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Organization of Spatiotemporal Information and Relational Memory in the Hippocampus

By

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Preliminary Examination Document

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*To my wife, friends, and family*

*And*

*All of my mentors and teachers*

Contents

[Contents 4](#_Toc499134713)

[Chapter 1: General Introduction 6](#_Toc499134714)

[1.1 Domains and Entities: Building Systematic Understanding of Reconstruction 7](#_Toc499134715)

[1.1.1 Illustratability Does Not Define Domains of Information 10](#_Toc499134716)

[1.1.2 Domains Other than Space and Time 10](#_Toc499134717)

[1.1.3 2D Spatial Reconstruction – The iPosition Task 12](#_Toc499134718)

[1.1.4 Sampling and Encoding During Study 16](#_Toc499134719)

[1.2 Overview of Chapters 17](#_Toc499134720)

[1.2.1 Reconstructing Relational Information 17](#_Toc499134721)

[1.2.2 Memory during Time Travel: Spatiotemporal Navigation, Contextual Boundaries, and Relational Memory Errors in Virtual Reality 18](#_Toc499134722)

[1.2.3 Spatiotemporal Navigation, Sampling, and Information Encoding in Virtual Reality 20](#_Toc499134723)

[Chapter 2: Reconstructing Relational Information 21](#_Toc499134724)

[2.1 Introduction 21](#_Toc499134725)

[2.2 Materials and Methods 24](#_Toc499134726)

[2.2.1 Participants 24](#_Toc499134727)

[2.2.2 Experimental Paradigm 25](#_Toc499134728)

[2.2.3 Analysis Methods 26](#_Toc499134729)

[2.2.3.1 Identity Remapping 27](#_Toc499134730)

[2.2.3.2 Global Error Transformations 27](#_Toc499134731)

[2.2.3.3 Location Placement Evaluation 28](#_Toc499134732)

[2.2.3.4 Compound Identity Error Evaluation 29](#_Toc499134733)

[2.2.3.5 Gestalten Shape-Like Information 30](#_Toc499134734)

[2.2.3.6 Statistical Analysis 31](#_Toc499134735)

[2.2.3.7 Reanalysis of Watson et al. (2013) Set Size Data 31](#_Toc499134736)

[2.3 Results 31](#_Toc499134737)

[2.3.1 Differences in Misplacement Accounted for by Global Errors 31](#_Toc499134738)

[2.3.2 First-Order and Higher-Order Relational Errors 33](#_Toc499134739)

[2.3.3 Differences in Accuracy of Item-Location Associations across Set Sizes 34](#_Toc499134740)

[2.4 Discussion 35](#_Toc499134741)

[Chapter 3: Memory during Time Travel: Spatiotemporal Navigation, Contextual Boundaries, and Relational Memory Errors in Virtual Reality 40](#_Toc499134742)

[3.1 Introduction 40](#_Toc499134743)

[3.2 Methods 42](#_Toc499134744)

[3.2.1 Participants 42](#_Toc499134745)

[3.2.2 Design and Procedures 42](#_Toc499134746)

[3.2.3 Analysis Metrics 44](#_Toc499134747)

[3.2.4 Statistical Analysis 45](#_Toc499134748)

[3.3 Results 45](#_Toc499134749)

[3.3.1 Overall Accuracy and Navigation (Misplacement Measures and Navigation Distance) 45](#_Toc499134750)

[3.3.2 Relational Memory Errors 46](#_Toc499134751)

[3.3.3 Temporal Context Boundary Effects 47](#_Toc499134752)

[3.4 Discussion 50](#_Toc499134753)

[Chapter 4: Spatiotemporal Navigation, Sampling, and Information Encoding in Virtual Reality 54](#_Toc499134754)

[4.1 Introduction 54](#_Toc499134755)

[4.2 Methods 57](#_Toc499134756)

[4.2.1 Participants 57](#_Toc499134757)

[4.2.2 Design and Procedures 57](#_Toc499134758)

[4.2.3 Proposed Navigation Analysis Metrics 60](#_Toc499134759)

[4.2.4 Proposed Order Analyses 61](#_Toc499134760)

[4.2.5 Statistical Analysis 63](#_Toc499134761)

[4.3 Results 63](#_Toc499134762)

[4.3.1 Overall Accuracy and Navigation 63](#_Toc499134763)

[4.3.2 Proposed Navigation Analysis Metrics Predictions 63](#_Toc499134764)

[4.3.3 Proposed Order Analyses Predictions 64](#_Toc499134765)

[4.4 Discussion 65](#_Toc499134766)

[Chapter 5: General Discussion 67](#_Toc499134767)

[5.1 Summary of Results 67](#_Toc499134768)

[5.2 Separable vs. Separate Hippocampal Representations 69](#_Toc499134769)

[5.3 Behavioral Inference, Sampling, and Task Richness 69](#_Toc499134770)

[5.4 Artificial Intelligence and Spatial Reconstructions 70](#_Toc499134771)

[5.5 Conclusion 71](#_Toc499134772)

[References 72](#_Toc499134773)

# Chapter 1: General Introduction

There are numerous ways to quantify memory efficacy, but when it comes to recollective memory few methods are richer or more detailed than navigation (Howard Eichenbaum, 2017b) and reconstruction tasks (Huttenlocher & Presson, 1979). Reconstruction tasks ask individuals to study some set of information and then, after a delay, recreate the information they saw it. Traditionally, individuals are given a set of items which are to be reconstructed in space (Jeneson, Mauldin, & Squire, 2010; M. Lou Smith & Milner, 1981; Watson, Voss, Warren, Tranel, & Cohen, 2013). The strength of these paradigms is that not only can one assess which aspects of the original information were or weren’t remembered, but also the degree to which they were remembered, as well as whether there are any systematic distortions in that memory. Ultimately, we are unable to know what precise thoughts, strategies, or information the participant did or did not have when performing the task just from the behavioral data, but by carefully picking the assumptions we are willing to make, we can strongly infer what was not done in the reconstruction (because if it were, the performance should have been better). Moreover, by systematically analyzing the performance in reconstruction, we can begin to hypothesize new models and test existing models of memory organization (Howard Eichenbaum, 2016) and representation (Howard Eichenbaum, 2004, 2017a; O’Reilly & Rudy, 2001; Schapiro, Turk-Browne, Botvinick, & Norman, 2017) across many different domains of information (Konkel, Warren, Duff, Tranel, & Cohen, 2008).

In addition to a theoretical introduction to assumptions and perspectives on reconstruction tasks, the work presented in this document will show how performance on reconstruction tasks can be broken down into specific and sensitive metrics of performance to elucidate some aspects of memory in two particular domains, space and time. Relational memory theory posits that the hippocampus is critical for the binding of arbitrary relations into rich memory representations, as well as for the flexible usage of these representations, regardless of the domain from which the information originates (Neal J. Cohen & Eichenbaum, 1993; Monti et al., 2015). Previous work has shown that binding of the identity of an item to a location in space (i.e. identity-location binding) may be one critical example of an arbitrary relation which is severely impaired in hippocampal damaged patients (Watson et al., 2013), with other accounts suggesting that not all relational information is impaired without specifying the precise nature of the deficits (Jeneson et al., 2010). Though these previous accounts hinted at specific aspects of information in reconstruction being impaired and spared, the analysis methods differed significantly, making it difficult to determine the precise nature of the deficits in reconstruction in hippocampal damaged patients. The work presented here attempts to reconcile these accounts with a novel methodological framework constructed from a principled approach to reconstruction data. The data show that certain (but not all) *types* of relational information are impaired in hippocampal damaged individuals (Chapter 2), but, critically, arbitrary identity-location information is impaired (i.e. the information was not derivable from other relations or elements which may have been remembered) while the location information (i.e. the ability to reconstruct items in studied locations regardless of the identity of the item) is not.

Hippocampal function is not exclusive to spatial information, however, with the identification of “time cells” in the hippocampus recently showing this via direct, electrophysiological evidence (Howard Eichenbaum, 2014; B. Kraus, Robinson, White, Eichenbaum, & Hasselmo, 2013). Additional sources of information (such as contextual information) can also bias representations (Ezzyat & Davachi, 2014; Zacks, Speer, Swallow, Braver, & Reynolds, 2007a), and these additional sources of information are critical in understanding the overall organization of memory and the hippocampal system, with most modern models of the region including cortical region interactions which involve the addition of these alternate sources of information (Kumaran, Hassabis, & McClelland, 2016; Sederberg, Howard, & Kahana, 2008; Wang, Cohen, & Voss, 2015). The reconstruction task presented in Chapter 3 embrace this complexity by allowing space and time to be explored simultaneously and asking participants to reconstruct events in space-time in the presence of temporal contexts. The data from this task show that in healthy adults, there may be differences in the representations of spatial and temporal information and systematic biases in different aspects of temporal representations due to contextual information.

Finally, sampling behavior in reconstruction is an equally critical element in overall performance. In previous work involving spatial sampling, eye movements, which are often thought of as “visual exploration” of an environment/scene (Voss, Bridge, Cohen, & Walker, 2017), in hippocampal damaged individuals and healthy individuals indicated both memory for an entire previously viewed scene and relations among elements in the scene; however, when the relations between items were changed, only healthy individuals showed differences in eye movements relative to the change, while hippocampal damaged patients did not (Neal J. Cohen & Banich, 2003). Similar sampling deficits in spatial navigation have been shown in rodents with hippocampal damage in the Morris Water Maze (R. G. M. Morris, Garrud, Rawlins, & O’Keefe, 1982). However, more recent work in humans shows that this deficit in navigation may be exclusive to precise, high-resolution information as humans with hippocampal damage in a Virtual Morris Water Maze were able to navigate to the correct quadrant of the spatial area but were impaired in finding the precise location of the target (Kolarik et al., 2016; Kolarik, Baer, Shahlaie, Yonelinas, & Ekstrom, 2017). The hippocampus’ role in spatial navigation has been compared extensively across species (especially rodents and humans), and the subject is still hotly debated (Howard Eichenbaum, 2017b). However, as stated in the previous paragraphs, hippocampal function is not exclusive to spatial processing and is critical for all domains of information. As such, this work (Chapter 4) examines exploration and navigation in a domain which has never been examined before, the temporal domain. Temporal exploration (aka Time Travel) may seem like a farfetched idea, but as many other authors all the way back to Tulving, 1989 (and more explicitly in Tulving, 2002a) have said, memory is time travel, with further evidence that MTL neurons “jump back in time” by replaying specific patterns of firing in response to repeated stimulus (Howard, Viskontas, Shankar, & Fried, 2012).

Before examining specific data on reconstruction and hippocampal function, several details regarding the theoretical prerequisites to analysis of this data should be explored. Information in reconstruction can be organized in a huge variety of ways, and it is useful to ensure that the analysis methods are capable of handling as many of these cases as possible. Also, by examining the assumptions made during task design, we can not only gain better insights into the nature of the task and analyses but we are also presented with an enormous variety of follow-up experiments and questions that future work outside of this dissertation may address. The next section breaks down properties of this task by examining the two critical elements of reconstruction, *domains* and *entities*, and enumerating properties and assumptions which warrant consideration in designing reconstruction tasks and analyses.

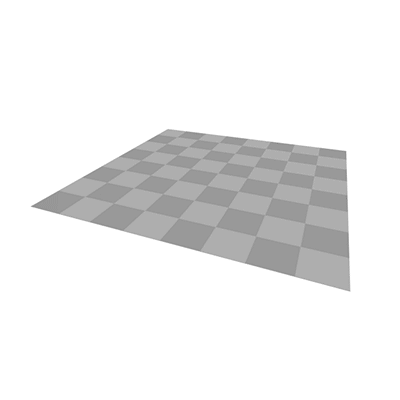
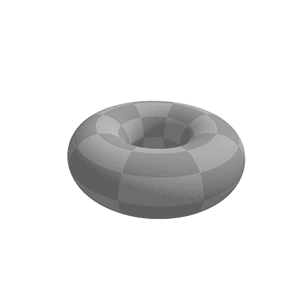
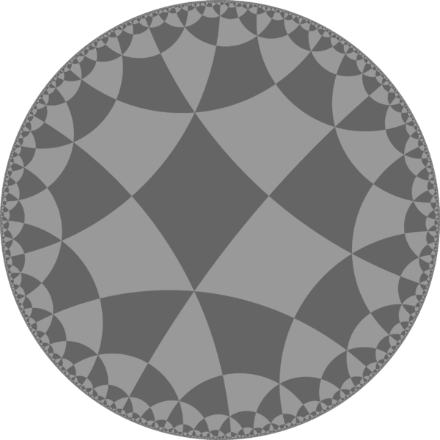
## 1.1 Domains and Entities: Building Systematic Understanding of Reconstruction

Reconstruction can be defined, in its most basic form, as containing two main components: a *domain,* i.e. an axis or set of axes into which *entities* (elements of a domain such as items, events, precise colors, pitches, etc.) can be embedded (see **Table 1** for an enumeration of key properties of domains and entities). It is interesting to see the similarities between this classification and the dorsal and ventral “where” and “what” pathways of the perceptual system, which converge in the hippocampal system (Insausti, Amaral, & Cowan, 1987; Squire & Zola-Morgan, 1991; Van Hoesen, Rosene, & Mesulam, 1979). While, of course, multiple types of domains and entities interact in memory, for the sake of our understanding of the memory representations which are involved in reconstruction, it is helpful to at first restrict our focus to instances in which only one domain and one type of entity are present, at least when developing our methodological and theoretical framework.



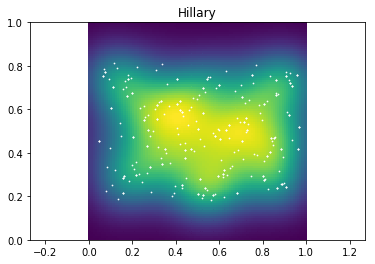
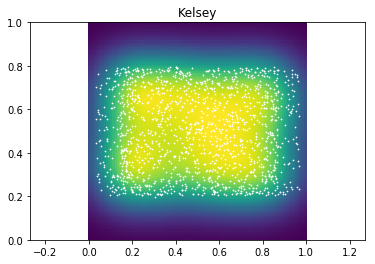
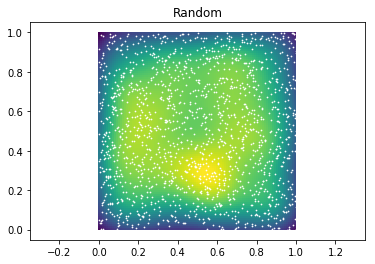
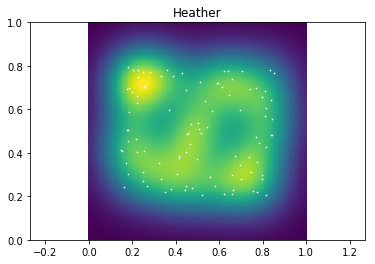
**Figure 1**. The Beckman Institute; an example of a 3D spatial domain populated by numerous entities which occupy specific points in space and have various identities. Red squares highlight entities which occupy the spatial domain. Some occupy fixed locations while others move at different time scales. The blue arrows illustrate the three spatial dimensions which comprise the spatial domain.

Let us take a specific example to which we can link the abstract terms defined in the previous paragraph to clarify their meaning. Imagine a 2D spatial domain on a table. Within this spatial domain exist items, i.e. discrete entities which have a precisely defined location on the table and locations relative to one-another. If we consider the number of restrictions we have already made, we can begin to understand how difficult the problem of a systematic breakdown of reconstruction is. First, the reader may have implicitly assumed (likely, rightfully so due to my examples) that the 2D space in question is finite. However, this was never explicitly stated. An infinite space opens up a variety of new problems of scale and geometry which future studies should address. For example, space could be a toroidal ring like we see in video games such as the classic, Asteroids (Wolf, 2010), wrapped on a sphere like we experience on maps from day-to-day (i.e. the earth; Snyder, 1987), in a hyperbolic space (a la a Penrose diagram in theoretical physics; Hawking & Ellis, 1973) where distance becomes asymptotically large as boundaries are approached, or something more exotic (Coxeter, 2008). Although humans more typically navigate a flat, 2D, Euclidean space, we are nonetheless capable of understanding and utilizing these other spaces.

**Figure 2**: Examples of spaces with different geometries. Euclidean, toroidal, and hyperbolic. From <http://blog.andreahawksley.com/170517301/> originally and latest from <https://en.wikipedia.org/wiki/File:Torus_from_rectangle.gif> and <https://en.wikipedia.org/wiki/File:H2chess_246a.png> . Also see <https://upload.wikimedia.org/wikipedia/commons/c/cb/Hyperbolic_domains_3222.png> .

Entities, on the other hand are typically restricted to have a precisely defined location, so entities which occupy multiple locations simultaneously have been eliminated. Entities typically have identities (rather than being anonymous) and are assumed to be equally likely to be positioned anywhere in the space while not occupying the same location as another entity (though we will see in the next section how subtle violations of this assumption can warp reconstruction). These systematic assumptions that both experimenter and participant make may seem unimportant as, if both parties make the same assumptions, it should not confound the results. However, participants which are unable to remember some information due to an impairment like hippocampal damage may fall back to these core assumptions and perform the task via heuristic, guessing locations based on an understanding of task design rather than an explicit knowledge of locations. There is mounting evidence that hippocampal damage impairs precision in spatial memory (Kolarik et al., 2016, 2017; Yonelinas, 2013a), which could be explained, in part, by a heuristic approach to memory. Alternatively, patients might actually be able to maintain relational information of some sort via alternative methods. Patients might, for instance, remember Gestalten perceptual features, i.e. configural features which constitute parts of a unified whole, rather than specific types of relations in order to reconstruct (Corsi, 1972; Kessels, van Zandvoort, Postma, Kappelle, & de Haan, 2000; Uttal & Chiong, 2004). Although we might be tempted to call heuristic performance “random” (because on some level, patients are “guessing” locations without any precise knowledge), or perceptually based performance “imprecise”, by acknowledging when our own assumptions of our task might become violated in a systematic way, we might gain insight into the sorts of information processing which are and are not impaired with damage to certain brain regions, and, by extension, we may better understand neural information processing as a whole.

**Figure 3**: Examples of heatmaps of item placement with different constraints. From left to right: random placement, random placement with aspect ratio constraint, random placement avoiding boundaries, random placement with a distance constraint (i.e. items must be a certain distance apart).

#### 1.1.1 Illustratability Does Not Define Domains of Information

Another critical assumption often made in reconstruction is the types of domains and entities which might be involved. Typically, reconstruction tasks have involved studying entities located in the spatial domain (as illustrated above). However, this is, once again, an arbitrary imposition on what reconstruction is, especially given the evidence that the hippocampus is critical for all domains of information (Konkel et al., 2008). Before enumerating examples of domains and entities which go beyond these examples, it’s useful to take a moment to consider why space (and sometimes time) may be so dominant. Reality, as we observe it, is intrinsically experienced in 3 spatial dimensions and 1 temporal dimension. All information of any type which we observe will exist, embedded in these 4 dimensions. This is often used as an argument as to why these must be the critical dimensions to neural systems, and perhaps, on some level, they are. However, it is incredibly restrictive to allow the definitions of domains which could be encoded to only be those which can be illustrated. Illustration requires, by its very nature, embedding whatever domain or idea is being observed into the observable 4D world. However, the set of all possible representable information need not be bound to what can be illustrated. An analogous situation happens when we imagine the dimensionality of data. We cannot easily illustrate data beyond 3 dimensions (see Abbott, 1884 for a playful exploration of attempting to visualize alternate numbers of dimensions). We can add color, animation, shape, size, and all sorts of other illustrative methods, but we can always add more dimensions to the data. If we stopped accepting dimensions beyond those that can be illustrated as easily as we stop accepting domains of information, much of the powerful mathematics used in the world today would be out of our reach. It is not a necessary precondition for a brain to represent information which can be illustrated.

#### 1.1.2 Domains Other than Space and Time

Several domains other than space and time have been examined in the literature in recent years. Social space, as defined by the relative affiliation and power between individuals (Howard Eichenbaum, 2015; Tavares et al., 2015), is another possible abstract space and has been investigated in the context of hippocampal function, finding that hippocampal fMRI activation located characters in a 2D power-affiliation “map”. Color can be thought of as an abstract domain where entities can be embedded in locations in a “color space” independently of locations in space and time (see Warren, Duff, Cohen, & Tranel, 2015 for an example of a reconstruction task involving color as a domain of interest). Of course, it is tempting to fall back into old habits and think of color as being on a 1D line, with the x axis defined as hue, and social space being illustrated via a scatter plot in 2 dimensions. These are useful illustrations, but domains of information are only illustrated to help us understand them. Their illustration does not define them. Additionally, although time has been discussed as if it can be easily lumped in with space up until now, it obviously has its own interesting properties. Time is intrinsically unidirectional. Time is continuous, and motion through it is obligatory. Few other domains have this property, and as such, time may be of special interest. Moreover time cells have been identified in the hippocampus (B. Kraus et al., 2013) which act much like place cells but activate corresponding with particular moments in time. Although it is difficult to disentangle temporal firing from spatial or distance firing, via careful task design, cells which fire to time and distance in exclusion of one another (as well as cells which fire for both) have been identified (B. J. Kraus et al., 2015) in the hippocampus. Together these pieces begin to paint a picture of a hippocampus in which entities can be bound within and across a variety of domains. Indeed, previous work has shown the hippocampus is critical for all manner (i.e. domain) of relations (Konkel et al., 2008). As such, our methodological framework should attempt to be agnostic to domain as much as is possible so that domain representation differences can be identified using the same metrics.

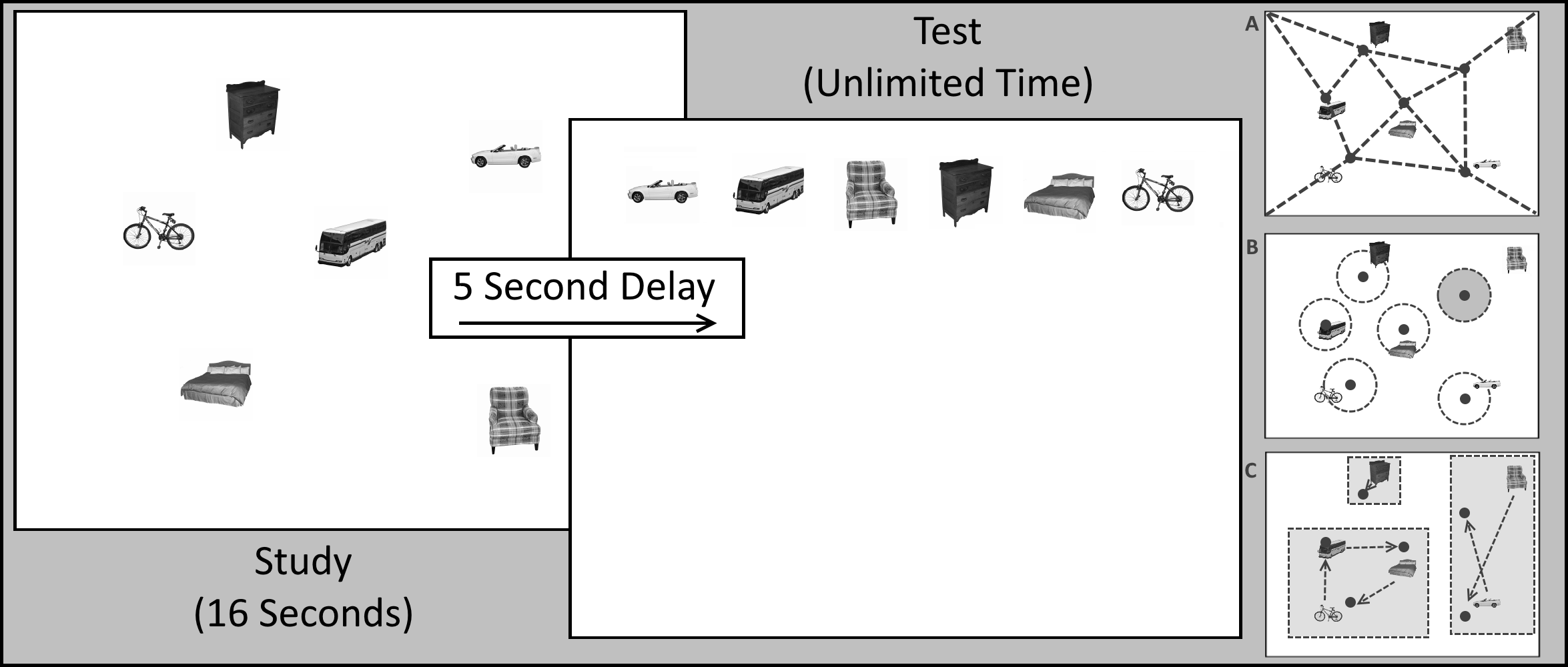
**Table 1**: Properties of Domains and Entities. This list is not necessarily exhaustive, but these properties represent some critical assumptions being made during any reconstruction task.

|  |  |
| --- | --- |
| Domains | Entities |
| **Finite vs. Infinite** (i.e. there are boundaries or not)  **C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\finite_infinite.png** | **Precisely Located** and **Encapsulated/Finite** (i.e. their position can be defined by one point)  C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\position.png |
| **Continuous vs. Discrete** (i.e. any location is valid or only some are)  **C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\discrete_continuous.png** | **Distribution**  (i.e. entities are more likely in some areas)  C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\scatter.png |
| **Dimensionality** (i.e. there are multiple of the same domain type)  C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\dimensions.png | **Constraint**  (i.e. positions of entities are relative to others) |
| **Geometry/Topology** (i.e. Euclidean, toroidal, hyperbolic)  C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\H2chess_246a.png | **Identity**  (i.e. they are anonymous or labelled)   C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\identities.png |
| **Disjoint vs. Connected**  (i.e. can all space be reached from anywhere)  C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\3dfigs.png | **Category**  (i.e. entities have distinct groupings)   C:\Users\Kevin\AppData\Local\Microsoft\Windows\INetCache\Content.Word\transform relations.png |

Relational memory theory (Neal J. Cohen & Eichenbaum, 1993) captures the vast majority of phenomena described in the previous paragraphs, but several properties that have been described have, to my knowledge, never been tested. It is not the goal of this dissertation to systematically test all of these variations, but rather, by describing these variations, a better understanding of the simpler cases of reconstruction can be gained which can generalize to other domains with more complex properties. In this way, relational memory theory can be refined to determine the *types* of relationships which are critical in different domains given different properties, and the organization of memory regardless of domain can become clearer. Although the complex cases described above of domains with toroidal geometry and disjoint features do exist in video games such as Asteroids or Portal and can be potentially addressed with the methods described in Chapter 2, a more fundamental understanding of reconstruction in the familiar domain of 2D Euclidean space should first be attained.

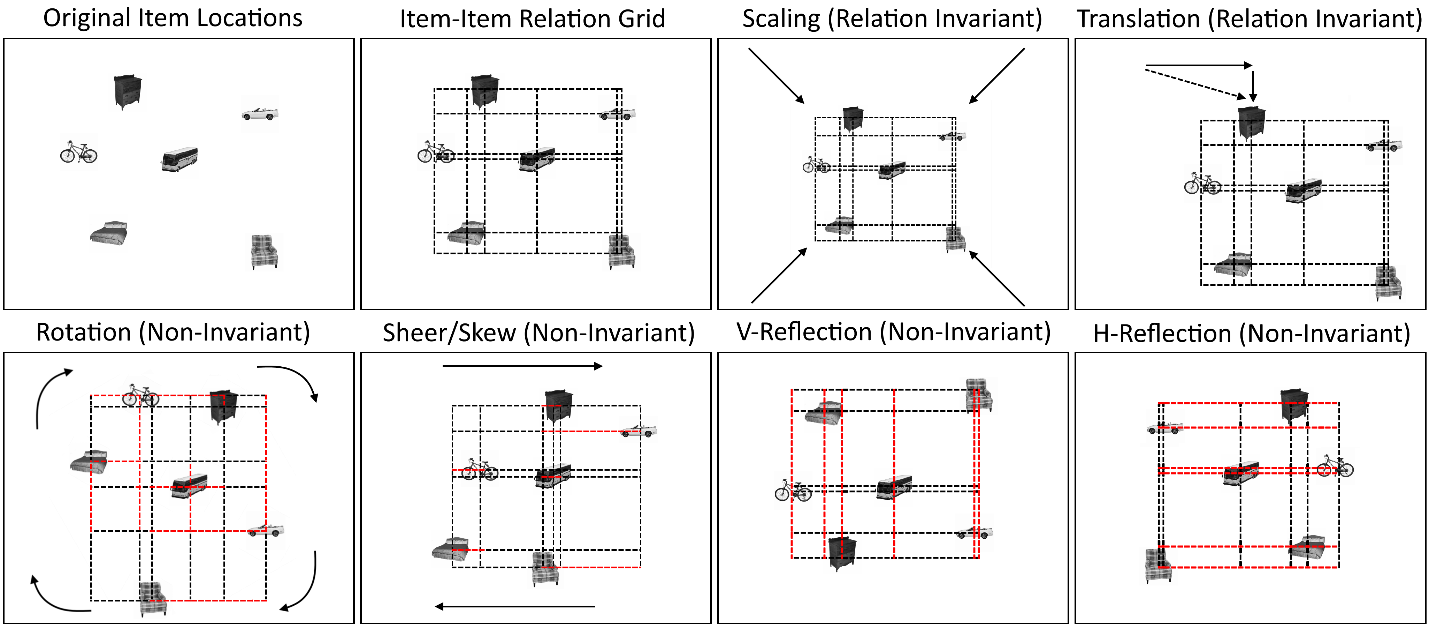
#### 1.1.3 2D Spatial Reconstruction – The iPosition Task

In the parlance of the previous sections, the iPosition task is comprised of a finite, continuous, 2D, Euclidean, spatial, connected domain (i.e. a computer screen) populated with 6, precisely located, finite, randomly distributed pictures of real-world entities which will not overlap/appear on top of one another and are sampled from a finite set of possible entities. This scenario has been used in several publications at this point (Jeneson et al., 2010; Lucas et al., 2016; Monti et al., 2015; Schwarb et al., 2017a; Schwarb, Johnson, McGarry, & Cohen, 2016; Watson et al., 2013) and has a proven track record of having hippocampal-dependent performance components. To break down this task, it is helpful to consider the information-theoretic content of the task. To determine the amount of information necessary to perfectly reconstruct a 6-item trial of the task, the simplest method is to assess how many numbers would be needed to describe 6 precise locations and the associated identity information. This question is intimately related to questions of information entropy (M.Cover, 2006; Shannon, 1948). A naïve approach to describing the location information would be to represent each of the 6 items with 2 numbers (x and y) and, assuming we have a list of the possible objects (or at least an understanding of the objects which are currently present), 1 additional number is needed to define the identity of each entity. So, in our naïve case, we can represent all 6 items with 18 numbers. However, as we’ll see in a moment, this naïve representation may or may not represent the actual amount of information storage used by an individual in remembering the configuration in this task.



**Figure 4**: Example Reconstruction Task: a finite, continuous, 2D, Euclidean, spatial, connected domain populated with 6, precisely located, finite, randomly distributed pictures of real-world objects which will not overlap/appear on top of one another and are sampled from a finite set of possible objects. Note that the study portion is timed, there is a short delay, then the test has unlimited time. These are constraints on sampling the environment and maintaining memory more than the information contained within the configuration.

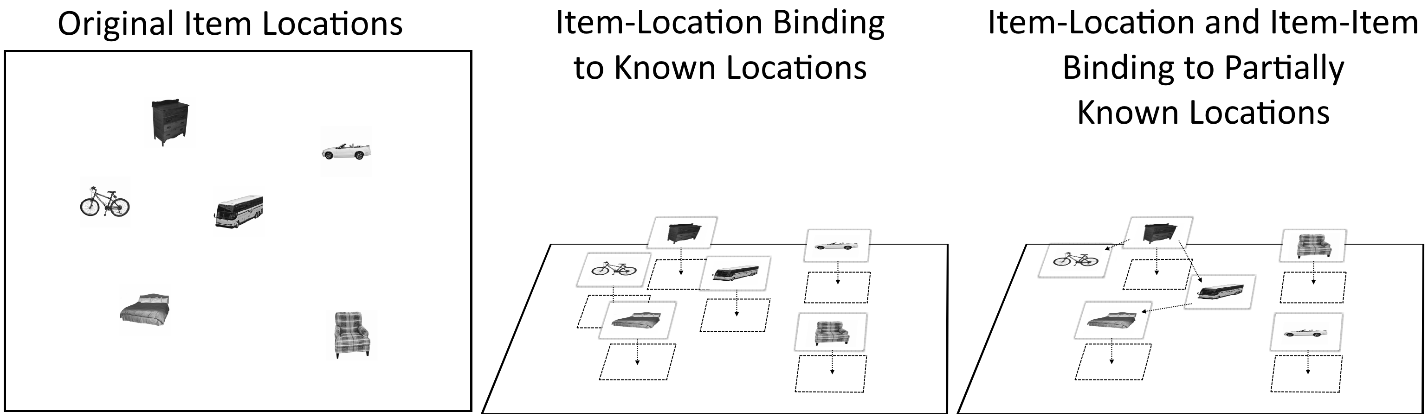
First, for location information, if the intent is to reconstruct an original configuration of these items, a precise reconstruction will require all 12 location numbers to be represented. However, for an approximate representation, a much more compressed option may be available. Suppose the positions of each element were encoded into a graph-like representation where the relations between a subset of the items was encoded instead of any explicit location. This is, in fact, a representational framework posited by relational memory theory (Neal J. Cohen & Eichenbaum, 1993). Now, if the graph can be represented more efficiently, only one position need be remembered precisely (i.e. the overall position of the graph within the environment). Moreover, with this representation, the positions can now be transformed in ways which are not obvious given a set of 6 unassociated points. For instance, if the space were to be scaled up or down (as was done in Muller & Kubie, 1987 in rodents), the relative relations would simply be scaled up or down in accordance (and in fact, Muller & Kubie showed that place cell firing in an open field remapped with scaling, maintaining the relative shape of spatial firing). If the space were to be translated (i.e. moved in any direction a fixed distance), the graph itself need not change, only the global position would need to be adjusted. In fact, within a space like the one we’ve defined, scaling and translation are the fundamental transformations which do not require alteration of the graph of relative positions. Interestingly, some theories of temporal memory for order also share this property of scale and translation invariance in time (Howard, Fotedar, Datey, & Hasselmo, 2005; Howard & Kahana, 2002; Howard & Natu, 2005; Shankar & Howard, 2015). Rotation, sheering, or other more complex transformations can potentially result in the relative positions of items being changed, but with scaling and translation, any item to the left of another will remain to the left, and any item on top will remain on top. This idea parallels similar ideas from physics and mathematics, where certain quantities are conserved (or invariant) under certain transformations. Noether’s theorem (Noether, 1971), in fact, specifically states that for any transformation (specifically, those which are differential symmetries of an action), there is some corresponding conservation law (conservation of energy is equivalent to translational symmetry in time, conversation of moment is translational symmetry in space, conservation of angular momentum is rotational symmetry in space, etc.). If we believe memory for the location information which describes a set of points is encoded in such a relational graph, we should similarly believe that the representation should only be conserved under those transformations which have relational invariance (i.e. scaling and translation) but not those which lack such an invariance (i.e. rotation and sheering). Moreover, we might suspect that transformations which conserve parts of the relational information (like reflection, which conserves relations on all but the reflected axis) might have a graded effect on memory for the locations. However, in 1D domains (such as time) a reflection would have a more extreme effect as it is guaranteed to damage the relational information between every item pair that isn’t directly on top of each other.



**Figure 5**: Relational Invariance in Affine Transformation Components in 2D: Note that via an item-item relational grid, we can observe the impact of different transforms on the relations present between items. Scaling and Translation have no impact on the relations between items (though scaling impacts distance between items. On the other hand, Rotation, Sheer/Skew, and Vertical/Horizontal Reflection all can modify relations in some systematic way. However, rotation uniquely can modify both dimensions relations.

Of course, the precision of the memory for the graph position and for the relational information may vary as well, but this can be treated as different types of noise which can be quantified in particular ways. The Precision and Binding Model (Yonelinas, 2013a) suggests that the hippocampus is critical for binding precise, high resolution information, and the associated measures of precision used in testing this model (a variable sized accuracy window) are one example of a quantification method which shows promise in providing more interpretability when working with complex path data (Kolarik et al., 2016, 2017). However, this model addresses precision in continuous domains, not precision for discrete information, and it does not address the specifics of how different binding configurations might influence memory. Moreover, because the theory addresses behavior only in a Virtual Morris Water Maze with a platform as the target entity, there is no identity information and no item-item relational information (item-environment relational information is present in the form of platform-landmark relations). Relational memory theory (Neal J. Cohen & Eichenbaum, 1993), on the other hand, very directly addresses how memory for arbitrary relations might form a flexible representation (in the graph-like manner discussed previously). However, even once we accept that a graph-like representation is at the core of memory for reconstruction, the problem is still far from solved. We don’t know, for instance, if a subset of the items are being represented relationally, bound to each other, while a single item is being bound to some aspect of the environment in exclusion of the other items. Additionally, the presence of higher-order organizational information (such as contextual information) might bias the reconstruction in ways which are measurable in the change of position of the groups of entities which share that higher-order property. The exact definition of context, however, is a topic of heavy debate and will not be resolved in this work.

Now, for identity information, we also have several possibilities. If the identity information is being convolved with some aspect of the spatial information, we would expect it to be subject to the same transformation and invariance rules outlined in the previous paragraph. If, however, the items are being bound to particular locations (as was suggested in Watson, Voss, Warren, Tranel, & Cohen, 2013), these bindings might be subject to their own invariance rules. This situation is more likely if the items are arbitrary, i.e. they just as easily could have been any item. Arbitrary items cannot be as easily convolved with location, as no expectancy can be formed about what item should be associated with a given location (thus, arbitrary). In reality, arbitrary items may still end up with alternative associations by chance (for instance, if an image of a plane happens to appear over an image of a tree, this obviously has a location-identity association which is non-arbitrary as planes tend to fly over trees, but it may have occurred by chance), but if the items are arbitrary, we can imagine them, in some way, as a disjoint domain of their own which must be bound to the continuous, connected domain of space. This binding may not be damaged by transformation of the space as it is being done via creating arbitrary relations from single points to identities. The various identities, however, could end up confused in some way if that information was not remembered but the location information was. In this way, particular identities might be assigned to the wrong location, or identities might switch places. If the relations are arbitrary, these errors should be thought of as distinct from the sorts which might result from some failure to remember location.



**Figure 6**: Examples of different identity binding methods. Item-Location Bindings to Known Locations assumes that item identities are being associated to particular locations and the locations are being remembered independently. Item-Location and Item-Item Binding to Partially Known Locations shows how, even in the absence of perfect location information, item-item relations can allow imprecise reconstruction of locations. Similarly, item-location binding can still be present, but identity can be misassigned even with perfect memory for location (i.e. the chair and the car are switched). Although we cannot easily know the particular representation being used by an individual on a particular trial, we can observe when these various errors occur and narrow down the possible representations and the information which is lacking.

#### 1.1.4 Sampling and Encoding During Study

Finally, the discussion up until now has been exclusive to the representational and retrieval portion of memory, but it largely neglects the encoding aspect of reconstruction. When performing a reconstruction task, individuals are given some amount of time to study the information. During this time, there are numerous behaviors which might be performed in order to attempt to gather the information. The structure of human sensory systems is such that we generally sample specific aspects of information one-at-a-time, rather than assimilating the whole environment simultaneously (see Kveraga & Bar, 2015 for a thorough treatment of the topic). This sampling behavior is of particular interest as it is often measurable. If the information being studies is all visual (such as a computer screen task), the eyes will be the only sampling medium and, as such, the movement of the eyes in some way determines the information which can be encoded. Eye movements have been successfully used to identify critical differences between viewing patterns in hippocampal damaged individuals and comparison participants due to memory (Neal J. Cohen & Banich, 2003; Deborah E. Hannula & Ranganath, 2009). In Virtual Reality or Real-World environments, navigation (the combination of body-movement and eye-movement) provides a more flexible form of sampling (and, in fact, eye movements can be a subset of this sampling as the technology to sample eye movement at the same time as head movement and environment position has been available for nearly 20 years; Duchowski et al., 2000). In either case, sampling comes down to a stream of information which is received by the system whose contents can be guided by in-the-moment demands; in fact the Covert, Rapid, Action-Memory Simulation (CRAMS) model specifically addresses this sort of rapid, in the moment, memory guided decision making, suggesting that prefrontal-hippocampal interactions provide rapid simulations of potential outcomes of decisions in order to guide behavior (Wang et al., 2015). If the task at hand has few demands, very little sampling will be required, however, in a demanding task, extensive sampling may be required to acquire the necessary information. Task are sometimes designed to require participants to sample particular aspects of an environment (via masking all but some small region of the environment, a la Yee, 2012, or by forcing the participant to acknowledge sampling of particular aspects of the environment before proceeding, for example), and these demands may also bias behavior in particular ways. Sampling is a complicated topic, and as such, it will only be examined in relation to the test performance and not in a more holistic, information rich manner.

## 1.2 Overview of Chapters

The remainder of this document will discuss algorithmic and mathematical formulations of domains and entities in reconstruction tasks, starting, specifically, with the aforementioned example of 2D space, validating the methods in hippocampal damaged patients. These methods will be used to show that hippocampal damage does uniquely impair some, but not all, measures of performance in reconstruction (Chapter 2). Later sections will show how these methods can be applied to a temporal domain and show how, despite its differences, temporal memory representations may be treated in much the same way as spatial memory representations (Chapter 3) under this theoretical framework. Temporal and spatial domains may share many similarities, but errors in each may be distinct in other ways which can be seen in reconstruction performance. In particular, contextual information may have a similar influence on memory in both space and time, when it comes to precise remembering of location information, but relational information may be in some way different in these two domains. Finally, we will examine aspects of sampling of a domain which might influence the ability to remember and reconstruct information (Chapter 4).

#### 1.2.1 Reconstructing Relational Information

In the second Chapter, a computational framework based on the theories outlined so far in the introduction is established which attempts to approach the task of inferring information about spatial reconstruction performance in hippocampal damaged patients from a principled perspective, making as few assumptions as possible and carefully defining different *types* of spatial relational information which are quantifiable in a reconstruction. Previous work has identified misplacement (i.e. the sum of Euclidean distance of the reconstructed locations of items to their target locations) as an error which shows greater magnitude in hippocampal damaged patients than comparison participants (Huttenlocher & Presson, 1979), and more recent work has hypothesized that some of this may be due to swapping of item identities between otherwise remembered locations (Watson et al., 2013). The work here expands on these ideas with a far more precise mathematical formulation of errors involving misassignments of items, global transformations (i.e. translation, scaling, and rotation), and swaps/cycles of items which are misassigned as a group. 3 hippocampal damaged patients are evaluated in a computer-based spatial reconstruction task with 6 unique items and 32 trials. 9 age, sex, and education matched comparison participants perform the same task. In agreement with previous theories of relational memory and hippocampal damage (Cohen & Eichenbaum, 1993; Eichenbaum & Cohen, 2001; Konkel & Cohen, 2009; Konkel, Warren, Duff, Tranel, & Cohen, 2008), single-item misassignments (i.e. placing of an item in another item’s location without any presumption about where the item which should’ve occupied that location was placed) are significantly more common in hippocampal damaged individuals than comparisons. However, patients and comparisons do not show a difference in the number of overall locations which are correctly reconstructed with some item (though not necessarily the correct item identity). This suggests that hippocampal patients are able to maintain certain relational information (i.e. general studied locations), potentially via an alternate representation that leverages other brain regions and/or memory systems.

Furthermore, despite previously identified differences in swapping between patient and comparison participants, with these more sensitive measures, we show that this difference is only present at low set-sizes (i.e. few items, <=4, in the reconstruction). At 5 items, comparison participants begin to commit identity-location spatial relational errors and, at this point, we find that no difference is present between patients and comparisons in the number of compound errors (swaps and cycles of items). Additionally, although identity information does account for the majority of the difference between patient and comparison participants, a significant difference remains in their misplacement even after all corrections are made. This “local” misplacement may represent a deficit in precision as described by others (Kolarik et al., 2016, 2017; Yonelinas, 2013b).

This work serves two primary purposes: first, the paper establishes a methodological framework for making inferences about spatial reconstruction performance (and, in general, reconstruction performance in any domain) which makes minimal assumptions and approaches the issue from a principled perspective. Second, the work clarifies the previous theoretical accounts of relational memory and the hippocampus by showing that it is the arbitrary identity-location information (i.e. the information which “could have just as easily been anything”) which is impaired in hippocampal damaged patients, not the overall location information. This work speculates as to how such information might be maintained or represented, but future studies which are not part of this work will be necessary to clarify how some relational information might still be maintained via alternate mechanisms.

#### 1.2.2 Memory during Time Travel: Spatiotemporal Navigation, Contextual Boundaries, and Relational Memory Errors in Virtual Reality

Beyond just the spatial domain, episodic memory (which is critically supported by the hippocampus; Tulving, 2002a) involves the temporal domain as well. There is an extensive literature studying the temporal domain showing that humans naturally segment events into discrete regions in time (Zacks et al., 2007a), that contextual boundaries impact perceived distances across time (DuBrow & Davachi, 2013), that order memory is impacted by recency, contiguity, and primacy effects (Howard, Shankar, Aue, & Criss, 2015), and an enormous litany of other discoveries, all which make the same crucial assumption – that time need always be sampled unidirectionally and in isolation of space, despite the fact that space and time are being constantly sampled together and memory for temporal events may involve more flexible representations than just a unidirectional sampling allows us to examine. The work presented in this section shows that this assumption is not necessary and space and time can be put on a more equal footing, allowing free exploration of both domains simultaneously (known as a Spatiotemporal Navigation Task) in Virtual Reality (VR). Virtual Reality allows increased measurement and control capabilities over other methods, increasing a sense of presence, and providing greater ecological validity than more traditional methods (Kuliga, Thrash, Dalton, & Hölscher, 2015; Schultheis, Himelstein, & Rizzo, 2002). Many of the same effects seen in more traditional tasks can be seen in this spatiotemporal navigation task (context boundary effects – in which items which share context are remembered as closer together and items across contexts further apart; misassignments – where one event (i.e. an entity whose identity is associated with a specific spatiotemporal location) is placed in another event’s location; overall misplacement improvement (i.e. the sum of the Euclidean distances of all events to their targets) due to repeated study of the same events. While many of these effects are similar to previous tasks, despite the present study allowing for the ability to traverse the timeline freely, some unique differences can be found between space and time when comparing relational information in each domain.

Leveraging the methodological work from Chapter 2, Chapter 3 shows that misassignments in time (i.e. placing an event in another event’s temporal location) is far more likely than misassignment in space (i.e. placing an event in another event’s spatial location) in healthy young adults even with the ability to freely explore both domains. This difference is persistent across trials, with spatial misassignment dropping to near perfect accuracy by the last trial while temporal misassignment remains significantly higher. However, a significant linear trend is present in the temporal misassignment across trial suggesting it might eventually plateau if more trials were utilized. The ability to improve an understanding of the relational information contained within the temporal component of the set of events is particularly interesting in light of work by Howard Eichenbaum and colleagues showing the existence of time cells in the hippocampus which fire in relation to specific points in time (Howard Eichenbaum, 2014; B. Kraus et al., 2013). It is unclear if these time cells are firing in accordance with an allocentric perspective on time (similarly to place cells) or an egocentric perspective (i.e. based on the subjective moment in time regardless of where in the series of events the individual is present). Based on what we know of other selective cells in the hippocampus (i.e. orientation selective), it’s reasonable to assume that time cells are in reference to allocentric time, however without the manipulation allowing for allocentric and egocentric perspectives on a timeline, it is difficult to dissociate the two. This task presents such a manipulation which might one day lead to a better understanding of these temporal representations.

This task does not only address spatial and temporal reconstruction; it also contains temporal contextual information in the form of changing background colors in the environment at different moments in time. Using these temporal contexts, temporal context boundary effects can be assessed. Although these effects have been looked at for temporal order memory in previous experiments (DuBrow & Davachi, 2013; Ezzyat & Davachi, 2014), those experiments never allowed the participant to freely transition between contexts at will, to (re)explore contexts as much as they would like, or retested on the same information several times (to assess improvements to contextual vs. overall memory). In this task, participants repeated the same event sequence 4 times, and showed improvements to their overall memory on each subsequent trial. However, despite improvements in performance across nearly every other metric, temporal context boundary effects did not diminish across trials. This strongly suggests that this “error” in placement is, in fact, a bias created by an organizational principle which uses context to separate groups of events from one another. This suggestion is consistent with other computational models of the impact of temporal context on memory (Howard et al., 2014); however, these models do not generally allow for the assumption of free traversal of time.

Interestingly, this contextual bias does not just impact memory for the relative distance between events, but contextual information also biases relational information in time (i.e. temporal misassignments, from earlier in this section). Across all trials, a significantly higher number of misassignments are to same-context locations that should occur by chance. Moreover, this effect actually increases across trials as the impact of context on distance judgements holds steady and the overall number of misassignments decreases, suggesting that this bias is not easily corrected with restudy and reflects an organizational principle which causes within-context items to be associated to each other but not necessarily with the same precision on an individual-item level.

Together, this task and the mathematical framework from Chapter 2 serve as a critical first step in forming a more comprehensive understanding of episodic memory and relational memory in space and time, simultaneously, showing that, when we put space and time on a more equal footing (by allowing participants to freely sample both domains), we can study memory for events with more flexibility and fidelity to illuminate critical elements of memory organization. In particular, we show that relational memory in space and time may not be represented with precisely the same organization (as shown by drastically different relational memory errors in each domain) and that contextual information creates systematic biases in both distance judgements and relational memory errors which do not necessarily improve with restudy.

#### 1.2.3 Spatiotemporal Navigation, Sampling, and Information Encoding in Virtual Reality

Previous sections have highlighted primarily test results, while leaving study-time behavior largely unaddressed. This section proposes various measures of study-time performance in the most complex case of the tasks discussed in this work, the spatiotemporal navigation task, and discusses some preliminary data and hypotheses related to this work. Previous work on eye tracking in hippocampally dependent tasks and hippocampal damaged populations has revealed a variety of visual sampling phenomena which are predictive of aspects of hippocampally dependent memory (Deborah E. Hannula, 2010; Deborah E. Hannula & Ranganath, 2009; Deborah E. Hannula, Ryan, Tranel, & Cohen, 2007). However, sampling in a 2D environment via eye movement is somewhat different from a computational perspective than navigation within a 4D environment. Basic navigation metrics such as the distance travelled in space and time have been evaluated, showing that performance on these metrics improves across trials in the spatiotemporal navigation task. Additional metrics from other work in spatial navigation (such as the Fractal Dimension measure; Daugherty et al., 2015) are planned to determine if coarse measures of study-time exploration can predict aspects of overall memory, relational memory, and contextual biases at test. Additionally, an analysis of the order of exploration versus order of reconstruction and associated accuracies (more akin to the Recency and Contiguity effects explored in traditional temporal free recall tasks) is planned.

The data from the Spatiotemporal Navigation Task are incredibly detailed and rich, and, as such, there are a huge variety of applicable analyses. Many of these have already been planned (as mentioned above) from the inception of the task, however, there are certainly more which are possible. Suggestions in regard to further analyses which might serve to elucidate aspects of exploration and navigation which impact future reconstruction are welcome and encouraged.

# Chapter 2: Reconstructing Relational Information

## 2.1 Introduction

Relational memory is critically supported by the hippocampus (Cohen & Eichenbaum, 1993; Eichenbaum & Cohen, 2001; Konkel & Cohen, 2009; Konkel, Warren, Duff, Tranel, & Cohen, 2008). For example, memory for relationships of items to spatial locations is highly sensitive to hippocampal damage in humans (Hartley et al., 2007; R. J. Allen, Vargha-Khadem, & Baddeley, 2014; Smith & Milner, 1981a; Watson, Voss, Warren, Tranel, & Cohen, 2013). Moreover, it has been shown previously that the hippocampus is necessary for all “manner” of relational memory (Konkel et al., 2008); that is, it is critical for binding information regardless of the informational domain, be it spatial, temporal, sequential, associative, etc. However, while the hippocampus can be involved regardless of the domain of information, there are many possible relations between the constituent elements within a given domain, such as item identities (i.e. labels that distinguish items from one another, such as names), locations (i.e. positions in the domain in which an item was present during study), and environmental elements (i.e. the boundary of the environment or landmarks). It is possible that not all of the relational information among these elements critically relies on the hippocampus, and that some *types* of relational information may not be impaired by hippocampal damage.

Importantly, we distinguish between a *manner* of relation and *type* of relation. Hippocampal involvement in all *manner* of relation means, more generally, that the hippocampus can be involved regardless of the informational domains (i.e. spatial, temporal, social, associative, etc.). However, within a given domain, particular *types* of relational information exist (and are enumerated here) which may not all be equivalent in terms of hippocampal involvement. It is possible that when comparing *types* of relations in two different domains, seemingly similar relations may have distinct representations with different amounts of reliance on specific memory systems. For instance, item-item relations within a spatial domain containing several items can be used to derive information about item locations even with an imperfect representation of each individual relation (this point will be elaborated upon later), while item-item relations in an arbitrary word pair cannot be easily used to derive additional information about other arbitrary word pairs. Similarly, item-environment relations in some spatial-relational tasks may or may not be informationally equivalent to item-environment relations in others (such as studying the location of a single item in a scene vs. the locations of many items within an empty environment). A primary reason for this difficulty is in the diversity of uses of terms like ‘item’ and ‘environment’ across different tasks.

It is the aim of this work to precisely define *types* of relations within the spatial domain in such a way as to determine if memory for specific *types* of spatial relations are impaired (or not) by damage to the hippocampus. To this end, we propose a framework for systematically classifying *types* of relations in a spatial memory task. This framework allows us to: 1) distinguish multiple types of first-order (i.e. pairwise or one-to-one) and higher-order (i.e. group-wise or many-to-many) spatial relations, and 2) determine if these various types of spatial relations are differentially impaired by hippocampal damage by inferring the presence or absence of relational information via observations of different types of errors in a reconstruction.

Here we take advantage of the rich data generated by spatial reconstruction (SR) paradigms, in which multiple items are studied in various spatial locations before participants are asked to reconstruct (i.e. freely place) each item in its remembered location. There is a long tradition of using SR paradigms to study spatial memory (Huttenlocher & Presson, 1979) and its susceptibility to hippocampal damage (Jeneson, Mauldin, & Squire, 2010; Smith & Milner, 1981; Watson et al., 2013). These experiments have historically used a general quantification of “misplacement error” in space by calculating the sum of the Euclidean distance between each placed item and its studied location. The typical finding of these experiments is that individuals with hippocampal damage show increased overall misplacement relative to comparison participants.

One critique of the use of misplacement as the sole metric of performance on SR tasks has been that it provides relatively little information about the nature of spatial memory deficits following hippocampal damage (Watson et al, 2013). In other spatial paradigms, such as the virtual Morris Water Maze (vMWM), some theories of hippocampal function such as the Precision and Binding Model (PBM; Yonelinas, 2013) would predict the increased misplacement seen in SR tasks, with PBM, in particular, predicting poorer precision of spatial memory in hippocampal damaged patients (Kolarik et al., 2016, 2017). This could be consistent with the explanation that high levels of misplacement could theoretically reflect an inability to remember coordinates on a “grid-like” mental representation of the display, with patients showing a deficit in the resolution of the grid. Alternatively, high misplacement could reflect a deficit in representing inter-object configural or relational information (among other possibilities, discussed below). Due to this resolution issue in using misplacement as a primary metric of performance, there have been recent attempts to develop additional metrics of spatial reconstruction performance that help to disentangle these possibilities (Jeneson et al., 2010; Watson et al., 2013). In particular, Watson et al., 2013 focused on a very specific type of spatial relational error termed a “swap” error. “Swap” errors are errors in which the relative position on each x and y axis for a pair of items is flipped. Such errors appear to be strongly influenced by hippocampal damage. In fact, patients with hippocampal lesions even make “swap” errors in set sizes as small as two items and at surprisingly short time scales (Watson et al., 2013).

These data suggest that when the hippocampus is impaired, relational binding errors occur regardless of the number of items to be remembered (e.g., in a set size invariant manner). Moreover, swap errors in Watson et al (2013) were found to be a significant contributor to the overall differences in misplacement rates between patients and healthy comparison participants. However, there are many additional potential relation-based explanations for increased misplacement in hippocampal patients. Patients could be making global errors of some sort (i.e. moving all items down, squishing items together, or rotating all the items), local or “noisy” errors (i.e. placing items pseudo-randomly based on a heuristic or limited memory for locations), or relational errors (i.e. placing items in the wrong location given their identity, but that location would have been valid for a different item). Thus, in the present study, rather than focus on one type of spatial relational error (e.g. swaps), we sought to identify the multiple types of relations in space, to organize them in a systematic framework, and to determine if all, or only some, types of relations are impacted by hippocampal damage.

At the core of our proposed framework is the classification of three primary types of first-order spatial relations: item-environment relations (e.g., one item is in the upper left corner of the display), item-item relations (e.g., one item is below and to the left of another item), and identity-location relations (e.g., item A belongs in location A). Note that terminologically, the use of the word “item” here is specific to location information (with identity information being separated out as identity-location information). An analogy to help clarify the meaning of these different relations can be found in navigating a shopping mall. While navigating, it may be important to remember the locations of stores. This would require you to remember location information about where the stores of interest are in relation to the shopping mall layout (i.e. item-environment relations) or perhaps the locations relative to other stores (i.e. item-item relations) as well as which store is in which particular location (i.e. identity-location relations). The hippocampus has been implicated for decades in item-environment relations. Indeed, animal models demonstrate hippocampal place cell firing tied to the distance and direction of item cues in an environment (Gothard, Skaggs, & McNaughton, 1996; Gothard, Skaggs, Moore, & McNaughton, 1996; John O’Keefe & Burgess, 1996). While humans with hippocampal damage are able to retain some item-location information via maintenance in working memory, this maintenance is transient (R. J. Allen et al., 2014; Libby, Hannula, & Ranganath, 2014). In both humans and animals, arbitrary item-item association has been extensively studied. Memory for item-item relations is impaired following selective damage to the medial temporal lobe in rodents (Bunsey & Eichenbaum, 1993), monkeys (Murray, Gaffan, & Mishkin, 1993), and humans (Giovanello, Verfaellie, & Keane, 2003). Furthermore, humans with hippocampal damage show item-item impairments for all manner of relations (e.g. spatial, temporal, associative, etc.; Konkel et al., 2008).

In addition to these first order relations, we examine higher-order, compound relations (e.g., item A, B, and C form a group), which can contribute to compound spatial relational memory errors (e.g. the group is translated to the left, all of the items are squished towards the group’s center, or two items swap locations). Compound relational errors can be seen in two forms in our analysis. Firstly, swaps of items (i.e. when two items are placed in each other’s location) and cycles of items (i.e. when more than two items are placed in each other’s locations) are forms of compound error primarily involving multiple identity-location errors. Secondly, various transformation errors (translation, scaling, and rotation) are forms of compound errors involving multiple item-item and/or item-environment errors.

In addition to first-order (i.e. pairwise) and higher-order (i.e. compound) relations, we can begin to consider the question of how general, Gestalten shape information, i.e. configural features which constitute parts of a unified whole, may be used independently of the hippocampus to maintain more global spatial information. While the current data cannot provide a definitive response to this proposal, the relevant data are suggestive and considered.

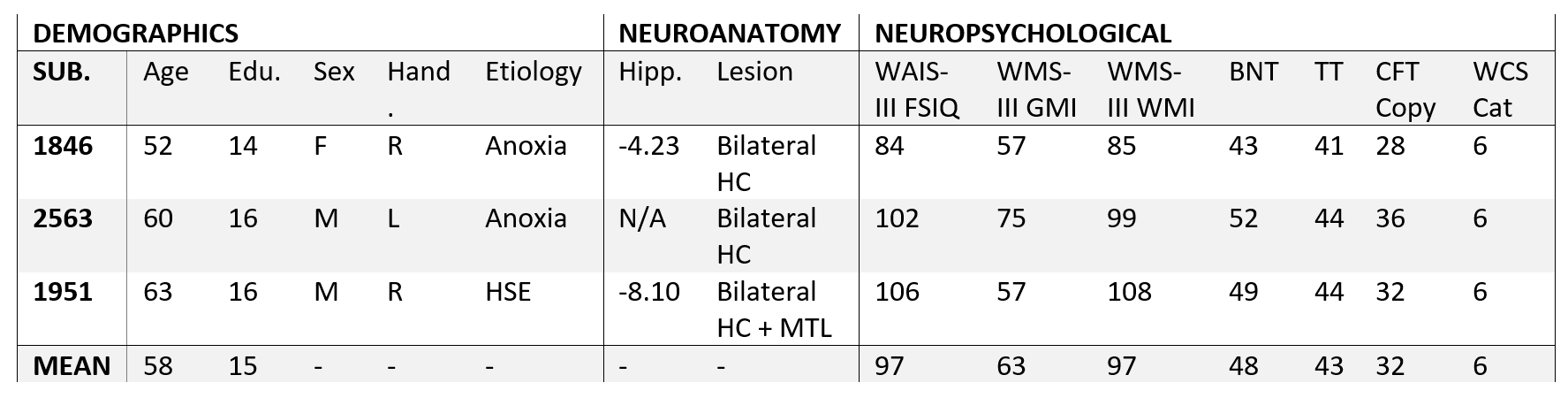
Finally, given the evidence that hippocampal damage impairs reconstruction performance even at very small set sizes (Watson et al., 2013), the implication of varying set size on memory for these different types of spatial relational information was considered. To this end, we take advantage of an existing dataset (Watson et al., 2013) that recorded SR task performance from hippocampal patients across set sizes (i.e., from 2 items to 5 items) and reanalyze those data using the current analysis framework. We first evaluate the extent to which hippocampal patients and comparison participants committed relational memory errors of particular types even at small set sizes (e.g., 2 items). Second, we determine whether those error types change or remain consistent as set size increased.

In summary, in the work presented here, we investigate the types of relations that are sensitive to hippocampal damage from a first principles approach by breaking down reconstruction errors in an SR task into multiple error types, which can then be evaluated simultaneously. We consider three types of first-order relations (i.e., item-environment, item-item, and identity-location relations) as well as two types of higher-order compound relations (i.e., swaps and cycles). We evaluate the degree to which the overall difference in misplacement between hippocampal patients and matched comparisons can be explained by these distinct error types. Finally, we discuss the implications of these findings for theories of hippocampal function.

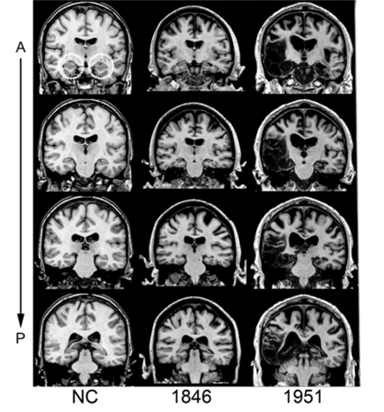
## 2.2 Materials and Methods

### 2.2.1 Participants

Behavioral data were collected from 3 patients with hippocampal damaged and profound declarative memory impairment or amnesia (see Table 1 for details) and 9 healthy comparison participants. Three of the healthy comparison participants were matched to each hippocampal patient for sex, age (+/- 5 years), and education (+/- 2 years).

  
“**Table 1**: Demographic, neuroanatomical, and neuropsychological characteristics of participants with hippocampal amnesia. Hand. = Handedness. Ed. = years of education. HSE = Herpes Simplex Encephalitis. HC = hippocampus. + MTL = damage extending into the greater medial temporal lobes. HC Volume = hippocampal volumetric z-scores as measured through high resolution volumetric MRI and compared to a matched healthy comparison group (J. S. Allen, Tranel, Bruss, & Damasio, 2006; Buchanan, Tranel, & Adolphs, 2005). WAIS-III FSIQ = Wechsler Adult Intelligence Scale–III Full Scale Intelligence Quotient. WMS-III GMI = Wechsler Memory Scale–III General Memory Index. BNT = Boston Naming Test. TT = Token Test. CFT = Complex Figure Test; WCT = Wisconsin Card Sorting Task; Cat = Number of categories achieved out of six.”

Two patients experienced anoxic/hypoxic episodes (1846, 2563) resulting in bilateral hippocampal damage and the third patient contracted herpes simplex encephalitis (1951) leading to more extensive bilateral MTL damage affecting the hippocampus, amygdala, and surrounding cortices (Figure 1). Structural MRI examinations completed on 2 of the 3 patients confirmed bilateral hippocampal damage and volumetric analyses revealed significantly reduced hippocampal volumes. Participant 2563 wears a pacemaker and was unable to undergo MRI examination and thus their damage was confirmed by computerized tomography; damage was confined to the hippocampus.

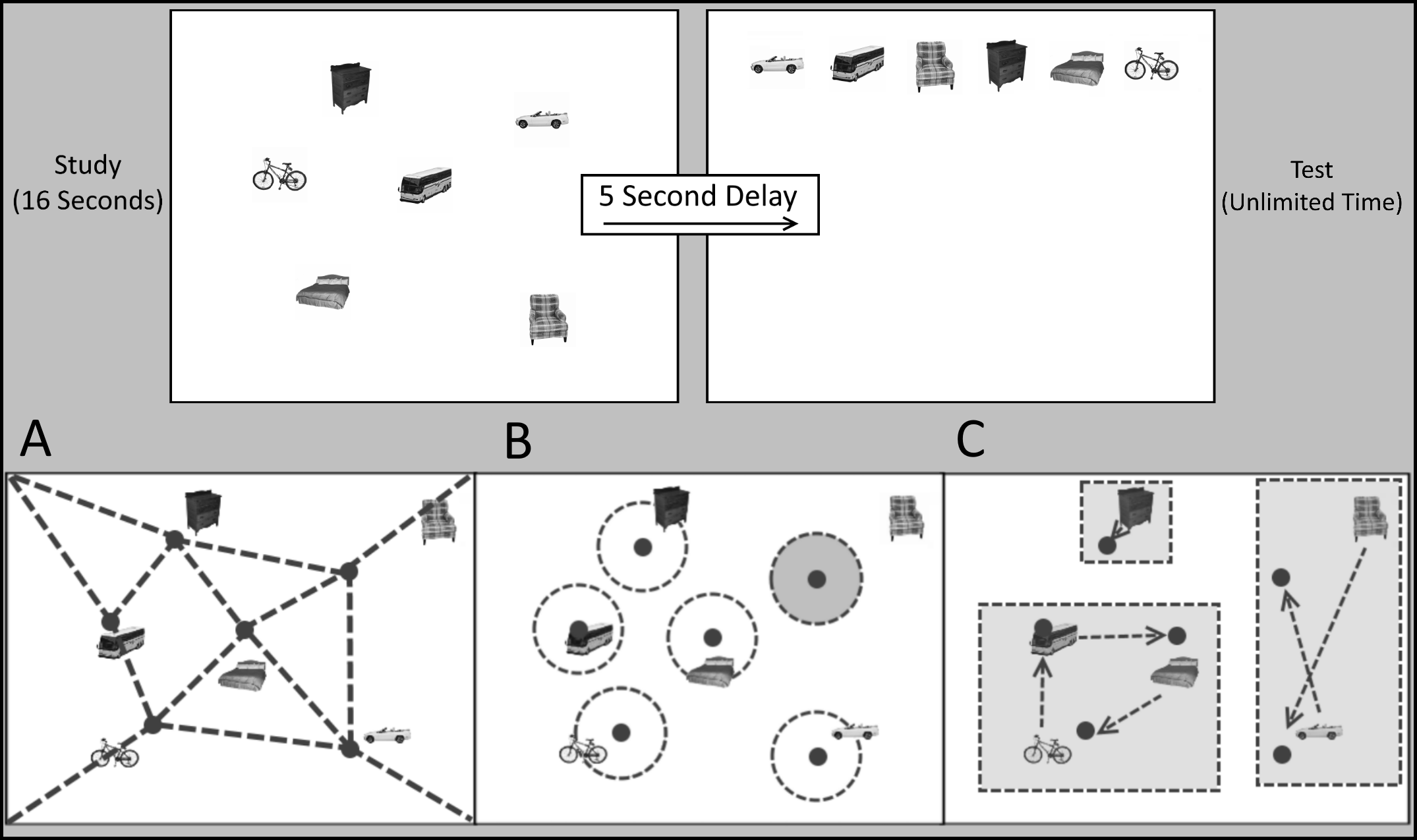


**Figure 1**: Magnetic resonance scans of hippocampal patients. Images are coronal slices through four points along the hippocampus from T1-weighed scans. Volume changes can be noted in the hippocampal region for patient 1846, and significant bilateral MTL damage including the hippocampus can be noted in patient 1951. A = anterior, P = posterior, NC = healthy comparison brain.”

Neuropsychological examination confirmed severe declarative memory impairment in all hippocampal patients (M =63; Wechsler Memory Scale-III General Memory Index, more than 2 SDs below population norms) in the context of within normal performance of standardized measures of intelligence, language, visual perception, working memory, and executive functioning (see Table 1).

### 2.2.2 Experimental Paradigm

Participants completed a computerized spatial reconstruction task (Monti et al., 2015; see top of Fig. 2). Participants studied 6 items (gray scale, nameable objects; Brodeur, Guérard, & Bouras, 2014) per trial, arranged pseudo-randomly in an pixel area within a pixel computer screen across 32 total trials. During the study phase, participants viewed the 6 items for 16 seconds, followed by a 5 second delay (blank screen). At test, which began immediately after the delay, items were randomly placed in a line at the top of the screen, and participants used a mouse to drag each item to its remembered location on the screen. Participants had unlimited time to reconstruct the studied display. When they were finished, participants pressed space bar to start the next study trial. Participants’ eye movements were recorded throughout the experiment. Eye tracking data are not reported here and will be reported elsewhere (Lucas, Duff, & Cohen, in preparation).

  
"**Figure 2**: A sample trial from the spatial reconstruction task; A, B, and C show different interpretations of the same reconstruction where the objects are in the reconstructed locations and the dots are the target locations from the study phase. (A) shows item-item and item-environment relations (dotted lines), which might be used to determine the locations of the dots. (B) shows reconstructed item to target location relations where gray shaded circles indicate a failure in placement of items to those locations (note that identity is ignored as, for example, the bus is not in its target location). (C) shows compound relations where some items roughly swap locations (although not necessarily precisely, in this case being a "partial swap"), some show cycle relationships (i.e. Bus🡪Bed🡪Bicycle🡪Bus), and some show single-item placement in the correct target location."

### 2.2.3 Analysis Methods

To determine if item-environment, item-item, identity-location, and compound relations showed selective differences in performance between patients and comparison participants, a new set of tools for analyzing spatial reconstruction data were created. These methodologies were designed with the intention of making as few assumptions as possible about the nature of the reconstruction to separate the types of errors via more mathematically rigorous and interpretable metrics. This approach applies Point Set Registration methods (see Besi & Mckay, 1992 for an introduction to the topic), in which a set of points (often derived from key points in an image) are assigned to an independent set of points (often from a reference image) based on an inferred relationship between the two sets. The SR paradigm is analogous to the Point Set Registration process of understanding the relationship between reconstructed points and their target (i.e., studied) counterparts, with two primary differences. Firstly, in the case of Point Set Registration, it is often not guaranteed that every point in the data set will correspond one-to-one with a point in the target. In the case of the SR task, we have a much stronger reason to assume that such a one-to-one correspondence should exist (though it may be interesting to consider the sorts of memory errors that might cause this assumption to be violated). Secondly, in Point Set Registration, it is often the case that there are many more points from which to define a model than exist in the SR task. For this second reason, especially, it is important that we proceed with caution in what models we apply to our data to avoid overfitting to a small set of points.

The model for the comparison of the reconstructed and target (i.e., studied) points can be thought of as having four primary components: identity remapping (wherein the identity of each item is removed and the set of placed item locations is mapped onto the target locations in a way which minimizes error), global error correction (wherein global translation, scaling, and rotation errors are subtracted from the placed item locations), location placement evaluation (wherein a binary determination of accuracy is made for each location), and compound error evaluation (wherein “swaps,” in which two items are misassigned to each other’s locations, and “cycles,” in which more than two items are misassigned to each other’s locations, are identified).

#### 2.2.3.1 Identity Remapping

For this first step, identity remapping, a one-to-one mapping between the reconstructed points and targets must be created. This mapping can be determined by a variety of methods, each with their own advantages and disadvantages (Burkard, Dell’Amico, & Martello, 2012); however, for the sake of simplicity and interpretability, it is often preferable to find the mapping which globally minimizes the overall error in the reconstruction (effectively eliminating any effects of item identity-location misassociation in the reconstruction). This can be solved using the following Assignment Problem (H. W. Kuhn, 1956; Harold W. Kuhn, 2010; Munkres, 1957) equation:

where is the cost matrix associating each vertex in a graph and is the binary assignment of an undirected edge to the graph. Using the above equation, we find the set of associations (which we will call “the map”) which results in the smallest numerical value, forming a minimal one-to-one mapping of the placed item location to a target (studied) location.

#### 2.2.3.2 Global Error Transformations

Once a one-to-one mapping has been found, the next primary component to be determined is the global error transformation which finds shared error across all the items. This transform could be any function, and with enough parameters, the items could be mapped perfectly onto their assigned target locations. However, because our intention is to differentiate between global relational errors and item-level errors, a simplified transformation is used such that only translation, scaling, and rotational errors are included in the model. Together, these transformation components describe a 4 parameter system (x translation, y translation, scale, and rotation), which can be used to model global error across all items in a trial (cf. Similarity Transform; Cederberg, 2001). One could speculate as to what might cause these different types of errors (i.e. translation being a misrepresentation of the entire stimulus space in the environment with an offset, scaling being a squishing or stretching of the stimulus space, and rotation being a misrepresentation of the directions in the environment). Regardless, by identifying this global error, we can subtract out its effects from each item’s location so as to get a more precise measure of individual item accuracy independent of shared, systematic, spatial errors. The similarity transform can be more precisely stated as a solution to the equation:

where is the ratio of similarity (or scaling factor), is an orthogonal matrix and is a translation vector. can be decomposed into a single value which represents the magnitude of rotation around the point set center. This transformation can be computed using Umeyama’s algorithm (Umeyama, 1991) which uses Singular Value Decomposition (Cline & Dhillon, 2006; Golub & Kahan, 1965) to obtain a transformation matrix. It is useful to note that it is not always possible to find a transformation given a set of points if they do not actually share any global error of the types we’ve specified (i.e. translation, scaling, and rotation). In our model, we allow rotation to fail independently of translation and scaling, as it is more difficult to find rotational components in small data sets. If all attempts to find a transformation fail, no global adjustments are made and the transformation data from those trials are excluded from the analysis. Singular Value Decomposition computes the transformation matrix by solving the following equation:

where is the dot product of the reconstructed and target point locations divided by the number of points, and are unitary matrices, and is a diagonal matrix of non-negative, real numbers. Umeyama’s algorithm allows the decomposition of the matrix into the translation, scaling, and rotation components.

#### 2.2.3.3 Location Placement Evaluation

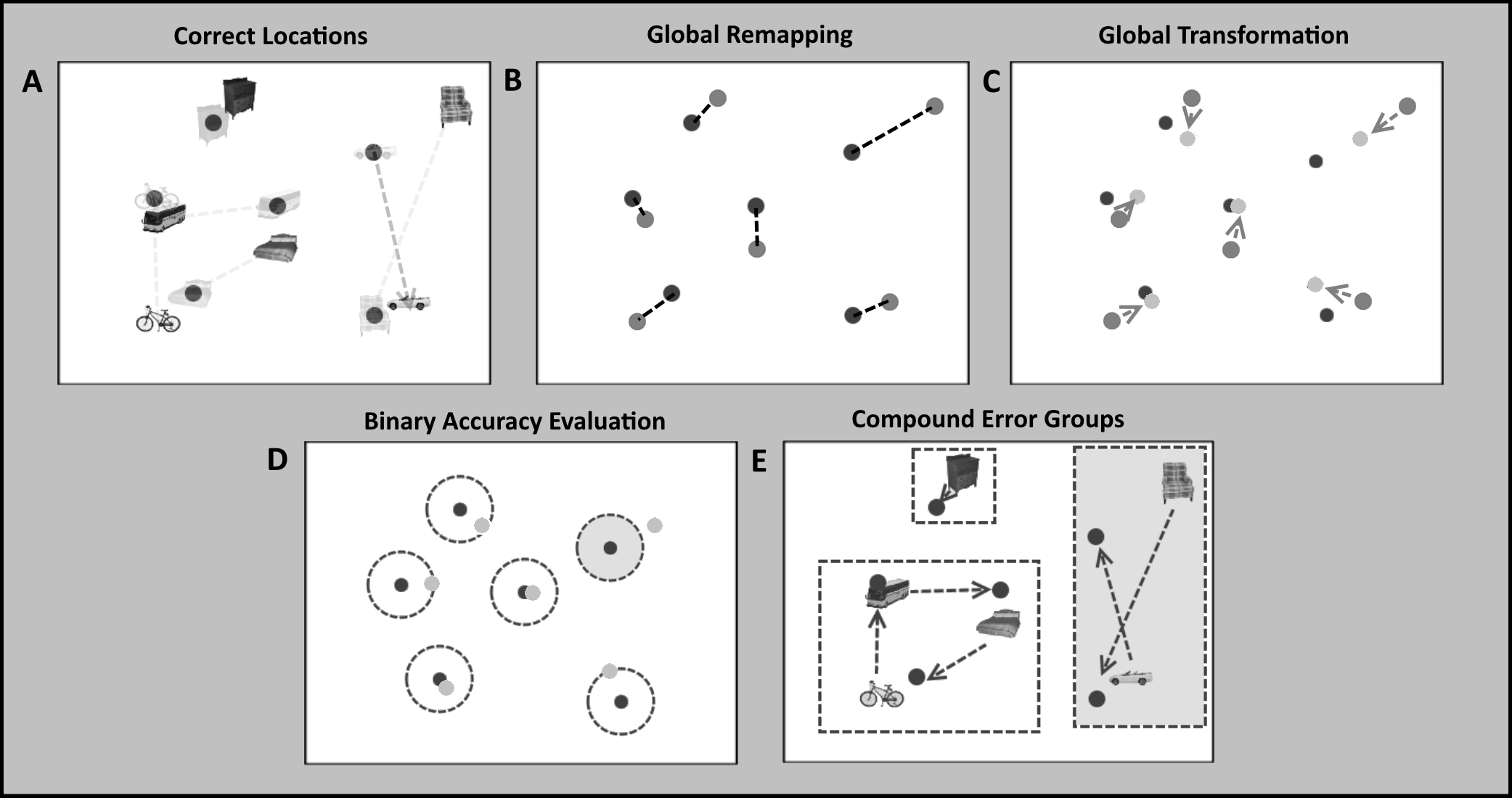
Now that associative and global errors have been subtracted from the point locations, a measure of reconstructed-to-target location placement accuracy can be evaluated in a manner that is not influenced by incorrect item-identity choices or global rearrangement. Previous studies have attempted to include accurate placement as an aspect of the analysis using an arbitrarily chosen distance value (Jeneson et al., 2010). However, an inflexible threshold imposes a very strict, nonlinear boundary on our evaluation of accuracy, which is difficult to handle without training participants to operate within this constraint (potentially influencing behavior in unintentional ways). It would be preferable for such a boundary decision to be made flexibly, based on the variability in local misplacement (i.e. misplacement that is not shared amongst the items nor due to item identity errors). To accomplish this goal, we determine accuracy based on the data by creating a statistical distribution of the misplacement after correcting for item-identity and global error and use the confidence intervals for the distribution (in this case, 95% confidence intervals) as the accuracy threshold. This distribution could be formed on a trial-by-trial basis, but it is more stable to compute it across all trials for an individual as there are more sample points (192 points instead of 6). This trade-off means that the threshold will be slightly stricter than the data would suggest for earlier trials and slightly less strict for later trials:

This choice trades a rigid, predetermined threshold condition for a new assumption: that the participant placement of items will generally be in the studied locations (to a degree specified by the confidence interval width). This assumption may not be correct for patients with hippocampal damage as overall misplacement for patients is greater than for matched comparisons (Huttenlocher & Presson, 1979; Jeneson et al., 2010; Smith & Milner, 1981a). Therefore, we opt to use the accuracy thresholds computed from the comparisons as the measure of accuracy for the patients. This choice allows our definition of placement accuracy to be unified between the groups, with the matched comparisons determining their associated patient’s placement accuracy threshold. This adjustment is necessary in deciding a threshold for patients because we are forming a statistical distribution based on individual item misplacement which incorporates all the individual item variability. This item variability is not necessarily matched between patients and comparisons given that the comparisons generally perform better. Thus, we use the stricter criteria, the comparison thresholds, for placement accuracy in patients.

#### 2.2.3.4 Compound Identity Error Evaluation

Finally, once all item-location assignment and global errors have been subtracted from the data and placement location accuracies have been determined, item-to-location mapping can be examined for both accurate locations and inaccurate locations. Using the mapping from the first step of the analysis and the accuracy from the previous step, we can also find if there are any accurate or partially accurate location-cycles of items where items were potentially assigned to the wrong location (i.e. within the threshold we have defined for our binary location accuracy judgement but with a center on a different item’s studied location). The cycles are computed via a graph-theoretical connected-components analysis where closed loops in the graph of associations are treated as individual components (Hopcroft & Tarjan, 1973). If an item exists in a single-component system, it is assigned correctly with its target (studied) location. Otherwise, the items in the component system form a cycle, where the simplest cycle would be a 2-cycle, which can also be thought of as a swap, and higher order cycles can also be found (up to a 6-cycle, as 6 items are being tested). In the general case, an N-cycle is possible where N is the number of items under test. Note, this “swap” is computed differently than our previous version of “swaps” (Watson et al., 2013), as the metric described here includes location accuracy (with item identity ignored) as part of the requirement for being called a “swap”. We believe that this new metric is more consistent with the general item-location misbinding interpretation of a “swap” error. These error types are collectively called compound errors.

In summary, this process produces a set of nine output metrics. The 1&2) translation (x and y), 3) scaling, and 4) rotation magnitudes from the transformation step, 5) the number of items within the location accuracy threshold after removing both the item identities and the number of compound errors of various types. For consistency with our previous work, we will consider 6) 2-cycles, aka swaps, in isolation of 7) >2-cycles in statistical analysis. Further, any system with one or more inaccurate items is treated as a 8&9) “partial” cycle (or swap), versus those in which all locations contain an accurately placed item.



“**Figure 3**: The analysis procedure as defined in the above sections. (A) shows the correct locations (dots with shadowed identities) and the reconstructed locations (items) along with shadowded dotted lines showing the original misplacement. Note that large amounts of misplacement error is accumulated via improper assignment of identities to locations. (B) shows the global remapping (dark dots are targets and light dots are reconstructed points) wherein identity is stripped away and a minimal one-to-one mapping is formed. (C) shows the global transformation (in this case a slight rotation and scaling error) where dark dots are targets, medium dots are reconstructed points, and light dots are post-transformation reconstructed points (i.e. points where the global error have been subtracted from the reconstructed points). (D) shows the binary accuracy evaluation on the post-transformed points (where the dark shaded circle signifies an inaccurate item). (E) shows the compound errors identified and labelled according to the previous steps (where shaded regions are considered “partial” groups where at least one item was inaccurately placed).”

#### 2.2.3.5 Gestalten Shape-Like Information

There are many ways to define “shape”, and this proposal evaluates only one such definition. Shape is defined here via the location vertices and their relative positions, such that the shape is altered with item placements in non-studied locations and unaltered with transformations such as translation and scaling. Under this definition of shape, shape can be thought of as the highest order of compound identity-location and item-item relational information which includes all pairwise relations amongst items without regard for item-environment relations. One way to dissociate identity-location and item-item relations is to strip away the identity information and treat all items as if they were anonymous (i.e. unlabeled) in order to determine if the placement locations match up with any studied locations (see Identity Remapping above for details). The current study takes steps to evaluate and dissociate the degree to which shape-like information may be maintained by hippocampal patients by comparing the number of correct location placements (disregarding item identity) and the magnitude of different types of global errors (i.e. error which is shared between multiple items in the reconstruction), such as translation (i.e. a fixed offset in x and/or y of all items), scaling (i.e. all items being closer to or farther from a central point without a change in angle between any item pair), and rotation (i.e. all items rotated some distance around a central point) between the groups which might suggest differences in shape memory.

#### 2.2.3.6 Statistical Analysis

All t-tests shown were conducted via Welch’s *t*-test for unequal variance and unequal sample size (two-tailed) unless otherwise indicated. An alpha level of 0.05 was used to determine significance. This means that the degrees of freedom for each *t*-test is the adjusted degrees of freedom given by the Welch-Satterthwaite equation which corrects for unequal sample size and variance. Repeated measures ANOVA were used when comparing metric performances and set size data. All ANOVA used Huynh-Feldt correction for non-sphericity.

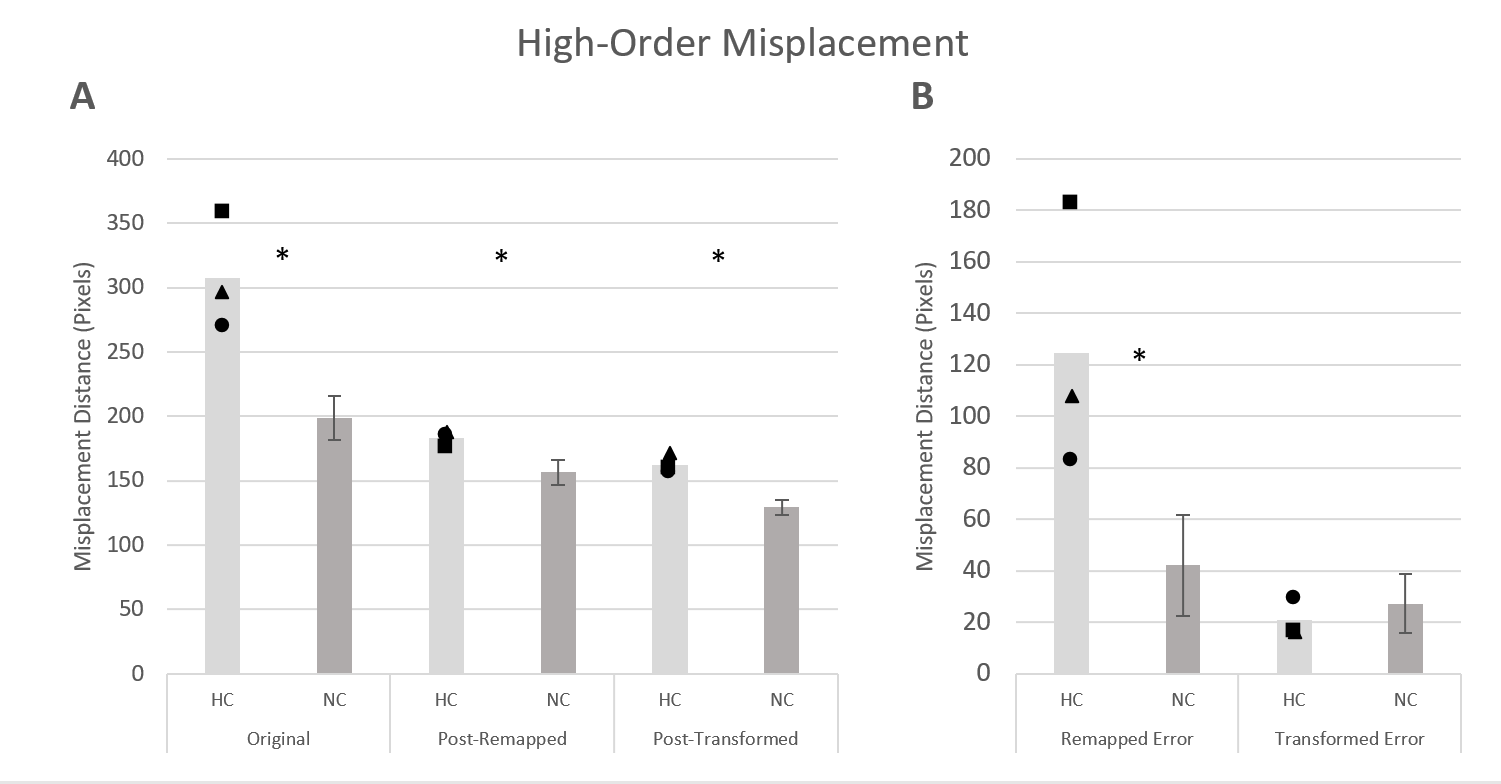
#### 2.2.3.7 Reanalysis of Watson et al. (2013) Set Size Data

Previous work from our group showed that hippocampal patients committed swap-like relational memory errors even at set sizes as small as 2 items, whereas such errors were virtually non-existent in comparison participants even at size sizes of 5. These data suggest that hippocampal damage leads to a pervasive inability to retain relational information even in the most restrictive circumstances. To investigate whether all types of relations are set size invariant, we conducted a reanalysis of a previously acquired data set (Watson et al., 2013) to determine if the patterns seen in the new data set hold in the previous one. The data contained four patients and four matched comparisons. Because that data set contained variations in set size, a repeated measures ANOVA was run to determine if the average error magnitudes across set sizes differed for each type of error. There was an overlap of one patient in both studies, 1846, though the data were collected approximately 4 years apart.

## 2.3 Results

### 2.3.1 Differences in Misplacement Accounted for by Global Errors

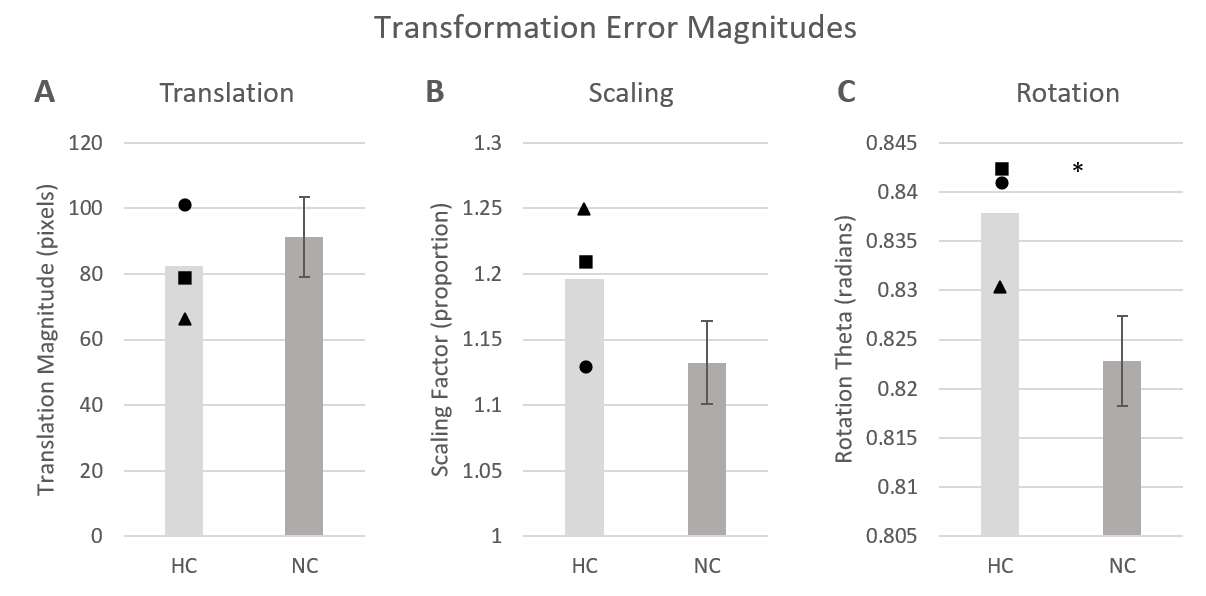
Consistent with previous work (Jeneson et al., 2010; M. Lou Smith & Milner, 1981; Watson et al., 2013), the hippocampal patients show significantly more overall misplacement (difference between means is 109.2 pixels; ) than the comparison participants (Fig. 4 “Original”). However, our new analysis framework allows us to determine the degree to which this misplacement difference can be accounted for by the different types of spatial relational errors. The first step in our analysis process was to remap the item-location relations to quantify the misplacement accounted for by identity-location errors. This quantity is the sum of all of the misplacement accounted for by each identity-location error (Fig. 4 “Post-Remapped”) and, indeed, performing this procedure removes the majority of the difference in misplacement between the two groups (difference between means is 26.6 pixels; ). This procedure also shows a significant difference in the magnitude of the reduction of overall misplacement between patients and comparison participants () as would be expected given the relative magnitudes of the original misplacement. Note that the reduction in misplacement from remapping accounts for over 75% of the difference between the groups. In other words, the majority of the difference in performance between patients and comparison is due to identity-location errors.



“**Figure 4**: Comparisons of Patient (HC) vs Comparison Participant (NC) groups for A) Misplacement Across Analysis Steps, i.e. misplacement magnitudes at each step of analysis and B) Reduction in Misplacement by High-Order Error Type, i.e. differences in misplacement accounted for by each step (i.e. the subtraction of A). For Patients, individual symbols are shown such that: Square is 1951, Triangle is 1846, and Circle is 2563. (\* means p<0.05)”

Regarding the transformation misplacement (Fig. 4 “Post-Transformed”), a repeated measures ANOVA was performed (Huynh -Feldt corrected) with group by misplacement (original, post-remapped, and post-transformed). A main effect of both group (F(1, 10) = 8.097, p=0.02) and misplacement (F(1.34, 13.41)=45.392, p<0.001) was found, as well as an interaction between group and misplacement (F(1.34, 13.41) = 7.536, p = 0.01). Follow up t-tests confirmed both patients and comparison participants show a significant reduction in their misplacement via the transformation procedure ( and respectively). However, the patients and comparison participants show no difference in the amount of misplacement accounted for by the global error amongst their items (). When the different transformation components (translation, scaling, and rotation; Fig 5c) are observed independently, we see that only rotation has a significantly different magnitude, with patients having larger magnitude rotation errors than comparisons ().

Once all global transformation procedures are performed, patients and comparisons still show differences in the remaining misplacement (difference between means is 33.0 pixels; ). This misplacement is “local” misplacement, which is not shared by all items nor accounted for by identity-location errors. Note that because there is no significant difference between patients and comparisons in the amount of global misplacement error, the final difference between the groups is still significant.



“**Figure 5**: Comparisons of Patient (HC) vs Comparison Participant (NC) in the magnitude of the three types of global transformation error; A) the Translation magnitude, B) the Scaling magnitude (where 1 means no scaling, <1 means shrinking, and >1 means stretching), and C) the Rotation angle (in radians). For Patients, individual symbols are shown such that: Square is 1951, Triangle is 1846, and Circle is 2563. (\* means p<0.05)”

### 2.3.2 First-Order and Higher-Order Relational Errors

When we evaluated the location placement accuracy of identities to their assigned locations, there were three primary first-order comparisons of interest. The first two comparisons addressed the question of whether patients could remember identity-location information as often as comparisons, evaluated by: 1) the number of correct placements and 2) the number of items placed in another item’s location. The third comparison of interest addressed the question of whether the patients could remember just the location information as often as comparisons regardless of identity, which was evaluated by examining the number of items placed in any valid location (note that this is just the sum of 1 and 2). To examine group differences in these quantities (particularly 2 and 3), we performed a between groups repeated measure ANOVA on the identity-location errors (i.e. 2, above) and the total number of items placed in any valid location (i.e. 3, above, the sum of the identity-location errors and the correctly placed items). We found a significant interaction of group and these two quantities (F(1, 10) = 17.127, p=0.002). Follow up Welch’s t-tests showed that hippocampal patients made fewer accurate placements of the correct identity to the correct studied location (e.g., successful identity-location binding) than comparison participants (t(5.21)=5.45,p=0.003;Fig 6). Importantly, however, patients had more placements of items in another item’s studied location (i.e. correct item-location relations with incorrect identity-location relation) than comparison participants (t(5.06)=2.83,p=0.04); Fig 6.), even after subtracting the global errors. When we looked at memory for locations (regardless of identity; i.e. items placed in any valid location), we found no significant difference between patients and comparisons (t(4.71)=0.71,p=0.51)).

In regard to compound errors (i.e. swaps or cycles), we saw no difference between patients and comparison participants (t(9.96)=0.39,p=0.71 for swaps and t(7.11)=1.75,p=0.12 for cycles, respectively) despite large differences in individual identity-location assignment.

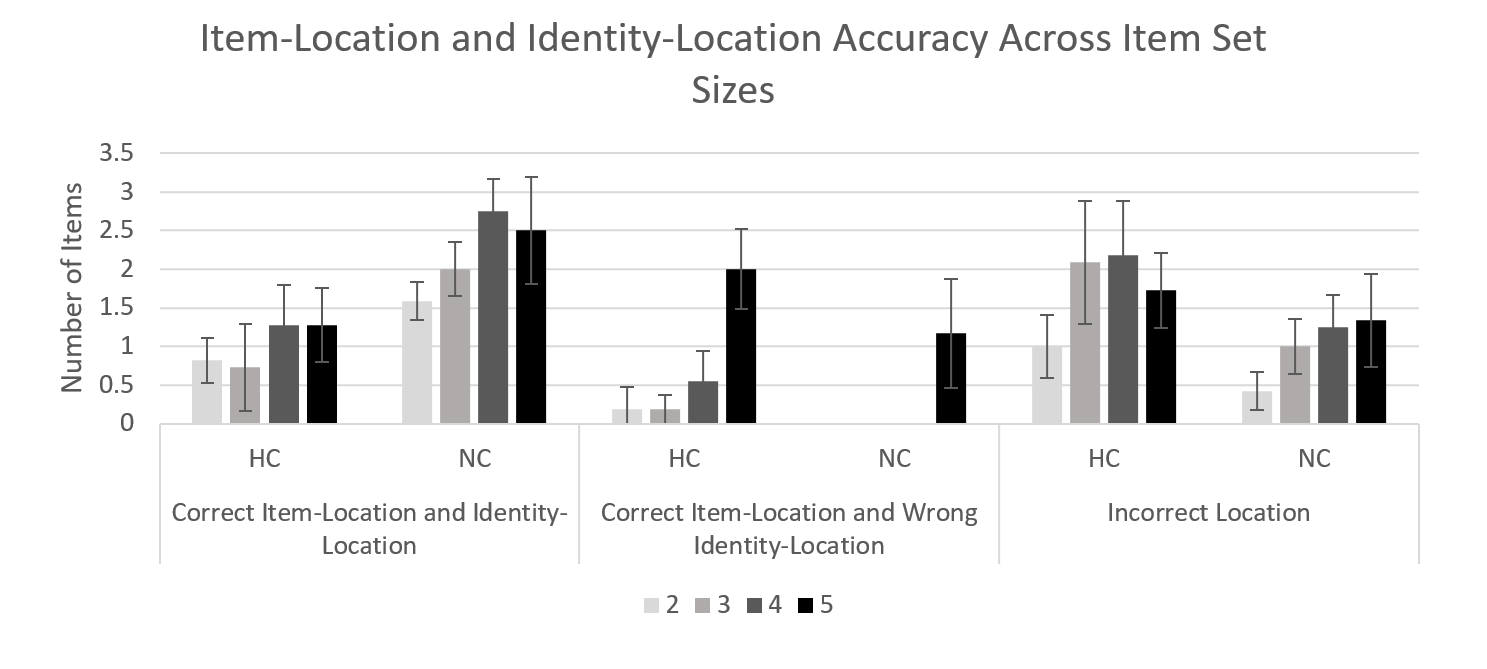
The fact that patients and healthy comparison participants had similar memory for locations (ignoring identity assignment) serves as the first piece of evidence suggesting the possibility that some shape-like information (albeit only in the form of a set of vertices) may be used by patients to reconstruct spatial location. In any case, it is clear that some aspects of relational information in the reconstruction (i.e. some combination of item-environment or item-item relations) was not impaired in hippocampal damaged patients.

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“**Figure 6**: Comparisons of Patient (HC) vs Comparison Participant (NC) in the number of items in which item-location and identity-location was correct and incorrect. Note that items which were not placed in any studied location are collapsed together as ‘Inaccurate Location’. For Patients, individual symbols are shown such that: Square is 1951, Triangle is 1846, and Circle is 2563. (\* means p<0.05)”

### 2.3.3 Differences in Accuracy of Item-Location Associations across Set Sizes

As our previous work showed that patients committed relational memory errors even at very low item set sizes, it is useful to ask if, given our new framework for analyzing various types of relational information, we see the same pattern of impairment across all set sizes. We took advantage of our previous data set from Watson et al 2013 to determine if the number of studied items impacts the different types of spatial-relational errors discussed here. In a 2 x 4 ANOVA with factors group (patients and comparisons) and set size (2, 3, 4, 5), hippocampal patients showed no main effect of set size () on accuracy of placing items in their target locations, placing roughly only a single item in its correct location (identity-location relation) regardless of set size (2 to 5). However, the main effect of set size was significant for comparisons (). Importantly, as reported previously (Watson et al., 2013), only patients committed identity-location errors at small set sizes; comparisons did not. Furthermore, when considering performance at set size 5, in which both groups made identity-location errors, there were no significant group differences for other types of compound relational errors, namely swaps and cycles; swaps () and cycles (). Taken together, these data show that across set sizes, patients show specific impairment to identity-location information without showing any significant compound relational error differences once the set size is sufficiently high for comparisons to begin making identity-location errors.



“**Figure 7**: Comparisons of Patient (HC) vs Comparison Participant (NC) Item-location and identity-location accuracy across set sizes for patients vs comparisons. Note that items which were not placed in any studied location are collapsed together as ‘Inaccurate Location’.”

## 2.4 Discussion

The present study investigated the impact of hippocampal damage on various types of relations in a spatial memory task. While the role of hippocampus in spatial memory has an extensive history (Hayes, Ryan, Schnyer, & Nadel, 2004; John O’Keefe & Nadel, 1978; L. Ryan, Lin, Ketcham, & Nadel, 2009), the present data demonstrated that patients with hippocampal damage are not impaired relative to healthy comparison participants on *all* *types* of spatial errors; rather they demonstrate particular deficits in identity-location relational memory.

There are many reasons why identity-location relationships, specifically, might be impaired with hippocampal damage. Consider a case where a single item is presented in a bounded spatial environment. Only one type of relational information, namely the item-environment relations, is necessary to remember where that item belongs. Remembering the identity of that item is not necessary to complete the task. However, if a second item is added to the display, each item has an item-environment relationship, but also item-item relations and identity-location relations. It is, of course, not necessary to encode all three relation types to represent the display because some relations provide redundant information (i.e. the item-item relations contain information which is redundant with the item-environment relations). However, for an accurate representation, the identity-location relationship is not redundant with other types of relations and must always be considered. Identity-location relations are entirely arbitrary (in the SR task) and the critical component for successful memory performance; perhaps unsurprisingly then, arbitrary identity-location relationships are the type of relations that are most hippocampally dependent in a spatial memory task. As mentioned previously, it is important to note that item-item and item-environment information in this task and framework are not necessarily equivalent to seemingly similar relations in other domains (i.e. item-item where both are words or item-environment where it is the mapping of an object *including its identity* to a spatial location); this is due primarily to the specificity with which we have defined these terms (i.e. ‘items,’ in this case, have had their identity information removed and specifically reference spatial-only information).

The assertion that the *arbitrary* type of relational information in this task is the type showing impairment is consistent with previous findings showing hippocampal damage impairs memory for *arbitrary* relations between words (Giovanello et al., 2003), spatial locations in a scene (D. E. Hannula et al., 2006), and temporal relations, and, indeed, all manner of relations regardless of the informational domain (Konkel et al., 2008). The data bear out this conclusion by showing that if we remove the identity information from the patient data, we see the difference between the groups in overall misplacement reduced by over 75%. Furthermore, when stripped of identity information, patients and healthy comparison participants do not differ on the number of correctly chosen locations. This shows that although patients show impaired memory for arbitrary relations in all stimulus domains, including spatial relations, they are not impaired on all *types* of spatial relations (i.e. they are able to reconstruct some item-environment and item-item relations). Patients with hippocampal damage show a deficit in reconstructing the *specific* item identity to its *specific* studied location.

The present data also demonstrated that hippocampal patients and comparison participants do not differ in compound spatial relational memory errors (e.g., translation, scaling, swapping, and cycles). And while rotation errors showed a statistical difference in magnitude between patients and comparison participants, the magnitude was quite small (0.86 degrees), accounting for very little overall misplacement difference between the groups. Moreover, because the very first step in the analysis is to remove identity information, the total amount of possible rotation is artificially restricted to no more than the half of the maximum angle between two items from the rotation center, making it more complicated to interpret global error type than scaling and translation that have no such restrictions. It is, of course, possible that the significant difference in rotation errors is due to additional memory deficits. Unlike scaling and translation, in which pairwise spatial relations are invariant (i.e. if item A is above and to the right of item B and a translation or scaling transform is performed, item A will always still be above and to the right of item B), pairwise spatial relations are not invariant under rotation. This could point to further, more subtle deficits in particular types of relations, but further investigation into this error type is needed.

It is interesting to note that some misplacement remains as local, “noisy” misplacement after the removal of identity and global errors, and this local misplacement was significantly greater in patients than comparison participants. This is consistent with other accounts of spatial memory and the hippocampus such as the Precision and Binding Model (Yonelinas, 2013a) which posits that the hippocampus is critical for “high-resolution” binding in space, predicting that hippocampal patients should have poorer spatial memory precision. These accounts may not generalize to all domains of information, however, as some evidence shows hippocampal damage relating to impairment in the quantity of information which can be remembered, rather than the quality (or precision) of the information when testing hippocampal patients on color information (Warren et al., 2015).

In regard to compound relations involving identity-location information (e.g., swaps and cycles), it has been proposed previously that a lack of memory for identity-identity and identity-location relations in hippocampal patients may result in more identity-identity swapping (Watson et al., 2013). However, the present data demonstrated no group difference in swaps or cycles after accounting for overall location accuracy. The reason for this discrepancy is likely a combination of: 1) a difference in mathematical formulation of swapping (i.e. not using accuracy as a prerequisite for a successful swap results in an over estimate of the number of swaps) and 2) the inability of hippocampal patients to represent a sufficient amount of relational information to commit compound-relational error such swaps (which requires memory for two locations and their positions relative to one another and/or the environment but no information about item-location relations) more than by chance. Specifically, on the second point, if hippocampal patients are not maintaining identity-location information, their ability to have group-wise reassignment errors will be limited because they do not have specific knowledge of the constituents of the group. These compound swap/cycle errors do occur in both patients and controls (although patients uniquely commit them at very small set sizes), but once the set size is sufficiently high (i.e. once the comparison group actually makes identity-location errors) the groups do not differ in the frequency of their occurrence. Said differently, just as identity-location errors seem to account for a substantial proportion of patients’ overall misplacement errors, the disproportionate occurrence of swap and cycle errors at small set sizes in patients can also be attributed to their overall deficit in identity-location binding.

What causes this sudden increase in identity-location errors in comparison participants at higher set sizes? One possibility requires consideration of accurate identity-location placements in isolation of other metrics. Across all set sizes, hippocampal patients make approximately one accurate identity-location placement. This accuracy could be due, in part, to a maintenance of a single identity-location relation in working memory across the relatively short time span between study and test. Comparison participants, on the other hand, make accurate identity-location placements proportional to the set size.

When we consider how hippocampal patients may be able to maintain item-environment and item-item spatial relational information, it is interesting to consider alternate representations which may be able to maintain those relations. Previous work suggests that hippocampal damage may not impair shape information in SR task performance, as hippocampal patients may be able to represent shapes via an alternative, “unitized” representation, which can be formed via Gestalten perceptual features, i.e. configural features which constitute parts of a unified whole, rather than relations (Corsi, 1972; Kessels et al., 2000; Uttal & Chiong, 2004). The present data provide a suggestive look at this assertion from a purely vertex-oriented definition of shape, as the patients and comparisons did not differ in the number of locations (i.e. vertices) in which they accurately placed an item (independent of item identity), nor did they differ in the amount of global misplacement (i.e. misplacement that is systematically shared by all items) of the entire item set. This suggests that, at least in this highly restrictive definition of shape being defined via vertices, a similar amount of shape-like information is present in both comparison participants’ and hippocampal patients’ reconstructions. That said, using global misplacement transformations as a measure of shape is not necessarily the optimal method for investigating this issue, even with shape being defined solely via vertices. Topological Data Analysis techniques may prove to be a better analysis framework for determining the degree to which high-level relational information is preserved in a reconstruction (Carlsson, 2009; Ghrist, 2007). In Topological Data Analysis (TDA), large groups of vertex relations can be evaluated and compared directly with minimal assumptions by forming a more mathematically rigorous definition of the high-order structure of these relations. A similar technique to TDA has been used previously in spatial memory by Kolarik et al. in analysis of data from hippocampal damaged patients using a virtual Morris Water Maze (Kolarik et al., 2016, 2017). It is unclear, however, if this technique scales well to a very small number of points, and, as such, these analyses are not included in this work; future investigations better suited to the technique should be considered.

There are alternate explanations for the ability to maintain item-environment and item-item spatial relations other than maintenance of shape-like information. It is possible individual relational information *is* being stored separately via a different brain region(s). For example, the parahippocampal place area has been shown to be involved in processing geometric information about scenes (Epstein, 2014), and the occipital place area has been related to processing of boundary relations between items and visible scene boundaries (Julian et al., 2016). If shape information were being used, regions such as the inferior temporal cortex could be involved in providing preprocessed representations of shape via shape selective neurons identified in this region (Perrett & Oram, 1993). Alternatively, some heuristic approach to reconstruction could be used which takes advantage of hidden constraints in the task (i.e. it is unlikely for two items to appear on top of each other, which constrains the possible reconstructions). Should the hypothesis that shape-like information is being used to maintain these relations be investigated, different experimental paradigms could be used in which various levels of complexity of shape-like information are superimposed on a point set and presented to participants to be learned then reconstructed. In particular, edges between the locations could be drawn to avoid the need to infer some item-item relations which may contribute to a shape-like representation. We would predict that patients would perform similarly to comparisons for simple shapes and show deficits primarily in identity information for the vertices. Patients may also show performance deficits for more complex shapes, which are not as easily unitized (thus preventing a non-hippocampal representation from being as helpful).

Taken together, the evidence presented here defines the various *types* of relations present in a spatial-relational paradigm by applying a systematic framework that allows a more thorough investigation of the role of hippocampus in spatial-relational memory. Consistent with previous theories of the role of hippocampus in relational memory via the arbitrary binding of information (Neal J. Cohen & Eichenbaum, 1993; Howard Eichenbaum & Cohen, 2001), patients with hippocampal damage demonstrated specific deficits in arbitrary binding of identity-location relational information. Patients do not show a deficit in compound relational errors or location accuracy, suggesting that some types of relational information (in fact, the non-*arbitrary* relational information; i.e. information which has alternative derivations or redundancy) can be maintained by memory systems which are not hippocampally dependent. These results further clarify the role of the hippocampus in relational memory theory to be specifically in maintaining *arbitrary* relations which cannot be derived from other information which might be remembered by the participant. We have also proposed several possible alternate means through which other, non-arbitrary information may be maintained (such as a shape-like representation), which can be investigated in future research. We would predict, however, that because one benefit of representing arbitrary relations is in the ability to flexibly use those relations with changing task demands, whatever alternative means is being used to maintain these relations may not permit the same amount of flexibility.

SR tasks have proven enormously informative in that they provide sensitive measures of relational memory abilities that have been tied not only to hippocampal damage, but to more subtle hippocampal deficits such as subjective memory complaints (Lucas et al., 2016), spatial pattern separation (Clark et al., 2017), and medial temporal lobe viscoelasticity (Schwarb et al., 2017b, 2016). Precision and specificity of the metrics and the ability to distinguish between several different types of spatial relational errors will undoubtedly serve these lines of investigation well as it will allow a far more resolute picture of the specific impairments that may be tied to particular behavioral, functional, and structural phenotypes.

# Chapter 3: Memory during Time Travel: Spatiotemporal Navigation, Contextual Boundaries, and Relational Memory Errors in Virtual Reality

## 3.1 Introduction

*Episodic memory* involves memory for events, i.e. things which happen in time and space, organized according to relational and contextual information, and is often referred to as the “ability to jump back in time and relive events from the past” (DuBrow & Davachi, 2013; Tulving, 2002b). In humans, the *hippocampus* has been shown to be a critical brain region for episodic memory such that hippocampal damage in humans causes pervasive *amnesia* (for review, see Cohen & Eichenbaum, 1993). There has been considerable historical success in studying hippocampal function in the spatial domain, with early experiments identifying “place cells” in the hippocampus of rodents which fire in association with the location of an animal in a spatial environment (John O’Keefe & Nadel, 1978). The temporal organization of memory has also received considerable attention, including the recent identification of “time cells” in the hippocampus which fire selectively for moments in time (Howard Eichenbaum, 2014). However, experiences are not restricted to space or time in exclusion of each other, but consistently involve a mix of both. Despite this, most studies do not simultaneously examine behavior in both space and time, possibly because space, as an explorable domain that can be selectively sampled, and time, as unidirectional flow of experience that cannot be selectively sampled, seem to be too distinct for direct comparison. This work takes the first step towards resolving this asymmetry by allowing both space and time to be explored by participants using *Virtual Reality* (VR), a technology which allows for increased measurement and control fidelity as well as increased ecological validity when compared to other methods (Schultheis et al., 2002). This approach provides a new framework to investigate and understand the nature of episodic memory, extending beyond the limitations of typical experimental environments.

*Relational memory theory* explores the relationship between different domains of information (such as, but not limited to, space and time) and their representation in the hippocampus. (Cohen & Eichenbaum, 1993; Eichenbaum & Cohen, 2001; Konkel & Cohen, 2009; Konkel, Warren, Duff, Tranel, & Cohen, 2008). According to relational memory theory, the hippocampal region critically supports episodic memory via relational memory, i.e. the learning of arbitrary relational information regardless of the domain (Konkel et al., 2008) – a function which is pervasively impaired in hippocampal damaged patients. To evaluate relational memory in humans, *spatial reconstruction* (SR) tasks have proven particularly effective in examining relational memory errors in space. This task can be used to infer an individual’s success in forming arbitrary associations between items and locations in space (Huttenlocher & Presson, 1979),and to determine the susceptibility of making relational memory errors due to hippocampal damage (Jeneson, Mauldin, & Squire, 2010; Smith & Milner, 1981; Watson et al., 2013). In an SR task, participants are asked to study the locations of items in space and, after a short delay during which the items are removed from the environment, place the items back where they were studied (i.e. reconstruct the study configuration). Hippocampal damage specifically impairs arbitrary identity-location binding, i.e. binding of the identity information for a specific item (i.e. the item was a boat, plane, boxing gloves, or flower) to a specific location (Horecka et al., 2017, under review). In healthy individuals, identity-location binding errors and compound memory errors (i.e. those in which groups of items are misbound to each other’s locations) can occur when the number of to-be-remembered items increases beyond approximately 4-5 items (Watson et al., 2013). SR tasks have been used successfully in examining the relationship between relational memory and subjective memory impairment (Lucas et al., 2016), medial temporal lobe viscoelasticity (Schwarb et al., 2017b, 2016), and spatial pattern separation (Clark et al., 2017), however, time has always been intentionally isolated into other tasks. In this work, we present the first *spatiotemporal reconstruction (STR) task* in which the locations of events in both space and time are studied and reconstructed.

There is substantial evidence that the hippocampus is critical for organizing information about the temporal order of events, and that in humans, hippocampal damage results in deficits in temporal-order memory for those events (Dede, Frascino, Wixted, & Squire, 2016). Additionally, functional imaging studies have shown hippocampal activation during encoding and retrieval of event order information (see Eichenbaum, 2014 for a review). In rodents, hippocampal lesions also impair temporal-order memory for non-spatial stimuli without impairing memory for the specific stimuli (Fortin, Agster, & Eichenbaum, 2002a; Kesner, Gilbert, & Barua, 2002). However, in all of these examples, event series have been viewed unidirectionally, critically restricting the directionality of temporal relations and information. Although physical space-time may have the restriction of direction-of-flow in time, this restriction can be, at least in part, artificially overcome in simulation.

Additionally, there is extensive evidence that contextual information influences temporal order memory in online processing of sequences (Ezzyat & Davachi, 2014). For example, Zacks et al. have suggested that an *event model* which is updated according to event *boundaries* can describe processing of events in time (Zacks, Speer, Swallow, Braver, & Reynolds, 2007b). In humans, *context boundary effects* (i.e., distance judgements of item pairs within vs across context boundaries are biased such that items which are separated by a context boundary are judged as further apart than those which are within a context) have been demonstrated (DuBrow & Davachi, 2013) and the hippocampus has been implicated in representing temporal order and distance in the presence of changes in context (Davachi & DuBrow, 2015). Taken together, these studies highlight the importance of context in episodic memory representations; importantly, however, this evidence was bound to a unidirectional timeline of events and often discretized such that time is not allowed to flow normally in a continuum (with the exception of the Zacks work), but is instead broken up into discrete events. It is unclear if, given the ability to freely explore a series of events organized by context in a continuous timeline, these same effects would persist. In particular, the ability to cross contextual boundaries in both directions as often as desired (a feature of real-world navigation which is far more common than the restriction that each boundary may only be experience once and in the same direction) has never been explored.

In this work, we introduce a powerful *spatiotemporal navigation task* for examining relational memory errors and the impact of context on memory for event locations in space *and* time by allowing participants to freely explore an environment in both space and time using Virtual Reality. Critically, we provide participants with the ability to “time travel” (i.e. decide the direction of the flow of time), placing the ability to explore space and time on more equal footing so that errors in either domain can be examined simultaneously. This “time travel” ability is necessary to allow spatiotemporal reconstruction where participants can visit events in time as freely as they can the spatial locations of events. To our knowledge, this is the first *spatiotemporal navigation task*.

## 3.2 Methods

### 3.2.1 Participants

43 participants (ages 18-24; mean 20.0 years; 23 males; 13.8 mean years of education) from the University of Illinois Urbana-Champaign participated in the study. In addition to the 43 participants being analyzed, 4 participants were excluded due to not completing the task within the allotted 2.5 hours. All participants signed informed consent prior to participation, approved by the University of Illinois Urbana-Champaign Institutional Review Board and were paid $8 per hour of their time.

### 3.2.2 Design and Procedures

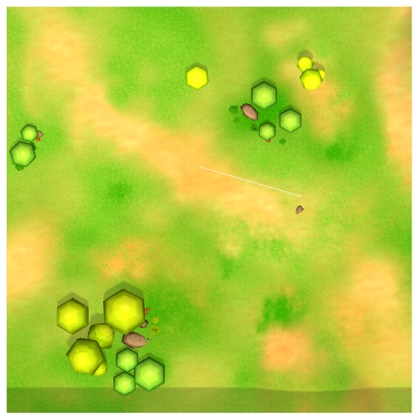
In this task, participants were placed in a virtual environment measuring 40 meters by 40 meters, bounded by walls on the exterior (see **Figure 1A)**. The environment resembles a small park with trees, rocks and plants. Participants used the Oculus Rift DK2 and a wireless Xbox controller to interact with the environment. Auditory cues were presented via a pair of over-ear, stereo headphones. Participants were given a single practice trial to learn the simulation mechanics as well as to gain competency in using the virtual reality hardware. Practice was not timed and participants were allowed as much time as they desired to become comfortable. The stimuli during practice were white boxes (0.5m x 0.5m x 0.5m) floating 0.25m above the ground with gray dots on each face. Five items were used in practice. In order to encourage exploration of the environment, an invisibility bubble 10m in diameter was placed around the participant such that any items beyond that distance away from the participant were not visible. A ring was visible on the ground to indicate to the participant the distance at which items were visible. In addition, some items were always present throughout the trial, while others underwent events (i.e., entered the display or were removed from the display) at specific time points during the simulation timeline (see **Figure 1** for a description). Thus, there were three event types 1) items flew into the sky and left the environment at specific times (an “up” event, i.e. disappearing), 2) items fell from the sky and land in the environment at specific times (a “down” event, i.e. appearing), and 3) items were stationary and thus always present in the environment. During practice, there were two up events, two down events, and one stationary item. An auditory cue was given every time an event occurred regardless of whether or not the item was in view. Item positions were determined via random number generator; however, they were constrained in time to balance for within vs. across context boundary distance.

Temporal context information was provided in the form of the simulation boundary walls changing colors at evenly spaced intervals throughout the simulation. Thus, context boundaries were defined as shifts from one color to the next. The colors yellow, red, green, and blue were used for the contextual information, which changed every 7.5 seconds during practice such that all contexts appeared within 30 seconds. The order of the temporal contexts was counterbalanced across participants with half receiving yellow, red, green, and blue and the other half receiving blue, green, red, and yellow.

**A**

**B**

**C**



**Figure 1**: The two types of events an item can undergo in time and a visualization of the environment. A) shows a “down” event, in which the item falls from the sky, B) shows an “up” event, in which the item flies into the sky, and C) shows the environment from a top-down view. Note that these two types of events are time-symmetric, in that they look identical when viewed from opposing directions (forward or backward) in time.

Participants could both walk around the environment (and turn their head to look in any desired direction). Temporal navigation was controlled via button press that could reverse the flow of time, at the same speed as the forward flow of time. To provide additional temporal information, ambient music was played for the entire timeline of the task, meaning reversing the flow of time reversed the music as well. Participants’ looking direction and location in space and time were logged at every time point in the simulation (~16ms intervals). If the participant reached the beginning or end of the simulation’s time course, time was paused but the participant was still allowed to freely move about the spatial axes in the environment. Participants were instructed to find the locations of each item in space and time, specifically when their events happened. To signify they had found the item at its event, there was a 0.5 second window during which participants could see the item’s event (if close enough) and press a button on the controller to acknowledge they witnessed the event. When the participants successfully click on the item during its event, the item would change to the background color during its event (with stationary items staying grayscale when clicked). Participants were given unlimited time to explore the environment, find each item, and acknowledge they had viewed each event.

After the practice trial, there were four experimental trials each with a study and test phase. Experimental study trials were identical to the practice trial with three exceptions. First, the number of items was increased to ten. Therefor there were four up events, four down events, and two stationary items. Second, the gray dots on the sides of each white box were replaced with namable object images (see **Figure 1B&C** for example). Third, the context changed every 15 seconds such that all contexts appeared within 60 seconds. Each context had two item events during its duration. Finally, the 4 study-test trials all used the same spatiotemporal item configuration, allowing learning across trials to be assessed.

During test, participants were asked to reconstruct each item in its spatiotemporal location as well as to determine which event type (up, down, stationary) the item underwent. To do this, participants were given an inventory of the items (an overlay on the screen) allowing them to freely select any item and its event type. As with study, participants could navigate space in on the x/y plane, and could navigate time via the reverse-time button. Context continued to change as it did during the study phase. Participants were given unlimited time to perform the reconstruction.

### 3.2.3 Analysis Metrics

Four primary analysis methods were used to evaluate reconstruction performance. First, a naïve misplacement distance error was computed across trials to confirm that participants were improving in all primary sources of information (spatial, temporal, and event type). Misplacement along continuous variables (space and time) was computed via the sum of the Euclidean distance between all placed items and their expected locations. The number of correct event types was determined by a simple comparison of the chosen event type to the expected (studied) event type for each item (i.e. summing the number they got wrong). Additionally, the participant navigation distance in space and time (separately) was observed across trials, during study to confirm that the study-time behavior was also improving. This spatial and temporal navigation distance was computed via the Euclidean distance between all points traversed by the participant in space (i.e. spatial distance in meters) and in time (i.e. temporal distance in seconds).

Second, an evaluation of relational memory efficacy was performed identity-location misassignment in space and in time (Horecka et al., 2017, under review). Identity-location accuracy was evaluated by first stripping away the identity of the items and determining if each was placed in any item’s location based on a 95% within-participant confidence interval of their misplacement. Then, identities were restored to determine if items were placed in their correctly associated locations (or in another item’s location). Identity-location misassignments are the number of instances in which an item was misassigned to another item’s location within a distance which was deemed “accurate” (see Horecka et al., 2017 for details). Identity-location misassignment has previously been identified as critically dependent on the hippocampus (Horecka et al. 2017). In order to isolate spatial and temporal information, two separate analyses were performed using these measures. The 1D temporal axis was analyzed (where location is defined as the position along the 1D axis), and the 2D spatial axes were analyzed (where location is defined in the traditional, spatial way).

Third, the effects of context boundaries on temporal memory distances were evaluated by normalizing the pairwise distance between within and across context items (dividing their reconstructed distance by the expected distance) then mean-centering to make 0 represent a perfect placement (i.e. d>0 represent items placed further than expected, and d<0 represent items placed closer than expected).

Finally, the impact of context on relational memory errors was evaluated by determining the number of identity-location misassignments to another within-context item (i.e. the other item with which it shared a temporal context) or an across-context item. Chance level for within- and across-context misassignments were computed by taking the number of identity-location permutations for within and across context identity-location pairs. The two items which had no temporal context were excluded from this part of the analysis, and, therefore, the chance levels were 8/8*P*2 and 1-8/8*P*2, or 0.143 and 0.857, respectively, where n*P*r represents the number of r-length permutations of n items and the number 8 is due to the 4 contexts containing 2 possible within-context misassignments each (i.e. items a and b within a context can be misassigned a🡪b’s location or b🡪a’s location).

### 3.2.4 Statistical Analysis

All analyses which compare trial-by-trial performance use repeated measures analysis of variance using SPSS. Where appropriate, Huynh-Feldt correction was applied. Comparisons which involved collapsing performance across trials or comparing trial-over-trial performance used either paired-sample, two-tailed t-tests or one-sample, two-tailed t-tests (for comparison to expected chance values). All tests used an alpha value of 0.05 to determine significance.

## 3.3 Results

### 3.3.1 Overall Accuracy and Navigation (Misplacement Measures and Navigation Distance)

A 4 by 3 repeated measures ANOVAs (trial number by test domain; i.e. space, time, and event type) across trials (1-4) revealed that accuracy in both space and time as well as event type improved significantly across trials (main effect of trial F(2, 167)=252.86, p<0.001 and significant interaction between domain and trial F(6, 334)=14.56, p<0.001; see **Figure 2**). Follow-up t-tests between trials for space, time, and event type showed a significant decrease in misplacement in space between trials 1 and 2 (t(42)=2.90, p=0.006) and trials 2 and 3 (t(42)=3.50, p=0.001) but *not* trials 3 and 4 (t(42)=1.51, p=0.138); misplacement in time decreased significant between all trials (t(42)=7.77, 3.97, and 3.99, p<0.001 for each trial pair); number of incorrect event types decreased significantly between trials 1 and 2 (t(42)=4.61, p<0.001), between trials 2 and 3 (t(42)=5.36, p<0.001), and between trials 3 and 4 (t(42)=2.35, p=0.024); Finally, the amount of distance travelled in space and time also improves across trials (main effect of measure, i.e. spatial or temporal distance, F(1, 168)=268.27, p<0.001 and interaction of trial and measure, F(3, 168)=19.10, p<0.001). Follow-up t-tests between trials for spatial and temporal distance travelled show that spatial distance travelled decreases between all trials (t(42)=5.22, 3.07, 2.34, p<0.025 for each trial pair); temporal distance travelled (i.e. number of seconds not paused at the beginning or end of the simulation) decreases across trials (t(42)=5.86, 4.12, 3.48, p<=0.001 for each trial pair). Together, these analyses show improved navigation efficacy in addition to test-time memory performance across trials in the task.

**Figure 2**: Overall errors along each of the three major information types in the task and navigation distances in space and time. Space misplacement and time misplacement are continuous variables computed via the sum of the Euclidean distance of all items in a trial to their expected locations in space and time. The number of incorrect event types is just a count of the number of items which were assigned the studied event type. Note that participants improved in all metrics between trials 1 and 4, showing the task was generally well understood. Moreover, navigation performance improved across trials in both space and time showing the improvement was not just in memory during test but also study performance.

### 3.3.2 Relational Memory Errors

Relational memory errors (identity-location misassignments) were evaluated in space and time separately (see **Figure 3**), showing that significantly more relational errors were committed in time than in space (t(171)=15.82, p<0.001). A 2x4 (domain, i.e. space and time, by trial number) repeated measures ANOVA was used to determine if a difference was present across trials. A main effect of domain F(1, 168)=250.62, p<0.001 was found; no significant interaction was present. In space, the number of relational errors decreased significantly between trials 1 and 2 (t(42)=2.75, p<0.01) but not between trials 2 and 3 or 3 and 4 (t(42)=1.86 and 1.36, p=0.07 and 0.18, respectively). In time, there was no significant difference between temporal relational errors between trials 1 and 2 (t(42)=1.3, p=0.20) but a significant difference was present between trials 2 and 4 and 3 and 4 (t(42)=2.70 and 2.32, p=0.010 and 0.025 respectively.

**Figure 3**: Relational memory errors were evaluated in both space and time independently by measuring the number of items which were assigned to another item’s location (i.e. a misbinding). The number of these errors in time was greater than the number in space. This difference did not change across trials, though both errors decreased as accuracy improved.

### 3.3.3 Temporal Context Boundary Effects

To evaluate temporal context boundary effects, only items that had been placed in their correct context were considered. A strong temporal context boundary effect (see **Figure 4**) was observed that within-context items were placed closer together than across context items in time (paired sample t-test; t(109)=9.78, p<0.001). This effect was numerically larger for the across context distances, but both within and across differed significantly from 0 (t(42)=16.02, p<0.001 and t(42)=10.61, p<0.001, respectively). A 2x4 (within and across by trial number) repeated measures ANOVA was used to compare within and across over trials. A significant main effect of within vs. across was found (F(1, 106)=80.84, p<0.001) but no interaction effect was present. No significant main effect of trial was present.

3.3.4 Effect of Context on Relational Memory Errors

**Figure 4**: Context boundary effects (i.e. the misjudgment of distance of within context items as being closer together than expected and across context items as being further apart than expected) can be seen both in within and across context items. These effects are persistent regardless of the trial number.

Finally, when evaluating the identity-location misassignments (i.e. the number of items placed in another item’s location) within vs. across contexts, within-context items were misassigned to each other’s locations far more often than would be expected by chance (t(42)=14.63, p<0.001 for across and t(42)=8.76, p<0.001 for within), suggesting that the contexts biased the relational memory representation, causing confusing between within-context temporal item locations (see **Figure 5**). A 2x4 repeated measures ANOVA (within and across by trial number) was performed to examine this effect trial-over-trial. An interaction effect of within and across context misassignment proportion and trial was found (F(3, 147)=12.12, p<0.001). Follow-up t-tests showed a significant increase in within-context misassignments between trials 1 and 2 (t(38)=-2.81, p<0.01) and trials 2 and 3 (t(36)=-4.196, p<0.001) but not trials 3 and 4 (t(30)=0.53, p=0.60). An opposite pattern can be observed on the across-context misassignment proportion as they are one minus each other. To determine if this effect is present in the absolute number of items being misassigned, another 2x4 repeated measures ANOVA was performed on the number of items to be misassigned within or across context. A main effect of within and across context measures was found (F(1, 168)=5.74, p=0.02) as well as an interaction between within and across context and trial (F(3, 168)=11.42, p<0.001). Follow-up t-tests show a significant increase in within-context misassignments between trials 1 and 2 (t(42)=-2.34, p=0.024) but not significant increase between trials 2 and 3 or 3 and 4 (t(42)=-1.11 and 1.50, p=0.27 and 0.14, respectively). A significant decrease in across context misassignment was seen between trials 1 and 2 (t(42)=3.44, p=0.001) and trials 2 and 3 (t(42)=4.61, p<0.001) but not trials 3 and 4 (t(42)=1.40, p=0.17.

**Figure 5**: The proportion of items which have been assigned to another item’s location within vs. across context. Although the within context items should be misassigned to each other’s locations by chance at a rate of approximately 14%, we see a substantially higher occurrence of >40%. Interestingly, this effect only gets stronger across trials despite improved accuracy across all non-context based error metrics (including number of misbound items). Note that this same pattern is present when the number of items assigned within versus across are compared directly (rather than as a proportion of the overall errors).

## 3.4 Discussion

In this work, we used a novel spatiotemporal reconstruction task to determine if, when space and time are put on a more equal footing, spatial and temporal relational memory errors would be committed with equal frequency. Furthermore, this work examined if, when a timeline of events can be explored omnidirectionally, the impact of context on distance judgements in time and the subsequent effect on order memory were consistent with previous findings on context boundary effects. This manipulation is critical for theories of the impact of contextual boundaries on memory as individuals can often re-explore across real-world boundaries arbitrarily. We found that, in this task, relational memory errors in time occurred far more frequently than relational memory errors in space. Context boundary effects were found in time such that within context items were judged to be closer together in time than across context items. Finally, we found that relational memory errors in time were influenced by contextual information as items were misassigned to within context locations far more often than expected by chance. Together, this evidence points to a deep interplay between relational and contextual information in both a spatial and temporal domain, and this evidence suggests that temporal representations in memory may be somehow distinct from spatial representations given the huge disparity between memory in each domain even when they are both able to be explored and sampled similarly. This difference may depend on task demands, and, given that participant performance on temporal measures of relational memory were improving across each trial, it is possible that if more trials were provided, this difference would be eliminated.

The hippocampus is critical for integrating information into relations representations to aid in flexible memory utilization (Neal J. Cohen & Eichenbaum, 1993). Its role in episodic memory in humans has been established through work with hippocampal damaged patients who have a pervasive inability to create new episodic memories. Additionally, in humans, some evidence shows the flexibility of the hippocampus’ potential involvement in real-world representations of space and time, even across long distances (Nielson, Smith, Sreekumar, Dennis, & Sederberg, 2015). In rodents, cells which fire in association with space (i.e. place cells; J. O’Keefe & Dostrovsky, 1971; John O’Keefe & Nadel, 1978), time (i.e., time cells; B. Kraus, Robinson, White, Eichenbaum, & Hasselmo, 2013), and distance (B. J. Kraus et al., 2015) have been identified in the hippocampus and its role in navigation (e.g., Eichenbaum, 2017) has been well established. In line with these observations, some have proposed that space and time make up a scaffolding upon which episodic memories are formed (Ekstrom & Ranganath, 2017). It is not clear, however, if space and time are coded together, as a unified space-time manifold, or if information is bound to each independently of one another. The evidence here cannot completely disentangle these possibilities, however, when using a relational memory error metric which has been shown to be particularly sensitive to hippocampal damage in human patients (Horecka et al. 2017) and the spatiotemporal reconstruction task we present here, we do find differences in space and time relational memory in healthy individuals such that relational memory errors in time are substantially more common than in space. This suggestions that although these domains may be representable as a unified whole, they are not necessarily so in all circumstances. Task demands may play a large role in determining the degree of interplay between spatially bound and temporally bound information; however, the emphasized domain (time, in this case) may not always benefit from being in focus.

There are several explanations for the phenomena we observe here beyond encoding differences between space and time. First, although both space and time could be explored freely in this task, time remained one dimensional while space had two explorable dimensions. The additional dimension adds more information which must be remembered in order to know spatial locations, but it also provides more information which relational representations may bind. Future tasks may attempt to disentangle these possibilities by restricting space to one dimension or expanding time to two dimensions. Additionally, because time can be explored in any order, it is possible that the ability to view events in any order hurts memory for order in a way which increases the chance of misbinding items to other item’s temporal locations. A similar debate has occurred in the rodent literature in spatial navigation such that distinct hippocampal representations for overlapping routes in a maze are not observed when rats are trained to run in either direction of a Y-maze (Lenck-Santini, Save, & Poucet, 2001). This raises an interesting question: can the relative position (i.e. order) of events in time in episodic memory be treated both allocentrically and egocentrically in the same way the spatial position can?

In spatial navigation, Cognitive Map Theory says that allocentric representations depend on the hippocampus (John O’Keefe & Nadel, 1978) with alternate strategies such as view-matching being used to overcome deficits in allocentric memory (Banta Lavenex, Colombo, Ribordy Lambert, & Lavenex, 2014). However, it is unclear what a view-matching strategy would be when exploring a temporal axis. Place cell firing is related specific to distal cues and is, therefore, seen as strong evidence for this allocentric perspective. The evidence here hints at the allocentric nature of time cells as well, and perhaps, with the proper observation of time cells in a task which allows the free exploration of a series of events, this hypothesis could be validated.

An additional potential explanation for the asymmetry between spatial and temporal relational memory errors is that the temporal axis in this task uniquely contained contextual information (i.e. the spatial axes did not), which may have caused confusion between within-context items (discussed more in future paragraphs). Tasks in which both spatial and temporal contextual information are present might help to clarify this impact, however, it may not be sufficient to simply include additional types of context to completely disentangle the impacts they have in space and time if spatial and temporal representations are truly distinct.

In addition to the interplay between spatial and temporal memory, this task also allows us to examine the impact of temporal contextual information on memory for a sequence of events. Similar to tasks which exclusively examine order memory, we find context boundary effects such that within context items are placed closer together in time than across context items, even when equidistant. However, this task shows these effects in a continuous timeline of events even when the timeline can be freely explored and the contexts can be restudied freely as often as the participant likes. Moreover, the effect does not diminish when the same short series of events is repeatedly studied. This provides strong evidence that the contextual information is biasing the reconstruction systematically. Critically, of all of the types of errors examined in this task, the context boundary effect is the only error which does not improve with repeated study of the event timeline. Some hierarchical models which attempt to describe how context might be used to organize memory representations suggest that context sits at the top of a hierarchy containing other information such as spatial, valence, and item information (McKenzie et al., 2014). This may explain, in part, why restudy and free exploration don’t improve the context boundary effect as the contextual information is being used as a very high level organizing principle for other, more granular information. This may be consistent with high-level theories of the interplay of multiple brain regions involved in contextual and relational learning such as the Complementary Learning Systems model which would suggest that cortical regions which represent and utilize this higher-order information are potentially slower to update than hippocampally-dependent relational information (McClelland, McNaughton, & O’Reilly, 1995). However, recent updates to this view complicate the issue as the speed of acquisition of information in cortical versus hippocampal systems may not be so clear cut (Kumaran et al., 2016). Alternative models which posit a rapid interaction between prefrontal and hippocampal regions in service of decision making (Wang et al., 2015) might better fit behavior in this task as the utilization of the contextual information is necessarily happening in a continuous, real-time manner. However, it is important to note that real-world contextual information is not nearly as clear and discrete as the artificially imposed contexts in this task, and future work might use contextual boundaries (such as night/day boundaries) which are more consistent with real-life experiences.

Finally, one of the most striking results in this work is the interplay between relational information and contextual information. Specifically, we see that the contextual information is related to poorer performance in order memory even when temporal accuracy improves. This is evaluated by determining the relative proportion of misassignments (i.e. relational memory errors) where an item is placed in another item’s location within vs. across a context boundary. If this error were to occur by chance (via randomly ordering the items), we would expect approximately 14% of misassignments to be to a within-context location. However, we find the error occurs more than twice as often as expected within-context. Moreover, within-context misassignment errors become more common (as a proportion of the total number of misassignments) on repeated study both as a proportion of the number of misassignments and in absolute number. This result disagrees with previous accounts which show that context boundaries should impair order memory for across context items and enhance memory within contexts (Davachi & DuBrow, 2015), and shows that, at least when a series of events can be freely explored, context can be related to worse order memory for within context items. There are several explanations beyond the organization of memory due to context which could account for this result. Firstly, it could be that the ability to view a timeline of events in any order results in more confusion for within context items as the viewing order of the context can be different on each exploration. However, it is important to note that participants were not required to view the items in a particular order and could have biased their exploration to avoid this issue. Additionally, if this were the case, we might expect more overall misassignment errors, but this would not completely account for why these errors are so much more common within context than expected unless the context was being used to organize the representation on some level. Another explanation might be that with a limited number of items in the context, not enough information is present to form a reliable relational representation. This explanation may be consistent with the interpretation described earlier that spatial relational information, by having an additional axis within which to bind relations, is easier to reconstruct than temporal relational information. In other words, more information may improve relational memory, to a point. This question could be tested by increasing the number of within-context items to see if this improves within-context order memory.

In summary, with the use of Virtual Reality to create a rich task environment, the importance of contextual information in organizing episodic memory representations can be seen with much more fidelity than previous experiments. Furthermore, contextual information is shown to bias relational memory errors, which were far more common in time than space, such that items were more likely to be misassigned to the temporal location of an item with which it shared contextual information that might be otherwise expected. Spatiotemporal navigation, as presented here, can hopefully serve as a first step in furthering our understanding of the flexibility and structure of relational memory representations in space and time and clarify the influence of context on different domains of information without the need to treat time differently than we treat space.

# Chapter 4: Spatiotemporal Navigation, Sampling, and Information Encoding in Virtual Reality

## 4.1 Introduction

Gallistel, (1990) said, “Navigation is the process of determining and maintaining a course or trajectory from one place to another”. This definition captures a surprising amount of cases which would be commonly considered navigation, and it has been echoed in recent reviews of navigation and hippocampal function in various species (Howard Eichenbaum, 2017b). Interestingly, however, the word “place” in this context strongly implies that navigation is generally restricted to space (and is used as the term to describe cells which fire relative to allocentric locations in space, i.e. “place” cells; O’Keefe & Dostrovsky, 1971). Introduced by Tolman, (1948) and elaborated upon in the context of hippocampal function by O’Keefe & Nadel, (1978), Cognitive Map Theory suggests that, at least in space, the hippocampus is responsible for maintaining map-like, allocentric representations, and this theory has been validated to various degrees across many human and rodent lesion studies (Astur, Taylor, Mamelak, Philpott, & Sutherland, 2002; Bartsch et al., 2010; R. G. M. Morris et al., 1982; J. O’Keefe & Dostrovsky, 1971; John O’Keefe, 1991). Tolman himself did not restrict this theory to space; however, later uses of the theory have tended to isolate space in exclusion of any other domains. Despite this isolation of navigation to space, “time” cells in the hippocampus have been identified which fire relative to particular moments in time (B. Kraus et al., 2013), and extensive evidence suggest the hippocampus is involved in mapping far more than just spatial information (Neal J. Cohen & Eichenbaum, 1993; H. Eichenbaum, Dudchenko, Wood, Shapiro, & Tanila, 1999; Howard Eichenbaum, 2015, 2017d; Howard et al., 2014; Konkel et al., 2008; B. J. Kraus et al., 2015; Ranganath & Hsieh, 2016; Schiller et al., 2015; Warren et al., 2015). It is, therefore, interesting to expand the definition of navigation to include not just movement from place to place, but also from time to time (or, potentially movement between any discrete locations in any domain). The previous chapter showed how this can be done in time (via having participants Time Travel), and participants successfully reproduce several test phenomena including relational memory errors (see Chapter 2) and Context Boundary Effects (DuBrow & Davachi, 2013), as well as some new phenomena which have not be previously explored; they also successfully navigate the environment to improve their memory for a timeline of events (see Chapter 3). One prediction which was made in the previous chapter is that time cells map an allocentric perspective on time, not an egocentric one, despite the fact that time (like space) is consistently experienced egocentrically. Of course, the primary way this hypothesis could be validated is via electrophysiological work with actual time cells. However, as successful as cellular recording studies have been in advancing our understanding of the organization of memory, using rodent models substantially constraints the complexity of tasks which can be used, potentially missing interesting aspects of the organization of human memory which require greater complexity. In this work, I demonstrate methods which are applied to the behavioral navigation data collected in the task described in Chapter 3 to adjudicate between allocentric and egocentric views on temporal information coding. Additionally, I proposed analyses which might clarify aspects of spatiotemporal navigation in general which relate to relational and contextual memory in space and time.

Spatial navigation is a critical capability of all creatures’ survival (Wolbers & Hegarty, 2010), and it has been extensively studied phenomenologically in humans (Dudchenko, 2010; Huth, 2013; Wolbers & Hegarty, 2010), animals (Poucet, 1993; Trullier, Wiener, Berthoz, & Meyer, 1997), and even robotic navigation (Franz & Mallot, 2000; Levitt & Lawton, 1990) which has, more recently, become an extremely popular topic in machine learning research (Mirowski et al., 2017). Traditionally, in a laboratory setting, tasks such as the Morris Water Maze (MWM; Morris, 1981) have been used to study both rodent and human navigation behaviors (using a virtual Morris Water Maze; vMWM; Moffat & Resnick, 2002), showing, in older adults, that smaller hippocampal volumes account for longer distance travelled and time taken in the task (Maguire, Burgess, O’Keefe, & O’Keefe, 1999; Moffat, 2009). Recently, more complex behavioral tasks have been attempted, such as observing hippocampal neurons in bats as they navigate in the real world (Geva-Sagiv, Las, Yovel, & Ulanovsky, 2015; Sarel, Finkelstein, Las, & Ulanovsky, 2017); however, this work is still in its infancy and should certainly be a target for additional investigation. Several models of hippocampal function in navigation have come out of simpler tasks such as the MWM. In rodents, theories of Pattern Separation/Pattern Completion (Marr, 1971; Rolls & Kesner, 2006) have suggested that hippocampal lesioned rodents’ deficits in spatial location accuracy are due to an inability to create precise representations of specific locations and differentiate them from other studied locations (i.e. a deficit in pattern separation; Gilbert, Kesner, & DeCoteau, 1998). Other have expanded on this theory suggesting that after converging “what” and “where” streams reach the DG and CA3 subregions of the hippocampus (Knierim & Neunuebel, 2016), DG specifically performances pattern separation (Leutgeb, Leutgeb, Moser, & Moser, 2007; McHugh et al., 2007), orthogonalizing inputs from one another, while CA3 performs pattern completion (Leutgeb et al., 2007; Nakazawa et al., 2002; Neunuebel & Knierim, 2014), auto-associating inputs with previously learned patterns. In humans, the Precision and Binding Model (PBM; Yonelinas, 2013), whose evidence shows hippocampal damaged patients are impaired on finding the precise location of a hidden platform but can find the general location (i.e. quadrant; Kolarik et al., 2016; Kolarik, Baer, Shahlaie, Yonelinas, & Ekstrom, 2017), says that the hippocampus is required for high-resolution information binding in spatial navigation. However, in rodents who have already learned a target location or who are attempting to navigate to a target location which has a cue, hippocampal damage does not impair the ability to find the target (see Eichenbaum, 2017c for review). Some models suggest that the long axis of the hippocampus represents progressively more precise information when viewed from anterior to posterior (Fanselow & Dong, 2010; Nadel, Hoscheidt, & Ryan, 2013). Similarly, view-matching strategies can help overcome deficits in allocentric memory of space via the subject finding an egocentric perspective which allows acquisition of the target (Pecchia & Vallortigara, 2010). Moreover, not all navigation phenomena which occur in rodents are equivalent in humans. Rodents with hippocampal damage show a deficit in path integration while human hippocampal damaged patients do not (Kim, Sapiurka, Clark, & Squire, 2013). Together, these pieces of evidence paint a complicated picture of hippocampal involvement in navigation in space and provide a foundational perspective on which we might attempt to understand temporal navigation (see Eichenbaum, 2017c for a review). In particular, across all of the above work, several attempts have been made to develop quantifications of navigation in space which we may apply to navigation in space and time.

Several measures of behavior in navigation have been used historically including simple visual inspection of individual paths (Moffat & Resnick, 2002; Sei, Arora, Skolnick, & Paul, 1992), heading error (i.e. the sum of the angular distance between the correct heading to the target and the actual heading to the target for a given path; A. D. Smith, McKeith, & Howard, 2013), distance and time to target (R. G. M. Morris et al., 1982), proximity to target (Kolarik et al., 2017; Richard G.M. Morris, 1981), path crossings (Buzsáki, 2005), and even search path classification via clustering (Davis, Franklin, Johnson, & Schrott, 2010). Each of these measures has computational advantages and disadvantages worth considering, especially if both spatial and temporal exploration are to be evaluated together. We consider them here as they relate to our Time Travel task. First, heading error is complicated by the fact that participants could be proceeding to one of many targets in a particular direction. The decided upon event (i.e. the item the participant interacts with next) could be used as a target, but this only makes sense if we assume at least some memory for the event position (not a valid assumption in trial 1 for much of the time). Similarly, path crossing has far less meaning in 3D (2 spatial and 1 temporal axis) than traditional 2D as it is incredibly unlikely for a 3D line to cross its self. Proximity to target, distance, and time are all potential methods of evaluation, however it is unclear which of these should be preferred for correlation with any particular output measure. Previous investigation into this issue has found that, with a high sampling rate, variable measure of target proximity can be very successful in differentiating hippocampal patient performance from controls (Kolarik et al., 2016, 2017), and the use of measures of fractal geometry (Mandelbrot, 1967) has shown some success in measuring natural navigation patterns in migration and grazing (Garcia, Carrère, Soussana, & Baumont, 2005; Gautestad, 2011; Gautestad & Mysterud, 2010). One particular measure of fractal geometry which has shown significant promise is Fractal Dimension (FD), a measure of the degree to which a path resembles a space-filling curve (Daugherty et al., 2015). This measure has been related to improved performance in the vMWM in humans independent of sex and age difference while sex and age tend to be related to more typical measures of navigation such as distance and time taken to perform the task (Daugherty et al., 2015). Moreover, FD has been shown to relate to hippocampal and parahippocampal gyrus volumes in healthy adults when distance and time did not. Finally, the process of computing FD also generates a second component which has not been analyzed in the past in the context of navigation. This second component is known as Lacunarity, and as will be discussed later, it can be thought of as a measure of systematicity of a path. In addition to the introduction of this new path measure, it is the intention of this work to determine which, if any, of a subset of these measures (enumerated in Navigation Analysis Metrics) relate to test-time performance as measured via the metrics of relational and contextual memory discussed in Chapter 3.

In addition to being critical for certain types of spatial navigation, in rodents, the hippocampus also critically organizes memory in terms of the orders of sequences (Fortin, Agster, & Eichenbaum, 2002b; Kesner et al., 2002) and humans (Dede et al., 2016). As mentioned previously, it is unclear of “time” cells measure time in some allocentric space or egocentrically. To illustrate this point, it is useful to consider the spatiotemporal navigation task in more detail. As was described in Chapter 3, participants are able to navigate space and time freely to study the order of a series of events distributed throughout space and time. At the beginning of the first trial, the participant has no knowledge of the location of any event and must search for each of the events (Franz & Mallot, 2000). They may run into a spatially located item and use a form of location navigation called *taxis* navigation (John O’Keefe & Nadel, 1978) to find its temporal location (i.e. simply waiting for the item to perform its event). Taxis in time is more obvious in this task than in more traditional spatial tasks because time is 1 dimensional and always flowing, so a taxis path to an event through time is a straight line in the temporal dimension. On the other hand, taxis in space requires movement in time and is therefore a diagonal line traversing space and time equally. In either case, taxis is a potential navigation strategy once an event location has been identified in either space or time, however in both cases, the distance of taxis is limited by the spatial and temporal distances observable by the participant (i.e. participants can only see events 5 meters spatially in front of them and 2 seconds temporally, due to the animation effect and auditory cue of the events). Eventually, the participant may acquire some simple *topological navigation* strategy where they know the locations of events only in the original order they in which they discovered them. Finding one item in the sequence would create a *recognition triggered response* (Franz & Mallot, 2000; Trullier et al., 1997), enabling them to more easily find the next item. This is consistent with other models of temporal memory which show contiguity effects (Howard et al., 2015). We might also expect recency and primacy effects in which first and last discovered items are better remembered and, therefore, navigated to in early trials. They may need to use a *guidance* strategy (Collett, Cartwright, & Smith, 1986), which involves following a precalculated path between events when the target is not visible (but distal cues in space and time are visible). In an *egocentric* strategy, this might be sufficient, however if an allocentric perspective on the timeline events was formed, a new method of navigation becomes available known is *survey* or *metric* navigation. In this method, a relational organization of the relative spatiotemporal locations of events is learned such that the order of exploration can be used flexibly according to the desires of the individual. It is inevitable that in early trials of this task, most individuals will not find the events in the “allocentric temporal order” (i.e. from the earliest time point in the sequence to the latest). However, it is an empirical question as to whether or not, by trial 4, participants begin to converge on navigating and reconstructing in this allocentric temporal order. If navigation converges to this order, this can be taken as evidence that an allocentric representation of time has been learned by the participants, and this representation is being used as a critical organizing principle for the cognitive map of time (and potentially influence the spatial domain reconstruction as well). This would be suggestive that some subset of the population of cells which would be identified as time cells, which are thought to relate to the temporal locations of events, might, in fact, relate to allocentric temporal points rather than some egocentric perspective on a fixed order of events – it just takes particular task demands to observe this distinction. The analysis methods proposed in this chapter allow us to assess these order-related issues behaviorally.

In summary, this work aims to determine if aspects of navigation relate to relational and contextual reconstruction memory measures. This will be accomplished by examining navigation data from a Spatiotemporal Navigation Task performed by human participants. Additionally, this work aims to provide the first preliminary evidence that hippocampal representations of time may converge to an allocentric map of time via relational memory, hypothesizing that “time cells” identified in the hippocampus may represent this map.

## 4.2 Methods

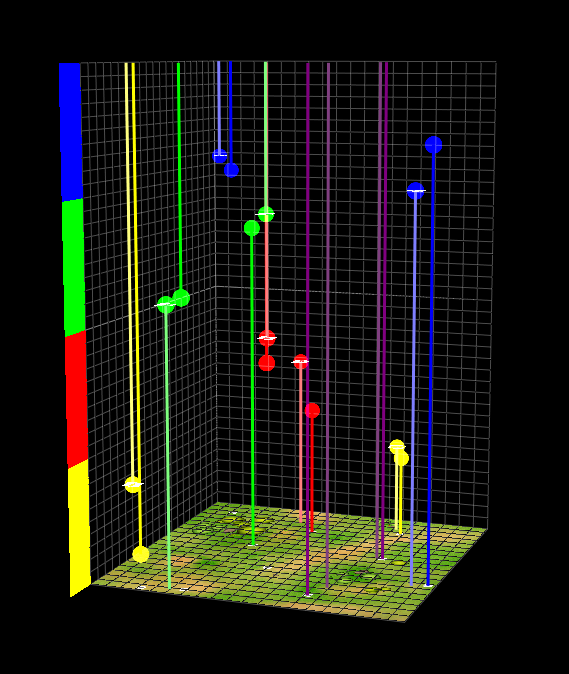
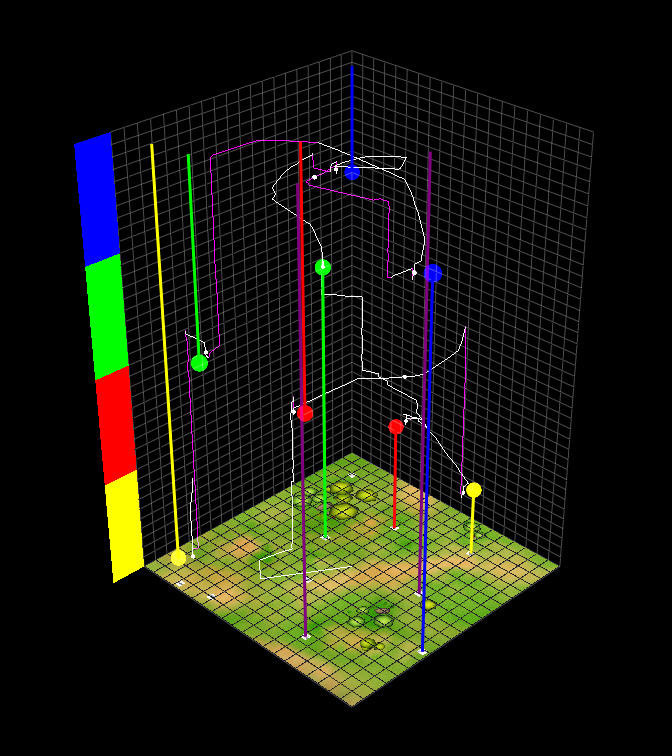
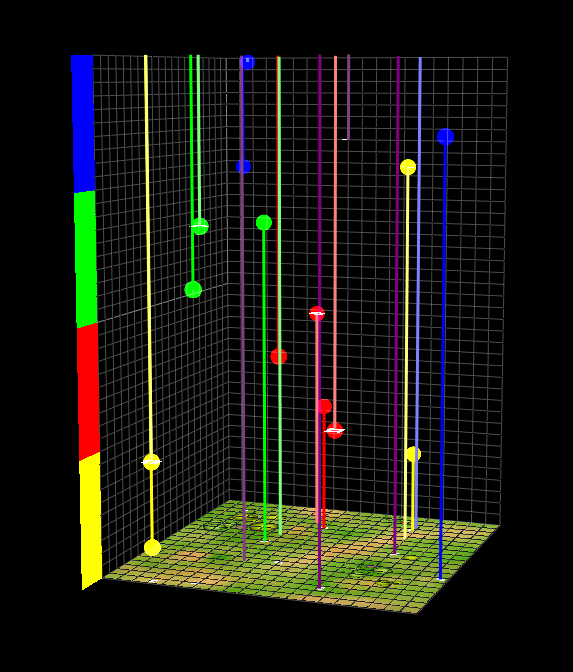
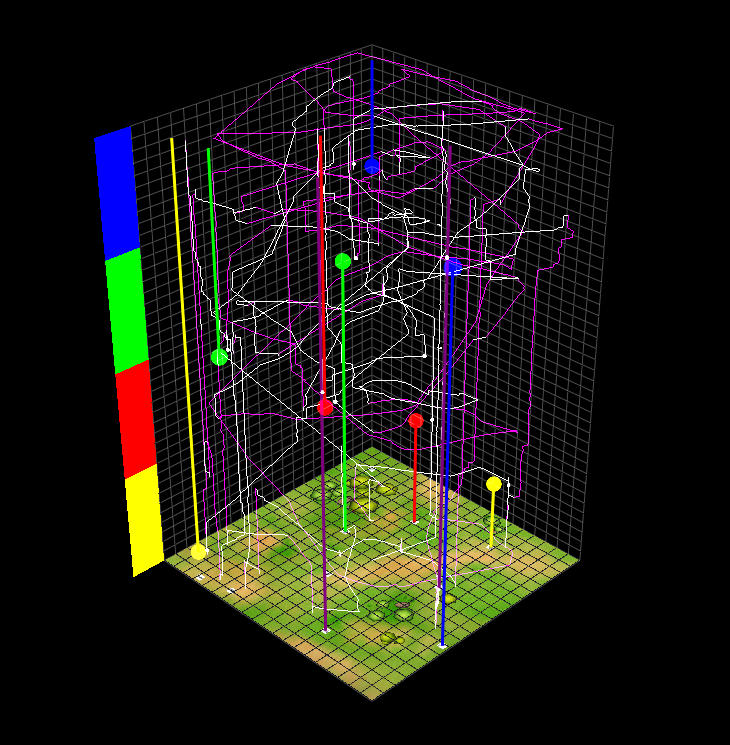
### 4.2.1 Participants

43 participants (ages 18-24; mean 20.0 years; 23 males; 13.8 mean years of education) from the University of Illinois Urbana-Champaign participated in the study. In addition to the 43 participants being analyzed, 4 participants were excluded due to not completing the task within the allotted 2.5 hours. All participants signed informed consent prior to participation, approved by the University of Illinois Urbana-Champaign Institutional Review Board and were paid $8 an hour for their time. Note the Navigation data discussed in this Chapter was collected at the same time as the Reconstruction data collected in Chapter 3.

### 4.2.2 Design and Procedures

This task was identical to the task presented in Chapter 3, so only elements of the task which are critical to Navigation will be reiterated here for clarity.

In this task, participants were placed in a virtual environment measuring 40 meters by 40 meters, bounded by walls on the exterior (see **Figure 1**). The environment resembles a small park with trees, rocks and plants. Participants used the Oculus Rift DK2 and a wireless Xbox controller to interact with the environment. Participants were given a practice to learn the simulation mechanics as well as to gain competency in using the virtual reality hardware. After the practice, 4 study-test trial pairs were given using the same environment as the practice but with new objects and spatiotemporal object-locations. In order to encourage exploration of the environment, an invisibility bubble 10m in diameter was placed around the participant such that any items beyond that distance away from the participant were not visible. An auditory cue was given every time an event happened regardless of whether the item was in view. Item positions were determined via random number generator; however, they were constrained in time to balance for within vs. across context boundary distance. Temporal context information was provided in the form of the simulation boundary walls changing colors at evenly spaced intervals throughout the simulation. Thus, context boundaries were defined as shifts from one color to the next. The colors yellow, red, green, and blue were used for the contextual information, which changed every 7.5 seconds during the 30 second practice and 15 seconds during the 60 second study and test. Each context had two item events during its duration. The order of the temporal contexts was counterbalanced across participants with half receiving yellow, red, green, and blue and the other half receiving blue, green, red, and yellow. Participants could both walk around the environment (and turn their head to look in any desired direction). Temporal navigation was controlled via button press that could reverse the flow of time, at the same speed as the forward flow of time.



**Figure 1**: A schematic of spatiotemporal navigation and reconstruction results from an example participant’s trial 1 and trial 4. The 3D volume represents both axes of space (horizontal axes) and the axis of time (vertical axis). The colored bars on the left indicate the temporal context at each vertical moment in time. The colored circles denote the moments in time in which an event occurred and the line denotes if the item associated with the event would’ve been present at that moment in time. A white exploration line represents forward temporal motion while purple represents backwards. The vertical purple lines are objects with no temporal information (always present). The small white dots during study represent moments of interaction with items. The second set of event dots in test represent the reconstructed spatiotemporal locations of each event. Note the path in Trial 1 study is complex and inefficient while the path in trial 4 is efficient, roughly temporally ordered (D🡪B🡪C🡪F🡪G🡪H🡪E🡪A; note that 5/8 are contiguous and forward-ordered) but not in a strict temporal order. Also note the improvement in reconstruction placement between trials 1 and 4.

Participants’ looking direction and location in space and time were logged at every time point in the simulation (~16ms intervals). If the participant reached the beginning or end of the simulation’s time course, time was paused but the participant was still allowed to freely move about the spatial axes in the environment. During practice and study, participants were instructed to find the locations of each item in space and time, specifically when their events happened. To signify they had found the item at its event, there was a 0.5 second window during which participants could see the item’s event (if close enough) and press a button on the controller to acknowledge they witnessed the event. Participants were given unlimited time to explore the environment, find each item, and acknowledge they had viewed each event.

During test, participants were asked to reconstruction the spatiotemporal location and identity information associated with each event. See Chapter 3 for more description on test-time data and analyses.

### 4.2.3 Navigation Analysis Metrics

The study and test time navigation data are analyzed using several methods, leveraging previous work in spatial navigation but extending these analyses to spatiotemporal navigation and determining if study-time navigation relates to later test performance. Chapter 3 showed the most basic method of analysis, a measurement of the distance travelled in space and time. The analysis of the relationship between these high-level metrics and the various test metrics of interest is presented here, however, there are many measures of exploration and navigation which have been applied to spatial navigation in the past which should also be considered. Specifically, analysis methods of theoretical interest which have been previously linked to hippocampally dependent memory will be examined.

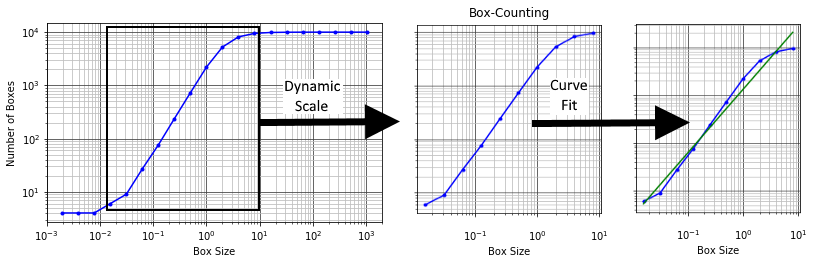
Path complexity, as an index of landmark mapping, has been used in ecological research for over a decade, and, more recently a specific measure of path complexity, fractal dimension (FD), has been linked to improved performance in navigation independent of the sex and age differences seen in typical measures such as distance traveled and time taken to perform the task (a virtual Morris Water Maze; Daugherty et al., 2015). Additionally, in the Daugherty study, both the hippocampus and parahippocampal gyrus volumes in healthy adults were related to FD, but not distance and time. As such, FD will be included in the current analysis as a study-time variable that might relate to later test-time variables of relational memory such as misassignments. The FD measure, which up until this point has only been used in reference to spatial path complexity, will be applied to both spatial and temporal path complexity, and will be one of the critical analyses in this work.

In the analysis of Fractal Dimension, the Box Counting Algorithm will be used to determine how changes in scale relate to changes in the measured complexity of the path. Ultimately, this algorithm involves doing a linear fit and extracting the slope (aka the Fractal Dimension). In previous studies of paths involving complexity measures, the intercept of this fit (aka Lacunarity) has been discarded, however, this measure is of unique interest as it abstractly represents the degree of systematicity of the path (i.e. the negative space of the path at infinitely small scale). A larger lacunarity is associated with less systematicity while a smaller one is associated with more.



**Figure 2**: Comparison of Lacunarity and Fractal Dimension of various lowpass-filtered random walks. The blue dots represent fully random walks, while the Light, Medium, Heavy, and Extreme filtered paths were filtered at with an Order 6 Butterworth Lowpass Filter with an assumed 30S/s sampling rate and frequency cutoffs of 0.4, 0.2, 0.08, and 0.02. Note that low Fractal dimension is often correlated with higher Lacunarity, but they are not equivalent. Lower Lacunarity within a given filter group shows a more systematic filling of the space while higher Fractal Dimension shows an increase in path complexity. Note that all lines are identical in length.

To see how these two measures relate to each other and to the nature of a path, we can observe these measures in the context of filtered random walks. A random walk is one in which a path begins at a particular point (usually (0, 0) in 2D space) and iteratively picks a random direction, moving some distance in that direction. The resulting paths have a fractal-like appearance and are of significant mathematical interest, however by lowpass filtering these paths, we can generate artificial data with various spatial properties in order to examine example paths which have various Lacunarity and Fractal Dimension values. Figure 2 shows 5 groups of randomly generated paths of equal length (10,000 points) with various levels of filtering. Each began as a random walk, but were filtered with an order 6 Butterworth Lowpass Filter with increasingly strict frequency cutoff parameters. The scale parameters for the Fractal analysis were picked dynamically (see Figure 3) by examining a large range of scales and using the standard deviation of the box counting number to remove the asymptotic regions of the measurement (thus, isolating the linear region of interest). Note that in the actual analysis of participant data, the scale range was determined dynamically first, then an identical scale parameter was used for all participants in the final measurement for consistency.



**Figure 4**: Dynamic Computational of Scale Parameters for FD and Lacunarity. In order to avoid issues with determining the precise scale of a path, dynamic scale detection can be used. First, a sufficiently wide range of scales is computed. The result should form a sigmoid where the slope at the center represents FD and the intercept of the line fitted to the center is Lacunarity. To dynamically find scale parameters, the Standard Error is computed for the sigmoid and any values exceeding one Standard Error from the Mean are excluded. This shrinks the scale window the linear region which is fit, extracting FD and Lacunarity from slope and intercept of the green line.

An additional metrics of interest for evaluating the impact of the contextual information on subsequent memory is context boundary crossings. Most studies of context boundaries do not allow participants to arbitrarily cross boundaries and sample contexts freely. As such, it will be interesting to determine if additional context boundary crossings are associated with a larger context boundary effect and more relational memory errors due to context. If context boundary crossings are being used to enhance memory for within context information and separate information in different contexts, we might expect a larger context boundary effect and better within-context relational memory performance to be related to context boundary crossing. However, if boundary crossings are exclusively related to better pattern separation, within context relational memory may be worse the more boundaries are crossed.

Table 1 provides a summary of the analyses and their associated hypotheses. Note that these are still coarse metrics, collapsing all of the information contained within a spatiotemporal path into a single variable. Additional Order analyses (reviewed in the next section) will be necessary to understand the complexity (especially the relational information) contained within the data.

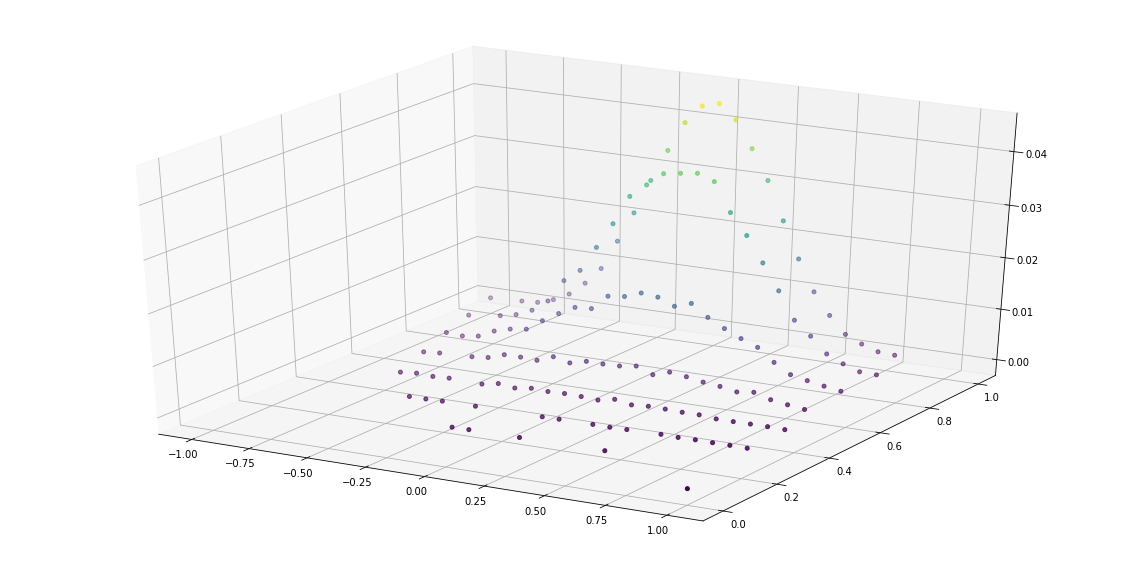
|  |  |  |  |
| --- | --- | --- | --- |
| **Measure** | **Comparison** | **Support** | **Hypotheses** |
| Spatial Distance | All Test Measures | (Maguire et al., 1999; Moffat, 2009; Moffat & Resnick, 2002) | None (exploratory) |
| Temporal Distance | All Test Measures | (B. J. Kraus et al., 2015) | None (exploratory) |
| Fractal Dimension | Relational Memory Error | (Daugherty et al., 2015) | Higher FD will relate to poorer relational memory performance. |
| Lacunarity | Relational Memory Error |  | Lower Lacunarity will related to better relational memory performance. |
| Context Boundary Crossings | Context Boundary Effect & Context-Relational Errors | (Ezzyat & Davachi, 2014; Zacks et al., 2007b) | More context crossings will relate to greater context boundary effects and more context-relational errors. |

**Table 1**: High-level navigation analyses. These analyses can and will be run on space and time in isolation of one another as well as together, when appropriate given the comparisons to test-time metrics.

### 4.2.4 Order Analyses

In addition to the simple navigation metrics which evaluate large amounts of the path (or the entire path) simultaneously, it may be of particular interest to look at the interactions the participants have with the events (and associated navigation) as related to the order of exploration. A prediction made in the introduction of this chapter is that time cells might represent an allocentric perspective on a timeline of events. Indirect evidence for an allocentric timeline might be found in observing the order of study and order of reconstruction of items after the first trial. If participants reliably converge towards reconstruction of the events in the implied “forward” direction of time, this could serve as preliminary evidence that this allocentric perspective on the timeline is what is being maintained in memory (rather than a perspective based on an egocentric attempt to replay the series of events as they happened to be seen in the first or second trials).

Analyzing order in this way can be a complex issue. Recency, contiguity, and primacy effects could lead to particular items receiving specialized treatment by chance or due to an overall bias towards allocentric patterns of reconstruction in time. One potentially robust way to compare reconstruction order is to develop a distance metric for the relative order of events. In other words, given two reconstructed orders (for instance, given A🡪B🡪D🡪C and B🡪D🡪A🡪C, which sequence is closer to the intended A🡪B🡪C🡪D ordering and by how much?). Considerable interest has been given to similar problems in comparing the similarity of sequences of DNA, word strings, and compressed data sequences (Birch, Osborne, & Blunsom, 2010; Bonham-Carter, Steele, & Bastola, 2014; Dinu & Ionescu, 2012; Giancarlo, Scaturro, & Utro, 2009). However, many of these involve a much more general case in which no guarantee of uniqueness of elements in the sequences is provided. Because the task requires each item to be placed precisely once, instead, the distance metric of interest should focus on three primary properties which might define the differences between two permutations. First, the elementwise-agreement of the lists can be used as a general distance metric. More specifically, the Kendall-Tau distance metric is appropriate for this, and it has the added benefit of providing a positive or negative correlation value which, if positive, suggests a closer distance to the forward order and, if negative, suggests a closer distance to the reverse order. Unfortunately, Kendall-Tau is incredibly unforgiving to contiguity effects. As such, a second distance metric which measures the number of contiguous sublists can be applied to generate a 2D space of potential distances between a hypothesized and observed order. This distance can be visualized and its probabilities for a fixed length permutation can be calculated explicitly (Fig 2). Together these two metrics provide sufficient information to determine if exploration or reconstruction order converge to a particular hypothesized order (specifically, the “allocentric” order 1,2,3,4,5,6,7,8, but also potentially other orders of interest such as [8,7,6,5,4,3,2,1] or [2,1,4,3,6,5,8,7]).



**Figure 5**: Discrete probability distribution for the 2D distance space with 8 items. The x and y axes are the distance metrics to analyze order, and the z (vertical) axis is the probability that that distance would be associated with random permutations. Note that near (0.0, 1.0), very high probability states represent extremely unordered lists (i.e. [4,8,2,1,5,7,6,3]). On the other hand, four very low probability states exist, with two of primary interest. The point (1.0, 0.0), circled by a black dotted line, represents the order [1,2,3,4,5,6,7,8] which is the only permutation associated with that point. Similarly, the point (-1.0, 1.0) uniquely represents [8,7,6,5,4,3,2,1]. The other two unique points which balance the two metrics are (-,) ([7,8,5,6,3,4,1,2]; associated with maximum contiguity with minimum element-wise distance) and (-,) ([5,6,7,8,1,2,3,4]).

In summary, this framework for evaluating order information will be used to observe changes in distance of exploration and reconstruction to the allocentric order across trials, predicting that both study-time navigation and test-time reconstruction order will trend towards allocentric order across trials (i.e. the low-probability location of (1, 0) on the above figure).

### 4.2.5 Statistical Analysis

All analyses which compare trial-by-trial performance use repeated measures analysis of variance (rANOVA) using SPSS with Huynh-Feldt correction. Hierarchical Linear Modeling is used in cases of navigation metrics being compared to test performance across trials to determine if changes in a study-time metric predict changes in the related test-time metric. Comparisons which collapsed trials together used either paired-sample, two-tailed t-tests or one-sample, two-tailed t-tests (for comparison to expected chance values). All tests used an alpha value of 0.05 to determine significance.

## 4.3 Results

### 4.3.1 Overall Accuracy and Navigation

Although the relationship of overall accuracy across trials has not been established, the general finding that accuracy and navigation time and distance improve across trials in both space and time was established in Chapter 3.

### 4.3.2 Proposed Navigation Analysis Metrics Predictions

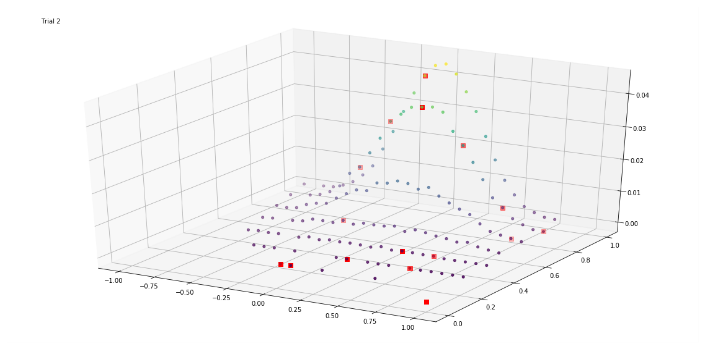
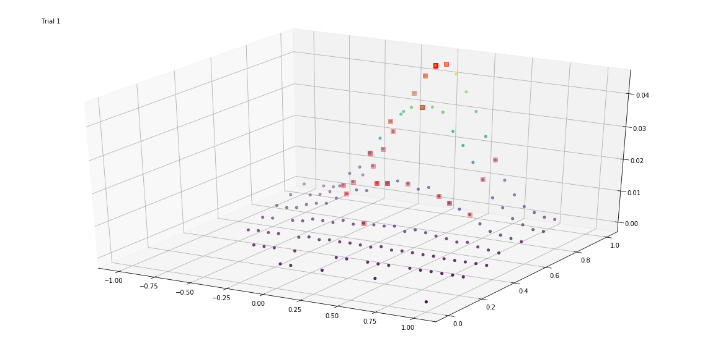
As shown in **Table 1**, although the simplest metrics, spatial and temporal distance, will be treated as exploratory metrics several metrics have specific hypotheses associated with them. In particular, FD is expected to negatively correlate with relational memory performance (such that higher FD will relate to poorer relational memory as judged by identity-location errors).

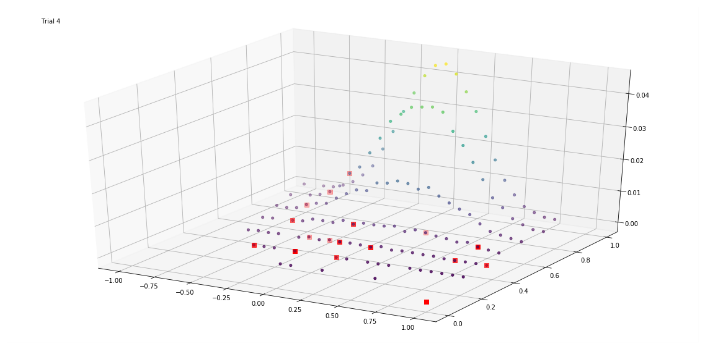
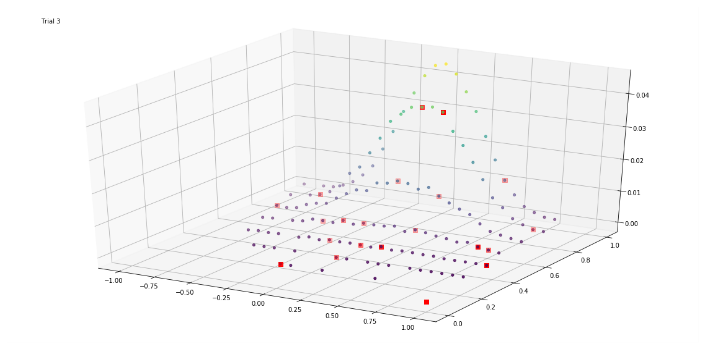
Context boundary crossings are predicted to relate to both context boundary effects (i.e. distance judgements within context being closer than expected and across context being further apart) and relational memory errors relative to context (i.e. the number of identity-location misassignments within vs. across context boundaries). Context crossings are predicted to positively correlate with context boundary effects such that more crossings mean more separation of contextually dependent information. Crossings are also expected to positive correlate with relational memory errors relative to context as viewing of within context information repeatedly in opposite directions might result in poorer memory for the relative order of within-context information (especially if the contexts are being used as the primary organizing principle).

Lastly, individual item sampling is expected to have a U shape relationship with subsequent memory for items. Items which are viewed extremely sparingly are predicted to reflect information which the participant already knows sufficiently well to not warrant attention while items which are viewed excessively may be associated with some prior difficulty in remembering that item which will not result in over-emphasis on its location. Items which are neither over-viewed nor under-viewed would, therefore, be predicted to be the worst remembered. This may be reflected in the absolute misplacement of each item, the relational memory component of each item, or the precision (i.e. leftover misplacement after correction) of each item.

### 4.3.3 Proposed Order Analyses Predictions

I predicted that both study-time navigation and test-time reconstruction order will trend towards allocentric order across trials, suggesting that the participant is acquiring an allocentric temporal representations which is independent of their incidental exploration and navigation behaviors during learning (see **Figure 3** for an illustration of hypothesized data). This result would be highly suggestive that time cells in the hippocampus may code for an allocentric representation of time, much in the same way that place cells code for allocentric spatial locations related to distal cues.





**Figure 6**: Simulated data in proposed 2D distance metric for evaluating order of exploration and reconstruction. Each dot represents a possible distance value for a permutation of length 8 (i.e. the number of temporal items in the task). The height/color of the dot corresponds to its probability of occurring in the space of all length 8 permutations. The red dots represent trial-over-trial simulated data, sampled from the original, random distribution transitioning via an exponential learning curve to a hypothesized “allocentric” distribution (centered on the front, (1, 0) coordinate). The trials numbers are written in the corner of each image. Note that in this simulated data, and the net motion of the dots is towards the hypothesized point, suggesting an allocentric strategy being used by participants.   
See https://www.youtube.com/watch?v=-cg58a97Pz0 for an animation of this figure.

## 4.4 Discussion

While the full pattern of results will, of course, only be apparent upon completion of this dissertation, there are still several points of interest for this investigation worthy of comment. Coarse navigation metrics such as those in Table 1 miss an enormous amount of the fidelity in this task, however, much of the moment-to-moment decision making in this task is currently beyond the reach of our ability to make inferences. Even in the simplest cases (such as the order of study of events), the inference of the intention of the participant becomes a critical one. This work, however, will likely inform future studies and highlight two primary strategies for future investigation: First, careful task design can strengthen the power of the analyses by restricting some possible strategies and intentions. For instance, restricting the spatial axis to 1D might help us determine if the differences in spatial and temporal memory are due to the spatial domain containing more information or due to the additional manipulations in the temporal domain. Secondly, as artificial intelligence via Deep Learning continues to advance, we are presented with the unique opportunity to use these systems as points of comparison to real neural systems. Deep Learning systems (such as Asynchronous Advantage Actor-Critic, A3C models; Juliani, 2016; Mirowski et al., 2017) can now perform astounding navigation tasks such as solving mazes using only visual input, motor output, and a simple reward signal (i.e. with no special knowledge of the environment or system beyond some sense of “good” and “bad” results of behavior). These systems may be modelled after biological systems, but they operate in very distinct ways. Nonetheless, they are now capable of performing may of the same complex navigation tasks that simple organisms can, and moreover, we can manipulate them in any way imaginable (and as often as we would like). This provides a fantastic test platform for theoretical approaches to navigation analysis which should not be ignored by cognitive science. Collaborations with deep learning researchers and cognitive scientists do exist (viz., Kumaran, Hassabis, & McClelland, 2016), but they are not nearly as common as one would hope given the power of these systems to make and test predictions about information processing and behavior.

The current work seeks to not just to examine spatiotemporal navigation in the same way as other researchers, but it also proposes a novel method of gathering early evidence that hippocampal representations of time may converge to an allocentric map of time via relational memory, hypothesizing that “time cells” identified in the hippocampus may represent this map. Although it is widely accepted that place cell firing is related to allocentric information relative to distal cues in the environment, other cell types which fire related to a variety of other relations have been identified. These include grid cells which fire in accordance with periodic spatial location arrays, cells that fire in accordance with goal vectors (Sarel et al., 2017), head-direction cells (Ranck Jr, 1984; Taube, Muller, & Ranck, 1990), time cells (B. Kraus et al., 2013), distance cells (B. J. Kraus et al., 2015), time-distance cells (that fire in relation to both variables), and cells that signal borders and speed (T. Hartley, Lever, Burgess, & O’Keefe, 2013; Kropff, Carmichael, Moser, & Moser, 2015). A naïve view of these cells might say that various tissues in the hippocampus are dynamically mapping to navigation (and only navigation). However, substantial evidence links hippocampal function to far more than just navigation (see Cohen & Eichenbaum, 1991 for a review of these arguments). A much more robust perspective would suggest that the hippocampus performs arbitrary binding and does so with any and all relevant domains of information. In the navigation view, one might interpret time cell firing as a simple navigatory pattern related to the egocentric time an organism has experienced in a particular context. However, if a more relational view of information processing is used, the time cells might be thought to be performing a more general binding operation – relating events within the temporal domain to create a map of a series of events. Electrophysiological evidence in rodents supports this as hippocampal networks have been shown to associated spatial and nonspatial dimensions (McKenzie et al., 2014). Task demands will, of course, dictate the degree to which such a map is necessary (as has been proposed by other; Ekstrom & Ranganath, 2017), but given the consistency with which causal temporal patterns in natural environments occur, forming an allocentric understanding of events has a clear advantage in the flexible use of that information. Indeed, in rodents, humans, and monkeys, recording studies have shown hippocampal involvement in mapping the time course of events independent of space (B. J. Kraus et al., 2015; B. Kraus et al., 2013; Naya & Suzuki, 2011; Pastalkova, Itskov, Amarasingham, & Buzsaki, 2008; Paz et al., 2010; Spiers, Burgess, Hartley, Vargha-Khadem, & O’Keefe, 2001). Ultimately, these questions will have to be answered via electrophysiological evidence, but early behavioral work, like the work presented here, may provide hints that this evidence exists. If exploration converges to an allocentric temporal navigation order (rather than, say, rehearsing the initially seen ordering which occurred by chance), this suggests that this allocentric order is being used as an organizing principle for memory in the task.

In summary, I believe this task and the associated methods provide a unique opportunity to study navigation and information sampling in space and time to further our understanding of navigation and memory organization. Moreover, if this experimental paradigm is to be used in follow-up experiments as have been suggested throughout this document, the exploratory elements suggested in this chapter will help us understand what aspects of navigation in the task will be good targets for further examination outside of the scope of this dissertation.

# Chapter 5: General Discussion

## 5.1 Summary of Results

The previous three chapters have shown a variety of data from both hippocampal damaged individuals as well as healthy adults which together establish a methodological framework which can be used to analyze and understand behavior in reconstruction tasks in any domain. Critically, certain error metrics associated with the ability to retain arbitrary relational information are identified as being related to hippocampal function via observing differences in these metrics between hippocampal damaged patients and controls. These same errors are then evaluated in healthy individuals in other domains to determine if two, omnipresent domains, i.e. space and time, have any differences in the relative commonality of these errors. In order to study space and time simultaneously, however, one additional manipulation is required to allow sampling of spatial and temporal information to be on more equal footing. By allowing participants to “time travel”, a bias which would have been present on temporal information (namely the typical inability to control what temporal information to sample and when) is balanced to allow for a more direct comparison of spatial and temporal memory. Finally, because this manipulation provides a new axis upon which sampling can occur, this sampling behavior can also be studied in time independently of spatial sampling. Together, the results show that arbitrary relational information (whose representation relies on the hippocampus) critically underpins reconstruction performance in both domains, but relational information in time may be represented with different constraints than spatial information, causing unique biases in the ability to retain relational representations in each domain. The presence of contextual information also biases the representation such that both distance judgements errors and relational memory errors occur more often (with distance judgement errors occurring across contextual boundaries and relational memory errors occurring within them). Finally, the sampling of the temporal domain may hint at the fact that substrates of the hippocampus which bind temporal relational information (i.e. “time” cells; B. Kraus et al., 2013) are, under some circumstances, mapping an allocentric representation of time which is fundamentally relational in nature.

In the second chapter, a framework for the analysis of reconstruction errors which attempts to assess many of the same informational metrics of previous work (Jeneson et al., 2010; Watson et al., 2013) but from a first-principled approach with minimal assumptions is introduced. Within this framework, misplacement, i.e. the sum of the Euclidean error in space in reconstruction, is treated as a coarse but fundamental measure of error. Misplacement, under this assumption, can then be broken into different error metrics in accordance with aspects of information which were not present in the reconstruction. Most importantly, identity information (i.e. the information which allows items to be distinguished from one another) is removed from the reconstruction during the first step of analysis to determine aspects of the spatial relationships between items and environment which are impaired. This includes evaluating the overall amount of translation, scaling, and rotation shared by items as well as the remaining local misplacement and accuracy for each item’s location information. Once these spatial errors are determined, the identity-related errors can be reinstated within this informational framework to determine if item identity is being misrepresented in a systematic way. The finding in this chapter shows that hippocampal damage impairs the ability to bind arbitrary identity information to locations, but it does not impair the ability to remember the locations themselves. Moreover, this impairment in identity information is fundamental, in that there is no evidence that it is due to compound identity errors in which multiple identities are systematically swapped/cycled amongst different positions. Although swaps and cycles are evaluated in this work and do uniquely occur at low item set sizes in hippocampal damaged patients, once both patients and comparison participants begin making the prerequisite error (i.e. any identity-location misassignment), there is no difference in the number of compound errors between groups. This finding is distinct from previous work on spatial reconstruction which showed significant differences in swapping at all set sizes (though most significantly at low set sizes; Watson, Voss, Warren, Tranel, & Cohen, 2013). The reason for this difference is in the increased sensitivity and specificity of the methods presented in this second chapter over those previous methods.

In the third chapter, the methodology established in the second chapter is applied to a more complex task in which both space and time are explorable domains, simultaneously; this task is known as a Spatiotemporal Reconstruction Task, or, if the path of the participant through the environment is of interest, a Spatiotemporal Navigation Task. In this task, participants were asked to reconstruct events in space and time while being allowed to simultaneously explore both domains. Although space was explored via translation, as usual, time was also allowed to be explored translationally via a “time travel” button which allowed the reversal of the direction of the flow of time. Participants performed this task on the same timeline of events, 4 times, and their performance on spatial, temporal, and item identity information improved across all trials. The identity-location misassignment metric introduced in the second chapter was used to assess difference between spatial and temporal relational memory across trials and found that significantly more temporal misassignments (i.e. events placed at the moment in time of another event) were committed that spatial misassignments. Additionally, the task contained 4 distinct temporal contexts (denoted by a change in the background color of the environment every 15 seconds) which could be used to help organize memory for temporal location information. A Context Boundary Effect (DuBrow & Davachi, 2013) was observed which showed a bias created by the contextual information such that items within the same temporal context were placed closer together than items which were in adjacent temporal contexts despite being equidistant. This effect did not diminish across trials, suggesting it reflects an underlying organizational principle for the temporal information. Moreover, this contextual information biased the misassignment information such that events were far more likely to be misassigned to another temporal location of an event with which it shared a context than would be expected by chance. Together, this evidence shows the critical interplay of contextual and relational information in the temporal domain and hints at differences in the ability to form relations in the temporal domain when compared to the spatial domain. Additionally, it shows that the influence of contextual information is likely not due to an error per se, but it reflects an organizational principle guiding memory.

In the fourth chapter, the Spatiotemporal Navigation task presented in chapter three is examined through the lens of navigation, rather than reconstruction, in order to determine the degree to which differences in exploration behavior can predict differences in test time performance. This chapter is currently incomplete (though the data has been collected), but several analyses are suggested based on prior work in spatial navigation (Daugherty et al., 2015; Howard Eichenbaum, 2017b; Kolarik et al., 2017) and some predictions are made based on work in space and time representations in the hippocampus (Howard Eichenbaum, 2017d). Moreover, analyses of the order information contained within navigation and reconstruction are suggested which might reveal whether an allocentric form of navigation is present for temporal navigation in much the same way as spatial navigation. This would, therefore, make the prediction that “time” cells in the hippocampus (B. Kraus et al., 2013) map an allocentric perspective on time, representing relational information between temporal events.

## 5.2 Separable vs. Separate Hippocampal Representations

There has been a great deal of debate in the literature over the separateness of different informational domains in the hippocampus. A common perspective is that major domains such as space and time provide a scaffolding in which binding of information from and to other domains might be embedded (Ekstrom & Ranganath, 2017). Relatedly, tasks which show hippocampal involvement in relations outside of the spatial or temporal domain have recently shown that hippocampal representations may move beyond the constraints of this scaffolding if task demands require (Howard Eichenbaum, 2015; Tavares et al., 2015; Warren et al., 2015). However, one crucial question has yet to be completely addressed: are different domains represented separately in the hippocampus or in some sort of alternate, overlapping representation? The data here cannot completely disentangle these possibilities (or the spectrum of possibilities in-between), but the techniques presented here, in addition to neuroimaging and patient behavior studies, may eventually elucidate the answer to this question. In the Spatiotemporal Reconstruction task, differences in relational information were seen in space and time, suggesting these domains may, in fact, be separate. They may be, for instance, multiplexed versions of the same representational ideal with cells switching between representing spatial and temporal information. Alternatively, the representations may overlap insofar as the task demands warrant it. This would suggest that in a task such as the spatiotemporal navigation task, cells which code for time and space should fire together. However, if temporal or spatial information were biased in some way (via attention, task manipulation, reward, or some other method), the degree of overlap between the domain representations may change. This hypothesis leads to a wider suggestion about domain representations in the hippocampus, namely, that hippocampal relational representations are *separable* but not necessary *separate*. This idea is consistent with relational memory theory (Neal J. Cohen & Eichenbaum, 1993) but extends the prediction that all arbitrary relationships are obligatorily bound in the hippocampus to say that the cell firing in association with the domain of information will depend on demands related to that domain (such as task, reward, attention, context, and emotion). Along these lines, cellular recording evidence has been presented showing time-selective and distance-selective cell firing overlapping as often as would be predicted by a joint distribution of both variables (B. J. Kraus et al., 2015). The behavioral evidence here also suggests a variable degree of interaction between spatial and temporal relational information as well as variable interactions with contextual information. The ability of the hippocampus to adjust to task demands to determine the degree of separability of encoding of different variables may be a critical component in memory representations, and as such, the distinction between hippocampal representations being separable, rather than separate, may be of fundamental importance to understanding the structure of hippocampally dependent memory in general.

## 5.3 Behavioral Inference, Sampling, and Task Richness

Two key contributions of this work are worth reiterating. First, the methodological framework presented in Chapter 2 and utilized in Chapter 3 approaches the issue of understanding information present in a spatial reconstruction from a principled perspective. That is to say, an attempt is made to make as few assumptions as possible about the nature of the high-level structure of the performance and subsequent data in the task, treating it as an information-containing system with no other significant preconceptions. The assumptions are enumerated in that chapter, any of which imply a particular set of choices for analysis. This means that in cases like the comparison of hippocampal damaged patients to comparison participants, adjustments to the assumptions (i.e. the assumption that participants will generally be accurate at placing items back in roughly the right positions) have associated adjustments in the methodology (i.e. using the accuracy threshold from the comparisons in which the assumption should be valid as the threshold for the patients). Similarly, other aspects of the method assume certain transformations might be present within the item-item and item-environment relational information (i.e. translation, scaling, and rotation), but the method allows for different transformations to be tested together or in isolation of one-another. Most importantly, by keeping the methodology general, it can be easily applied to other domains (i.e. time), domains with even more dimensions (i.e. 3D space), or even domains with stranger properties (see the Introduction for more information on possible properties of domains). In this way, the tools used to study representations in reconstruction do not have to change as we expand the domains into which we would like to perform these analyses.

The second contribution which has not been emphasized up until now is the combination of navigation behavior with reconstruction in multiple domains, simultaneously. This allows for three important secondary impacts on the study of memory. 1) The ability to navigate domains other than space allows the study of the impact of exploration and navigation in different domains on subsequent memory. 2) The ability to simultaneously navigate multiple domains means that exploration/navigation behaviors and preferences between domains can be examined (i.e. is there a “hierarchy” of domains and how flexible is such a domain preference; McKenzie et al., 2014). 3) The overall richness of this task as well as the resulting findings shows that many of the effects observed in more restrictive behavioral tasks will still be present when the task is more ecologically realistic (and more difficult). This added richness also affords more information and control with which to make observations and predictions about the interplay of different behaviors (navigation and reconstruction) and the brain systems which may support different types of information (scene sampling, contextual information, relational information, and more). In summary, by embracing the rich, complex possibilities available with modern behavioral platforms such as Virtual Reality, we obtain an equal richness and complexity of scientific inquiry.

## 5.4 Artificial Intelligence and Spatial Reconstructions

One field which is intimately related to the work presented in this document which has yet to be addressed is Machine Learning and Artificial Intelligence. These cognitive and behavioral concepts may become more critical to the development of artificially intelligent (AI) systems in the coming decades as advances in deep learning systems which go beyond reinforcement learning begin to emerge. Spatial reconstruction, as a task, is an incredibly difficult one for AI systems to perform. In particular, the incredible degree of variability in environments makes navigation in general a challenge. To add on to this the requirement that specific, arbitrary information about elements of the environment need to be remembered and used flexibly at some unknown point in the future makes the task beyond the scope of what current AI can successfully do. Recent advances in deep learning have developed systems which can navigate environments in an end-to-end fashion (i.e. mapping visual input to motor output without any additional “cheating” information provided by the programmer; Mirowski et al., 2017). These systems, however, likely lack the flexible, relational memory representations necessary to perform reconstruction. Some recent work has shown networks which can be trained to understand spatial relational information (Santoro et al., 2017), however, it is unclear how related these representations are to real brain representations (despite the attempts of some authors often make to architect their systems similarly to biological systems at a coarse level). Spatial reconstruction tasks which also involve navigation may serve as a crucial test platform for future AI to determine the degree of flexibility of their representations. Moreover, spatial reconstruction in humans typically involve only one viewing of the information in question. Although so-called “one-shot” learning (Shaban, Bansal, Liu, Essa, & Boots, 2017; van der Spoel et al., 2015) is a topic of intense interest in AI, the ability for navigation systems to perform one-shot learning is still lacking. Representational systems which can perform computational like what is thought to occur in the hippocampus may serve as one of the major improvements on deep learning AI in the coming decades, bridging the performance gap on general tasks (and potentially tasks which require creativity) between humans and AI.

## 5.5 Conclusion

Our understanding of hippocampally-dependent memory organization has come a long way in the past several decades, and with the advent of new technologies and theoretical frameworks, the pace of discovery does not seem to be abating. Here, it has been shown using a new methodological framework that the hippocampus is necessary for some, but not all, relational information (critically, the arbitrary information but not the location information). These same methods were then applied to a novel task, the Spatiotemporal Reconstruction tasks, which allows for spatial and temporal relational memory and the influence of context to be examined simultaneously. Far more temporal relational memory errors are present in this task than spatial relational memory errors despite the ability to freely navigate time and space, and these errors are heavily influenced by contextual information. The Context Boundary Effect, in which events in time are placed closer together within a context and further apart when separated by a boundary despite being equidistant, is observed in time despite the ability of participants to cross the boundaries in either direction and as often as desired and despite repeated restudy of the same events. Moreover, the relational memory errors are far more common within a context than would be expected by chance, suggesting that the contextual information is not just biasing distance judgements but also order information in a disadvantageous way. Finally, navigation behavior in spatiotemporal navigation is examined to determine if particular aspects of navigation is space and time predict later performance and relational or contextual memory errors. This same navigation behavior can provide hints as to whether or not temporal representations in the hippocampus are allocentric in nature, with navigation tending towards an allocentric perspective (i.e. exploring a timeline in an A🡪B🡪C order rather than an egocentric order based on when particular events happen to be seen). The richness of Spatiotemporal Navigation and Reconstruction has provided (and will likely to continue to provide) interesting findings on the interplay between navigation in space, navigation in time and how these ultimately may relate to navigation in memory.

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