

## 1.2 이동 평균법

### \* Simple Moving Average

·  $X_t = c + a_t$ ,  $c$ 는 상수이며  $a_t$ 는 white noise로 볼림.

·  $\min_c Q = \sum_{t=T-N+1}^T (X_t - c)^2$ ,  $\hat{c} = \frac{1}{N} \sum_{t=T-N+1}^T X_t$  이며  $\hat{c} = M_t$ 로 표기

·  $M_T = \frac{1}{N} \sum_{t=T-N+1}^T X_t$ ,  $E[M_T] = E[X_t] = c$ ,  $\text{Var}[M_T] = \frac{1}{N^2} (N \cdot \text{Var}[X_t]) = \frac{\sigma_a^2}{N}$

### \* One-step-ahead forecast (Simple MA)

·  $f_{T:1} = E[X_{T+1} | X_T, \dots] = c$

$\hat{f}_{T:1} = \hat{c} = M_T$

·  $\hat{f}_{T:k} = \hat{c} = M_T$ ,  $k=1, 2, 3, \dots$  ( $k$ -step ahead)

· 예측오차:  $e_{T:1} = X_{T+1} - \hat{f}_{T:1} = X_{T+1} - M_T$

예측오차의 분산:  $\text{Var}[e_{T:1}] = \text{Var}[X_{T+1} - M_T] = \text{Var}[X_{T+1}] + \text{Var}[M_T]$   
 $= \sigma_a^2 + \frac{1}{N} \sigma_a^2 = (1 + \frac{1}{N}) \sigma_a^2$

### \* Double Moving Average

·  $X_t = c + bt + a_t$ ,  $M_T^{(2)} = \frac{1}{N} \sum_{i=T-N+1}^T M_i$   
 선형추세

· 이중이동 평균: 최근  $N$ 개의 단순이동 평균이 다시 이동 평균을 취한 값

·  $E[M_T] = \frac{1}{N} \sum_{t=T-N+1}^T E[X_t] = \frac{1}{N} \sum_{t=T-N+1}^T E[c + bt + a_t]$   
 $= c + b \cdot T - \frac{N-1}{2} b$

·  $E[M_T^{(2)}] = \frac{1}{N} \sum_{t=T-N+1}^T E[M_i] = \frac{1}{N} \sum E[c + bT - \frac{N-1}{2} b]$   
 $= c + bT - (N-1)b$

·  $E[M_T]$ 과  $E[M_T^{(2)}]$ 에 대한 연결방정식의 결과

$$\Rightarrow c = 2 \cdot E[M_T] - E[M_T^{(2)}] - bT$$

$$b = \frac{2}{N-1} (E[M_T] - E[M_T^{(2)}])$$

· (과  $b$ 에 대한 추정치)

$$\Rightarrow \hat{c} = 2M_T - M_T^{(2)} - bT$$

$$\hat{b} = \frac{2}{N-1} (M_T - M_T^{(2)})$$

$$\Rightarrow E[M_T] - E[M_T^{(2)}] = \frac{N-1}{2} b$$

\* One-step-ahead forecast (double MA)

$$\cdot f_{T,1} = E[X_{T+1} | X_T, \dots] = c + b(T+1)$$

$$\cdot \hat{f}_{T,1} = \hat{c} + \hat{b}(T+1) = 2M_T - M_T^{(2)} + \hat{b}$$

$$\cdot \underline{\hat{f}_{T,k}} = \hat{c} + \hat{b}(T+k) = 2M_T - M_T^{(2)} + k\hat{b}, \quad k=1, 2, \dots$$

$k$ -step-ahead forecast

### 1.3 지수 평활법

#### \* 단순지수평활법 (Simple Exponential Smoothing, EWMA)

· 가중치  $\lambda$ 를 공하여 시간적 효과를 고려

$$\cdot \min_c Q = \sum_{t=1}^T \lambda^{T-t} (X_t - c)^2 \quad (\text{과거로 갈수록 가중치  $\lambda$  작아짐})$$

$$\cdot \hat{c} = \frac{1-\lambda}{1-\lambda^T} \sum_{t=1}^T \lambda^{T-t} \cdot X_t$$

$$T \rightarrow \infty \sim \hat{c} = (1-\lambda) \cdot \sum_{i=0}^{\infty} \lambda^i \cdot X_{T-i} = S_T$$

· 여기서  $\alpha = 1-\lambda$ 로 정의하면 다음과 같음

$$S_T = \alpha \cdot X_T + (1-\alpha) S_{T-1}, \quad \alpha \text{ 는 smoothing constant.}$$

$$E[S_T] = \alpha \cdot \sum_{i=0}^{\infty} (1-\alpha)^i E[X_{T-i}] = c \cdot \alpha \cdot \sum_{i=0}^{\infty} (1-\alpha)^i = c$$

$$\begin{aligned} \text{Var}[S_T] &= \alpha^2 \cdot \sum_{i=0}^{\infty} (1-\alpha)^{2i} \cdot \text{Var}[X_{T-i}] = \alpha^2 \cdot \sigma_a^2 \cdot \sum_{i=0}^{\infty} (1-\alpha)^{2i} \\ &= \frac{\alpha}{2-\alpha} \sigma_a^2 \end{aligned}$$

$$\cdot \hat{f}_{T,k} = \hat{c} = S_T, \quad k=1, 2, 3, \dots \quad (k\text{-step-ahead forecast})$$

$$e_{T,k} = X_{T+k} - \hat{f}_{T,k} = X_{T+k} - S_T$$

$$\begin{aligned} \text{Var}[e_{T,k}] &= \text{Var}[X_{T+k} - S_T] = \text{Var}[X_{T+k}] + \text{Var}[S_T] \\ &= \frac{2}{2-\alpha} \cdot \sigma_a^2 \end{aligned}$$

#### \* Brown 이중지수평활법 (Double Exponential Smoothing)

$$\begin{aligned} \cdot S_T^{(2)} &= \alpha \cdot \sum_{i=0}^{\infty} (1-\alpha)^i S_{T-i} \\ &= \alpha \cdot S_T + (1-\alpha) S_{T-1}^{(2)} \end{aligned}$$

$$\cdot E[S_T] = c + bT - \frac{1-\alpha}{\alpha} b = E[X_T] - \frac{1-\alpha}{\alpha} b$$

$$\cdot E[S_T^{(2)}] = E[S_T] - \frac{1-\alpha}{\alpha} b$$

↳ Simple ES의 기대값과 Double ES의 기대값 간에 격차 존재.

$$\cdot \hat{b} = \frac{\alpha}{1-\alpha} (S_T - S_T^{(2)}), \quad \hat{c} = 2 \cdot S_T - S_T^{(2)} - \hat{b} T.$$

$$\cdot \hat{f}_{T,1} = \hat{c} + \hat{b}(T+1) = \left(2 + \frac{\alpha}{1-\alpha}\right) S_T - \left(1 + \frac{\alpha}{1-\alpha}\right) S_T^{(2)}$$

$$\hat{f}_{T,k} = \hat{c} + \hat{b}(T+k) = 2 \cdot S_T - S_T^{(2)} + k \cdot \hat{b}, \quad k=1,2,\dots$$

### \* Holt의 선형추세 지수평활법

· 수준( $L_t$ )과 추세( $b_t$ )를 갱신

$$L_t = \alpha \cdot X_t + (1-\alpha)(L_{t-1} + b_{t-1})$$

$$b_t = \beta(L_t - L_{t-1}) + (1-\beta)b_{t-1}$$

$0 < \alpha < 1$ : 수준에 대한 평활 상수,  $0 < \beta < 1$ : 추세에 대한 평활 상수

초깃값:  $L_1 = X_1, \quad b_1 = X_1 - X_0$ .

$$\cdot \hat{f}_{T,k} = L_T + k \cdot b_T$$

### \* 계절성을 고려한 Winters 모형.

· Holt 모형 + 계절성(Seasonality)

$$\cdot L_t = \alpha \cdot \frac{X_t}{S_{t-m}} + (1-\alpha)(L_{t-1} + b_{t-1})$$

$$b_t = \beta(L_t - L_{t-1}) + (1-\beta)b_{t-1}$$

$$S_t = \gamma \cdot \frac{X_t}{L_t} + (1-\gamma)S_{t-m} \quad (\text{계절성 지수, } m: \text{계절성 주기, } \gamma: \text{평활상수})$$

$$\cdot \hat{f}_{T,k} = (L_T + k \cdot b_T) S_{T-m+k}, \quad k=1,2,\dots$$

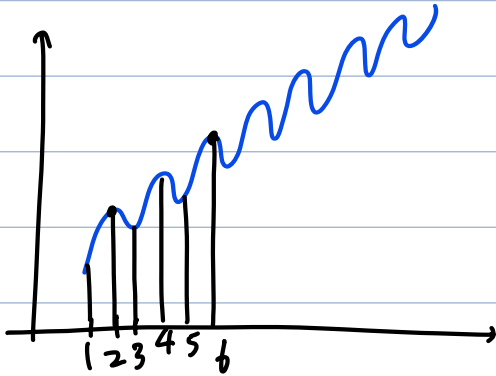
## 1.4 분해법을 이용한 예측

### \* Decomposition Method - Addictive

· trend과 계절성을 분리

$$X_t = b_t + S_t + \varepsilon_t, \quad S_t = S_{t-m}, \quad \sum_{i=1}^m S_i = 0$$

·  $m$ : 주기



⇒ trend를 제거시켜야 함

(detrend)

$$\downarrow$$

$$\text{CM}_t \text{ 이용} \Rightarrow \underline{DX_t^{(T)} = X_t - \hat{CM}_t}$$

$t$	$X_t$	$M_t (N=4)$	$CM_t$
1	$X_1$		
2	$X_2$		
3	$X_3$		
4	$X_4$	$M_4 = \frac{X_1 + X_2 + X_3 + X_4}{4}$	$CM_4 = \frac{0.5X_1 + X_2 + X_3 + 0.5X_4}{4}$
5	$X_5$		
6	$X_6$		
7	$X_7$		
8	$X_8$		

· 짝수인 경우  $CM_t$  ( $m=2g$ )

$$\hat{CM}_t = \frac{1}{m} (0.5X_{t-g} + X_{t-g+1} + \dots + 0.5X_{t+g})$$

· 홀수인 경우  $CM_t$  ( $m=2g+1$ )

$$\hat{CM}_t = \frac{1}{m} (X_{t-g} + X_{t-g+1} + \dots + X_{t+g})$$

### \* Decomposition method - Multiplicative

$$X_t = b_t \times S_t \times \varepsilon_t, \quad S_t = S_{t-m}, \quad \sum_{i=1}^m S_i = m$$

## 1.5 예측성능척도

· MSE, RMSE, MAD, MAPE