

12.4 Cross Product

Defn $\langle a_1, a_2, a_3 \rangle$
Let a, b be vectors in \mathbb{R}^3 . Then the cross product
 $\langle b_1, b_2, b_3 \rangle$

$$a \times b = \langle a_2 b_3 - a_3 b_2, a_3 b_1 - a_1 b_3, a_1 b_2 - a_2 b_1 \rangle.$$

It is also a vector ~~that~~ \otimes

~~that~~

1) \otimes orthogonal to a and b ,

\swarrow z direction

\nwarrow b direction

2) whose direction is determined by the right-hand rule.

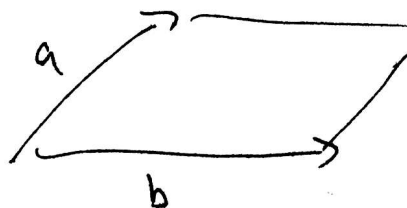
3) whose magnitude is $|a||b|\sin \theta$

compute $\langle 1, 2, 0 \rangle \times \langle 2, 4, -1 \rangle$ and $i \times j, j \times k, j \times i$.

Two nonzero vectors a and b are parallel
iff

$$a \times b = 0.$$

The length of $a \times b$ is the area of the
parallelogram determined by a and b .



Properties

See book.

key ones $a, b \in \mathbb{R}^3, c \in \mathbb{R}$

$$a \times b = -b \times a$$

$$a \times 0 = 0$$

$$c(a \times b) = (ca) \times b = a \times (cb).$$

(2)

Torque is

$$\tau = r \times F, \quad \text{talk about RHR rule.}$$

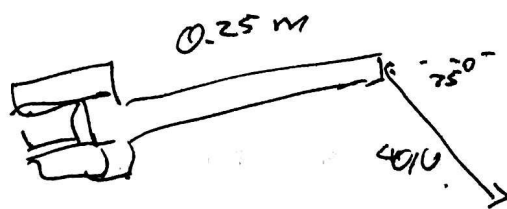
~~torque~~

$$|\tau| = |r \times F| = |r||F| \sin \theta.$$

"stranger" when $\theta = \pi/2$.

Ex

A bolt is tightened by applying a torque force to a 0.25 m wrench as shown below



What is the magnitude of the torque?

$$\begin{aligned} |\tau| &= |r \times F| \\ &= |r||F| \sin \theta \\ &= 0.25 \cdot 40 \cdot \sin 25^\circ \end{aligned}$$

12.5 Equation of lines and planes

Lines

~~A line can be defined with the following~~
 The defining data for a line can be:

~~take one point and by the vector~~
~~the vector formed by taking difference.~~

{ two points } \rightarrow { a point and a direction }

distinct
 two points
 a, b
 r_0, s_0

a point and a direction.
 $r, v \neq 0$

$$\begin{aligned} a &\rightarrow b \\ a + v &\rightarrow b \\ r_0 &\rightarrow r \\ r + v &\rightarrow s \end{aligned}$$

~~the vector~~

then

Let L be a line. Then the vector equation

for L is

$$r = r_0 + t v$$

Writing this equation out, we have

$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle$$

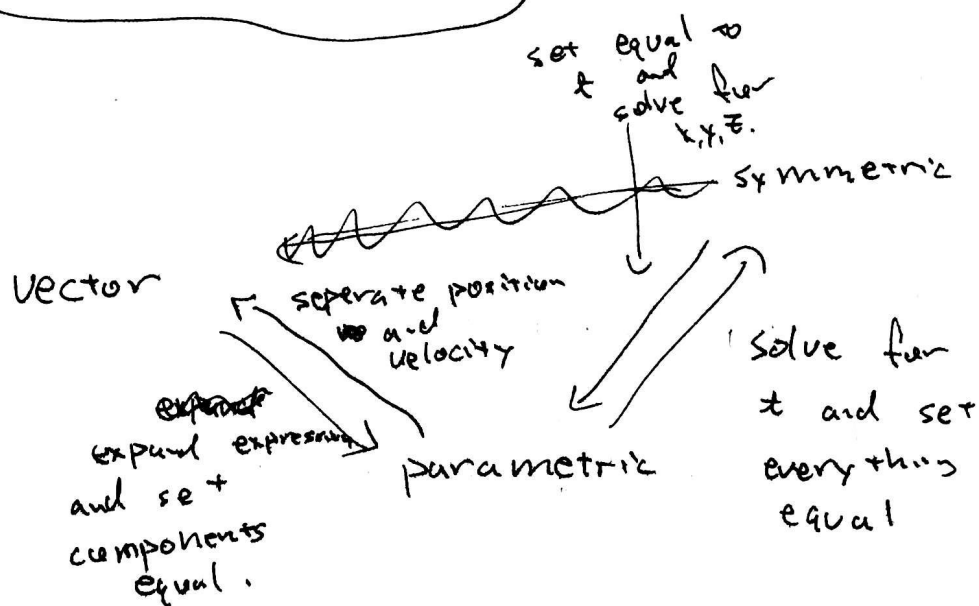
$$= \langle x_0 + at, y_0 + bt, z_0 + ct \rangle$$

By equating components, we obtain the
parametric equations for L

$$\begin{aligned}x &= x_0 + at \\y &= y_0 + bt \\z &= z_0 + ct.\end{aligned}$$

By ~~solving~~ solving for t , we obtain the
 symmetric equations for L ,

$$t = \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$



~~Examples~~

~~Step~~ Skew : does not intersect, not same direction
 Parallel : same direction
 intersecting : intersects.

Let $L_1 : x = 1 + t, y = -2 + 3t, z = 4 - t$

$L_2 : x = 2s, y = 3 + s, z = -3 + 4s.$

Do conversions.
 skew? Parallel? intersecting?