

Autonomous_Robotics_with_ROS_for_mmWave Manifest

04-23-2018

Manifest ID - SRAS00004585

Legend

(explanation of the fields in the Manifest Table below)

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Autonomous_Robotics_with_ROS_for_mmWave Manifest Table

See the Legend above for a description of these columns.

Software Name	Version	License Type	Delivered As	Modified by TI		
turtlebot_mmwave_launchers package	1.1	BSD-3-Clause	Source	N/A	Location	[installed p turtlebot_1

Software Name	Version	License Type	Delivered As	Modified by TI		
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ROS navigation/move_base package	1.14.2	BSD-3-Clause	Source	YES	Location	[installed path]/navi
					Obtained from	https://gitl planning/r
ROS navigation/rotate_recovery package	1.14.2	BSD-3-Clause	Source	YES	Location	[installed path]/navi
					Obtained from	https://gitl planning/r
ROS turtlebot packages	N/A	BSD-3-Clause	Source	YES	Location	[installed p
					Obtained from	https://gitl



Credits

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Autonomous_Robotics_with_ROS_for_mmWave Licenses

turtlebot_mmwave_launchers package:

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