## Soft Matter and Polymer Physics

problem set November 29, 2016

Free energy of Gaussian chain – force-extension curve

Consider a Gaussian polymer,  $\{\mathbf{r}_i\}$ , that is comprised of N segments,  $i = 0, \dots, N-1$ . The Hamiltonian is given by

$$\beta \mathcal{H}_0 = \frac{3(N-1)}{2R_{e0}^2} \sum_{i=0}^{N-2} (\mathbf{r}_{i+1} - \mathbf{r}_i)^2$$
 (1)

where  $\beta = 1/k_BT$  denote the inverse temperature. The partition function,  $\mathcal{Z}_0$ , of this Gaussian polymer is given by

$$\mathcal{Z}_0 = \frac{1}{\lambda_T^{3N}} \int \prod_{i=0}^{N-1} d^3 \mathbf{r}_i \ e^{-\beta \mathcal{H}_0} = \frac{V}{\lambda_T} \left( \frac{2\pi R_{e0}^2}{3(N-1)\lambda_T^2} \right)^{\frac{3(N-1)}{2}}$$
(2)

where V and  $\lambda_T$  denote the volume of the system and the thermal de-Broglie wavelength, respectively.

Consider two ensembles:

(a) fixed end-to-end distance,  $\mathbf{R}$  – The end-to-end distance  $\mathbf{r}_{N-1} - \mathbf{r}_0$  along is fixed to  $\mathbf{R}$ , and the partition function takes the form

$$\mathcal{Z}_{a}(\mathbf{R}) = \frac{1}{\lambda_{T}^{3N}} \int \prod_{i=0}^{N-1} d^{3}\mathbf{r}_{i} e^{-\beta \mathcal{H}_{0}} \delta(\mathbf{r}_{N-1} - \mathbf{r}_{0} - \mathbf{R})$$
$$= \mathcal{Z}_{0} \langle \delta(\mathbf{r}_{N-1} - \mathbf{r}_{0} - \mathbf{R}) \rangle_{0}$$
(3)

where the  $\mathcal{Z}_0$  is the partition function of a Gaussian polymer, see Eq. (2), and the average  $\langle \cdots \rangle_0$  refers to the canonical average of a free Gaussian polymer. Define the free-energy of a polymer with a fixed end-to-end distance vector  $\mathbf{R}$  (thermodynamic macrostate) by

$$\beta F(\mathbf{R}) = -\ln \mathcal{Z}_a(\mathbf{R}) \tag{4}$$

(b) force along the end-to-end distance,  ${\bf f}$  – In addition to the bonded Hamiltonian (i.e., harmonic springs between neighboring beads along the chain) there acts a force  ${\bf f}$  between the first and last bead. Let , the partition function takes the form

$$\mathcal{Z}_{b}(\mathbf{f}) = \frac{1}{\lambda_{T}^{3N}} \int \prod_{i=0}^{N-1} d^{3}\mathbf{r}_{i} e^{-\beta\mathcal{H}_{0}-\beta\mathbf{f}\cdot(\mathbf{r}_{N-1}-\mathbf{r}_{0})}$$

$$= \frac{1}{\lambda_{T}^{3N}} \int \prod_{i=0}^{N-1} d^{3}\mathbf{r}_{i} e^{-\beta[\mathcal{H}_{0}+\mathcal{H}_{b}(\mathbf{f})]}$$
with  $\beta\mathcal{H}_{b}(\mathbf{f}) \equiv \beta\mathbf{f}\cdot(\mathbf{r}_{N-1}-\mathbf{r}_{0})$  (5)

The concomitant free energy of this ensemble is given by

$$\beta G(\mathbf{f}) = -\ln \mathcal{Z}_b(\mathbf{f}) \tag{6}$$

Using analytical considerations or computer simulations, consider the following tasks:

- Use Eqs. (3) and (4) to calculate the free-energy difference  $\beta \Delta F_{21}(R)$  between the states (1)  $\mathbf{R} = 0$  and (2)  $\mathbf{R} = R\mathbf{e}_x$  in a computer simulation.
- Calculate the force that acts between the end segments in state (2) according to

$$\beta \tilde{\mathbf{f}}(\mathbf{R}) \equiv -\frac{\partial \beta \Delta F_{21}(\mathbf{R})}{\partial \mathbf{R}} \tag{7}$$

Use thermodynamic integration to compute the free energy change,

$$\beta \Delta F_{21}(R) = -\int_0^R dR' \,\beta \tilde{\mathbf{f}}(R'\mathbf{e}_x) \tag{8}$$

- Calculate the force-extension curve in the ensemble (b), i.e.,  $\mathbf{R}(\mathbf{f}) \equiv \langle \mathbf{r}_{N-1} \mathbf{r}_0 \rangle_b$ .
- Use the force-extension curve to compute the free-energy change between the states (1)  $\beta \mathbf{f} = 0$  and (2)  $\beta \mathbf{f} = \frac{3R}{R_{e0}^2} \mathbf{e}_x$

$$\beta \Delta G_{21}(f) = \int_0^f \mathrm{d}f' \left\langle \frac{\partial \beta \mathcal{H}_b}{\partial f'} \right\rangle_b \tag{9}$$