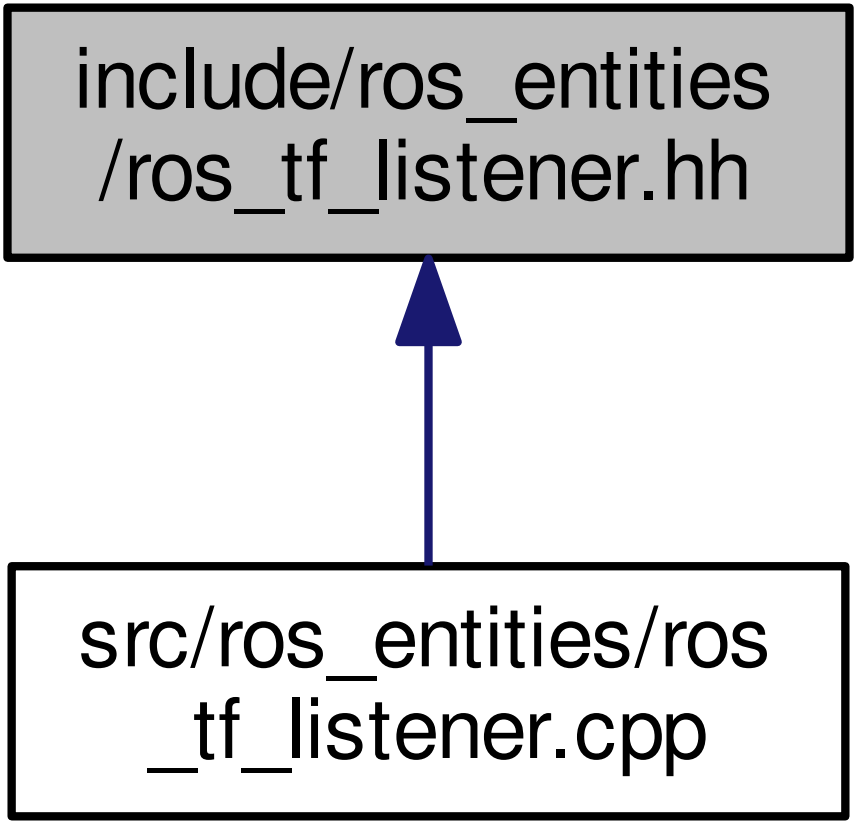
include/ros_entities
/ros_tf_listener.hh
src/ros_entities/ros
_tf_listener.cpp