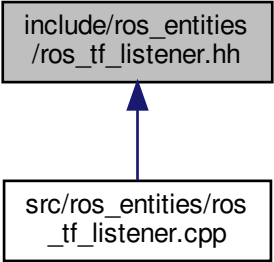


include/ros_entities
/ros_tf_listener.hh



```
graph BT; A["src/ros_entities/ros_tf_listener.cpp"] --> B["include/ros_entities/ros_tf_listener.hh"]
```

src/ros_entities/ros
_tf_listener.cpp