assurance Based Development (?, ?)

#### ▶ Problem:

Assurance cases often fail to guide developers' decisions

- ► Key Idea:
  - Co-developing the software system and its assurance case
- ► Main Contributions:
  - ► Integrating assurance into development process.
  - ► Assurance requirements drive development decisions

# Knight's Assurance Based Development

- ▶ Pros:
  Detecting the assurance difficulties from the earliest stages
- ► Cons:
  Hard to validate that their approach is optimal

Basir's Automatically Generated Argument (?, ?)

### ▶ Problem:

Formal proofs are complex and machine-oriented

### ► Key Idea:

Automatically generating a safety argument by converting natural deduction style proofs

- ► Main Contributions:
  - ▶ helps human understand the formal proofs

## Basir's Automatically Generated Argument

#### ▶ Pros:

Providing easier-to-understand proofs

#### ► Cons:

- ▶ No benefit over an hand-generated, informal argument
- ► Far from satisfactory as the proofs contain too many details

Bosch's Mobile Service Oriented Architectures (?, ?)

#### ▶ Problem:

It's hard to achieve success in realizing mobile services

### ► Key Idea:

Defining the architecture drivers that make success

#### ► Main Contributions:

- ▶ Identified the goals for mobile service oriented architectures
- ▶ Identified ilities that influence the success of mobile services
- ▶ Predicted future trends of mobile service

Lundberg's Architecture Design Guidelines (?, ?)

#### ▶ Problem:

There are conflicts between modifiability and performance

## ► Key Idea:

Providing guidelines in software architecture design

- ► Main Contributions:
  - ► A taxonomy for performance and modifiability related QA
  - ► Four software architecture design evaluation approaches
  - ► Four architecture design transformation strategies
  - ▶ Eight guidelines in software architecture design

# Lundberg's Architecture Design Guidelines

#### ▶ Pros:

- ► Revealed the relationships among architecture, quality attributes, and implementation
- ▶ The guidelines are extracted from real industry experience

#### ► Cons:

- ► Only focus on performance and modifiability
- ► Such studies may not fit domains other than software design

Knight's Success Arguments (?, ?)

#### ► Problem:

Failure rate of software development efforts is high

- ► Key Idea:
  - Defining success argument to establish confidence
- ► Main Contributions:
  - ► Structuring and documenting the argument
  - ▶ Recording the argument and exposing it to examinations

# Knight's Success Arguments

#### ► Pros:

- ▶ Helps structure the reasoning and expose it to criticism
- ► Helps explain the evidence to the reviewers

#### ► Cons:

► Informal, Hard to validate

# Our approach

- ► Combining Bosch's innovation experiment systems theory
- ► Integrating Boehm's theory and Ross's approach
- ▶ Using rigorous formal specification and software synthesis
- ► Refining and expressing quality theories using Coq
- ▶ Building web-based tools to implement the theory concepts
- $\blacktriangleright$  Driving theory testing, evolution, and validation with tools

### Framework Architecture

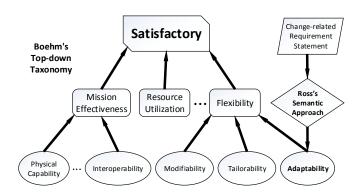


Figure: The overall architecture of our framework

## Top-Most System Value – Satisfactory

Introduction

```
 \begin{aligned} & \textbf{Class Satisfactory} \; (System: \, \textbf{Set}) \; (Stakeholder: \, \textbf{Set}) \; (Context: \, \textbf{Set}) := \left\{ \\ & \text{sys:} \; System \\ & ; \; \text{physicalCapability} : \; System \rightarrow Stakeholder \rightarrow Context \rightarrow \text{Prop} \\ ; \; \text{cyberCapability} : \; System \rightarrow Stakeholder \rightarrow Context \rightarrow \text{Prop} \\ ; \; \text{humanUsability} : \; System \rightarrow Stakeholder \rightarrow Context \rightarrow \text{Prop} \\ & \dots \\ ; \; \text{adaptability} : \; System \rightarrow Context \rightarrow \text{Prop} \end{aligned}
```

- ; me: MissionEffective  $System\ Stakeholder\ Context$  sys physicalCapability cyberCapability humanUsability speed endurability maneuverability accuracy impact scalability versability interoperability
- ; ru: ResourceUtilization System Context sys cost duration keyPersonnel otherScareResources manufacturability sustainability
- ; dp: Dependable  $System\ Context$  sys security safety reliability maintainability availability survivability robustness
  - ; fl: Flexible  $System\ Context$  sys modifiability tailorability adaptability

## Top-Most System Value – Satisfactory

Introduction

```
Class Satisfactory (System: Set) (Stakeholder: Set) (Context: Set) (Phase: Set):= {
         sys: System
      ; physicalCapability : System \rightarrow Stakeholder \rightarrow Context \rightarrow Phase \rightarrow Prop
      ; cyberCapability : System \rightarrow Stakeholder \rightarrow Context \rightarrow Phase \rightarrow Prop
      ; humanUsability : System \rightarrow Stakeholder \rightarrow Context \rightarrow Phase \rightarrow Prop
      : exchangeability: Sustem \rightarrow Stakeholder \rightarrow Context \rightarrow Phase \rightarrow Prop
      : affordable: Affordable Sustem Stakeholder Context Phase sus
                                physicalCapability cyberCapability humanUsability speed endurability
                                maneuverability accuracy impact scalability versability interoperabilitycost
                                duration keyPersonnel otherScareResources manufacturability sustainability
      ; resilient: Resilient System Stakeholder Context Phase sys
                            security safety reliability maintainability availability survivability robustness
                            modifiability tailorability adaptability valueRobustness valueSurvivability
                            ross_robustness classicalPassiveRobustness ross_survivability evolvability
                            ross_adaptability ross_flexibility ross_scalability ross_modifiability extensibility
                            agility reactivity formReconfigurability operationalReconfigurability
                            functionalVersatility operationalVersatility exchangeability
}.
```

# Mission Effectiveness in QA Taxonomy [Boehm, to app]

Mission Effectiveness: a System has achieved a
Stakeholders-satisfactory balance of
Physical Capability, Cyber Capability, Human Usability,
Speed, Endurability, Maneuverability, Accuracy, Impact,
Scalability, Versatility, and Interoperability.

## Second-Level Property – Mission Effective

Introduction

MissionEffective System Stakeholder Context sys mission\_effective physical\_capable cyber\_capable human\_usable speed endurable maneuverable accurate impact scalable versatile interoperable.

```
Inductive Flexible (System: Set) (Context: Set) (sys: System) (flexible: System \rightarrow Context \rightarrow Prop) (modifiable: System \rightarrow Context \rightarrow Prop) (tailorable: System \rightarrow Context \rightarrow Prop) (adaptable: System \rightarrow Context \rightarrow Prop) : Prop :=
```

mk\_flexibility:

Introduction

 $egin{aligned} Modifiable & System & Context & sys & modifiable & 
ightarrow \ Tailorable & System & Context & sys & tailorable & 
ightarrow \ Adaptable & System & Context & sys & adaptable & 
ightarrow \end{aligned}$ 

Flexible System Context sys flexible modifiable tailorable adaptable.

Introduction

```
 \begin{array}{c} \textbf{Inductive } \textit{Adaptable} \ (\textit{System}: \ \texttt{Set}) \ (\textit{Context}: \ \texttt{Set}) \ (\textit{sys}: \ \textit{System}) \\ & (\textit{adaptable}: \ \textit{System} \rightarrow \textit{Context} \rightarrow \texttt{Prop}) \\ & : \ \texttt{Prop} := \\ mk\_adaptability: \\ (\forall \ \textit{cx}: \ \textit{Context}, \ \textit{adaptable} \ \textit{sys} \ \textit{cx}) \rightarrow \\ \textit{Adaptable} \ \textit{System} \ \textit{Context} \ \textit{sys} \ \textit{adaptable}. \end{array}
```

Define System, Stakeholder, and Context for a Smart Home

```
Require Import Satisfactory. Require Import Changeable.
```

```
Definition Smart_Home_System := Datatypes.unit.

Inductive Smart_Home_Stakeholder := investor | end_user |
developer | maintainer | public.

Inductive Smart Home Context := normal.
```

Introduction

Create a Specific Adaptability Requirement using Ross's Approach

```
Definition smart_home_system_adaptability_requirement :
changeStatement :=
  mk_changeStatement
    (perturbation_shift "low temperature")
     (context_circumstantial "late at night")
    phase_preOps
     (agent_internal "controller")
     (mk_change direction_increase (parameter_level "knob angle")
(origin_one "degree") (destination_one "degree") aspect_function)
    (mechanism_description "regulating the airflow")
     (mk_change direction_increase(parameter_level "temperature")
(origin_one "degree") (destination_one "degree") aspect_function)
    (abstraction_architecture " ")
    valuable_simple
```

#### Corresponding requirement statement:

In response to (Perturbation\_shift) low temperature (Context\_circumstantial) late at night, during (Phase\_preOps) of system, desire (Agent\_internal) controller to be able to (Direction\_increase) the (Parameter\_level) of knob angle from (Origin\_one) state(s) to (Destination\_one) state(s) in the system (Aspect\_function) through (Mechanism\_description) regulating the airflow that results in the effect of (Direction\_increase) the (Parameter\_level) of temperature from (Origin\_one) state(s) to (Destination\_one) state(s) in the system (Aspect\_function) for a (Abstraction\_architecture) that is (Valuable\_simple).

Check a given system meets the adaptability requirement

```
Inductive systemMeetsSpecificAdaptabilityRequirement:
```

```
Smart\_Home\_System \rightarrow changeStatement \rightarrow Prop :=
  systemMeetsSpecificAdaptabilityRequirement_proof:
```

 $\forall s: \mathsf{Smart\_Home\_System}, \forall c: \mathsf{changeStatement},$ In adaptability (tipeAssignment c)  $\rightarrow$ 

systemMeetsSpecificAdaptabilityRequirement s c.

Check a given system has adaptability quality

```
Inductive adaptability (sys: Smart_Home_System) (cx:
Smart_Home_Context): Prop :=
   adaptability_proof:
systemMeetsSpecificAdaptabilityRequirement sys
smart_home_system_adaptability_requirement →
   adaptability sys cx.
```

Formalize two properties with trivial proofs

```
Inductive systemCanControlFurnaceOnOffSwitch:
```

 $\mathsf{Smart\_Home\_System} \to \mathsf{Prop} :=$ 

 $system CanControl Furnace On Off Switch\_proof : \ \forall \ s:$ 

 ${\sf Smart\_Home\_System}, \ \textbf{systemCanControlFurnaceOnOffSwitch} \ \textit{s.}$ 

#### ${\tt Inductive}\ \textbf{systemCanControlGarageDoorOpener}:$

 $\mathsf{Smart\_Home\_System} \to \mathsf{Prop} :=$ 

 $systemCanControlGarageDoorOpener\_proof: \forall s:$ 

 $Smart\_Home\_System, \ \textbf{systemCanControlGarageDoorOpener} \ s.$ 

Check a given system has Physical Capability quality

```
Inductive physicalCapability (sys: Smart_Home_System) (sh: Smart_Home_Stakeholder) (cx: Smart_Home_Context): Prop := physicalCapability_proof: systemCanControlFurnaceOnOffSwitch sys \land systemCanControlGarageDoorOpener sys \rightarrow physicalCapability sys \ sh \ cx.
```

Introduction

Define an instance of Satisfactory for a smart home project

```
Instance Smart_Home_Instance: Satisfactory Smart_Home_System
Smart_Home_Stakeholder Smart_Home_Context := {
    sys := tt

; physicalCapability := physicalCapability
; cyberCapability := cyberCapability
; humanUsability := humanUsability
.....
; tailorability := tailorability
; adaptability := adaptability
}.
```

#### Our Contributions

- ► A parameterizable hierarchy of qualities and relationships
- ► Quality-specific languages for expressing requirements
- ► Integration of the distinct, previously conflicting theories.
- ▶ Web-based software implementations of the theory concepts
- ► An approach for theory testing, evolution, and validation

The overall contribution of this work is a novel, rigorous, and promising new approach to developing, promulgating, testing, evolving, and validating the scientific theory that is needed to underpin rigorous new approaches to comprehensive system quality engineering.

# Why do we think it will work?

- ▶ Replaces vague prose with *verifiable propositions*
- ► Every proposition has corresponding assurance case
- ▶ Practitioners never have to see formal specifications
- ► Web-based tools provide for *broad accessibility*
- ► Evolution of theory driven by feedback from use
- ► Social process of learning, testing, theory validation

### Conclusion

► To be added

# Bibliography