## Metropolis Hastings

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The Metropolis-Hastings (MH) algorithm is a sampling algorithm that generates samples from a *target distribution*  $\pi(\cdot)$ . MH is most effective in the case where  $\pi(\cdot)$  is intractable. Let's express  $\pi(\cdot)$  as the following fraction,

$$\pi(\cdot) = \frac{f(\cdot)}{K}$$

where  $f(\cdot)$  is some tractable density function and K is an intractable normalizing constant. MH enables us to sample from  $\pi(\cdot)$  without knowing anything about the intractable normalizing constant K!

The idea behind MH is to construct a Markov Chain whose stationary distribution is  $\pi(\cdot)$ . How do we do this? From Markov Chain theory we know that if a Markov Chain is reversible, the detailed balance equation holds,

$$\pi(x)p(x,y) = \pi(y)p(y,x)$$

where  $\pi(\cdot)$  is the stationary distribution and p(x,y) is the transition kernel. Hence, if we can find a transition kernel p(x,y) which satisfies this reversibility condition, we can sample from the target distribution  $\pi(\cdot)$ .

We start by defining some **tractable** proposal distribution q(x, y), which generates a proposal y given some current state x (this is something you pick). Since q(x, y) is a transition kernel, does it satisfy the reversibility condition? Let's derive a general solution. Assume q(x, y) does not satisfy the reversibility condition (if it does, then we just have the Metropolis algorithm). We have the following,

$$\pi(x)q(x,y) > \pi(y)q(y,x) \qquad (w.l.g)$$

An intuitive interpretation of what this equation is saying is basically we are moving from state x to state y more than we are vice versa; in short, detailed balance is not satisfied. To correct this, we introduce a probability  $\alpha(x,y)$  that the move is actually made,

$$\pi(x)q(x,y)\alpha(x,y) = \pi(y)q(y,x)$$

Rearranging we obtain,

$$\alpha(x,y) = \frac{\pi(y)q(y,x)}{\pi(x)q(x,y)}$$

Reiterating, we interpret  $\alpha(x,y)$  as the probability of moving from state x to state y. Since it is a probability, it cannot exceed 1 so the final definition is,

$$\alpha(x,y) = \min[\frac{\pi(y)q(y,x)}{\pi(x)q(x,y)},1]$$

Note that  $\alpha(x, y)$  is the transition kernel p(x, y) that we were after! It satisfies the detailed balance equation by definition; however, does it deal with the pesky intractable normalizing constant K? Yes! We have that,

$$\frac{\pi(y)q(y,x)}{\pi(x)q(x,y)} = \frac{\frac{f(y)q(y,x)}{K}}{\frac{f(x)q(x,y)}{K}}$$
$$= \frac{f(y)q(y,x)}{f(x)q(x,y)}$$

So we no longer have to worry about K (yay!). Ergo, we can simply use  $\alpha(x,y)$  as our transition kernel for our Markov Chain and rest assured that as long as we obtain enough samples, they will be distributed according to the stationary distribution; voila, we have samples from the intractable distribution  $\pi(\cdot)$ !

## Algorithm 1 Metropolis Hastings

```
Initialize x_0
for j=1,2,\ldots,N do

Generate y from q(x^{(j)},\cdot) and u from U(0,1)
if u\leq \alpha(x^{(j)},y) then
x^{(j+1)}=y
else
x^{(j+1)}=x^{(j)}
end if
end for
\operatorname{Return} x^{(1)},x^{(2)},\ldots,x^{(N)}
```

## 1 Notes

- $\pi(x)$  is the target distribution
  - this is the distribution we want to generate samples from
  - $-\pi(x) = \frac{f(x)}{K}$ ; the normalizing constant K is usually intractable!
- q(x,y) is the proposal distribution
  - generates a proposal y given the current state x
  - you pick the distribution! (which means you are able to sample from it easily, provided you don't use some intractable distribution)
- $\alpha(x,y) = \min\left[\frac{\pi(y)q(y,x)}{\pi(x)q(x,y)}, 1\right]$ 
  - this **is** the transition kernel that will satisfy detailed balance
  - probability of moving from state x to state y
  - notice that

$$\frac{\pi(y)q(y,x)}{\pi(x)q(x,y)} = \frac{\frac{f(y)q(y,x)}{K}}{\frac{f(x)q(x,y)}{K}}$$
$$= \frac{f(y)q(y,x)}{f(x)q(x,y)}$$

so we don't have to worry about the intractable normalizing constant (yay!)

- $\pi(x)p(x,y) = \pi(y)p(y,x)$  is the reversibility condition
  - necessarily,  $\pi(\cdot)$  is the stationary distribution
  - -p(x,y) is a transition kernel