sympy

March 29, 2022

1 Basic usage

```
x
x^{2}
\sin(x)
x^{2} + 4x + 3
(x^{2} + 4x + 3)^{2}
(x + 1)^{2}(x + 3)^{2}
x^{4} + 8x^{3} + 22x^{2} + 24x + 9
```

2 Solve equations

smp.solve(f, x) will find x that makes f(x) = 0 Hence, it's important to rearrange the equation so that f(x) = 0

[-3, -1]

[-I, I]

[]

[5/2 - sqrt(29)/2, 5/2 + sqrt(29)/2]

[5/2 + sqrt(29)/2]

[5/2 - sqrt(29)/2]

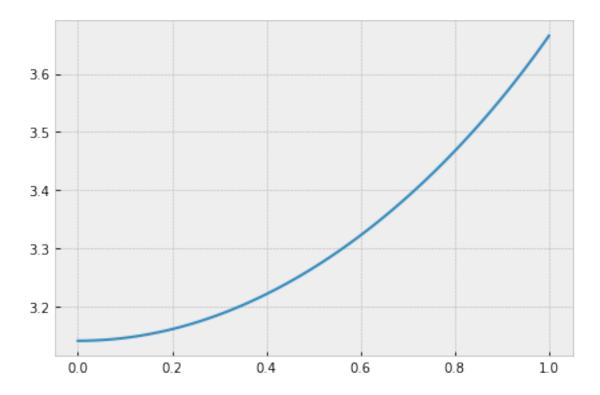
$$x^2 + y \sin(z)$$

x: [-sqrt(-y*sin(z)), sqrt(-y*sin(z))]
y: [-x**2/sin(z)]
z: [asin(x**2/y) + pi, -asin(x**2/y)]

asin $\left(\frac{x^2}{y}\right) + \pi$

<function _lambdifygenerated(x, y)>

3.6651914291880923



$$x^2 + y\sin\left(z\right)$$

$$x^2 + \sin(y)\cos(y)$$

Example given two equations,

$$h_o(t) = h_0 - v_0 t - \frac{1}{2}gt^2$$

$$h_p(t) = v_p t + \frac{1}{2} q t^2$$

solve for t, v_0 when,

$$h_o(t) = h_p(t)$$

$$\frac{dh_o}{dt}(t) = -\frac{dh_p}{dt}(t)$$

use smp.Rational(x,y) for fraction

$$-\frac{gt^2}{2} + h_0 - tv_0$$

$$\frac{qt^2}{2} + tv_p$$

rearrange so that f(x) = 0

$$h_o(t) - h_p(t) = 0$$
$$\frac{dh_o}{dt}(t) + \frac{dh_p}{dt}(t) = 0$$

$$-\frac{gt^2}{2} + h_0 - \frac{qt^2}{2} - tv_0 - tv_p$$
$$qt + qt - v_0 + v_p$$

$$\frac{-\frac{2v_p}{3} + \frac{\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2v_p^2}}{3}}{g + q}$$

$$\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2h_0q}$$

$$\frac{v_p}{3} + \frac{\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2v_p^2}}{3}$$

use .simplify() to simplify the expression

$$\frac{g\left(-\frac{2v_p}{3} + \frac{\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2v_p^2}}{3}\right)}{g + q} - \frac{v_p}{3} - \frac{\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2v_p^2}}{3}$$

$$\frac{-gv_p - \frac{qv_p}{3} - \frac{q\sqrt{6gh_0 + 6h_0q + 4v_p^2}}{3}}{g + q}$$

$$\frac{gv_p + \frac{qv_p}{3} + \frac{q\sqrt{6gh_0 + 6h_0q + 4v_p^2}}{3}}{a + q}$$

3 Calculus

3.1 Limit

$$\lim_{x \to \pi} \sin(\frac{x}{2} + \sin(x))$$

$$\sin\left(\frac{x}{2} + \sin\left(x\right)\right)$$

3.2 Derivatives

$$\frac{d}{dx} \left(\frac{1 + \sin x}{1 - \cos x} \right)^2$$

$$\frac{\left(\sin\left(x\right) + 1\right)^2}{\left(1 - \cos\left(x\right)\right)^2}$$

$$\frac{2(\sin(x) + 1)\cos(x)}{(1 - \cos(x))^2} - \frac{2(\sin(x) + 1)^2\sin(x)}{(1 - \cos(x))^3}$$

$$\frac{d}{dx}f(x+g(x))$$

$$(f(x + g(x)), g(x))$$

$$\left(\frac{d}{dx}g(x) + 1\right) \frac{d}{d\xi_1} f(\xi_1) \Big|_{\xi_1 = x + g(x)}$$

$$\left(\frac{d}{dx}\sin(x) + 1\right) \left. \frac{d}{d\xi_1} f(\xi_1) \right|_{\xi_1 = x + \sin(x)}$$

$$\left(\cos\left(x\right)+1\right)\left.\frac{d}{d\xi_{1}}f(\xi_{1})\right|_{\xi_{1}=x+\sin\left(x\right)}$$

3.3 Integrals

$$\csc(x)\cot(x)dx$$

$$\cot(x)\csc(x)$$

$$-\frac{1}{\sin\left(x\right)}$$

$$\int_0^{\ln(4)} \frac{e^x}{\sqrt{e^{2x} + 9}} dx$$

$$\frac{e^x}{\sqrt{e^{2x}+9}}$$

$$-\sinh\left(\frac{1}{3}\right) + \sinh\left(\frac{4}{3}\right)$$

$$\int_{1}^{t} x^{10} e^{x} dx$$

 $x^{10}e^x$

1334961e

Vector and Matrix

$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\lfloor u_3 \rfloor$$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

$$v_2$$

$$\begin{bmatrix} 2u_1 + v_1 \\ 2u_2 + v_2 \\ 2u_3 + v_3 \end{bmatrix}$$
$$u_1v_1 + u_2v_2$$

$$u_1v_1 + u_2v_2 + u_3v_3$$

$$\begin{bmatrix} u_2v_3 - u_3v_2 \\ -u_1v_3 + u_3v_1 \\ u_1v_2 - u_2v_1 \end{bmatrix}$$

$$\begin{bmatrix} u_1v_1 & u_1v_2 & u_1v_3 \\ u_2v_1 & u_2v_2 & u_2v_3 \\ u_3v_1 & u_3v_2 & u_3v_3 \end{bmatrix}$$

$$[u_1v_1 + u_2v_2 + u_3v_3]$$

$$\sqrt{|u_1|^2 + |u_2|^2 + |u_3|^2}$$

$$proj_v(u) = \frac{u \cdot v}{|v|^2}v$$

$$proj_v_u = u.dot(v) / (v.norm()**2) * v proj_v_u$$

$$\begin{bmatrix} 3t \\ \sin(t) \\ t^2 \end{bmatrix}$$

$$\begin{bmatrix} 3\\\cos\left(t\right)\\2t \end{bmatrix}$$

$$\begin{bmatrix} e^t \cos(t) \\ t^4 \\ \frac{1}{t^2 + 1} \end{bmatrix}$$

$$\begin{bmatrix} \frac{e^t \sin(t)}{2} + \frac{e^t \cos(t)}{2} \\ \frac{t^5}{5} \\ \operatorname{atan}(t) \end{bmatrix}$$

$$\begin{bmatrix} e^{t^2}\cos^3(t) \\ e^{-t^4} \\ \frac{1}{t^2+3} \end{bmatrix}$$

[0.84483859],

[0.30229989]])

Partial Derivatives

$$y^2 + \sin\left(x + y\right)$$

$$\cos(x+y)$$

$$2y + \cos(x + y)$$

$$\frac{\partial^3 f}{\partial x u^2}$$

$$-\cos(x+y)$$

$$-\cos(x+y)$$

5.1 Chain rule

$$w(x(t),y(t),z(t))$$

$$\frac{d}{dx(t)}w(x(t),y(t),z(t))\frac{d}{dt}x(t)+\frac{d}{dy(t)}w(x(t),y(t),z(t))\frac{d}{dt}y(t)+\frac{d}{dz(t)}w(x(t),y(t),z(t))\frac{d}{dt}z(t)$$

6 Multiple Integrals

- rarely works correctly using symbolic method
- usually needs numpy and scipy

this is the rare case that works

$$\int_{0}^{1} \int_{0}^{1-x^{2}} \int_{3}^{4-x^{2}-y^{2}} x dz dy dx$$

 $\frac{1}{8}$