C++ Inheritance and Polymorphism

Inheritance in C++

class header may include a derivation list:

```
class Screen { ... };
class Window : public Screen { ... };
```

- Screen is a public base class of Window
- Window is derived from Screen
- Window inherits data and member functions from Screen
- derived class can then itself be a base class class Menu: public Window {...};
- Menu inherits data and member functions from Window

Example: Vector

class Vector implements an unchecked, uninitialized array of ints

```
class Vector
  int *buf;
  int sz;
public:
  Vector (int s)
    : sz (s), buf (new int[s])
  ~Vector()
    delete[] buf;
  int size()
    return sz;
  int & operator[] (int i)
    return buf[i];
int main()
  Vector v(10);
  v[6] = v[5] + 4; // oops, no init values
  int i = v[10]; // oops, out of range!
  //...
```

Benefit of Inheritance

- Inheritance allows you to extend a class hierarchy
- You need not modify the source code for the rest of the system
- Example: we need a vector whose bounds are checked when indexing
- Derive a new class Checked Vector
- It inherits characteristics of base class Vector
- We can add to or modify characteristics as needed

The best code is code you don't have to write at all (inheritance facilitates this)

Example: Range Checked Vector

```
class CheckedVector
  : public Vector
public:
  CheckedVector(int s)
    : Vector(s)
  int &operator [](int i)
    if (i < 0 | | i >= size())
      throw range error();
    else
      return (* (Vector *) this) [i]; // invoke Vector::operator[]
     Vector::size() and ~Vector are inherited from Vector
int main()
  CheckedVector v(10);
  int i = v[10]; // Error detected!
```

Data Hiding and Derived Classes

- Derived class can access public and protected members of base class
- Derived class MAY NOT access private members
- Protected members should hide representation from derived classes
- These features protect derived classes from base class representation change

```
class Vector
{
  int *buf;
  int sz;
protected:
  // allow derived classes direct access
  int &element(int i) { return buf[i]; }
  int in_range(int i) { return i>=0 && i < sz; }
  int &vector_size() { return sz; }
public:
  int &operator [](const int i)
{ if (in_range(i)) return element(i); }
};</pre>
```

Type and Subtype Relationships

- Derived class introduce a subtype of base class
- Pointer or reference to base may refer to any derived instance

```
Menu m; Window \&w = m; Screen *ps = \&w;
```

• This allows polymorphic programming

```
void driveAll( Vehicle * a[], int n)
{
  for ( int i = 0; i < n; i++ )
    a[i]->start(); // start depends on kind of Vehicle
}
```

Type and Subtype Relationships (cont'd)

- New subtypes can be added to a system without changing the rest of the system
- Example uses
 - adding a new stack or queue representation to your holder library
 - adding an AVL tree to your table library
 - adding a new car to your vehicle hierarchy
 - adding a new type of menu to your GUI widget set

Types vs Classes

- Types exist outside of OOP and correspond to mathematical sets
 - subtype = subset
 - e.g., naturals are a subtype (subset) of integers
- Classes are germane to OOP
 - subclass = particular kind of subset
 - more specialized behavior restricts the range of objects populating the set

Subtype Example

```
extern void dump_image (Screen &s);
Screen s;
Window w;
Menu m;
Bit_Vector bv;
dump_image(w); // OK: Window is a kind of Screen
dump_image(m); // OK: Menu is a kind of Screen
dump_image(s); // OK: argument types match exactly
dump_image(bv); // Error: Bit_Vector not a kind of Screen!
```

Dynamic vs. Static Binding

consider the following:

```
CheckedVector cv(20);
Vector &vp = cv;
do_something_with(vp[0]);
```

- which version of operator [] is called?
 - static binding
 - operator is chosen at compile time based on declared type of ${\bf vp}$
 - calls Vector::operator[]
 - dynamic binding
 - decision is deferred until run-time when actual type of object is known
 - calls CheckedVector::operator []

Dynamic Binding

dynamic binding is used only for virtual member functions

```
class Base {
  protected:
    virtual int virtual_fn();
    int non_virtual_fn();
};
```

 when over-riding a virtual function in a derived class, virtual is optional

```
class Derived : public Base {
  protected:
    int virtual_fn(); // still virtual
    int non_virtual_fn();
  // ...
};
```

• preferred style is to include virtual when overriding

Use of Dynamic or Static Binding

Static binding

- useful when dealing with *homogeneous* set of similar objects
- inheritance here allows reuse of portions of base class

Dynamic binding

- useful when dealing with a *heterogeneous* mix of objects
- they share common attributes and/or operations
- implementation of attribute may vary with each object
- inheritance here allows mixing of various similar objects

Static binding examples

- Vector, CheckedVector, InitVector, InitCheckedVector

• Dynamic binding examples

- Screen, Window, Menu of widget toolkit
- holders like stack, queue, deque, bag
- tables like array, hash_table, search_list, binary_search_tree
- Symbols, operators, AST, or intermediate codes in a compiler

Example Use of Dynamic Binding

- A shape hierarchy in a GUI (graphical user interface)
- Shapes, like Circle, Square, Rectangle, and Triangle, are derived from a base class, Shape
- class Shape defines common member functions:
 - Point where(); // return coordinates of a Shape
 - void move (Point to); // move a Shape to new coordinates
 - void rotate(int degrees); // rotate the Shape by a specified degree
 - void draw(); // draw the Shape on the screen
- in C, we would use a union to represent Shape
 - a tag indicates kind of shape in a Shape
 - each Shape operation must switch on kind of shape
 - error-prone (tag---operation link not enforced by the compiler)
 - e.g.,

```
void rotate_shape(Shape *sp, int degrees)
{
    switch (sp->type_tag) {
        case CIRCLE:
            do_rectangle_rotation(); // compiler says A-OK
            case SQUARE:
            do_circle_rotation(); // compiler says A-OK
}
```

C++ Solution

In C++, dynamic binding replaces switching on specific kind of object

```
class Shape {
public:
    virtual void rotate(int degrees);
};
class Circle : public Shape {
public:
    virtual void rotate(int degree) { }// no-op
};
class Rectangle : public Shape {
public:
    virtual void rotate(int degree);
};
```

- Any Shape can now be rotated independent of specific method of rotation
- Can be done with pointer or reference

```
void rotate_shape(Shape *sp, int degrees)
{
    sp->rotate(degrees);
}
    OR
void rotate_shape(Shape &sp, int degrees)
{
    sp.rotate(degrees);
}
```

Extensibility

- Virtual functions allow you to define polymorphic operations
- Can add to type hierarchy without modifying polymorphic operations

```
class Square : public Rectangle {
public:
   virtual void rotate(int degree)
   {
     if (degree % 90 != 0)
        Rectangle::rotate(degree);
   }
};
```

• We can still rotate any Shape object by saying

```
void rotate_shape(Shape *sp, int degrees)
{
   sp->rotate(degrees);
}
```

Extensibility (cont'd)

- in C, we must modify every function dealing with Shape
- we must add a new case for new object to each switch

```
void rotate_shape(Shape *sp, int degree)
{
   switch (sp->type_tag) {
     case CIRCLE:
       return;
   case SQUARE:
     if (degree % 90 == 0)
         do_rectangle_rotation();
   /* ... */
}
```

• C approach prevents adding Square if the code of rotate_shape() can't be modified (e.g., is in a library)

Where is inheritance useful?

Inheritance can be used for different purposes:

- to allow dynamic binding
 - e.g., Circle is a subclass of Shape
- to allow extension/modification of an existing class
 - e.g., CheckedVector that inherits from Vector
- to allow reuse of an implementation
 - Stack that inherits from Vector

public, protected, private Inheritance

- Implementation could be a misuse of public inheritance
 - When no subtype/kind-of relationship to base class
 - Operations on base class may not apply to derived
 - e.g., class Stack: public Vector array subscripting into a stack??
- private inheritance
 - base class public and protected members become private in derived
 - only members/friends can convert to base class reference
- protected inheritance
 - base class public and protected members become protected in derived
 - members/friends and derived classes can convert to base reference

Abstract Base Classes

- a base class is a (sub)root of an inheritance hierarchy
- may contain function stubs called pure virtual functions
- a class with pure virtual functions is called an abstract base class

```
class Shape {
public:
   Shape(int x = 0, int y = 0);
   virtual void move(Point to);
   virtual void draw() = 0;
   virtual void rotate(int degrees) = 0;
};
```

- draw() and rotate() can't be written yet, but move() can
- cannot instantiate Shape
 - can declare only references or pointers to abstract class

Virtual Function Example

```
// Abstract Base Class and Derived Classes
class Shape {
private:
  Point shape center;
  Color shape color;
public:
  Point where() const { return shape center; }
  void move(const Point &to) { shape center = to; draw(); }
  virtual void draw() const = 0;
  virtual void rotate(int degrees) = 0;
} ;
class Circle : public Shape {
private:
  int radius;
public:
  void draw(); // Code to draw a circle
  void rotate(int degrees) { /* do nothing */ }
};
class Rectangle : public Shape {
private:
  int width;
  int length;
public:
  void draw(); // Code to draw a Rectangle
  void rotate(int degrees); // Code to rotate a Rectangle
};
```

Polymorphism

- Polymorphism
 - when the specific operation invoked by a call depends on the type of an object
- Static polymorphism via overloading
- Dynamic polymorphism via virtual functions
 - useful for dealing with sets of objects having similar interface, but different implementations
 - Vehicles, Shapes, GUI Widgets

Polymorphic Function Example

 Example function that rotates all size shapes by angle degrees:

```
void rotate_all(Shape *vec[], int size, int angle)
{
  for (int i=0; i < size; i++)
    vec[i]->rotate(angle);
}
```

- vec[i]->rotate() is a virtual function call resolved at run-time
- Which rotate depends on actual type of shape in vec[i]

Virtual Function Example (cont'd)

Example use of function rotate_all()

```
Shape *shapes[] = {new Circle, new Square,
new Rectangle};
int size = sizeof shapes / sizeof *shapes;
rotate_all(shapes, size, 90);
```

- Specific types of shapes are unknown until run-time
- However, they are all derived from common base class Shape

Virtual Base Classes

- a base class may appear only once in a derivation list
- however, a base class may appear multiple times within a derivation hierarchy
- this presents two problems with multiple inheritance:
 - it may introduce member function and data object ambiguity
 - it may also cause unnecessary duplication of storage
- "virtual base classes" are included only once even if repeated

Virtual Multiple Inheritance

- a class can be simultaneously derived from two or more base classes
- Example:

```
class CheckedVector : public virtual Vector {
   /* ... */
};
class InitVector : public virtual Vector {
   /* ... */
};
class InitCheckedVector : public CheckedVector, public InitVector {
   /* ... */
};
```

- the virtual keyword prevents two copies of Vector in InitCheckedVector
- virtual base classes have certain restrictions:
 - they must possess constructors that take no arguments
- understanding and using virtual base classes can be difficult

Multiple Inheritance Ambiguity

```
Member names can conflict in multiple inheritance class Base1 { int foo(); /* ... */ }; class Base2 { int foo(); /* ... */ };
class Derived : Base1, Base2 { /* ... */ };
int main()
   Derived d;
   d.foo(); //q++: error: request for member 'foo' is ambiguous
```

- Two ways to fix this problem:
 - qualify the call with the name of the class and the scope qualifier, e.g., d.base1::foo();
- Add a new member function foo to class Derived, e.g., class Derived : Base1, Base2 {

```
int foo() {
    base1::foo();
    base2::foo();
};
```

Type and Subtype Conversion

A derived class can add new members not defined in base class, e.g.

- Upcasting: always OK
 - Derived contains a Base and operations are well defined
 Base *bp = &d; // OK, a Derived can be a Base
 bp->i = 10; bp->foo();
- Downcasting: programmer must ensure dp operations don't access undefined members
 - Base does not contain a Derived and operations aren't defined
 dp = static_cast<Derived *>(&b); dp->j = 20; // compiles, but undefined behavior
 // static_cast = "compiler, trust me"
 Derived *dp = &b; // g++: error: invalid conversion from 'Base*' to 'Derived*'
 dp = dynamic_cast<Derived *>(&b); // g++ warning:dynamic_cast of 'Base b' to 'class
 Derived*' can never succeed

Extended Example (Static Binding)

Geometric Shape Hierarchy

```
class Shape
protected:
  Point origin;
  Color color;
  Shape( Point newOrigin, Color newColor )
    : origin( newOrigin ), color( newColor )
  void moveTo(Point to)
    origin = to;
// derived class Circle
class Circle
  : public Shape
private:
  const double PI = 3.14159;
protected:
  double radius;
 Circle ( double newRadius, Point newOrigin, Color newColor )
    : Shape ( newOrigin, newColor ), radius ( newRadius )
  // inherits moveTo from Shape
  double circumference()
    return 2.0 * PI * radius;
};
```

- derived class can access public and protected members
- cannot access private members
- note: base class constructor, Shape(), must be called

Creating And Destroying Derived Classes

- derived class must call base constructor
 - otherwise, the default constructor (no args) is called
- order of construction: base classes then new data members
- virtual destructor is required for hierarchy with virtual functions
- virtual destructor must be introduced at root class
- in case any derived class requires a destructor
- may be eliminated if no destruction will ever be needed (rare)