

October 4

Announcements

- Section 1.1, 1.2 due tomorrow
- Worksheet 1 due Friday - there are html issues, see pdf version
- Section 2.1, 2.2 due next Thursday
- Office hours today after class and tomorrow 12-1

Linear combinations and span

Definition: If u_1, u_2, \dots, u_m are vectors and c_1, c_2, \dots, c_m are scalars, then

$$c_1 u_1 + c_2 u_2 + \dots + c_m u_m$$

is a *linear combination* of u_1, \dots, u_m . Note that the constants can be negative or zero.

Definition: Let $S = \{u_1, u_2, \dots, u_m\}$ be a set of vectors. Then the span of S , $\text{span} S$, is the set of all linear combinations of u_1, u_2, \dots, u_m .

What vectors in \mathbb{R}^2 are a linear combination of $(1, 0)$ and $(0, 1)$? In other words, what vectors are in the span of $(1, 0)$ and $(0, 1)$?

What vectors in \mathbb{R}^2 are a linear combination of $(1, 2)$ and $(0, 1)$? Talk about lines and averages here.

Is $(3, 4)$ a linear combination of $(1, 2)$ and $(0, 1)$? In other words, is $(3, 4)$ in the span of $(1, 2)$ and $(0, 1)$? In other words, does there exist $x_1, x_2 \in \mathbb{R}$ such that $x_1(1, 2) + x_2(0, 1) = (3, 4)$? In other words, system of equations!

Every system of equation can be interpreted in this way.

Theorem: Let u_1, \dots, u_m and v be vectors in \mathbb{R}^n . Then $v \in \text{span}(\{u_1, \dots, u_m\})$ if and only if the linear system with augmented matrix $[u_1 \ u_2 \ \dots \ u_m | v]$ has a solution.

The solution space can be expressed as a linear combination.

Theorem: Let u_1, u_2, \dots, u_m be vectors in \mathbb{R}^n . If $u \in \text{span}(\{u_1, \dots, u_m\})$, then $\text{span}(\{u_1, \dots, u_m\}) = \text{span}(\{u_1, \dots, u_m, u\})$.

When does a set of vectors span \mathbb{R}^n ?

Theorem: Let u_1, u_2, \dots, u_m be vectors in \mathbb{R}^n . Let $A = [u_1 \ u_2 \ \dots \ u_m]$ and $B \sim A$, where B is in echelon form. Then $\text{span}(\{u_1, \dots, u_m\}) = \mathbb{R}^n$ if and only if B has a pivot position in every row.

give outline of proof

We can write linear systems as $Ax = b$.