

/home/mnaveau/devel  
/workspace/src/catkin  
/dg\_control/dynamic\_graph  
\_manager/src/ros\_init.cpp

```
graph TD; A["/home/mnaveau/devel  
/workspace/src/catkin  
/dg_control/dynamic_graph  
_manager/src/ros_init.cpp"] --> B["dynamic_graph_manager  
/ros_init.hh"]; B --> C["ros/ros.h"];
```

dynamic\_graph\_manager  
/ros\_init.hh

ros/ros.h