

Chapter 7 Conditional Heteroscedastic Models (Part A)

For time series $\{y_t\}$, denote the information up to time t by

$$I_t = \sigma\{y_t, y_{t-1}, y_{t-2}, \dots\}.$$

- (A) The conditional mean $\mu_t = E(y_t|I_{t-1})$ can be used to predict y_t based on past information I_{t-1} .
- (B) Note that the auto-correlation coefficients in y_t are "almost" 0; the prediction is almost impossible
- (C) How about the conditional variance (risk, or volatility)

$$\sigma_t^2 = \text{cov}(y_t|I_{t-1}) = E\{(y_t - \mu_t)^2|I_{t-1}\}$$

- (D) Definition: asset **volatility** is conditional standard deviation of the asset returns.

(E) Importance of σ_t

(a) Option (derivative) pricing, e.g., Black-Scholes formula

(b) Risk management, e.g. value at risk (VaR)

(c) Asset allocation, e.g., minimum-variance portfolio.

(d) Interval forecasts

(e) σ_t^2 can also help to explain the special patterns in financial data, such as the heavy tail, and **volatility clustering**.

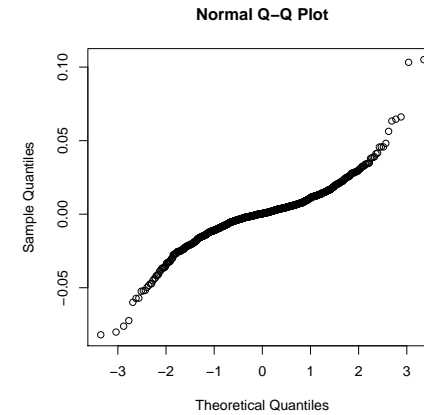
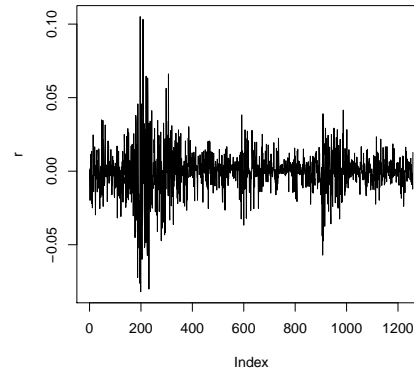
Example 0.1 For the SP500, the daily return r_t from 2008-2013, the original return r_t and standardized residuals

$$(r_t - \mu_t)/\sigma_t$$

are shown below (here $\mu_t = 0$ is assumed). It can be seen that after removing the conditional

standardization, the return follows normal.

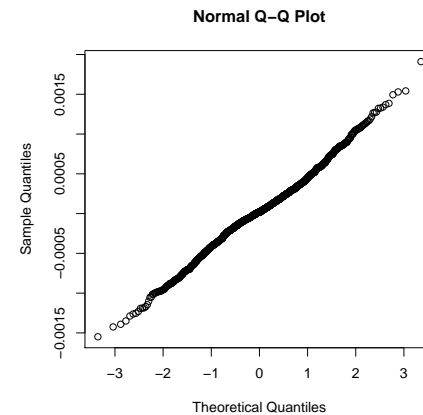
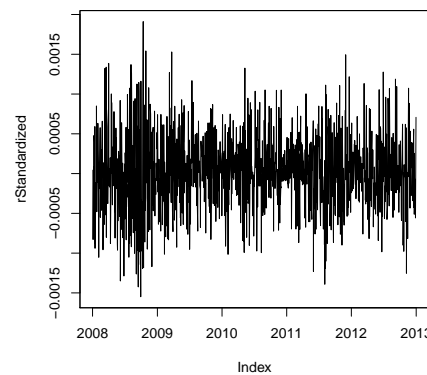
original return:



Stylized facts: volatility clustering, i.e. “large changes tend to be followed by large changes, of either sign, and small changes tend to be followed by small changes.”, or

$$\text{corr}(|r_t|, |r_{t+1}|) > 0$$

return with σ_t removed:

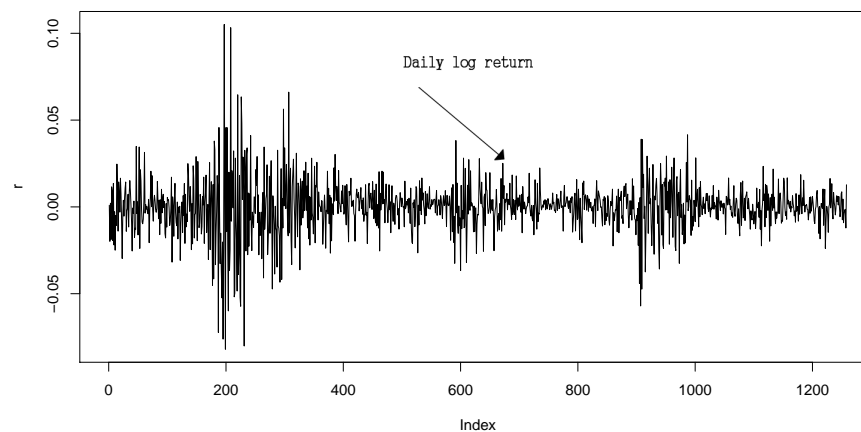


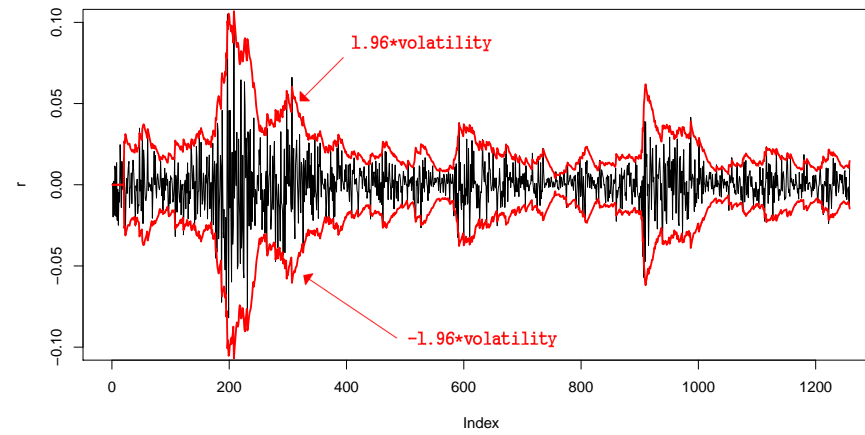
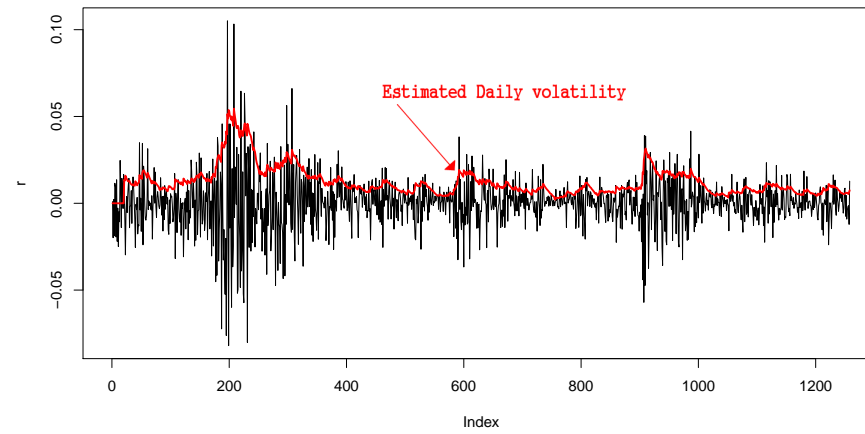
(F) Given I_{t-1} , if we can observe y_t repeatedly (actually we can; all the trading prices in a day), then we can estimate σ_t^2 . This is what people do by using high frequency data. Such as the realized-volatility; see

<http://en.wikipedia.org/wiki/Realizedvariance>

(G) A key problem: σ_t is not directly observable!! So its calculation is an important topic of research

Example 0.2 For DJI from 1/1/2008-1/4/2013; see [code06A1.R](#).

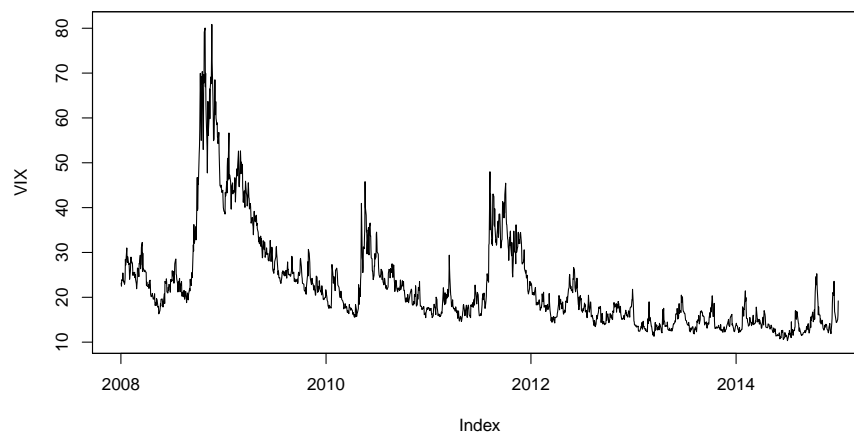




How to calculate volatility?

(A) Use high-frequency data: Realized volatility of daily returns in recent literature: use intraday log returns.

(B) Implied volatility of options data, e.g, VIX (<http://en.wikipedia.org/wiki/VIX>). See Figure below, the data is available in Yahoo <https://sg.finance.yahoo.com/>



(C) weighted average (Exponential smoothing, ARCH, GARCH)

Weighted average approach: exponential smoothing, ARCH, GARCH

(a) Suppose the returns u_i have mean 0, otherwise consider $u_i - E(u_i)$.

(b) We estimate the variance by

$$\sigma_t^2 = \sum_{i=1}^m w_i u_{t-i}^2 \quad (\text{for prediction})$$

or

$$\sigma_t^2 = \sum_{i=0}^{m-1} w_i u_{t-i}^2 \quad (\text{for fitting})$$

where $w_1 + \dots + w_m = 1$. Usually, w_i decreases with i .

(c) m can be infinity providing $w_1 + w_2 + \dots = 1$, a special case is

$$w_k = (1 - \lambda)\lambda^{k-1}, \quad k = 1, \dots$$

$$\sigma_t^2 = (1 - \lambda) \sum_{i=1}^{\infty} \lambda^{i-1} u_{t-i}^2 \quad \text{i.e. } m = \infty$$

(d) This leads to a recurrence formula,

$$\sigma_t^2 = (1 - \lambda)u_{t-1}^2 + \lambda\sigma_{t-1}^2$$

popular choices of λ are close to 1.

For example, RiskMetrics, a financial risk management company, tends to use a λ of 0.94.

See the first plot on page 6.

(e) Note that in the above model, the sum of coefficients of σ_{t-1}^2 and u_{t-1}^2 are respectively λ and $1 - \lambda$,

we can make it more general, leading to GARCH model

$$\sigma_t^2 = \omega + \alpha u_{t-1}^2 + \beta \sigma_{t-1}^2$$

with $\omega \geq 0, \alpha \geq 0, \beta \geq 0$, but $\alpha + \beta \leq 1$.

(f) More general case is the GARCH(p,q) model [Generalized Autoregressive Conditional Heteroskedasticity] to be discussed later.

(g) A special case of GARCH(1,1) is that

$$\alpha + \beta = 1, \quad \text{or} \quad \alpha = \lambda, \quad \beta = 1 - \lambda.$$

which is also called IGARCH(1,1) [Integrated Generalized Autoregressive Conditional Heteroskedasticity]

(h) However, if $\alpha + \beta > 1$, the time series will diverge to infinity

Econometric modeling of the conditional variance/volatility:

For return r_t , denote the conditional mean by μ_t

$$r_t = \mu_t + u_t;$$

and usually we model μ_t by ARMA(p,q) model

$$\mu_t = \phi_0 + \sum_{i=1}^p \phi_i r_{t-i} + \sum_{i=1}^q \psi_i u_{t-i};$$

Later on, we shall omit the discussion of μ_t in most cases.

Volatility models are concerned with the modelling of

$$\begin{aligned}\sigma_t^2 &= \mathbf{cov}(r_t | r_{t-1}, r_{t-2}, \dots) \\ &= \mathbf{cov}(u_t | r_{t-1}, r_{t-2}, \dots)\end{aligned}$$

the conditional variance of a return.

Univariate volatility models

- (1) Autoregressive conditional heteroscedastic (ARCH) model of Engle (1982),
- (2) Generalized Autoregressive Conditional Heteroscedastic (GARCH) model of Bollerslev (1986),
- (3) GARCH-M (GARCH-in-Mean) models,
- (4) IGARCH models (used by RiskMetrics), Exponential GARCH (EGARCH), TGARCH, ...
- (5) Asymmetric parametric ARCH (APARCH) models of Ding, Granger and Engle (1994)
- (6) Stochastic volatility (SV) models

ARCH(m) model

$$r_t = \mu_t + u_t,$$

$$u_t = \sigma_t \epsilon_t; \quad \sigma_t^2 = \omega + \alpha_1 u_{t-1}^2 + \dots + \alpha_m u_{t-m}^2$$

where $\{\epsilon_t\}$ is a sequence of iid random variables (and independent of u_{t-1}, u_{t-2}, \dots) with

$$E(\epsilon_t) = 0, \quad \text{cov}(\epsilon_t) = 1 \quad (\text{if it exists}),$$

and, $\omega > 0$ and $\alpha_i \geq 0$ for $i > 0$,

ϵ_t is independent of $\{u_s, s < t\}$

ϵ_t and $\{\sigma_s, s \leq t\}$ are independent

We call $u_t = r_t - \mu_t$ “residuals” and ϵ_t “standardized residuals”.

Commonly used distribution of ϵ_t :

- (i) Standard normal,
- (ii) standardized Student-t,

Properties of ARCH models

Consider an ARCH(1) model

$$r_t = \mu_t + u_t, \quad u_t = \sigma_t \epsilon_t; \quad \sigma_t^2 = \omega + \alpha_1 u_{t-1}^2;$$

where $\omega > 0$ and $\alpha_1 \geq 0$.

(1) $E(u_t) = 0$ and $E(u_t | r_{t-1}, r_{t-2}, \dots) = 0$

(2) u_t is called the residuals, but ϵ_t is called standardized residuals, or innovation

(3) the model can be written as

$$u_t^2 = \omega + \alpha_1 u_{t-1}^2 + \eta_t$$

where $\eta_t = \sigma_t^2(\epsilon_t^2 - 1)$.

(4) If $\alpha_1 < 1$, $E u_t^2$ is constant, and u_t^2 is also stationary

(5) u_t is WN, but u_t^2 (or $u_t^2 - Eu_t^2$) is not White Noise.

(6) assuming $\text{cov}(u_t)$ is constant for all t^1 , then

$$\text{cov}(u_t) = \frac{\omega}{(1 - \alpha_1)}, \quad \text{if } 0 < \alpha_1 < 1$$

[Proof:

$$E(u_t^2) = \omega + \alpha_1 Eu_{t-1}^2$$

i.e.

$$\text{2nd moment } \mu_2 = \text{cov}(u_t) = \omega + \alpha_1 \text{cov}(u_t). \quad]$$

(7) Under normality, i.e. $\epsilon_t \sim N(0, 1)$, and assuming the moments are constants for all t^2 ,

$$\text{4th moment } \mu_4 = \frac{3\omega^2(1 + \alpha_1)}{(1 - \alpha_1)(1 - 3\alpha_1^2)}$$

¹actually this assumption is true, please try to prove it

²this assumption is also true

provided $0 < \alpha_1^2 < 1/3$. However, the 4th moment does not exist if $\alpha_1^2 > 1/3$.

[Proof: by (3),

$$\begin{aligned} u_t^4 &= \omega^2 + 2\omega\alpha_1 u_{t-1}^2 + \alpha_1^2 u_{t-1}^4 + \eta_t^2 \\ &\quad + 2(\omega + \alpha_1 u_{t-1}^2) * \eta_t. \end{aligned}$$

Taking expectation, we have by the assumption that ϵ_t is independent of σ_t

$$E\{(\omega + \alpha_1 u_{t-1}^2) * \eta_t\} = 0,$$

and the normality of ϵ_t ,

$$E\eta_t^2 = E\sigma_t^4 E((\epsilon_t^2 - 1)^2) = 2E\sigma_t^4.$$

By the model $\sigma_t^2 = \omega + \alpha_1 u_{t-1}^2$, we have

$$E\sigma_t^4 = \omega^2 + 2\omega * \alpha_1 \mu_2 + \alpha_1^2 \mu_4$$

Taking expectation to the first equation, we have

$$\mu_4 = 3(\omega^2 + 2\omega\alpha_1\mu_2) + 3\alpha_1^2\mu_4$$

By (6),

$$\begin{aligned}\mu_4 &= 3\left(\omega^2 + 2\omega\alpha_1\frac{\omega}{1-\alpha_1}\right) + 3\alpha_1^2\mu_4 \\ &= 3\omega^2\left(1 + 2\frac{\alpha_1}{1-\alpha_1}\right) + 3\alpha_1^2\mu_4 = 3\omega^2\frac{1+\alpha_1}{1-\alpha_1} + 3\alpha_1^2\mu_4\end{aligned}$$

Thus the result follows.]

(8) The kurtosis is

$$\frac{\mu_4}{\mu_2^2} = 3\frac{(1-\alpha_1^2)}{(1-3\alpha_1^2)} > 3$$

(9) This explains why the data has heavy tail if it indeed follows a ARCH model! even if the innovation is indeed normally distributed.

Estimation of ARCH using MLE

The log-likelihood function for normal distributed u_t is

$$L(\omega, \alpha_1, \dots, \alpha_m) = -\frac{n}{2} \log(2\pi) - \frac{1}{2} \sum_{t=m+1}^n \left\{ \log(\omega + \alpha_1 u_{t-1}^2 + \dots + \alpha_m u_{t-m}^2) + \frac{u_t^2}{\omega + \alpha_1 u_{t-1}^2 + \dots + \alpha_m u_{t-m}^2} \right\}$$

The MLE is

$$(\hat{\omega}, \dots, \hat{\alpha}_m) = \arg \max_{\omega, \alpha_1, \dots, \alpha_m} \{L(\omega, \alpha_1, \dots, \alpha_m)\}$$

The selection of m can be done by AIC or BIC

$$AIC(m) = -2L(\omega, \alpha_1, \dots, \alpha_m) + 2\frac{m+1}{n}$$

and

$$BIC(m) = -2L(\omega, \alpha_1, \dots, \alpha_m) + \log(n)\frac{m+1}{n}$$

Prediction of σ_{t+h}^2 based on u_1, \dots, u_t

$$\hat{\sigma}_{t+1}^2 = \omega + \alpha_1 u_{t+1-1}^2 + \dots + \alpha_m u_{t+1-m}^2$$

Because ($u_{t+1}^2 = \sigma_{t+1}^2 + \sigma_{t+1}^2(\epsilon_{t+1}^2 - 1)$) and

$$\begin{aligned} \sigma_{t+2}^2 &= \omega + \alpha_1 u_{t+2-1}^2 + \alpha_2 u_{t+2-2}^2 + \dots + \alpha_m u_{t+2-m}^2 \\ &= \omega + \alpha_1 \sigma_{t+2-1}^2 + \alpha_2 u_{t+2-2}^2 + \dots + \alpha_m u_{t+2-m}^2 + \alpha_1 \sigma_{t+1}^2 (\epsilon_{t+1}^2 - 1) \\ &\approx \omega + \alpha_1 \sigma_{t+2-1}^2 + \alpha_2 u_{t+2-2}^2 + \dots + \alpha_m u_{t+2-m}^2 \end{aligned}$$

Thus

$$\hat{\sigma}_{t+2}^2 = \omega + \alpha_1 \hat{\sigma}_{t+2-1}^2 + \alpha_2 u_{t+2-2}^2 + \dots + \alpha_m u_{t+2-m}^2$$

$$\hat{\sigma}_{t+3}^2 = \omega + \alpha_1 \hat{\sigma}_{t+3-1}^2 + \alpha_2 \hat{\sigma}_{t+3-2}^2 + \dots + \alpha_m u_{t+3-m}^2$$

R

```
library(fGarch)
```

```
[object] = garchFit(~ arma(p,q) + garch(m, s),
```

```
    data = [mydata],
```

```
    cond.dist = c("norm", "snorm", "ged", "sged",
```

```
        "std", "sstd"), shape=??, trace = TRUE)
```

```
summary([object])
```

```
predict([object], n.ahead = ??)    # please note that this
```

```
                                     # is to predict the mean in the older version
```

```
# in above, shape=?? only for the degree-of-freedom of
```

```
t-distribution
```

[object]@residuals: (raw, unstandardized) residual values u_t .

[object]@fitted: the fitted values.

[object]@h.t: the conditional variances ($h.t = \sigma.t^2$).

[object]@sigma.t: the conditional standard deviation.

[object]mGARCHt@fit\$se.coef: estimated parameters in the model

plot([object])

plot has a number of plots for model check

another useful QQ plot (against t-distribution)

qqplot(qt((1:n)/(n+1), df = ??), [data])

or qqplot(qt(ppoints(n), df = ??) [data])

where n is the length of [data]

Example 0.3 We fit ARCH(5) to the daily return of DJI, $r_t * 100$ (for easy of exposition). The fitted ARCH(5) model is

$$r_t * 100 = 0.003659 + u_t; \quad u_t = \sigma_t \epsilon_t; \quad \epsilon_t \sim N(0; 1)$$

and

$$\begin{aligned} \sigma_t^2 = & 0.388298 + 0.042448u_{t-1}^2 + 0.203262u_{t-2}^2 \\ & + 0.197531u_{t-3}^2 + 0.223231u_{t-4}^2 + 0.188031u_{t-5}^2 \end{aligned}$$

Model checking statistics indicate that there are some higher order dependence in the volatility. By checking the QQ-plot, it seems that the innovation ϵ_t does not follow normal.

```
Call:
garchFit(formula = ~garch(5, 0), data = r * 100, delta = 2, cond.dist = "norm",
include.delta = F, trace = F)
```

Mean and Variance Equation:

```
data ~ garch(5, 0)
<environment: 0x093c4874>
[data = r * 100]
```

Conditional Distribution:

norm

Coefficient(s):

	mu	omega	alpha1	alpha2	alpha3	alpha4	alpha5
	0.003659	0.388298	0.042447	0.203263	0.197531	0.223230	0.188031

Std. Errors:

based on Hessian

Error Analysis:

	Estimate	Std. Error	t value	Pr(> t)
mu	0.003659	0.026337	0.139	0.8895
omega	0.388298	0.042772	9.078	< 2e-16 ***
alpha1	0.042447	0.022453	1.890	0.0587 .
alpha2	0.203263	0.039950	5.088	3.62e-07 ***
alpha3	0.197531	0.039836	4.959	7.10e-07 ***
alpha4	0.223230	0.043942	5.080	3.77e-07 ***
alpha5	0.188031	0.038788	4.848	1.25e-06 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Log Likelihood:

-1995.987 normalized: -1.586635

Description:

Sat Mar 21 13:12:03 2015 by user: xia

Standardised Residuals Tests:

			Statistic	p-Value
Jarque-Bera Test	R	Chi^2	88.1211	0
Shapiro-Wilk Test	R	W	0.982711	4.179757e-11
Ljung-Box Test	R	Q(10)	15.43769	0.1169006
Ljung-Box Test	R	Q(15)	18.39082	0.2426765
Ljung-Box Test	R	Q(20)	20.57512	0.4225087
Ljung-Box Test	R^2	Q(10)	34.98461	0.0001256224
Ljung-Box Test	R^2	Q(15)	43.07804	0.0001531184
Ljung-Box Test	R^2	Q(20)	48.14984	0.0004052813
LM Arch Test	R	TR^2	48.73513	2.326924e-06

Information Criterion Statistics:

AIC	BIC	SIC	HQIC
3.184399	3.212985	3.184338	3.195142

Based on the test, it seems there is still information in the fitted residuals.

We then try ARCH(8)

Error Analysis:

	Estimate	Std. Error	t value	Pr(> t)	
mu	3.659e-03	2.583e-02	0.142	0.887353	
omega	2.786e-01	4.067e-02	6.851	7.32e-12	***
alpha1	1.000e-08	2.154e-02	0.000	1.000000	
alpha2	1.361e-01	3.508e-02	3.878	0.000105	***
alpha3	1.273e-01	3.580e-02	3.556	0.000377	***
alpha4	1.452e-01	4.131e-02	3.516	0.000439	***
alpha5	1.393e-01	3.438e-02	4.051	5.09e-05	***
alpha6	1.067e-01	3.609e-02	2.957	0.003105	**
alpha7	1.447e-01	3.651e-02	3.962	7.42e-05	***
alpha8	6.818e-02	2.747e-02	2.482	0.013072	*

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Log Likelihood:

-1958.38 normalized: -1.556741

Standardised Residuals Tests:

			Statistic	p-Value
Jarque-Bera Test	R	Chi ²	58.83563	1.675327e-13
Shapiro-Wilk Test	R	W	0.9874148	5.978969e-09
Ljung-Box Test	R	Q(10)	14.11174	0.1679557
Ljung-Box Test	R	Q(15)	17.40699	0.295122
Ljung-Box Test	R	Q(20)	19.36417	0.4982802
Ljung-Box Test	R ²	Q(10)	8.637683	0.5667988
Ljung-Box Test	R ²	Q(15)	17.28372	0.3021885
Ljung-Box Test	R ²	Q(20)	21.43408	0.3719906
LM Arch Test	R	TR ²	12.92092	0.3748148

Information Criterion Statistics:

AIC	BIC	SIC	HQIC
3.129379	3.170216	3.129254	3.144727

The standardized residuals show no auto-correlation.

The fitted model ARCH(8) with Student-t innovations is

$$r_t * 100 = 0.003659 + u_t; \quad u_t = \sigma_t \epsilon_t; \quad \epsilon_t \sim t(7)$$

and

$$\begin{aligned} \sigma_t^2 = & 0.25564955 + 0.0000u_{t-1}^2 + 0.1314u_{t-2}^2 \\ & + 0.1365u_{t-3}^2 + 0.1054u_{t-4}^2 + 0.1774u_{t-5}^2 \\ & + 0.1298u_{t-6}^2 + 0.14718u_{t-7}^2 + 0.07543u_{t-8}^2 \end{aligned}$$

By checking the QQ-plot, it seems that the innovation ϵ_t is more close to $t(7)$.

see [code06A2.R](#).

For prediction of volatility:

(i) by calling `[object]@residuals`, the last 8 residuals $r_t - \mu_t$ are -0.747866173, 0.446203960, -0.915879087, -0.396824391, -0.190223445, -0.143142976, -1.218988145, 1.271440116.

$$(ii) \sigma_{T+1}^2 = 0.25564955 + 0.0000 * 1.271440116^2 + 0.1314 * (-1.218988145)^2 + 0.1365 * (-0.143142976)^2 + 0.1054 * (-0.190223445)^2 + 0.1774 * (-0.396824391)^2 + 0.1298 * (-0.915879087)^2 + 0.14718 * (0.446203960)^2 + 0.07543 * (-0.747866173)^2 =$$

$$(iii) \sigma_{T+2}^2 = 0.25564955 + 0.0000 * \sigma_{T+1}^2 + 0.1314 * 1.271440116^2 + \dots + 0.14718 * (-0.143142976)^2 + 0.07543 * (-1.218988145)^2 =$$