Math 308G/H - Winter 2018 Midterm 2 2018-02-21

KEY

Question	Points	Score
1	12	
2	12	
3	12	
4	12	
5	12	
Total:	60	

- There are 5 problems on this exam. Be sure you have all 5 problems on your exam.
- The final answer must be left in exact form. Box your final answer.
- You are allowed the TI-30XIIS calculator. It is possible to complete the exam without a calculator.
- You are allowed a single sheet of 2-sided handwritten self-written notes.
- You must show your work to receive full credit. A correct answer with no supporting work will receive
 a zero.
- Use the backsides if you need extra space. Make a note of this if you do.
- Do not cheat. This exam should represent your own work. If you are caught cheating, I will report you to the Community Standards and Student Conduct office.

Conventions:

- I will often denote the zero vector by 0.
- When I define a variable, it is defined for that whole question. The A defined in Question 2 is the same for each part.
- I treat row and column vectors as the same.
- For any linear transformation T, there exists a matrix A such that T(x) = Ax. I defined the determinant, rank, and nullity of T using A. This means,

$$det(T) = det(A)$$
, $rank(T) = rank(A)$, $nullity(T) = nullity(A)$.

- 1. Give an example of each of the following. If it is not possible, write "NOT POSSIBLE". You do not need to justify your answers.
 - (a) (3 points) If possible, give an example of a linear transformation $T: \mathbb{R}^4 \to \mathbb{R}^2$ with rank(T) = 3.

Solution: NOT POSSIBLE.

(b) (3 points) If possible, give an example of a linear transformation $T: \mathbb{R}^4 \to \mathbb{R}^2$ with nullity(T) = 3.

Solution: Let $T: \mathbb{R}^4 \to \mathbb{R}^2$ be defined by T(w, x, y, z) = (w, 0). The nullspace is the w = 0 hyperplane which is 3-dimensional.

(c) (3 points) If possible, give an example of a linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$ such that T is one-to-one but T^2 is not onto.

Solution: NOT POSSIBLE. Since T is a one-to-one linear transformation from the same dimension to the same dimension, it is invertible. The composition of invertible maps is invertible so T^2 is invertible and thus onto.

(d) (3 points) If possible, give an example of a basis for \mathbb{R}^3 where each basis element lies in the 2x + y + z = 1 plane. (Hint: Note that $1 \neq 0$.)

Solution: The first thing to observe is that the 2x + y + z = 1 plane is not a subspace. A basis for \mathbb{R}^3 that lies in the plane is $\{\frac{1}{2}e_1, e_2, e_3\}$.

2. (a) (6 points) Suppose $T: \mathbb{R}^2 \to \mathbb{R}^2$ is a linear transformation with the property that

$$T(2,0) = (3,0), T(1,1) = (0,2).$$

What is $|\det(T)|$? (Hint: A picture could be helpful here.)

Solution: The linear transformation T sends a triangle with area 2 to a triangle with area 3. Therefore, $|\det(T)| = 3/2$.

(b) (6 points) Let

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 2 & 0 & 21 \\ 3 & 8 & 2018 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 & 5 \\ 0 & 2 & 3 \\ 0 & 0 & -3 \end{bmatrix}, C = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

• What is det(B)?

Solution: -6

• What is det(C)?

Solution: 3

• What is $det(2A^{-1}B^TAC^2)$? Here B^T denotes the transpose of B. You may leave your answer as a product of numbers and their powers.

Solution: Using properties of determinants,

$$\det(2A^{-1}B^TAC^2) = \det(2I_3)\det(B)\det(C)^2 = (2^3)(-6)(3^2).$$

3. Let A and C be equivalent matrices given by

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 2 & 3 & 1 \\ 3 & 0 & 6 \\ 4 & 8 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = C.$$

Let T be the linear transformation defined by T(x) = Ax.

- (a) (6 points) For each of the following subspaces, write down a basis for the subspace. If you write your answer as a matrix, I will draw frowny faces on your exam and will consider taking off points
 - \bullet col(A)

Solution: $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \\ 8 \end{bmatrix} \right\}$

• $\ker(T)$

Solution: $\left\{ \begin{bmatrix} -2\\1\\1 \end{bmatrix} \right\}$

• row(A)

Solution: $\left\{ \begin{bmatrix} 1\\0\\2 \end{bmatrix}, \begin{bmatrix} 0\\1\\-1 \end{bmatrix} \right\}$

- (b) (6 points) Let $U = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$. You do not need to justify the following answers.
 - What is rank(T)?

Solution: 2

• What is nullity(AU)?

Solution: 1

• What is nullity $(2C^T)$?

Solution: 2

4. Let A and C be equivalent matrices defined by

$$A = \begin{bmatrix} 1 & 1 & 2 & 0 \\ 2 & 1 & 3 & 3 \\ 3 & 1 & 4 & 0 \\ 4 & 1 & 5 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = C.$$

(a) (4 points) What is a basis for row(A)?

Solution:

$$\left\{ \begin{bmatrix} 1\\0\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\1\\1 \end{bmatrix} \right\}$$

- (b) (4 points) Denote the basis for row(A) found in the previous part by \mathcal{B} . If possible, write the following vectors as linear combinations of the element of \mathcal{B} . Otherwise, write "NOT POSSIBLE" and justify why is it not possible.
 - (2, 2, 4, 0)

Solution: The membership problem is really easy with this basis. You can essentially read off the answer.

$$\begin{bmatrix} 2\\2\\4\\0 \end{bmatrix} = 2 \begin{bmatrix} 1\\0\\1\\0 \end{bmatrix} + 2 \begin{bmatrix} 0\\1\\1\\0 \end{bmatrix}$$

 \bullet (2,1,0,1)

Solution: NOT POSSIBLE. The associated linear system to this membership problem is:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} x = \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix}.$$

This linear system has no soluton because the first 3 lines are claiming:

$$x_1 = 2$$
, $x_2 = 1$, $x_1 + x_2 = 0$.

(c) (4 points) Hopefully, you determined that \mathcal{B} does not span \mathbb{R}^4 . Give an example of a vector that could be added to \mathcal{B} so that together they span \mathbb{R}^4 . Be sure to justify your answer.

Solution: Since A has rank 3, we just need to add one vector not row(A). For example, (2,1,0,1).

5. Let

$$u_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, u_2 = \begin{bmatrix} 3 \\ 0 \\ 8 \end{bmatrix}, u_3 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}.$$

Let $U = [u_1 \ u_2 \ u_3]$ and $\mathcal{B} = \{u_1, u_2, u_3\}$. We have that U is invertible. Let $T : \mathbb{R}^3 \to \mathbb{R}^3$ be a linear transformation with the property:

$$T(u_1) = u_1, \quad T(u_2) = 2u_2, \quad T(u_3) = 2u_1.$$

From lecture, we know that

$$T(x) = U \begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix} U^{-1}x.$$

- (a) (4 points) You do not need to show work for the following quick questions:
 - What is rank(T)?

Solution: 2

• What is det(T)?

Solution: 0

• What is $\operatorname{nullity}(T)$?

Solution: 1

• Is T invertible?

Solution: No.

(b) (4 points) What is $T(2u_1+u_2)$? You may express your answer as a linear combination of u_1, u_2, u_3 .

Solution: Let C be the matrix between U and U^{-1} .

$$T(2u_1 + u_2) = UCU^{-1}(2u_1 + u_2)$$

$$= UC(2e_1 + e_2)$$

$$= U(2e_1 + 2e_2)$$

$$= 2u_1 + 2u_2$$

(c) (4 points) Suppose $[x]_{\mathcal{B}} = (2,1,0)$. What is $[T(x)]_{\mathcal{B}}$? (Hint: a intermediate step could be to determine what x is. Then look at the previous part.)

Solution: If $[x]_{\mathcal{B}} = (2, 1, 0)$, then $x = 2u_1 + u_2$. So by the last part, $T(x) = 2u_1 + 2u_2$. This means $[T(x)]_{\mathcal{B}} = (2, 2, 0)$.