

Entity



```
graph BT; dynamic_graph_RosPublish[dynamic_graph::RosPublish] --> Entity
```

A UML class diagram illustrating inheritance. At the bottom is a gray-shaded box labeled 'dynamic\_graph::RosPublish'. A blue arrow points vertically upwards from this box to a white box labeled 'Entity' at the top. The arrow indicates that 'dynamic\_graph::RosPublish' inherits from 'Entity'.

dynamic\_graph::RosPublish