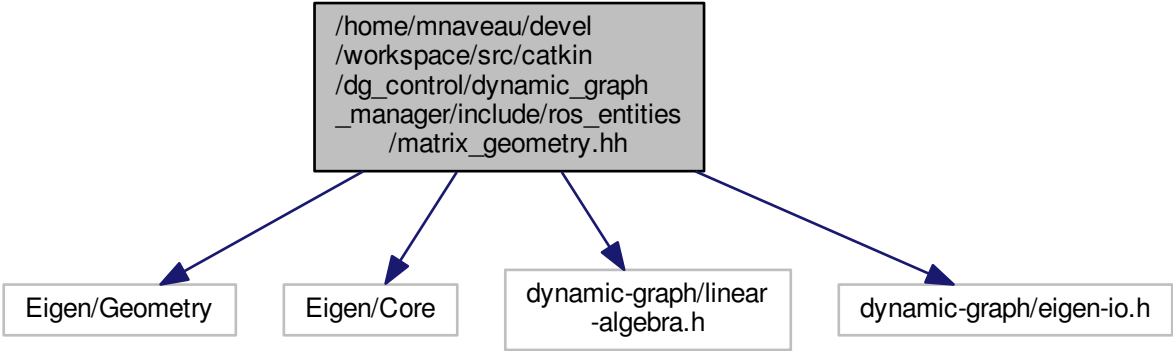


/home/mnaveau/devel
/workspace/src/catkin
/dg_control/dynamic_graph
_manager/include/ros_entities
/matrix_geometry.hh



```
graph TD; A["/home/mnaveau/devel  
/workspace/src/catkin  
/dg_control/dynamic_graph  
_manager/include/ros_entities  
/matrix_geometry.hh"] --> B["Eigen/Geometry"]; A --> C["Eigen/Core"]; A --> D["dynamic-graph/linear-algebra.h"]; A --> E["dynamic-graph/eigen-io.h"];
```

Eigen/Geometry

Eigen/Core

dynamic-graph/linear
-algebra.h

dynamic-graph/eigen-io.h