The preprocessing steps are taken from kaggle notebook

In [2]: import numpy as np import pandas as pd import seaborn as sns import matplotlib.pyplot as plt import shutil from sklearn.model selection import train test split import tensorflow as tf from sklearn.model_selection import train test split import numpy as np import pandas as pd import os import tensorflow as tf import cv2 from tensorflow.keras import layers from tensorflow.keras.layers import Input, Add, Dense, Dropout, Activation, ZeroPadding2D , BatchNormalization, Flatten, Conv2D, AveragePooling2D, MaxPooling2D, GlobalMaxPooling2 D, Global Average Pooling 2D, Concatenate, ReLU, Leaky ReLU, Reshape, Lambda from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateScheduler, EarlyStopp ing, ReduceLROnPlateau from tensorflow.keras.optimizers import Adam,SGD from tensorflow.keras.preprocessing.image import ImageDataGenerator from tensorflow.keras.models import Sequential, load model, Model from tensorflow.keras.callbacks import LearningRateScheduler from tensorflow.keras.preprocessing import image from tensorflow.keras.utils import to categorical from tensorflow.keras import metrics from tensorflow.keras.preprocessing import image from tensorflow.keras.applications.imagenet utils import preprocess input from tensorflow.keras.initializers import glorot uniform from tqdm import tqdm import imgaug as ia from imgaug import augmenters as iaa from PIL import Image import keras.backend as K K.set image data format('channels last') K.set learning phase(1) /usr/local/lib/python3.7/dist-packages/keras/backend.py:450: UserWarning: `tf.keras.backe nd.set learning phase is deprecated and will be removed after 2020-10-11. To update it, simply pass a True/False value to the `training` argument of the ` call ` method of you r layer or model. warnings.warn('`tf.keras.backend.set_learning_phase` is deprecated and ' In [3]: # getting the labels corresponding to the image label df = pd.read _csv('/content/drive/My Drive/crowd-counting/labels.csv') label_df.columns = ['id' , 'people'] label df.head()

Out[3]:

	id	people
0	1	35
1	2	41
2	3	41
3	4	44
4	5	41

```
In [4]:
# loading the images in vector format
img = np.load('/content/drive/My Drive/crowd-counting/images.npy')
#img = img.reshape(img.shape[0], img.shape[1], img.shape[2], img.shape[3],1)
img.shape
Out[4]:
(2000, 480, 640, 3)
In [5]:
labels = np.array(label df['people'])
labels
Out[5]:
array([35, 41, 41, ..., 25, 26, 26])
In [6]:
# setting features and target value
x train, x test, y train, y test = train test split(img, labels, test size=0.1)
print(x train.shape[0])
print(x_test.shape[0])
1800
200
In [ ]:
!pip install split-folders
I will be using resnet upgraded for crowd counting
By using resnet
Customize way # 01
In [7]:
from tensorflow.keras.applications.resnet50 import ResNet50
In [8]:
resnet model = ResNet50(
   weights='imagenet',
   include top=False,
   input shape=(480, 640, 3),
   pooling='avg',
Downloading data from https://storage.googleapis.com/tensorflow/keras-applications/resnet
/resnet50 weights tf dim ordering tf kernels notop.h5
In [9]:
x = resnet model.output
x = Dense(\overline{1024}, activation='relu')(x)
predictions = Dense(1, activation='linear')(x)
```

In [10]:

```
In [11]:
k = -7
for layer in model.layers[:k]:
    layer.trainable = False
print('Trainable:')
for layer in model.layers[k:]:
    print(layer.name)
    layer.trainable = True
Trainable:
conv5 block3 3 conv
conv5_block3_3_bn
conv5 block3 add
conv5 block3 out
avg pool
dense
dense 1
In [12]:
import tensorflow as tf
model.compile(loss=tf.keras.losses.Huber(),
              optimizer=tf.keras.optimizers.Adam(),
              metrics=['mae'])
Applying Callbacks
In [13]:
def scheduler(epoch, lr):
  if epoch < 10:</pre>
    return lr
  else:
    return lr * tf.math.exp(-0.1)
In [14]:
reduce lr = tf.keras.callbacks.ReduceLROnPlateau(monitor='val loss', factor=0.2, patienc
e=5, min lr=0.001)
early stopping = tf.keras.callbacks.EarlyStopping(monitor='loss', patience=3)
learning rate scheduler = tf.keras.callbacks.LearningRateScheduler(scheduler)
In [1]:
from google.colab import drive
drive.mount('/content/drive')
Mounted at /content/drive
In [ ]:
history = model.fit(x train,
          y train,
          validation_data=(x_test, y_test),
          epochs=100,
          batch size=8,
In [ ]:
# Check libcudnn8 version
!apt-cache policy libcudnn8
# Install latest version
| apt install --allow-change-held-packages libcudnn8=8.4.1.50-1+cuda11.6
```

model = Model(inputs=resnet model.input, outputs=predictions)

```
# Export env variables
!export PATH=/usr/local/cuda-11.4/bin${PATH:+:${PATH}}
!export LD_LIBRARY_PATH=/usr/local/cuda-11.4/lib64:$LD_LIBRARY_PATH
!export LD_LIBRARY_PATH=/usr/local/cuda-11.4/include:$LD_LIBRARY_PATH
!export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/usr/local/cuda/extras/CUPTI/lib64

# Install tensorflow
!pip install tflite-model-maker==0.4.0
!pip uninstall -y tensorflow && pip install -q tensorflow==2.9.1
!pip install pycocotools==2.0.4
!pip install opency-python-headless==4.6.0.66
```

Scores for resnet50

```
In [ ]:
# model error on training dataset
score = model.evaluate(x train,
                          y train,
                          verbose = 0)
print("\nTrain error: %.1f%%" % (100.0 * score[1]))
Train error: 3122.7%
In [ ]:
# model error on test dataset
score = model.evaluate(x test,
                          y test,
                          verbose = 0)
print("\nTest error: %.1f%%" % (100.0 * score[1]))
Test error: 3087.7%
In [ ]:
eval score = model.evaluate(x test, y test)
print("Test loss:", eval score[0])
print("Test error:", eval score[1])
Test loss: 1005.265625
Test error: 30.876514434814453
```

Graphs

In []:

Loss vs error graphs

```
In []:

plt.plot(history.history['mae'])
plt.plot(history.history['val_mae'])
plt.title('model error per epoch')
plt.ylabel('mae')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```

```
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss per epoch')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```

ResNet50 model prediction

```
In [ ]:
re = model.predict(x train)
print('Training set --')
        ground truth: ', np.sum(y_train, axis=0))
print('
print(' evaluate count: ', np.sum(re*(re>0.3), axis=0).astype('int'))
re = model.predict(x test)
print('Testing set --')
print(' ground truth: ', np.sum(y_test, axis=0))
       predict count: ', np.sum(re*(re>0.3), axis=0).astype('int'))
print('
```

```
By using efficientnetb0
In [ ]:
from tensorflow.keras.applications.efficientnet import EfficientNetB0
In [ ]:
efficientnetb0 model = EfficientNetB0(
    weights='imagenet',
   include top=False,
   input shape=(480, 640, 3),
   pooling='avg',
)
In [ ]:
x = efficientnetb0 model.output
x = Dense(1024, activation='relu')(x)
predictions = Dense(1, activation='softmax')(x)
In [ ]:
model = Model(inputs=efficientnetb0 model.input, outputs=predictions)
In [ ]:
for layer in model.layers[:k]:
   layer.trainable = False
print('Trainable:')
for layer in model.layers[k:]:
   print(layer.name)
    layer.trainable = True
In [ ]:
import tensorflow as tf
model.compile(loss=tf.keras.losses.Huber(),
             optimizer=tf.keras.optimizers.Adam(),
              metrics=['mae'])
In [ ]:
```

```
history = model.fit(x train,
          y train,
          validation data=(x test, y test),
          epochs=100,
         batch size=8,
          callbacks = [reduce_lr, early_stopping, learning_rate_scheduler]
        )
```

Scores for efficientnetb0

```
In [ ]:
# model error on training dataset
score = model.evaluate(x_train,
                              y train,
                              verbose = 0)
print("\nTrain error: %.1f%%" % (100.0 * score[1]))
In [ ]:
# model error on test dataset
score = model.evaluate(x test,
                              y test,
                              verbose = 0)
print("\nTest error: %.1f%%" % (100.0 * score[1]))
In [ ]:
eval score = model.evaluate(x test, y test)
print("Test loss:", eval score[0])
print("Test error:", eval score[1])
```

Graphs

Error vs accuracy grapghs

```
In []:

plt.plot(history.history['mae'])
plt.plot(history.history['val_mae'])
plt.title('model error per epoch')
plt.ylabel('mae')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```

```
In []:

plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss per epoch')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```

EfficientNetB0 model prediction

```
In []:

result = model.predict(x_train)
print('Training set --')
print(' ground truth: ', np.sum(y_train, axis=0))
print(' evaluate count: ', np.sum(result*(result>0.3), axis=0).astype('int'))

result = model.predict(x_test)
print('Testing set --')
print(' ground truth: ', np.sum(y_test, axis=0))
print(' predict count: ', np.sum(result*(result>0.3), axis=0).astype('int'))
```