

include/ros\_entities  
/ros\_publish.hxx

```
graph BT; A["src/ros_entities/ros_publish.cpp"] --> B["include/ros_entities/ros_publish.hh"]; B --> C["include/ros_entities/ros_publish.hxx"]
```

include/ros\_entities  
/ros\_publish.hh

src/ros\_entities/ros  
\_publish.cpp