

FACE MASK DETECTION



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INTRODUCTION





Background

- COVID-19 has posed a serious threat to global health.
- Wearing face masks in public areas is one of numerous precautions that may be taken to stop the spread of this infection.
- It is challenging to make sure that people are wearing masks in public transportation.

Objectives



Using computer vision and deep learning to detect whether a person is wearing mask, not wearing mask or improperly wearing mask.



DATA CLEANING & EDA



DATASET

843 IMAGES WITH
ANNOTATIONS

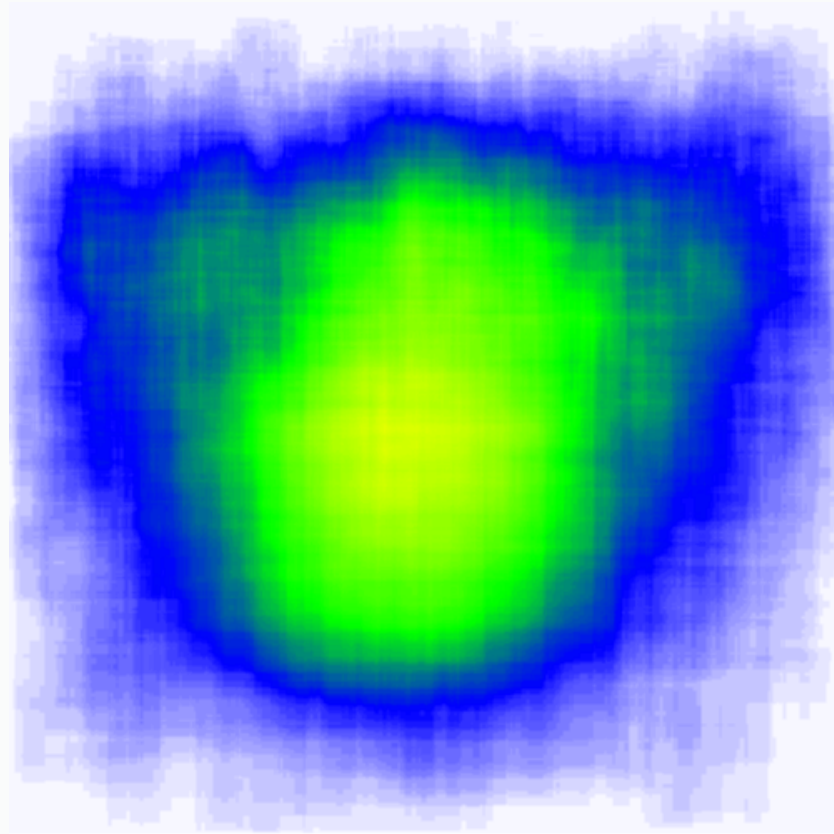
MEDIAN IMAGE RATIO

400 X 281

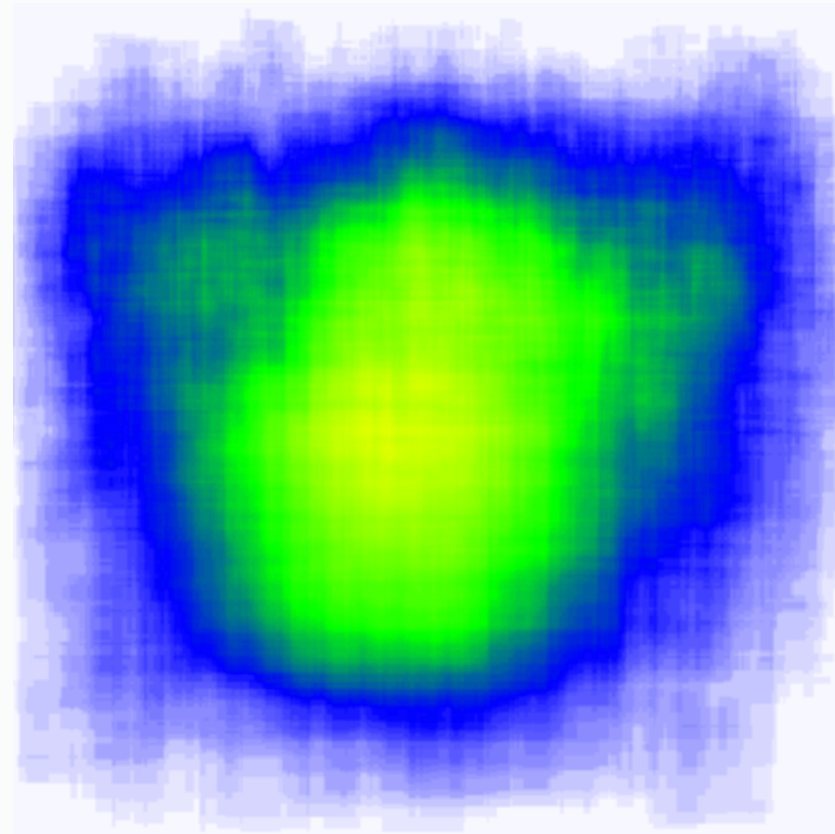
IMBALANCED CLASS

- with_mask : 79%
- without_mask : 18%
- mask_wearred_incorrect : 3%

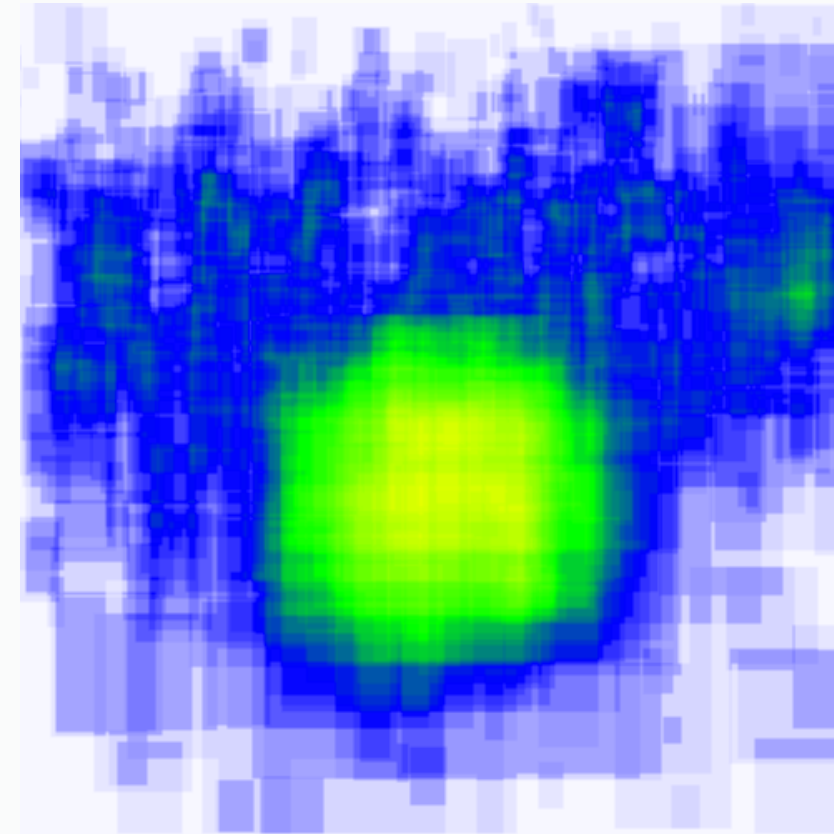
Annotation Heatmap



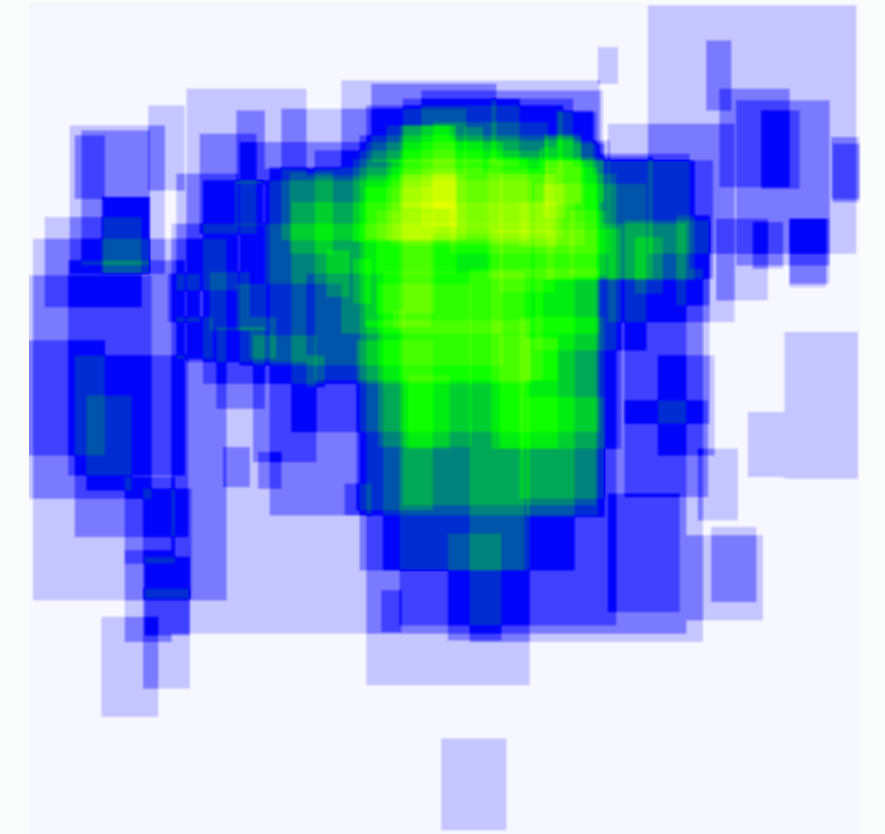
All
(4,021)



with_mask
(3,184)



without_mask
(716)



mask_wearied_incorrect
(121)

MODELLING



Classification vs. Object Detection

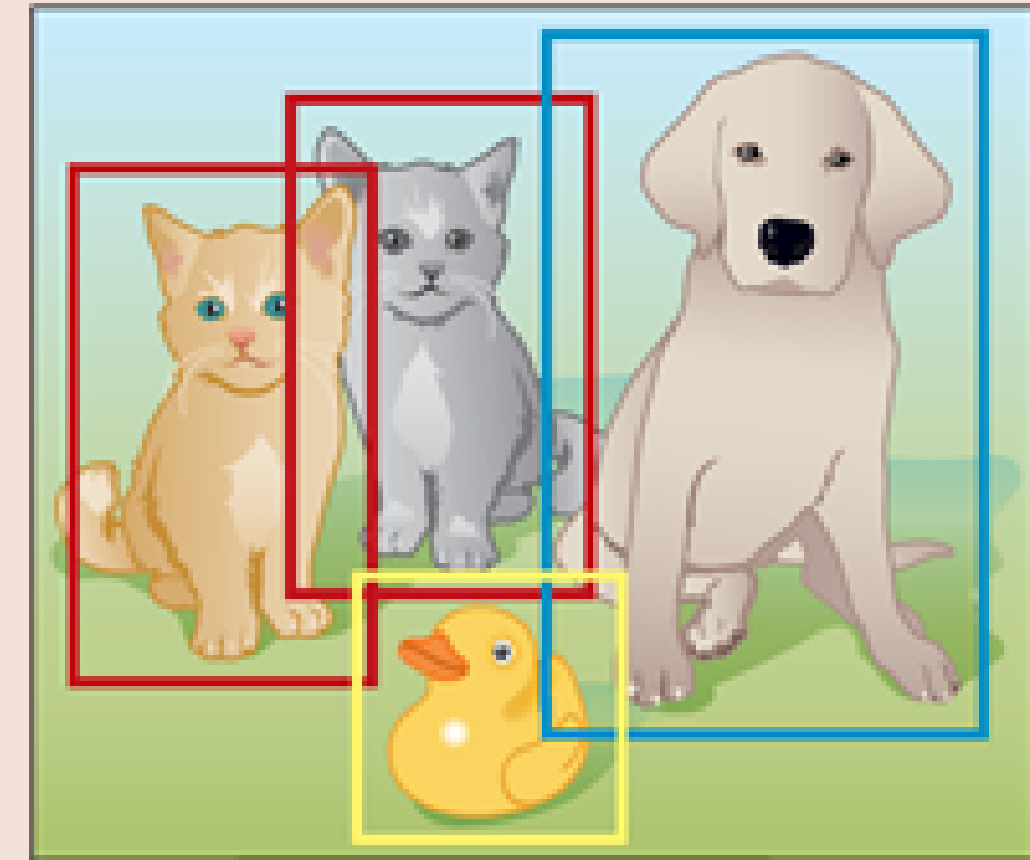
Image Classification



Cat

- One object and one label per image

Object Detection (classification and localization)



Cat, Cat, Duck, Dog

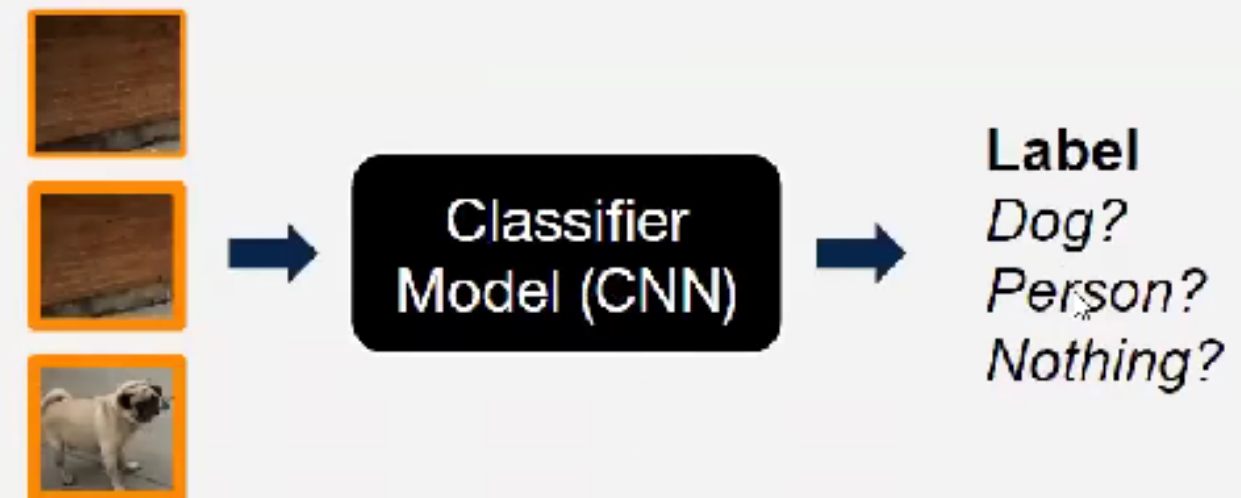
- Multiple objects per image
- Determine objects' location by drawing bounding boxes (bbox)
- Bbox described as (x, y, w, h)

Naive Approach

1. Scan the image with a sliding window



2. Feed the image to a classifier model to predict a label for that region

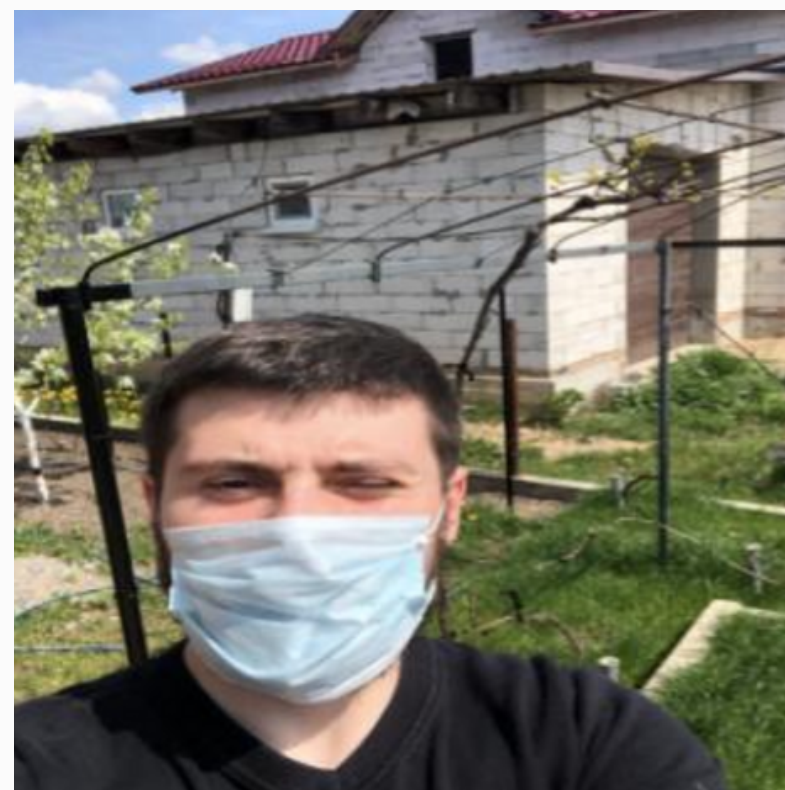


- Slow → Not good for real time uses
- Improved version: Region-based Convolutional Neural Net (**R-CNN**)
 - Strategically selects interesting regions to run through the classifier.

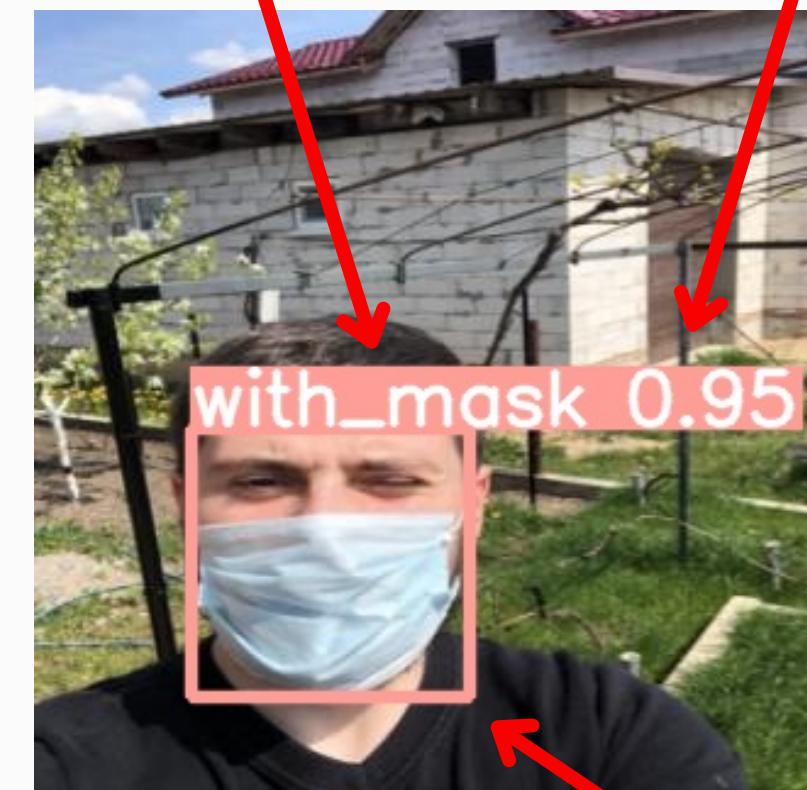
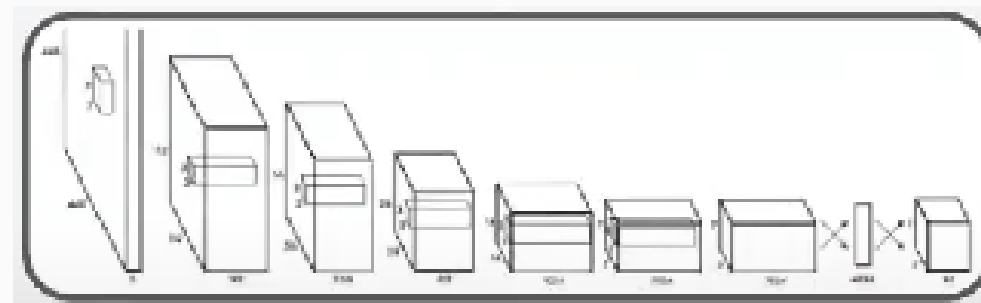


YOLO - You Only Look Once

- Instead of making predictions on many regions of an image, YOLO passes the entire image at once into a CNN (much faster!)
- The CNN that predicts the **labels, bounding boxes, and confidence probabilities** for objects in the image



Convolutional
Neural Network



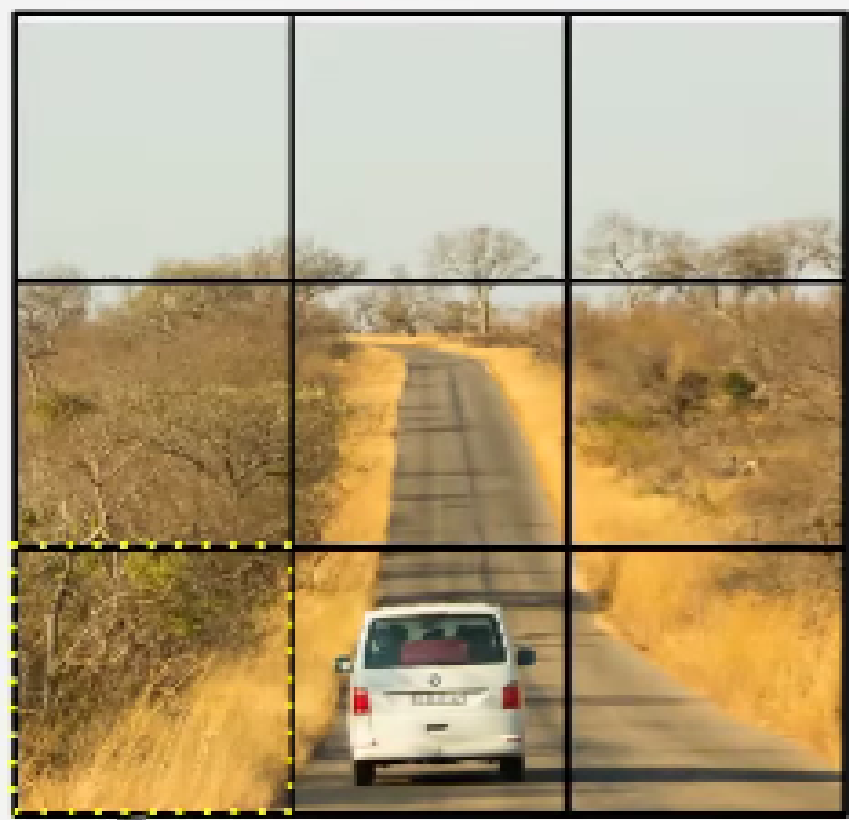
label

confidence probability

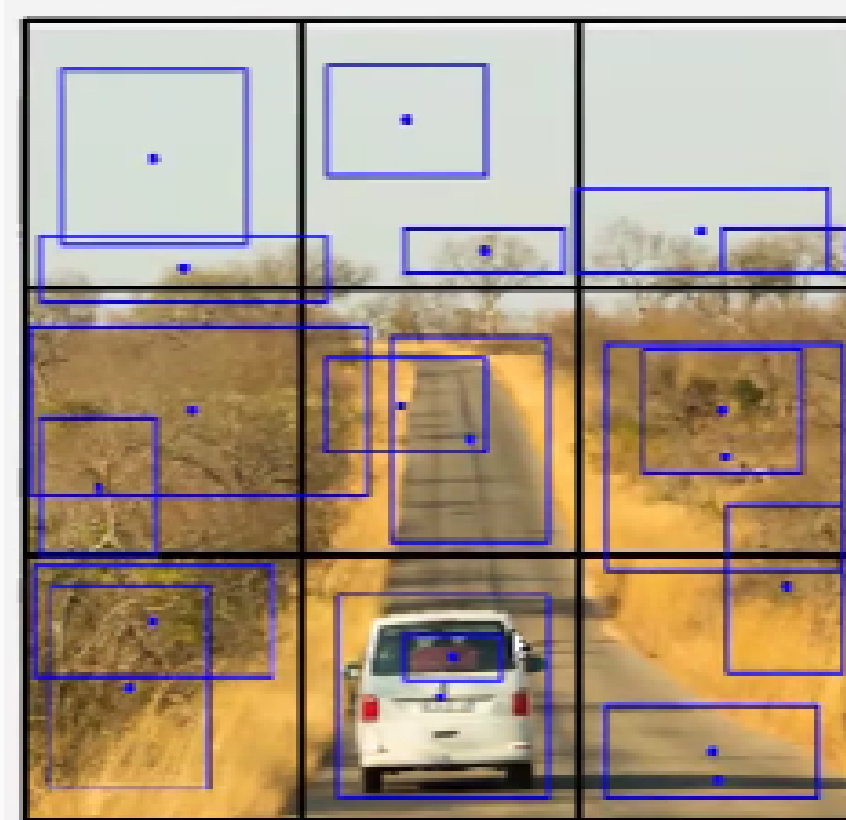
bounding box

YOLO Steps

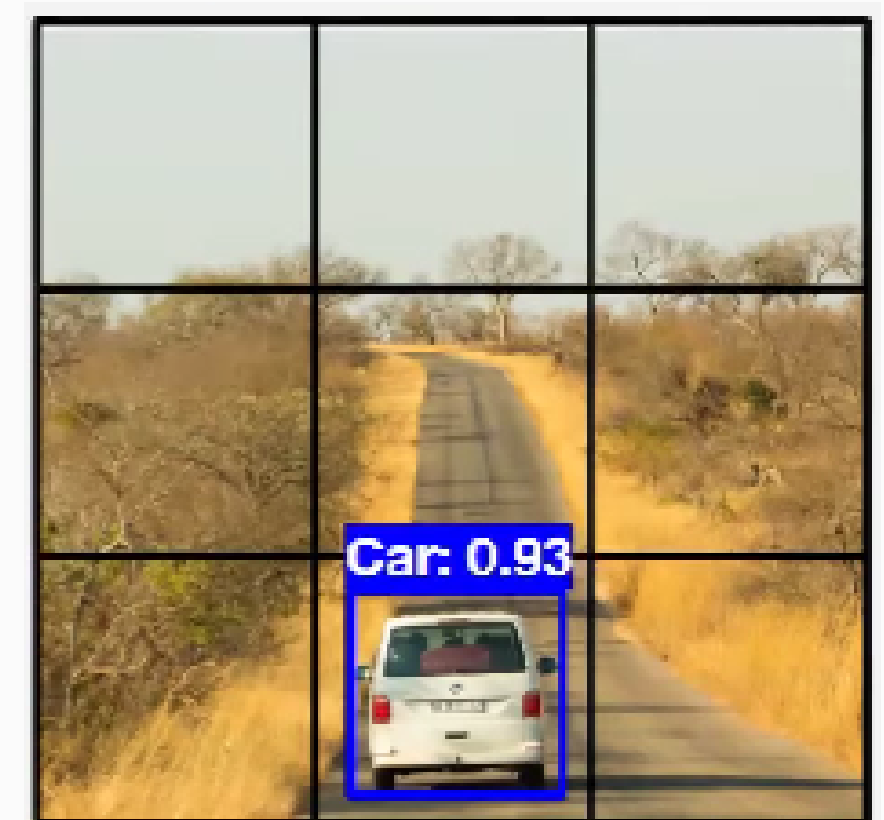
1. Divide the image into cells with an $S \times S$ grid.



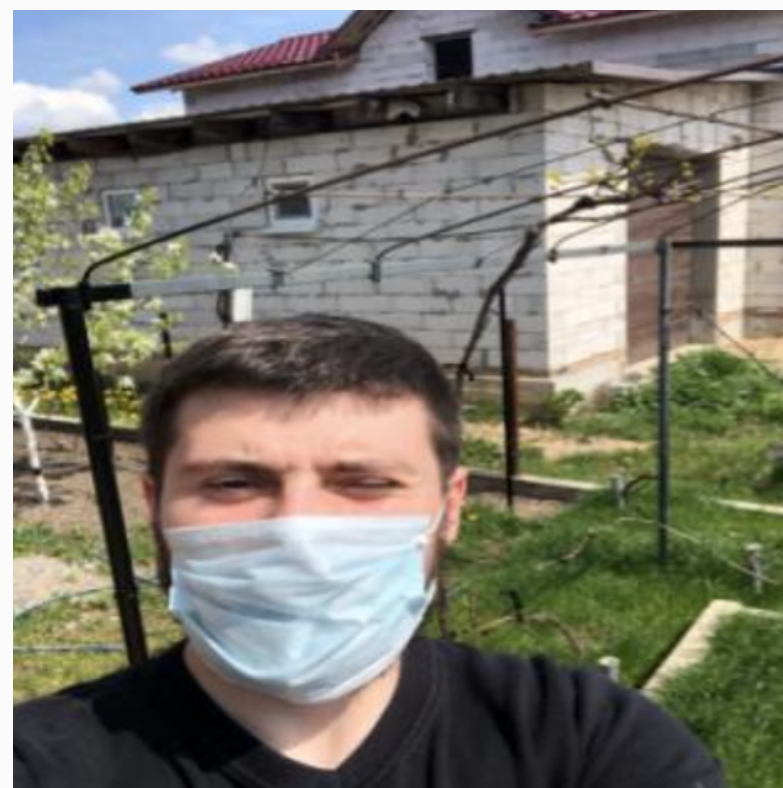
2. Each cell predicts B bounding boxes



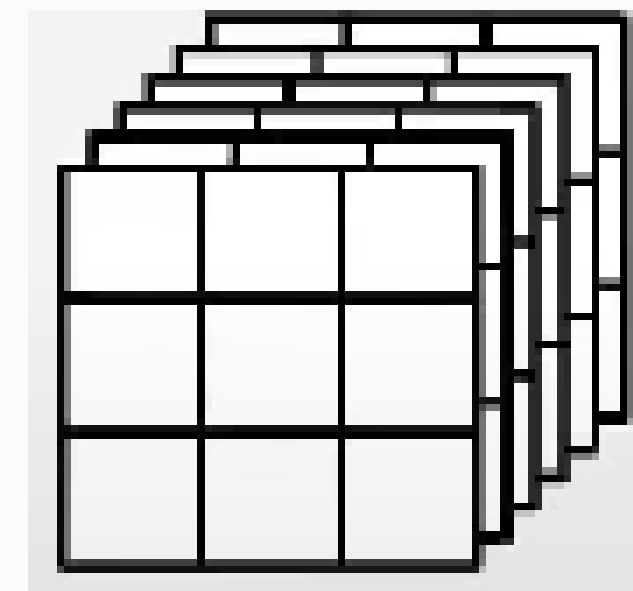
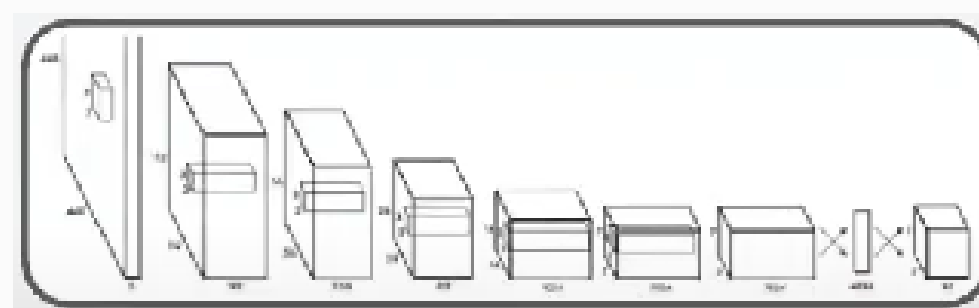
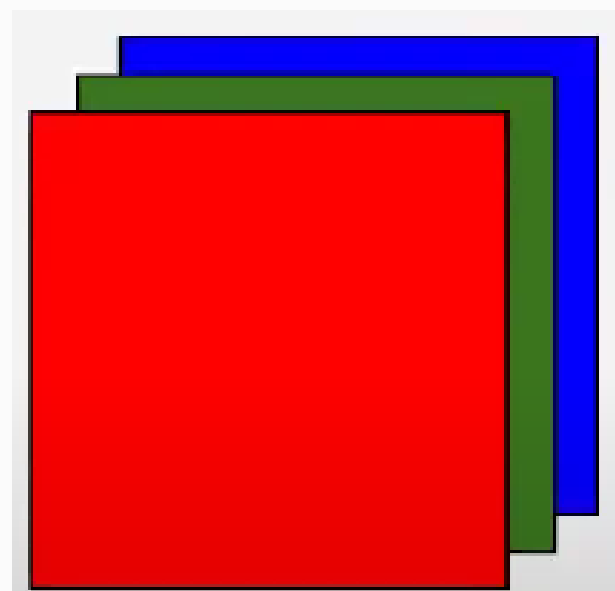
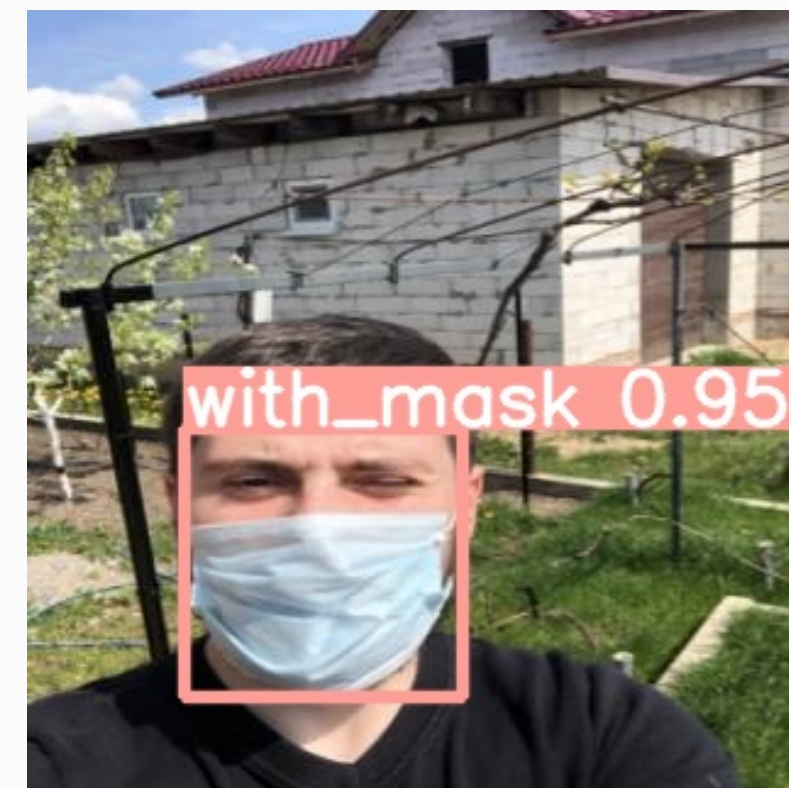
3. Return bounding boxes above confidence threshold



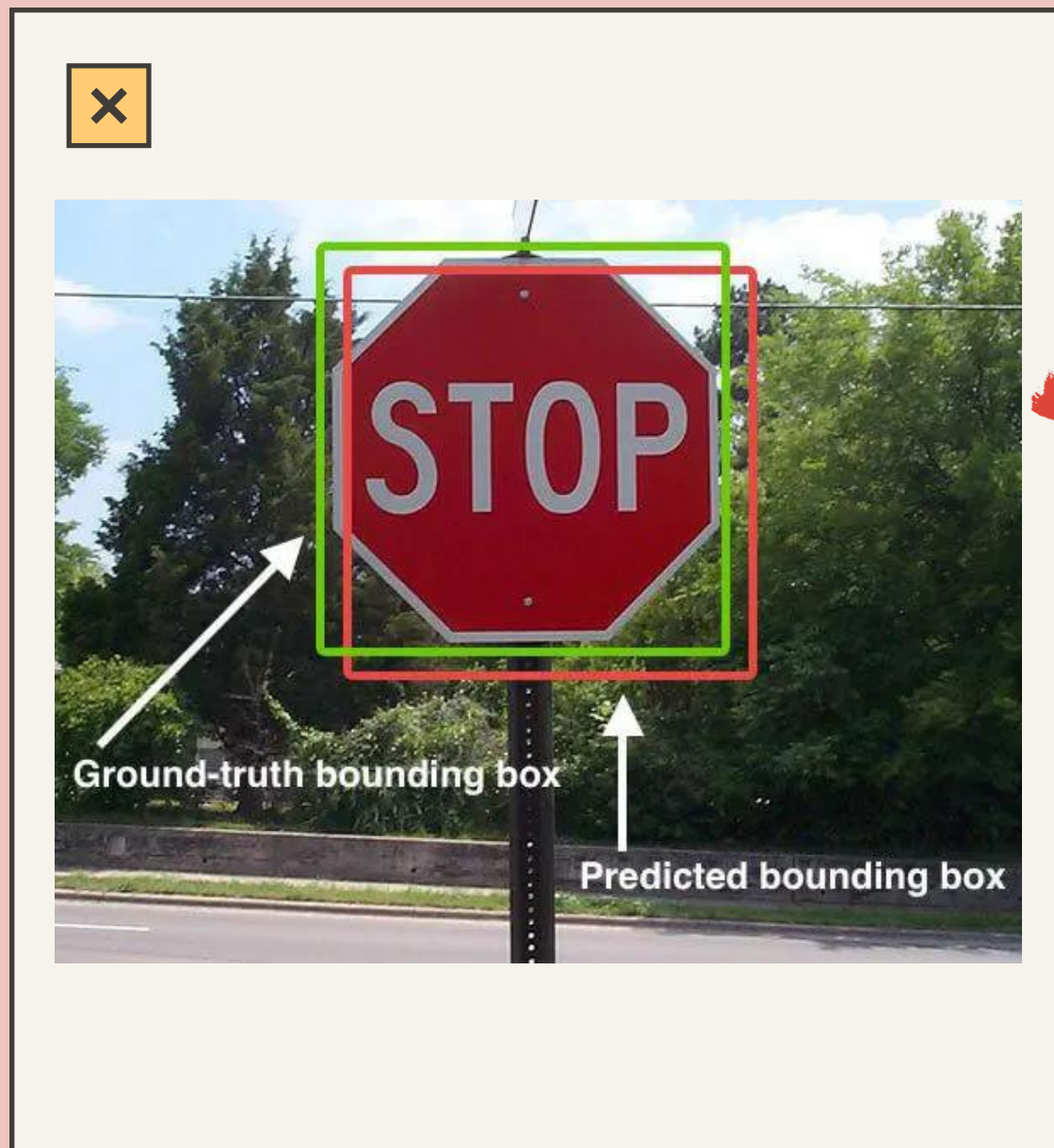
YOLO Overview



Convolutional
Neural Network



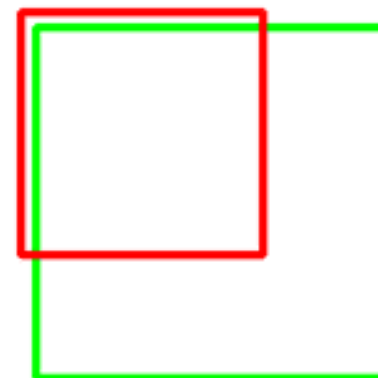
Evaluation Metric : Intersection Over Union (IoU)



$$\text{IoU} = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$

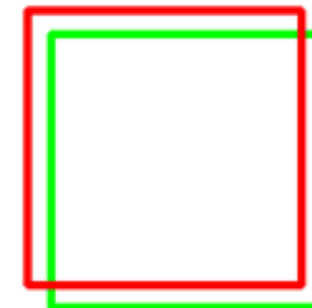


IoU: 0.4034



Poor

IoU: 0.7330



Good

IoU: 0.9264

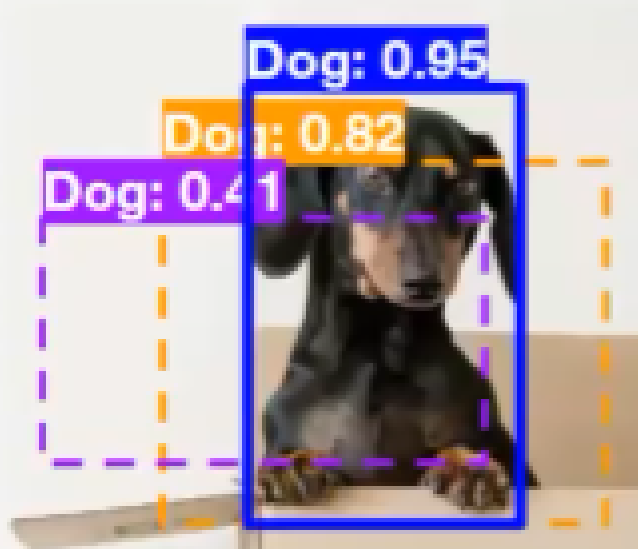


Excellent

Non-Max Suppresion

Double Counting Objects

NMS solves multiple counting by removing the box with lower confidence probability when the IoU between 2 boxes with the same label is above some threshold.



1. Identify the box with the highest confidence



IoU : 0.62



IoU : 0.47

2. Calculate the IoU between the highest confidence box and each of the other boxes

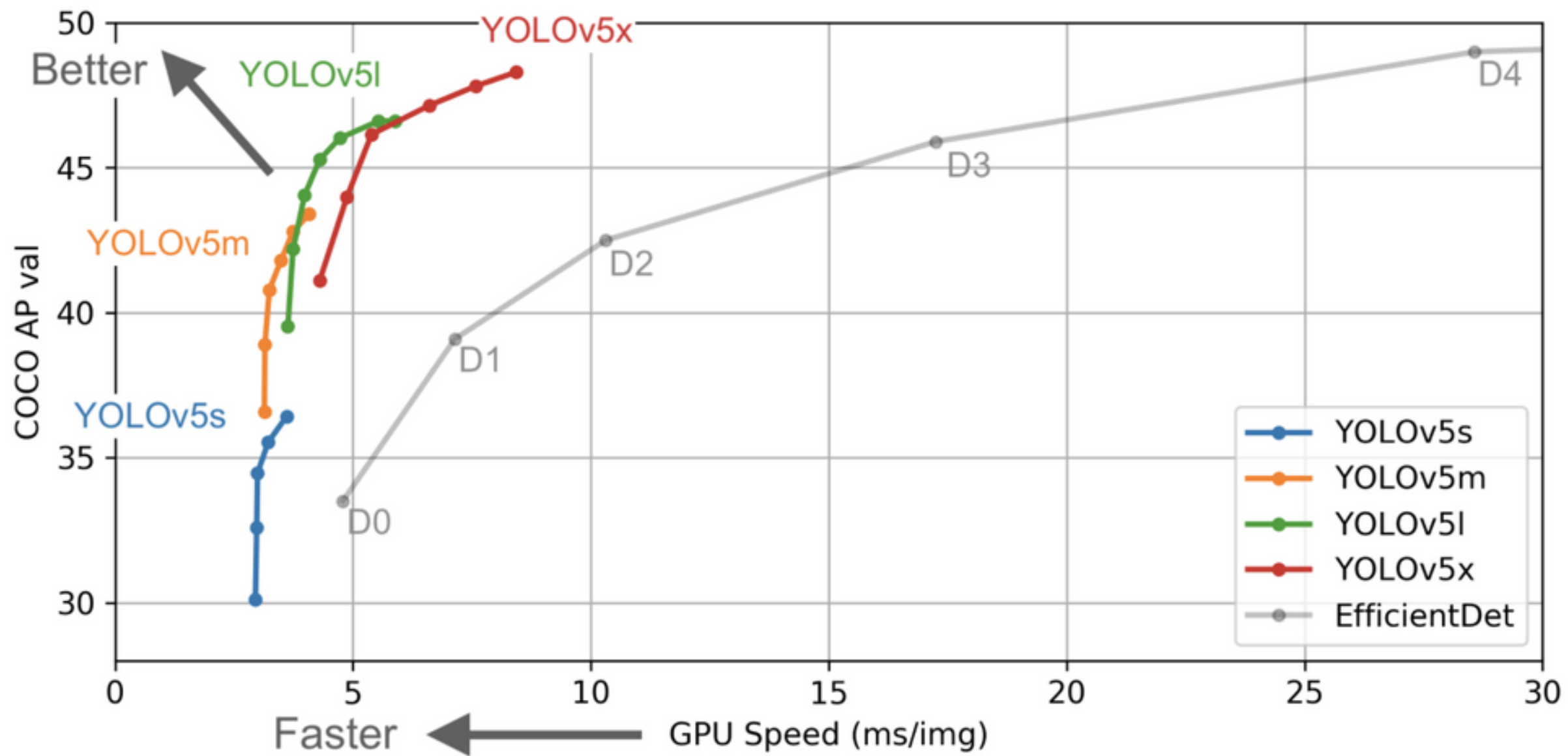


3. Suppress boxes with IoU above a selected threshold

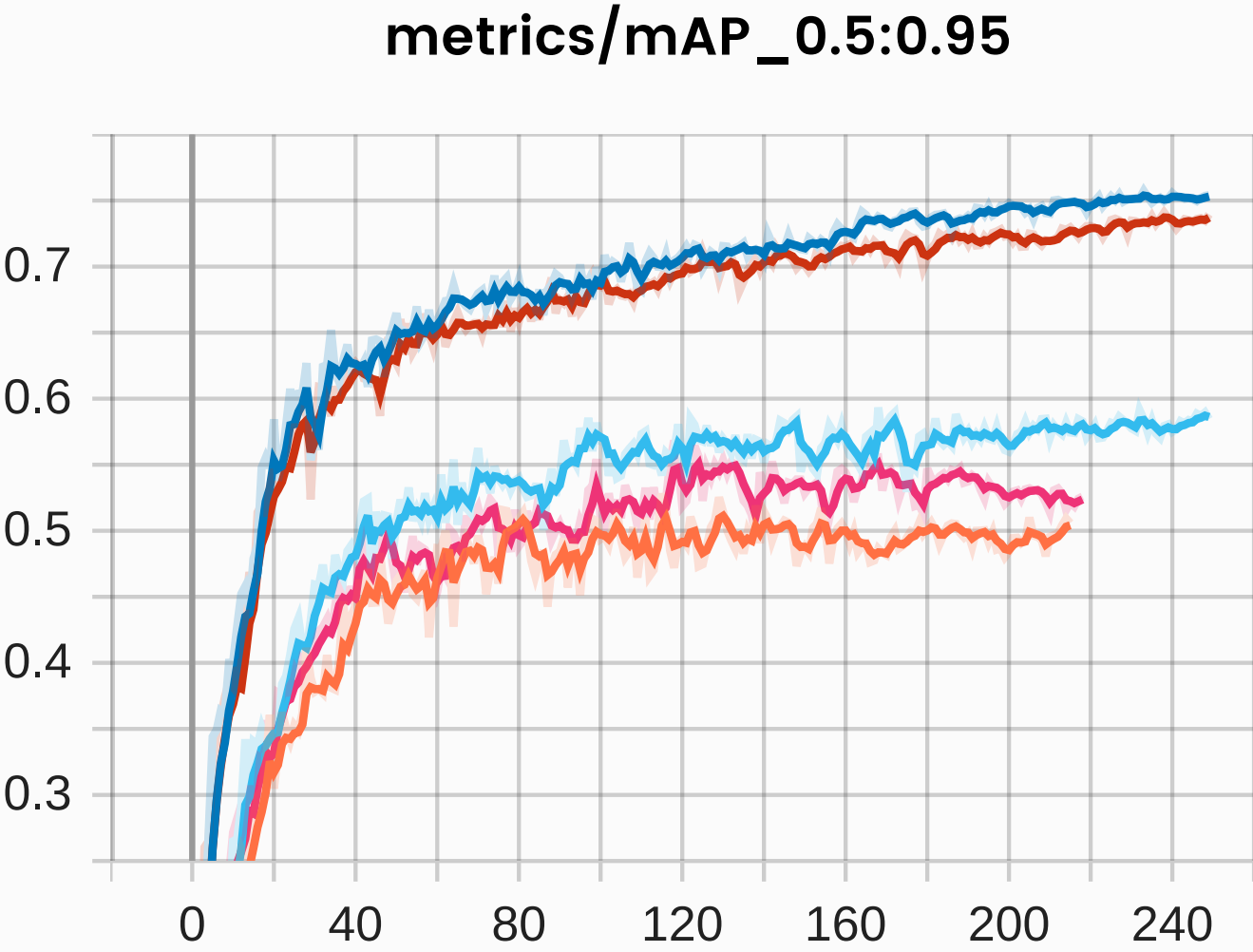
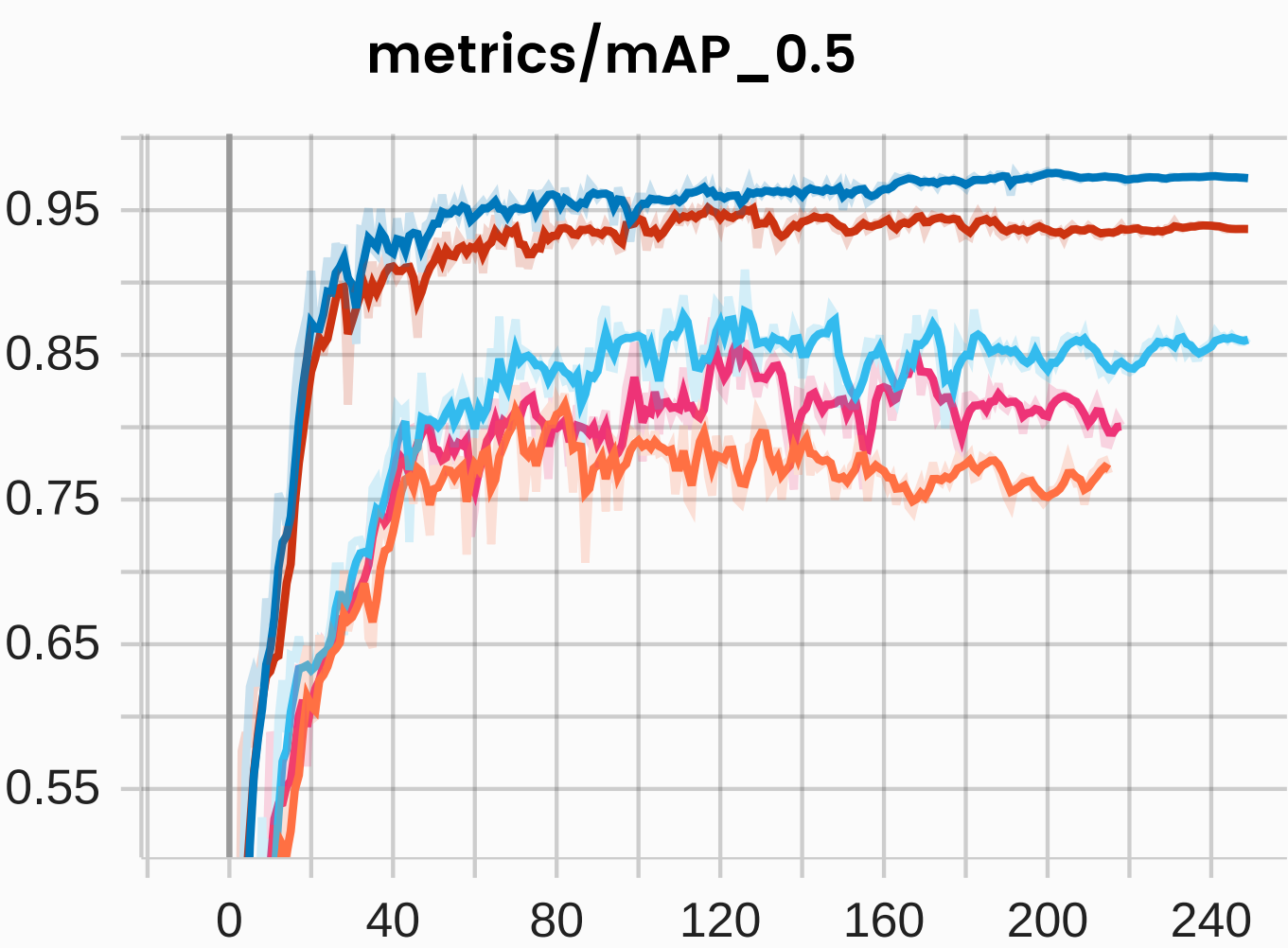
**IMPLEMENTING
YOLO**



YOLO-V5 MODEL SELECTION



EVALUATION METRICS

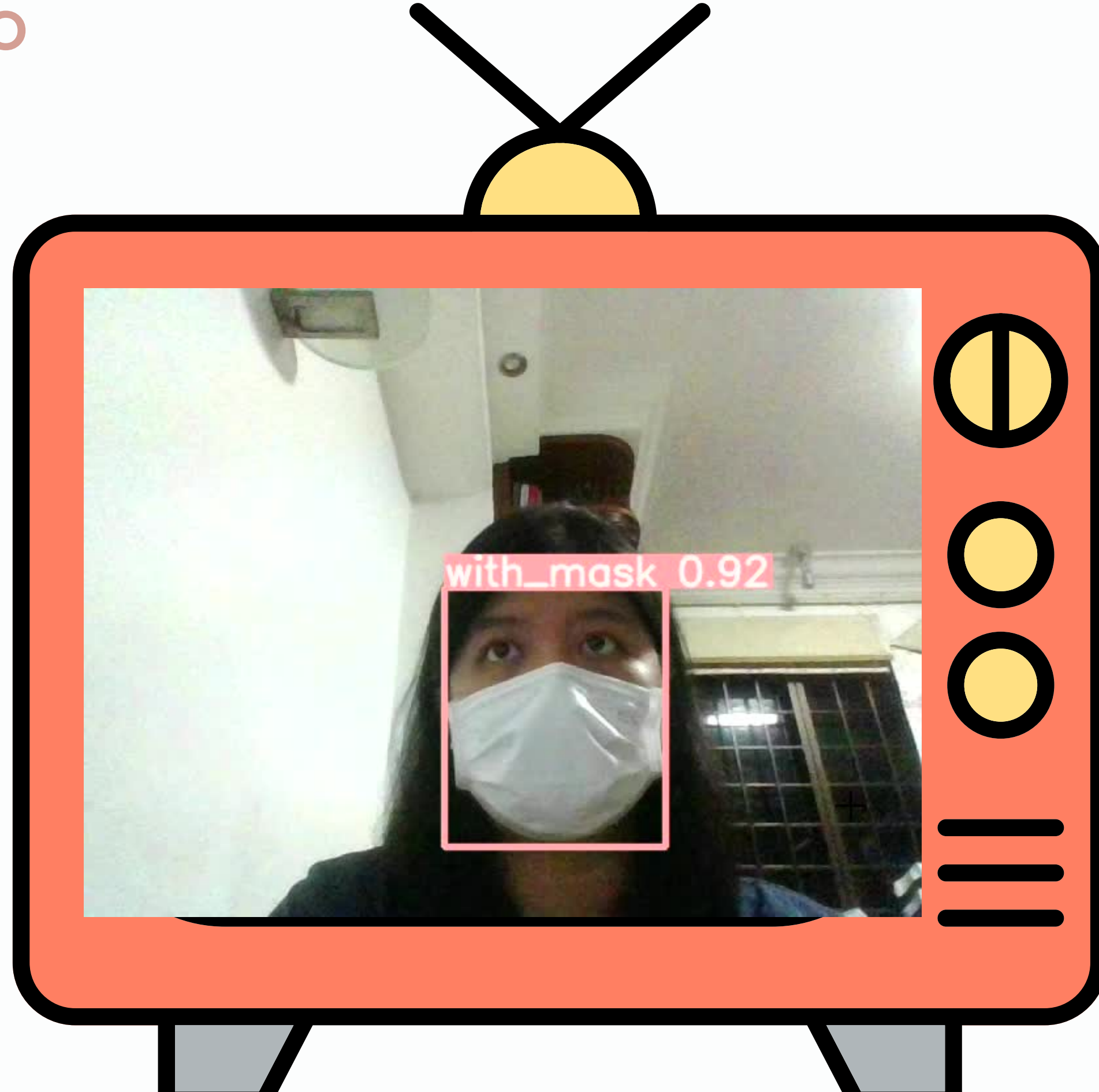


Models	mAP_0.5	m_AP_0.5:0.95
yolov5_416	0.82896	0.49641
yolov5_640_augment	0.97706	0.74817
yolov5_320_augment	0.95884	0.68944
yolov5_640	0.90891	0.57962
yolov5_320	0.87565	0.56838



CONCLUSION

VIDEO DEMO



FUTURE WORKS

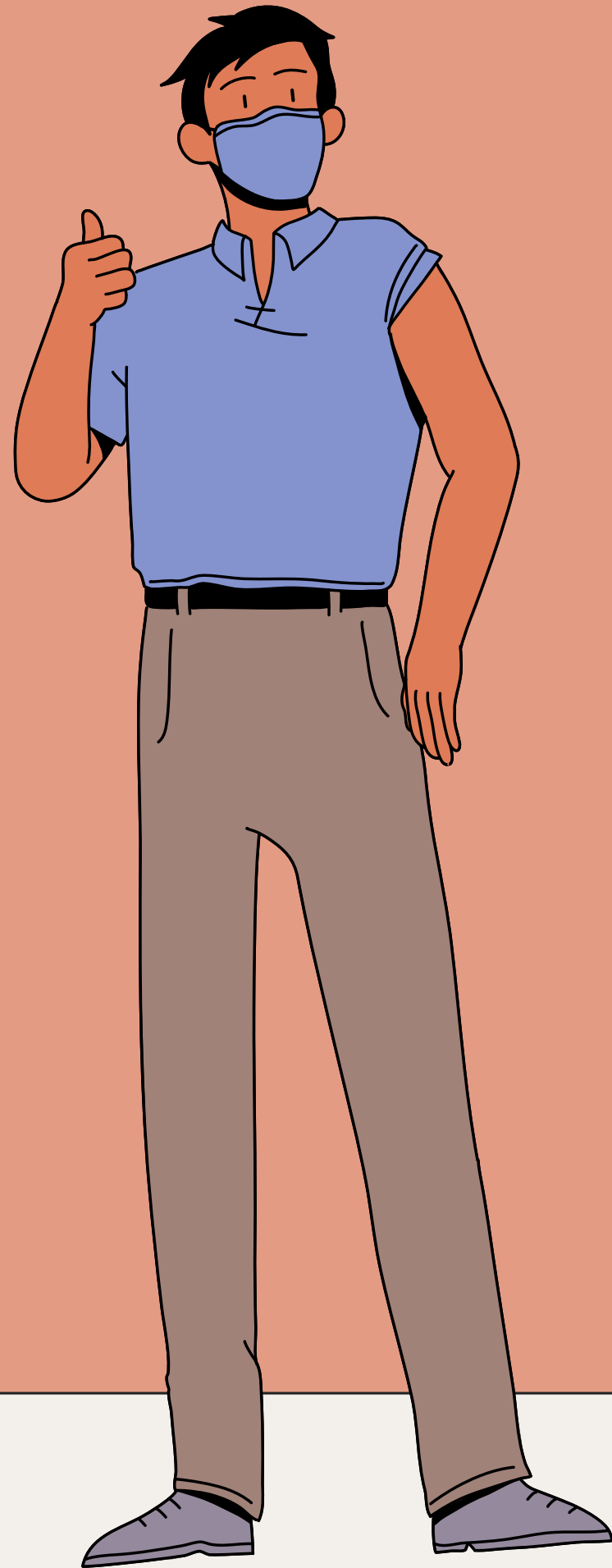
01 Collect more data

02 Explore other deep learning models such as Faster RCNN

03 Deploy the model

04 Fine tune the features





Thanks!

Any questions?

