

src/ros\_init.cpp

```
graph TD; A[src/ros_init.cpp] --> B["dynamic_graph_manager<br>/ros_init.hh"]; B --> C[ros/ros.h];
```

A vertical flowchart with three rectangular boxes. The top box is shaded gray and contains the text 'src/ros\_init.cpp'. A blue arrow points down from this box to a white box in the middle containing 'dynamic\_graph\_manager' and '/ros\_init.hh' on two lines. Another blue arrow points down from the middle box to a white box at the bottom containing 'ros/ros.h'.

dynamic\_graph\_manager  
/ros\_init.hh

ros/ros.h