

```
graph BT; A["/home/mnaveau/devel  
/workspace/src/catkin  
/dg_control/dynamic_graph  
_manager/src/ros_entities  
/ros_robot_state_publisher.cpp"] --> B["/home/mnaveau/devel  
/workspace/src/catkin  
/dg_control/dynamic_graph  
_manager/include/ros_entities  
/ros_robot_state_publisher.hpp"]
```

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