

include/dg\_blmc\_robots  
/dgm\_single\_motor.hpp

```
graph TD; A["include/dg_blmc_robots<br>/dgm_single_motor.hpp"] --> B["dynamic_graph_manager<br>/dynamic_graph_manager.hh"]; A --> C["blmc_robots/single<br>_motor.hpp"];
```

The diagram illustrates the include relationships for the file `include/dg_blmc_robots/dgm_single_motor.hpp`. It is shown in a grey box at the top. Two blue arrows point downwards from this box to two other boxes below it. The left box contains `dynamic_graph_manager/dynamic_graph_manager.hh` and the right box contains `blmc_robots/single_motor.hpp`.

dynamic\_graph\_manager  
/dynamic\_graph\_manager.hh

blmc\_robots/single  
\_motor.hpp