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Fractional Brownian Motion and its Application in Financial Mathematics

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Abstract

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1 Introduction

2 Gaussian Process and Brownian Motion

In this section we start off the general concept of probability spaces and stochastic processes. Of this, a most important case we then discribe, is Gaussian process. It bring us to introduce the Brownian Motion as a fine example.

2.1 Probability Space and Stochastic Process

DEFINITION 2.1. Let \mathscr{A} be a collection of subsets of a set Ω . \mathscr{A} is then a σ - Algebra on Ω if it satisfies the following conditions:

- (i) $\Omega \in \mathscr{A}$.
- (ii) For any set $F \in \mathcal{A}$, its complement $F^c \in \mathcal{A}$.
- (iii) If a serie $\{F_n\}_{n\in\mathbb{N}}\subseteq\mathscr{A}$, then $\cup_{n\in\mathbb{N}}F_n\in\mathscr{A}$.

DEFINITION 2.2. A mapping \mathcal{P} is said to be a *probability measure* from \mathscr{A} to $\mathscr{B}(\mathbb{R}^n)$, if $\mathcal{P}\left[\sum_{n=1}^{\infty}F_n\right]=\sum_{n=1}^{\infty}\mathcal{P}\left[F_n\right]$ for any $\{F_n\}_{n\in\mathbb{N}}$ disjoint in \mathscr{A} satisfying $\sum_{n=1}^{\infty}F_n\in\mathscr{A}$.

DEFINITION 2.3. A probability space is defined as a triple $(\Omega, \mathscr{A}, \mathcal{P})$ of a set Ω , a σ -Algebra \mathscr{A} of Ω and a measure \mathcal{P} from \mathscr{A} to $\mathscr{B}(\mathbb{R}^n)$.

The σ - Algebra generated of all open sets on \mathbb{R}^n is called the *Borel* σ - Algebra which we denote as usual by $\mathscr{B}(\mathbb{R}^n)$. Let μ be a probability measure on \mathbb{R}^n . Indeed, $(\mathbb{R}^n, \mathscr{B}(\mathbb{R}^n), \mu)$ is a special case that probability space on \mathbb{R}^n . A function f mapping from $(\mathcal{D}, \mathcal{D}, \mu)$ into $(\mathcal{E}, \mathscr{E}, \nu)$ is measurable if its collection of the inverse image of \mathscr{E} is a subset of \mathscr{D} . A random variable is a \mathbb{R}^n -valued measurable function on some probability space. Let \mathscr{P} represent a probability measure, recall that in probability theory, for $B \in \mathscr{B}(\mathbb{R}^n)$ we call $\mathscr{P}[\{X \in B\}]$ the distribution of X. We write also $\mathscr{P}_X[\cdot]$ or $\mathscr{P}[X]$ for convenience of the notation above.

DEFINITION 2.4. Let $(\Omega, \mathscr{A}, \mathcal{P})$ be a probability space. A *n*-dimensional *stochastic* process (X_t) is a family of random variable such that $X_t(\omega): \Omega \longrightarrow \mathbb{R}^n, \forall t \in T$, where T denotes the set of Index of Time.

DEFINITION 2.5. A stochastic process $(X_t)_{t\in T}$ is said to be *stationary*, if the joint distribution

$$\mathcal{P}\left[X_{t_1},\ldots,X_{t_n}\right] = \mathcal{P}\left[X_{t_1+\tau},\ldots,X_{t_n+\tau}\right]$$

for t_1, \ldots, t_n and $t_1 + \tau, \ldots, t_n + \tau \in T$.

Remark that, definition 2.5 means the distribution of a stationary process is independent of a shift of time.

2.2 Definition of Gaussian Process

DEFINITION 2.6 (1-dimensional normal distribution). A \mathbb{R} -valued random variable X is said to be *standard normal distributed*, if its distribution can be discribed as

$$\mathcal{P}[X \le x] = \int_{-\infty}^{x} (2\pi)^{-\frac{1}{2}} e^{-\frac{u^2}{2}} du$$

for $x \in \mathbb{R}$.

DEFINITION 2.7. A \mathbb{R} -valued random variable X is said to be *normal distributed* with a mean μ and a variance σ^2 , if

$$(X-\mu)/\sigma$$

is standard normal distributed.

We use a notation $X \sim Y$, which means X and Y have the same distribution. In similar way it is denoted by $X \sim (2\pi)^{-\frac{1}{2}} e^{-\frac{x^2}{2}} dx$, if it is standard normal distributed. In order to identifing the behaviour of a normal distributed random variable we recall the characteristic function in probability theory, see[1].

PROPOSITION 2.8. Let X be a \mathbb{R} -valued standard normal distributed random variable. The characteristic function of X

$$\Psi_X(\xi) := \int_{\mathbb{R}} e^{ix\xi} \mathcal{P}\left[X \in dx\right] = e^{-\frac{\xi^2}{2}} \tag{2.1}$$

for $\xi \in \mathbb{R}$.

Proof. According the definion of characteristic function

$$\Psi_X(\xi) = \int_{\mathbb{R}} (2\pi)^{-\frac{1}{2}} e^{-\frac{x^2}{2}} e^{ix\xi} dx,$$

take differentiating both sides of the equation by ξ , then

$$\Psi'_{X}(\xi) = \int_{\mathbb{R}} (2\pi)^{-\frac{1}{2}} e^{-\frac{x^{2}}{2}} e^{ix\xi} ix \, dx$$

$$= (-i) \cdot \int_{\mathbb{R}} (2\pi)^{-\frac{1}{2}} (\frac{d}{dx} e^{-\frac{x^{2}}{2}}) e^{ix\xi} \, dx$$

$$\stackrel{part.int.}{=} - \int_{\mathbb{R}} (2\pi)^{-\frac{1}{2}} e^{-\frac{x^{2}}{2}} e^{ix\xi} \xi \, dx$$

$$= -\xi \Psi_{X}(\xi).$$

Obviously, $\Psi(\xi) = \Psi(0)e^{-\frac{\xi^2}{2}}$ is the solution of the partial differential equation above, and $\Psi(0)$ is equal to 1.

In particular, the characteristic function of a normal distributed random variable with a mean μ and a variance σ^2 , which denoted by $\Psi_{X_{\mu,\sigma^2}}(\xi)$, is $e^{i\mu\xi-\frac{1}{2}(\sigma\xi)^2}$. To achieve this result, we just need to substitute x by $(x-\mu)/\sigma$ in the calculation before.

DEFINITION 2.9. Let X be a \mathbb{R}^n -valued random variable. X is said to be *normal distributed*, if for any $d \in \mathbb{R}^n$ such that $d^T X$ is normal distributed on \mathbb{R} .

PROPOSITION 2.10. Let X be a \mathbb{R}^n -valued normal distributed. Then there exist $m \in \mathbb{R}^n$ and a positive definite symmetric matrix $\Sigma \in \mathbb{R}^{n \times n}$ such that,

$$\mathbf{E} e^{i\xi^T X} = e^{i\xi^T m - \frac{1}{2}\xi^T \Sigma \xi} \tag{2.2}$$

For $\xi \in \mathbb{R}^n$. Furthermore, the density function of X is

$$(2\pi)^{-\frac{d}{2}} (\det \Sigma)^{-\frac{1}{2}} e^{-\frac{1}{2}(x-m)^T \Sigma^{-1}(x-m)} dx.$$
 (2.3)

Remark, the equation (2.2) can also be as definition of characteristic function of a n-dimensional normal distributed random variable.

Proof. Since X normal distributed on \mathbb{R}^n , then $\xi^T X$ is normal distributed on \mathbb{R} . Due to the proposition 2.8 there is

$$Ee^{i\xi^T X} = Ee^{i\cdot 1\cdot \xi^T X}$$

$$= e^{iE[\xi^T X] - \frac{1}{2}Var[\xi^T X]}$$

$$= e^{i\xi^T E[X] - \frac{1}{2}\xi^T Var[X]\xi}.$$

According the uniqueness theorem of characteristic function (Satz 23.4 in [1]), then we can deduce the density function of the equation (2.3).

A normal distributed normal random variable can be characterized by its mean and variance respectively mean vector and covariance vector because of the characteristic function.

DEFINITION 2.11. Let $(X_t)_{t\in T}$ be a \mathbb{R}^n -valued stochastic process. (X_t) is said to be a gaussian process if

$$c_1^T X_{t_1} + \dots + c_n^T X_{t_n}$$

has a normal distribution for any $c_1 \cdots c_n \in \mathbb{R}^n$, $t_1 \dots t_n \in T$ and $n \in \mathbb{N}$.

The definition immediately shows for every X_t in gaussian process has a distribution.

3 Fractional Brownian Motion

4 Fractional Ornstein Uhlenbeck Process Model

5 Application in Financial Mathematics

6 Conclusion

References

[1] BAUER, H. (2002). Wahrscheinlichkeitstheorie(5th. durchges. und verb. Aufl.). Berlin: W. de Gruyter