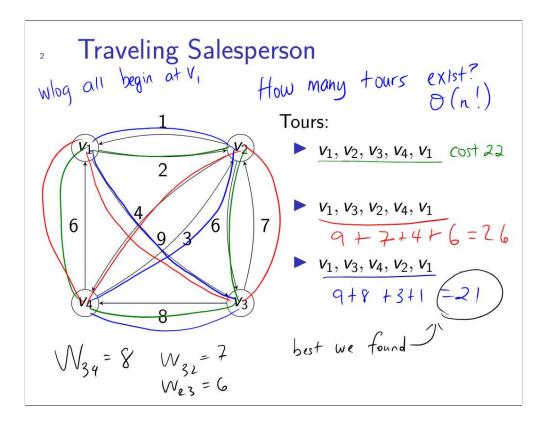
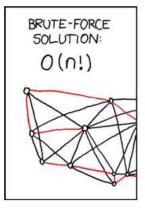
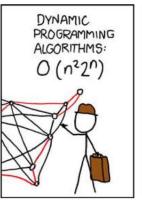
Computer Science 161
Spring 2021 Lecture 18:
Dynamic Programming:
Traveling Salesperson



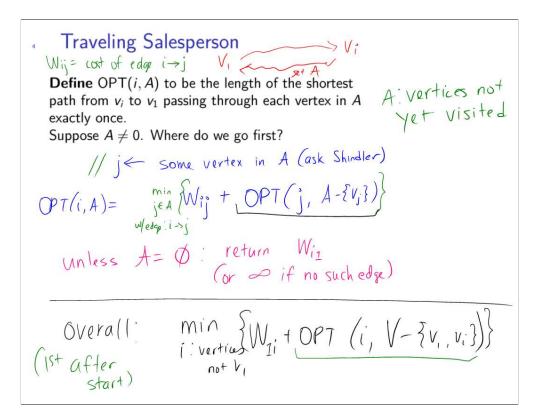
XKCD # 399







What's the complexity class of the best linear program cutting-plane techniques? I couldn't find it anywhere. The Garfield guy doesn't have these problems....



Traveling Salesperson Time Complexity

$$//\mathsf{OPT}(i,A) = \mathsf{min}_j\{w_{ij} + v_j, A - \{v_j\}\}\$$

1. How many sub-problems are there?

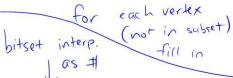
2. How long does each take to compute? (Assume that recursive calls are $\mathcal{O}(1)$ lookups)

$$\mathcal{J}(n^2 \cdot 2^n)$$

Traveling Salesperson Iterative

$$//\mathsf{OPT}(i,A) = \min_{j} \{ w_{ij} + (v_j, A - \{v_j\}) \}$$

1. How to store incremental solutions?



The subset in subset in increasing site

3. How to find the optimal cycle?

Stationary for each subset in increasing site

(not in subset)

for each vertex

(not in subset)

fill in

Stationary vector (unsigned, unsigned) table