





Splinoids project outline

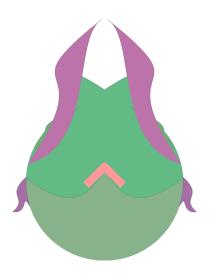
GODIN-DUBOIS Kevin

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Generated on April 6, 2020 Perma-link: kgd-al@github

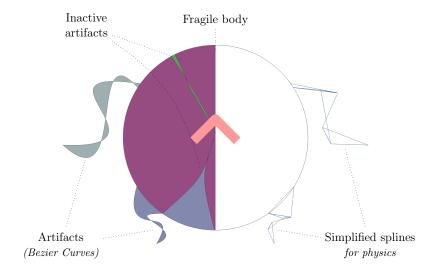
Splinoids

Spline + Boids



- 2D creatures
- Low-level combat
- Low-level vision
- Growth
- Autonomous reproduction
- Sexual dimorphism

Anatomy

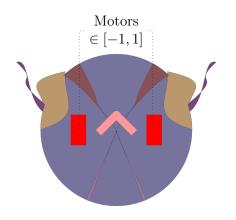


Combat

- Based on physical collision of primitives
- Both creatures receive damage¹
- Artifacts are denser and more resilient than the body
- Health regenerates but is costly

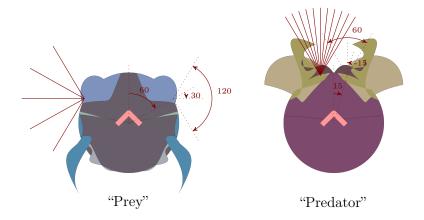
¹Unlike [2]

Motion



Tank-like behavior: $\{1, 1\} \rightarrow \text{Foward}$ $\{-1,-1\} \rightarrow \text{Backward}$ $\{-1, 1\} \rightarrow \text{Rotation}$ $\{1,-1\} \rightarrow$

Vision

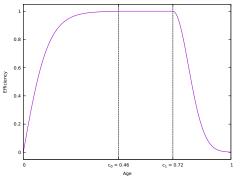


Parameterized by number of rays and angles

Audition Not implemented

- Similar approach to [1]
- Multiple emission channels (neural-controlled)
- As many reception
- Hearing range managed by physics engine
- Signal intensity = strength / distance²

Life-Cycle



Age conditions life-step:

- $[0, c_0]$ youth
- $[c_0, c_1]$ maturity
- $[c_1, 1]$ old age

Life-Cycle Youth



- Progressive growth of body size and artifacts
- Initial states are highly vulnerable

Life-Cycle Maturity

- Reproductive behavior
- Based on energy accumulation²
- ANN-controlled decision
- Not yet implemented

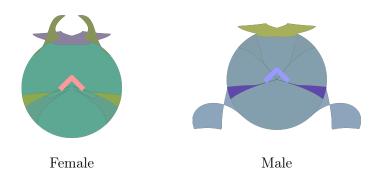
 $^{^{2}}$ as in [3]

Life-Cycle Senescence

Reduction of maximal speed

> increased chance of star vation and being preyed upon

Sexual dimorphism



Identical genotype (except gender)

 \rightarrow different phenotypes (shapes and colors)

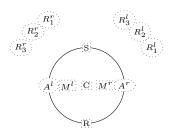
Metabolism

- Energy extracted from plants or corpses
- Baseline life cost
- Consumed energy returned to the environment

Metabolism Clock speed

- ANN-controlled value
- Genetically controlled bounds
- Impacts:
 - Motion speed
 - Resource absorption
 - Resource consumption
 - Regeneration

Neural controller



Inputs

 $R_i^s\colon$ retina cell triplet (r,g,b) i on side

 A^s : auditive cells (equal to number of channels)

-: proprioceptors (health, energy, efficiency)

Outputs

M^s: motor

C: Clock speed

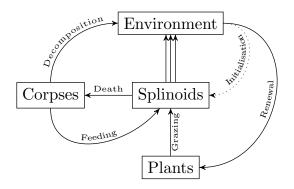
R: Reproduction

S: Multi-channel signal

Most nodes are geometrical \rightarrow HyperNeat?

Environment

Environment



Closed system with constant total energy level

Environment

Potential genetic variables:

- Size
- Taurus (bool)
- Obstacles (distribution)
- Plants (distribution)

Extensions

Extensions

- Asymetrical offspring investment
 - \rightarrow Emergence of sexual specialisation?
- Day/night cycle
 - \rightarrow Darkening of colors
 - \rightarrow Emergence of night-vision?

References

• References



David Kadish, Sebastian Risi, and Laura Beloff. "An artificial life approach to studying niche differentiation in soundscape ecology". In: *The 2019 Conference on Artificial Life*. Cambridge, MA: MIT Press, 2019, pp. 52–59.



Thomas Miconi. "Evosphere: Evolutionary dynamics in a population of fighting virtual creatures". In: 2008 IEEE Congress on Evolutionary Computation (IEEE World Congress on Computational Intelligence). IEEE, June 2008, pp. 3066–3073.



Peter Paul Pichler and Lola Cañamero. "Evolving morphological and behavioral diversity without predefined behavior primitives". In: Artificial Life XI: Proceedings of the 11th International Conference on the Simulation and Synthesis of Living Systems, ALIFE 2008 (2008), pp. 474–481.