

## EDUCATION

### UNIVERSITY OF WASHINGTON

DATA SCIENCE M.S.  
Spring 2020

### UNIVERSITY OF CALIFORNIA, LOS ANGELES

COMPUTER SCIENCE B.S.  
Spring 2017

### HONORS / SCHOLARSHIPS

Upsilon Pi Epsilon  
Eta Kappa Nu  
Commencement Student Speaker  
Henry M. Showman Prize  
Gerald J. Popek Scholarship in  
Computer Science  
Eric and Peggy Johnson Scholar-  
ship in Engineering

## SKILLS

### LANGUAGES

Python, C++/C, MATLAB/Octave,  
HTML/CSS, Javascript, SQL

### TECHNOLOGIES

VSTS | Kusto | Lens | PowerBI  
Shell/Bash | Arduino IDE | Git  
AutoDesk | OpenCV | Sklearn

## LINKS

Github: /kfrankc  
LinkedIn: /kfrankc  
Medium: @kfrankc  
Goodreads: /kfrankc

## COURSEWORK

Artificial Intelligence  
Machine Learning  
Mathematical Modeling  
Operating Systems  
UNIX/Linux Programming  
Database Systems  
Functional Programming  
Cybersecurity

## LEADERSHIP

### Resident Assistant

Fall 2015–June 2017  
Responsible for a floor of 90  
residents in UCLA Residential  
Dorms.

### LA Hacks Director of Mentorship

Fall 2015–Spring 2017  
Mentorship organizer of UCLA's  
Student Hackathon

### Bruin Entrepreneurs

Fall 2014–Spring 2015  
Led incubator program for UCLA  
student entrepreneurs

## EXPERIENCE

### MICROSOFT

#### PROGRAM MANAGER

Seattle, WA | July 2017 – present

- > Saved Service Engineers hundreds of hours using ML to auto-route SAP incidents
- > Drive onboarding & adoption for 1000+ components in CSE to Unified Telemetry Platform
- > Early in Career Lead for Core Platform Engineering, part of Diversity & Inclusion Initiative

### JET PROPULSION LABORATORY

#### COMPUTER VISION RESEARCH INTERN

Pasadena, CA | June 2015 – June 2016

- > Research Intern under Dr. Thomas Lu (349B)
- > Achieved 90 % accuracy for segmenting IR multi-bandwidth targets using neural network
- > Published two papers at SPIE conferences

### CENTER FOR VISION, COGNITION, LEARNING, AND AUTONOMY

#### UNDERGRADUATE RESEARCHER

Los Angeles, CA | March 2016 – April 2017

- > Undergraduate researcher for Dr. Song-Chun Zhu
- > Research in robot learning & fluent extraction
- > Built detection + tracking modules in OpenCV for teaching robots to fold shirts
- > Submitted papers to NIPS, IJCAI, and CoRL conferences.

### WORKDAY

#### APPLICATION DEVELOPMENT INTERN

Pleasanton, CA | June – Sept 2016

- > Implemented Tax Location Mapping Reports as part of Workday 28 Release.
- > Created get/put APIs for Workday Web Services

### TABOOOLA

#### SOFTWARE ENGINEERING INTERN

Los Angeles, CA | March – June 2016

- > Implemented user authentication systems using React & Node.js
- > Built modules to communicate with Taboola Backstage API from scratch

### CS 88S: UNDERGRADUATE STUDENT INITIATED EDUCATION (USIE)

#### STUDENT FACILITATOR

Los Angeles, CA | Sept 2016 – June 2017

- > Designed a 10-week undergraduate computer science seminar to introduce students to cybersecurity fundamentals & protecting themselves in cyberspace
- > Reached an international audience, with more than 1400 people subscribed to my weekly email updates on topics and relevant articles covered in the course

## PROJECTS

### IEEE NATCAR

Los Angeles CA | Sept 2014 – June 2015

Design, build, & race an autonomous RC car on tracks marked by 1"-wide white tape

**1st place** at UC Davis NATCAR Competition of 40+ teams.

**3rd place** at UCSD Grand PrIEEE Competition out of 30+ teams

### ROBOHOME [IDEA HACKS 2016]

Los Angeles CA | Feb 2016

Created model home with door, lights, shower, and TV that can be remotely controlled using Myo armband, Pebble, Smartphone, and laptop.

**1st Place** out of 200+ competitors

### MYODRONE [PENNAPPS 2015]

Philadelphia, MA | Jan 2014

Built a selfie-drone controlled using the Myo armband + Intel Edison

**Top 30** out of 1000+ competitors

## PUBLICATIONS

- |      |      |   |
|------|------|---|
| 2016 | SPIE | Cross-Correlation and Image Alignment for Multi-Band IR Sensors                     |
| 2017 | SPIE | Intelligent multi-spectral IR image segmentation                                    |
| 2017 | CoRL | Learning Human Utility from Video Demonstrations for Deductive Planning in Robotics |