

include/dg_blmc_robots
/common_header.hpp

```
graph TD; A["include/dg_blmc_robots  
/common_header.hpp"] --> B["blmc_drivers/devices  
/motor.hpp"]; A --> C["blmc_drivers/devices  
/analog_sensor.hpp"];
```

The diagram illustrates the include relationships between three header files. At the top, a grey box contains the file 'include/dg_blmc_robots/common_header.hpp'. Two blue arrows point downwards from this box to two white boxes below. The left box contains 'blmc_drivers/devices/motor.hpp' and the right box contains 'blmc_drivers/devices/analog_sensor.hpp'.

blmc_drivers/devices
/motor.hpp

blmc_drivers/devices
/analog_sensor.hpp