## Extract an unknown function in a non-parametric way

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1 The standard Bayes approach already contains the "sequential" calibration of parameters.

3 A non-parametric way to parametrize the unknown functional of  $\hat{q}(T)$ .

## The standard Bayes approach

Suppose the following dependence of two sets of observables y on parameters x.

- $\mathbf{y}_1 = \mathbf{y}_1(x_1)$  only depends on  $x_1$ .
- $\mathbf{y}_2 = \mathbf{y}_2(x_1, x_2)$  depends on both  $x_1, x_2$ .

Suppose, people have measured  $\mathbf{y}_1$  long ago in the past:  $\mathbf{y}_1^{\mathrm{exp}} \pm \delta \mathbf{y}_1^{\mathrm{exp}}$ , and then someone used it to extract information of  $x_1$ ,

$$P_1(x_1) = \operatorname{Prior}(x_1) \operatorname{Likelihood}\left(\frac{\mathbf{y}_1(x_1) - \mathbf{y}_1^{\exp}}{\delta \mathbf{y}_1^{\exp}}\right)$$

Few years later,  $\mathbf{y}_2^{\mathrm{exp}} \pm \delta \mathbf{y}_2^{\mathrm{exp}}$  are measured, but we don't want to vary  $x_1$  arbitrarily when extracting  $x_2$ , so we use  $P_1(x_1)$  as informative prior:

$$P_{12}(x_1, x_2) = P_1(x_1) \operatorname{Prior}(x_2) \operatorname{Likelihood} \left( \frac{\mathbf{y}_2(x_1, x_2) - \mathbf{y}_2^{\operatorname{exp}}}{\delta \mathbf{y}_2^{\operatorname{exp}}} \right)$$

$$= \operatorname{Prior}(x_1) \operatorname{Prior}(x_2) \operatorname{Likelihood} \left( \frac{\mathbf{y}_2(x_1, x_2) - \mathbf{y}_2^{\operatorname{exp}}}{\delta \mathbf{y}_2^{\operatorname{exp}}} \right) \operatorname{Likelihood} \left( \frac{\mathbf{y}_1(x_1) - \mathbf{y}_1^{\operatorname{exp}}}{\delta \mathbf{y}_1^{\operatorname{exp}}} \right)$$

The same as calibrated to both dataset simultaneously.



## The subtly is in the parametrization of unknown functionals

For example, usually, we try temperature dependence of  $\hat{q}$ 

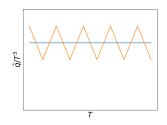
$$\frac{\hat{q}}{T^3} = A + B \left(\frac{T}{T_c}\right)^C$$

The problem: A, B, and C controls the temperature dependence in a highly correlated manner  $\rightarrow$  May leads to correlated change of all parameters when we include new dataset.

Step-function like parameterization

$$\frac{\hat{q}}{T^3} = a_0(1 \sim 1.5 T_c) + a_1(1.5 \sim 2 T_c) + a_2(2 \sim 2.5 T_c) + a_3(2.5 \sim 3 T_c) + a_4(3 \sim 4 T_c)$$

Decorrelate from one temperature to another. Potential problem: lack of adjacent correlation:



To avoid the yellow case, we can manipulate the choice of prior in a correlated way! Not long range correlation, but finite-range correlation that  $P_0(x \to x_1) = P_1(x_1)$ .  $\to$  no need to change the model computation procedure, just need a carefully designed prior.

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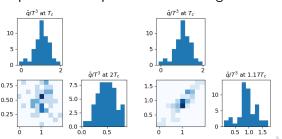
# A proposed way to parametrize unknown functional form of $\hat{q}/T^3$

- Treat  $\hat{q}/T^3$  as some unknown function in a functional space that:
  - ▶ If I know  $\hat{q}/T^3$  at low temperature, I am still agnostic to its high-T behavior.
  - If I know  $\hat{q}/T^3$  at  $T_1$ , its value at adjacent temperature must be close to the value at  $T_1$ .
- Easily modeled by a random function sampled by the Gaussian process.

$$P[\hat{q}(T)] \sim \mathcal{GP}\left( ext{mean} = \hat{q}_0, ext{cov} = Ce^{-rac{(\ln T - \ln T')^2}{2\sigma^2}} 
ight)$$

14 12 10 10 15 20 25 30 35 40 10 15 20 25 30 35 40

"Infinitely" many points, but effectively only  $\frac{\ln(T_{\text{max}}/T_{\text{min}})}{\sigma}$  d.o.f.. A smooth version of "independently vary"  $\hat{q}$  at temperature far apart with short-range correlation.



### Workflow

#### Run physical model:

- Generate, e.g. 100, realization of  $P[\hat{q}(T)]$ .
- Model predictions: centrality, energy, collision system,  $p_T$  dependent.

The following jobs is purely statistical.

- The fact that the parameterization  $\hat{q}(T)$  is uncorrelated from  $\hat{q}(T')$  if T and T' are sufficently different prevents low-T-sensitive data from constraining high-T parameters.
- Use emulators to learn the mapping from  $\hat{q}(T_i, i = 1, 2, 3 \cdots)$  to observables.
- Using Bayes theorem to get the posterior distribution of  $\hat{q}$ :

$$P(\hat{q}[T]) = \int D[\hat{q}(T)] P_{\mathcal{GP}}[\hat{q}(T)] \text{Likelihood}(\frac{\mathbf{y}_{\text{emulator}}[\hat{q}(T)] - \mathbf{y}^{\text{exp}}}{\delta \mathbf{y}^{\text{exp}}})$$

A non-parametric way to extract  $\hat{q}(T)$ 

I do not know any application like this before in literature. We may need to use a "toy" model to evaluate its performance before using real model.